

Consistent Subtyping for All

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The University of Hong Kong ESOP 2018, Thessaloniki, Greece

Gradual Typing 101

 The key external feature of every gradual type system is the unknown type *.

```
f (x : Int) = x + 2 \frac{--\text{ static checking}}{--\text{ dynamic checking}}
h f
```

- Central to gradual typing is type consistency ~, which relaxes type equality: * ~ Int, * → Int ~ Int → *,...
- Dynamic semantics is defined by type-directed translation to an internal language with runtime casts:

$$(\langle \star \hookrightarrow \star \to \star \rangle g) (\langle \star \hookrightarrow \mathsf{Int} \rangle 1)$$

Many Successes

Gradual typing has seen great popularity both in academia and industry. Over the years, there emerge many gradual type disciplines:

- Subtyping
- Parametric Polymorphism
- Type inference
- Security Typing
- Effects
- . . .

Many Successes, But...

Gradual typing has seen great popularity both in academia and industry. Over the years, there emerge many gradual type disciplines:

- Subtyping
- Parametric Polymorphism
- Type inference
- Security Typing
- Effects
- . . .
 - As type systems get more complex, it becomes more difficult to adapt notions of gradual typing.

 [Garcia et al., 2016]

Problem

• Can we design a gradual type system with *implicit higher-rank* polymorphism?

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- State-of-art techniques are inadequate.

Why It Is interesting

 Haskell supports implicit higher-rank polymorphism, but some "safe" programs are rejected:

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• If we had gradual typing...

```
let f(x : \star) = (x [1, 2], x ['a', 'b'])
in f reverse
```

Why It Is interesting

 Haskell supports implicit higher-rank polymorphism, but some "safe" programs are rejected:

• If we had gradual typing...

```
let f(x : \star) = (x [1, 2], x ['a', 'b'])
in f reverse
```

 Moving to more precised version still type checks, but with more static safety guarantee:

```
let f (x : \forall a. [a] \rightarrow [a]) = ... in f reverse
```

Contributions

- A new specification of consistent subtyping that works for implicit higher-rank polymorphism
- An easy-to-follow recipe for turning subtyping into consistent subtyping
- A gradually typed calculus with implicit higher-rank polymorphism
 - Satisfies correctness criteria (formalized in Coq)
 - A sound and complete algorithm

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Definition (Consistent Subtyping à la Siek and Taha)

The following two are equivalent:

- 1. $A \lesssim B$ if and only if $A \sim C$ and C <: B for some C.
- 2. $A \lesssim B$ if and only if A <: C and $C \sim B$ for some C.

Design Principle

Gradual typing and subtyping are orthogonal and can be combined in a principled fashion.

Challenge

- Polymorphic types induce a subtyping relation: $\forall a. \ a \rightarrow a <: \mathsf{Int} \rightarrow \mathsf{Int}$
- Design consistent subtyping that combines 1) consistency 2) subtyping 3) polymorphism.

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- Polymorphic types induce a subtyping relation: $\forall a, a \rightarrow a <: Int \rightarrow Int$
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- Gradual typing and polymorphism are orthogonal and can be combined in a principled fashion.¹

¹Note that here we are mostly concerned with static semantics.

Problem with Existing Definition

Odersky-Läufer Type System

 The underlying static language is the well-established type system for higher-rank types. [Odersky and Läufer, 1996]

Types	A, B	::=	Int $\mid a \mid A ightarrow B \mid orall a.$ A
Monotypes	τ, σ	::=	Int $\mid a \mid au ightarrow \sigma$
Terms	е	::=	$x \mid n \mid \lambda x : A.\ e \mid \lambda x.\ e \mid e_1\ e_2$
Contexts	Ψ	::=	$\bullet \mid \Psi, x : A \mid \Psi, a$

Subtyping

$$\Psi \vdash A <: B$$

(Subtyping)

$$\frac{a \in \Psi}{\Psi \vdash a <: a} \qquad \frac{\Psi \vdash B_1 <: A_1 \qquad \Psi \vdash A_2 <: B_2}{\Psi \vdash A_1 \to A_2 <: B_1 \to B_2}$$

$$\frac{\Psi \vdash \tau \qquad \Psi \vdash A[a \mapsto \tau] <: B}{\Psi \vdash \forall a. A <: B} \qquad \frac{\Psi, a \vdash A <: B}{\Psi \vdash A <: \forall a. B}$$

$$\frac{\Psi, a \vdash A <: B}{\Psi \vdash A <: \forall a, B}$$

Subtyping with Unknown Types

$$\Psi \vdash A <: B$$

(Subtyping)

$$\frac{a \in \Psi}{\Psi \vdash a <: a} \qquad \frac{\Psi \vdash B_1 <: A_1 \qquad \Psi \vdash A_2 <:}{\Psi \vdash A_1 \to A_2 <: B_1 \to B_2}$$

$$\overline{\hspace{1em}\psi\vdash}$$

$$\frac{\Psi \vdash B_1 <: A_1 \qquad \Psi \vdash A_2 <: B_2}{\Psi \vdash A_1 + A_2 <: B_2 + B_2}$$

$$\frac{\Psi \vdash \tau \qquad \Psi \vdash A[a \mapsto \tau] <: B}{\Psi \vdash \forall a. \ A <: B}$$

$$\overline{\Psi \vdash A <: \forall a. B}$$



Type Consistency

 $A \sim B$

(Type Consistency)

$$\frac{}{A \sim A} \qquad \frac{}{A \sim \star} \qquad \frac{A_1 \sim B_1}{} \qquad \frac{A_2 \sim B_2}{} \qquad \frac{}{A_1 \rightarrow A_2 \sim B_1 \rightarrow B_2}$$

