

b)

The list is sorted, so
start from the end, at the
greatest x -coordinate. $O(1)$

Add this coordinate to the list,
staircase and save its y -value as
stair-height. $O(1)$

Iterating from greatest to least, if
an element in the list has a $y \geq \text{stair-height}$, $O(n)$
add the coordinate to staircase and
 $\text{stair-height} := y$.
Repeat until reaching end of list.

c)

Find the rightmost point, $O(n)$
and add it to list "staircase". $O(1)$
Let $\text{current} \leftarrow \text{rightmost point}$ $O(1)$

From current point, search all points. If any point lies below this point, ignore it. From these points, choose the point closest in X-distance.

Add this point to staircase.

Current \leftarrow closest in X-distance

Repeat until no point lie above current

$O(n)$

$$O(n + 1 + 1 + n(h+1))$$

$$O(n + n + nh)$$

$$O(nh)$$

$h+1$, because an additional check to ensure no point lie above the last point.

a)

Divide & Conquer

- We split all points until they are in groups of 1.

There are 4 cases for any two points, say a and b:

$$1 \ a_x > b_x \text{ and } a_y > b_y$$

$$2 \ a_x = b_x \text{ and } a_y > b_y$$

$$2 \ a_x = b_x \text{ and } a_y > b_y$$

$$3 \ a_x > b_x \text{ and } a_y = b_y$$

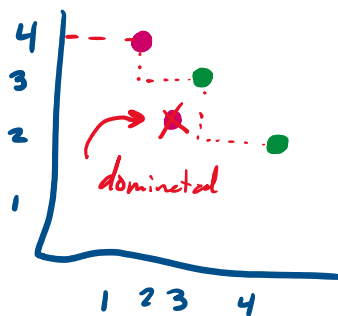
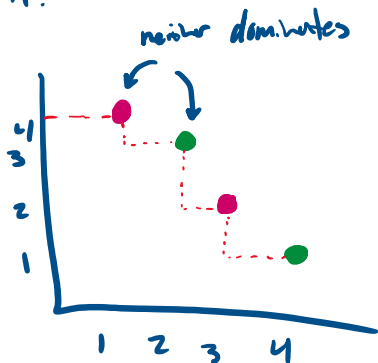
$$4 \ a_x > b_x \text{ and } a_y < b_y$$

In cases 1, a

'dominates' b, meaning we can simply drop the point because it cannot be part of the staircase. a passes on.

In case ^{2,3,4}, neither dominates and both can be part of the staircase, sort by x and pass a and b on.

In the merging step, scan from lowest x sides and track a running maximum x and y. If any point is dominated by the running local \max_x or \max_y , drop it.



Keep merging until complete.

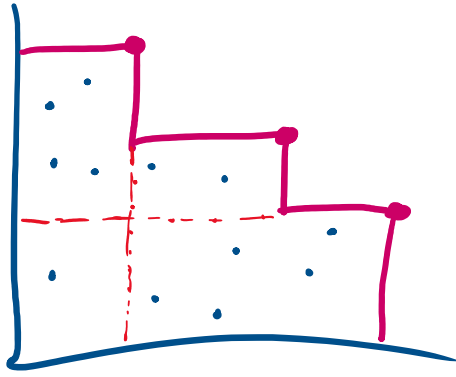
There are $\log(n)$ levels and a linear $O(n)$ scan is done at each level.

$$O(n \cdot \log(n))$$

d) To improve the algorithm in part A from $O(n \cdot \log(n))$ to $O(n \cdot \log(h))$, we can only pass points on that must be on the staircase.

Observe that the 'top' of the staircase has the smallest x and greatest y . Conversely, the 'bottom' has the largest x and smallest y .

We can track these globally to exclude more points, preserving only global extremes.



We can split from the median $O(n)$ into left and right, such that all points lie below the median in the left group and above the median on the right (on the x-axis).

Split until we have groups length ≤ 2 .

When merging on a left, track the left's

\max_x , and drop any points where $y < \max_y$, or dominated like part A.

In parallel, on the right, track the right's \max_x ,

and drop any points where $x < \max_x$, or dominated like part A.

Sort by x-coordinate and pass on the extremals, like part A.

Sorting two sorted lists is $O(n)$

Repeat until complete.

Median selection using median of medians is $O(n)$.

Scanning and sorting two sorted lists is $O(n)$.

There are $\log(h)$ levels

because each merge step guarantees one extremal is found due to the \max_x and \max_y . If each merge step guarantees a point, there can be at most $\log(h)$ levels.

$$T(n, h) = 2n + T\left(\frac{n}{2}, h\right) + T\left(\frac{n}{2}, h\right)$$

$$T(n, h) = n \log h$$

$$\boxed{O(n \log h)}$$