

b)

The list is sorted, so start from the end, at the greatest  $x$ -coordinate.  $O(1)$

Add this coordinate to the list, staircase and save its  $y$ -value as stair-height.  $O(1)$

Iterating from greatest to least, if an element in the list has a  $y >$  stair-height, add the coordinate to staircase and  $\text{stair-height} := y$ .  $O(n)$

Repeat until reaching end of list.

c)

Find the rightmost point, and add it to list "staircase".  $O(n)$   
Let current  $\leftarrow$  rightmost point.  $O(1)$

From current point, search all points. If any point lies below this point, ignore it. From these points, choose the point closest in X-distance.

$O(n)$

Add this point to staircase.

Current  $\leftarrow$  closest in X-distance

Repeat until no point lie above current

$O(n + 1 + 1 + n(n+1))$

$n+1$ , because an additional check to ensure no point lie above the last point.

$O(n + n + nh)$

$O(nh)$

a)

Divide & Conquer

- We split all points until they are in groups of 1.

There are 4 cases for any two points, say a and b:

1  $a_x > b_x$  and  $a_y > b_y$

2  $a_x = b_x$  and  $a_y > b_y$

1  $a_x = b_x$

2  $a_x > b_x$  and  $a_y = b_y$

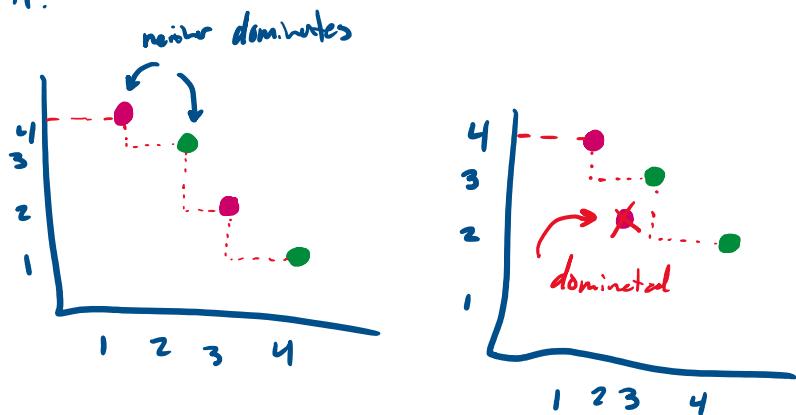
3  $a_x < b_x$  and  $a_y < b_y$

In cases 1, a

'dominates'  $b$ , meaning we can  
simply drop the point because it cannot  
be part of the staircase. a passes on.

In case 2,3,4,  
neither dominate and both  
can be part of the staircase, sort by  $x$   
and pass a and b on.

In the merging step, Scan from  
lowest  $x$  sides and track a running  
maximum  $x$  and  $y$ . If any point is  
dominated by the running local  $\max_x$  or  $\max_y$ ,  
drop it.



Keep merging until complete.

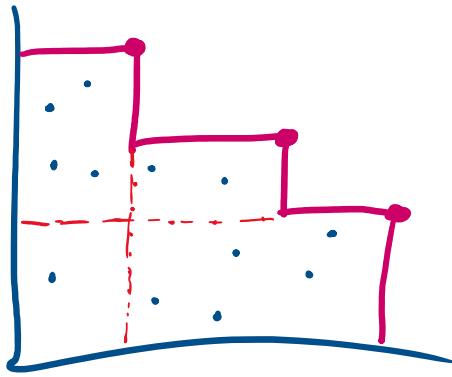
There are  $\log(n)$  levels and  
a linear  $O(n)$  scan is done at  
each level.

$$O(n \cdot \log(n))$$

d) To improve the  
algorithm in part A  
from  $O(n \cdot \log(n))$  to  
 $O(n \cdot \log(h))$ , we can only pass  
points on that must be on the  
staircase.

Observe that the 'top' of the  
staircase has the smallest  $x$  and  
greatest  $y$ . Conversely, the 'bottom'  
has the largest  $x$  and smallest  $y$ .

We can track these globally to  
exclude more points, preserving only  
global extremals.



We can split from the median  $O(n)$  into left and right, such that all points lie below the median in the left group and above the median on the right (on the x-axis).

Split until we have groups length  $\leq 2$ .

When merging on a left, track the left's  $\max_x$ , and drop any points where  $y < \max_y$ , or dominated like part A.

In parallel, on the right, track the right's  $\max_x$ , and drop any points where  $x < \max_x$ , or dominated like part A.

Sort by x-coordinate and pass on the extremes, like part A.

Sorting two sorted lists is  $O(n)$

Repeat until complete.

Median selection using medians of medians is  $O(n)$ .

Scanning and sorting two sorted lists is  $O(n)$ .

There are  $\log(h)$  levels

because each merge step guarantees one extremal is found due to the  $\max_x$  and  $\max_y$ . If each merge step guarantees a point, there can be at most  $\log(h)$  levels.

$$T(n,h) = 2n + T\left(\frac{n}{2}, h\right) + T\left(\frac{n}{2}, h\right)$$

$$T(n,h) = n \log h$$

$$\boxed{O(n \log h)}$$