

MM: 110

Question paper is printed on BOTH sides (total 6 questions). Symbols have their usual notations.
 YOUR ANSWERS MUST BE JUSTIFIED. Simply writing YES/NO will not fetch you any marks.
 All parts of a question must be answered together and in the same sequence as given in question paper. ELSE NO MARKS will be awarded for plots without proper labeling of axes.

Q1. Find the Z-transform & ROC of

$$(i) x(n) = 2\left(\frac{5}{6}\right)^n u(-n-1) + 3\left(\frac{1}{2}\right)^n u(n)$$

Sketch the ROC and pole-zero location, also comment on causality & stability of this system. 8

(ii) Find the Z-transform of $x(n)$, where $x(n)$ is:

$$x(n) = \{2, 1, 3, 5, 0, 7\}$$

(iii) Obtain T-equivalent model, of a Z-parameter matrix of a two port network at $\omega = 100$ rad/s given by:

$$[Z] = \begin{bmatrix} 4 & 2+j1 \\ 2+j1 & -3j \end{bmatrix}$$

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Q2 (i) Find the 8 point DFT using decimation in time FFT for the given signal. 10

$$x(t) = A \cos(8\pi t), \text{ Assume } A=2;$$

(ii) Find the sampling rate and sampling interval of the pulse signal as shown in the Figure 2. Assume that the pulse is generated from its first ten harmonics only. Assume T=0.2 sec.

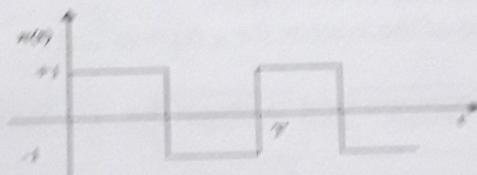
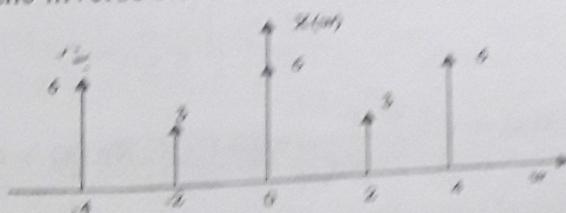


Figure 2. Pulse signal

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Q3 (i) Find the inverse Fourier transform of the spectrum shown in Figure 3 (i) 10



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Figure 3(i)

(ii) For the signal $x(t)$ shown in Figure 3(ii), evaluate the following quantities without explicit computing $X(\omega)$: (a) $\int_{-\infty}^{\infty} X(\omega) d\omega$ (b) $\int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$ (c) $\int_{-\infty}^{\infty} X(\omega) e^{j2\omega} d\omega$ (d) $X(0)$ 8

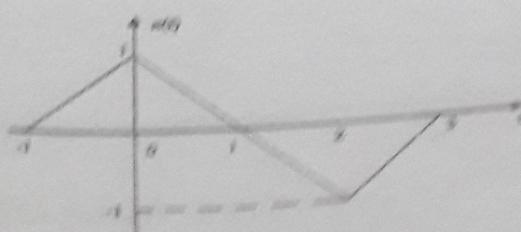


Figure 3(ii)

Q4. (i) Find the trigonometric Fourier series for the waveform shown in Figure 4(i).

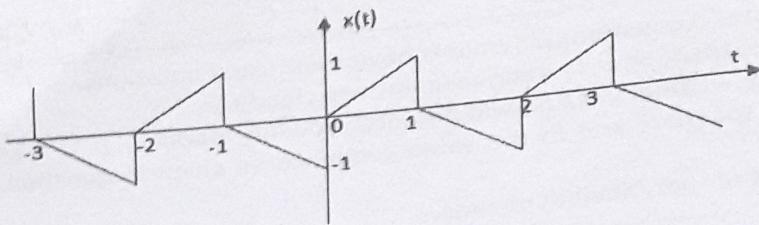


Figure 4(i)

(ii) Find the discrete-time Fourier series coefficients for $x(n)$

$$x(n) = \sin\left(\frac{\pi}{3}\right)n + \cos\left(\frac{\pi}{6}\right)n$$

Q5. (i) Given the system having input $x(n)$ and output $y(n)$ and described by the relationship:

$$y(n) = \sum_{k=-\infty}^n x(k+2),$$

Determine if the system is:

(a) Memory-less, (b) stable, (c) causal, (d) linear and (e) time invariant.

(ii) Evaluate and sketch $y(t) = x(t) * h(t)$ for a continuous-time LTI system whose impulse response $h(t)$ and the input $x(t)$ are given by:

$$h(t) = u(t) - u(t-4) \text{ and } x(t) = 2[u(t-4) - u(t-6)] \quad [\text{Use the graphical method only}].$$

(iii) The input & output of a causal LTI system are described by the differential equation:

$$\frac{d^2 y(t)}{dt^2} + \frac{3dy(t)}{dt} + 2y(t) = x(t)$$

- a) Find the frequency response of the system.
- b) Find the impulse response of the system.
- c) What is the response of the system for $x(t) = te^{-t}u(t)$?

Q6. (i) Use the properties of Laplace transform to obtain the $X(s)$ of the following:

$$(a) x(t) = \frac{d}{dt} \{ t e^{-t} u(t) \}$$

$$(b) x(t) = u(t-1) * e^{-2t} u(t-1)$$

(ii) Use the properties of Laplace Transforms to determine the time signals that correspond to the following bilateral Laplace transforms

$$(a) X(s) = e^{5s} \frac{1}{s+2} \text{ with ROC } \operatorname{Re}(s) < -2$$

$$(b) X(s) = s^{-2} \frac{d}{ds} \left| \frac{e^{-3s}}{s} \right| \text{ with ROC } \operatorname{Re}(s) > 0$$

(iii) Suppose the following facts are given about the signal $x(t)$ with Laplace transform $X(s)$:

(a) $x(t)$ is real and even

(b) $X(s)$ has four poles, no zeroes in the finite s -plane.

(c) $X(s)$ has a pole at $s = (1/2)e^{j\pi/4}$

$$(d) \int_{-\infty}^{\infty} x(t) dt = 4$$

Determine $X(s)$ and ROC.