Type Consistency with Polymorphic Types

 $A \sim B$

(Type Consistency)

$$\frac{}{A \sim A} \qquad \frac{}{A \sim \star} \qquad \frac{}{\star \sim A} \qquad \frac{A_1 \sim B_1}{A_1 \rightarrow A_2 \sim B_1 \rightarrow B_2}$$

$$\frac{A \sim B}{\forall a. A \sim \forall a. B}$$

Type Consistency with Polymorphic Types

$$A \sim B$$

(Type Consistency)

$$\overline{A \sim A}$$

 $\overline{A} \sim \star \qquad \qquad \star \sim A$

$$\frac{A_1 \sim B_1}{A_1 \rightarrow A_2 \sim B_1 \rightarrow B_2}$$

$$\frac{A \sim B}{\forall a. \ A \sim \forall a. \ B}$$

The simplicity comes from the orthogonality between consistency and subtyping!

Definition (Consistent Subtyping à la Siek and Taha)

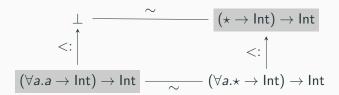
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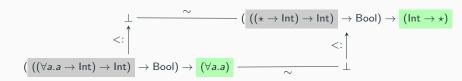
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Revisiting Consistent Subtyping

Consistent Subtyping vs. Subtyping

• Subtyping validates the *subsumption principle*

$$\frac{\Psi \vdash e : A \qquad A <: B}{\Psi \vdash e : B}$$

Consistent Subtyping vs. Subtyping

 Subtyping validates the subsumption principle, so should consistent subtyping

$$\frac{\Psi \vdash e : A \qquad A \lesssim B}{\Psi \vdash e : B}$$

Consistent Subtyping vs. Subtyping

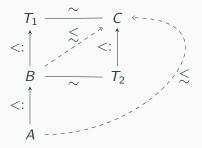
 Subtyping validates the subsumption principle, so should consistent subtyping

$$\frac{\Psi \vdash e : A \qquad A \lesssim B}{\Psi \vdash e : B}$$

Subtyping is transitive, but consistent subtyping is not

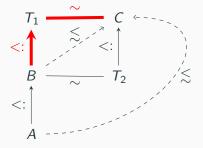
Observation (I)

If A <: B and $B \lesssim C$, then $A \lesssim C$.



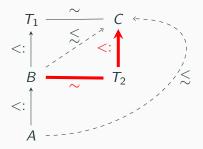
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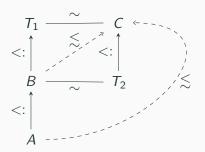


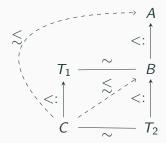
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Observation (II)

If $C \lesssim B$ and B <: A, then $C \lesssim A$.





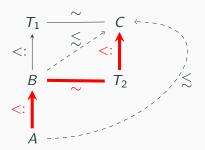
Observations

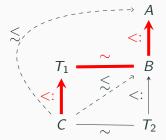
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Consistent Subtyping, the Specification

Definition (Generalized Consistent Subtyping)

$$\Psi \vdash A \lesssim B \stackrel{\mathit{def}}{=} \Psi \vdash A <: A', \ A' \sim B' \ \mathsf{and} \ \Psi \vdash B' <: B \ \mathsf{for \ some} \ A' \ \mathsf{and} \ B'.$$

Consistent Subtyping, the Specification

Definition (Generalized Consistent Subtyping)

$$\Psi \vdash A \lesssim B \stackrel{\text{def}}{=} \Psi \vdash A <: A' \text{, } A' \sim B' \text{ and } \Psi \vdash B' <: B \text{ for some } A' \text{ and } B'.$$

$$(((\star \to \mathsf{Int}) \to \mathsf{Int}) \to \mathsf{Bool}) \to (\mathsf{Int} \to \star)$$

$$<: \qquad \qquad \qquad \\ <: \qquad \qquad \\ <: \qquad \qquad \\ ((((\forall a.a \to \mathsf{Int}) \to \mathsf{Int}) \to \mathsf{Bool}) \to (\forall a.a)$$

$$A = ((\forall a.a \to \mathsf{Int}) \to \mathsf{Int}) \to \mathsf{Bool}) \to (\mathsf{Int} \to \mathsf{Int})$$

$$B = ((\forall a.\star \to \mathsf{Int}) \to \mathsf{Int}) \to \mathsf{Bool}) \to (\mathsf{Int} \to \star)$$

Non-Determinism

Definition (Generalized Consistent Subtyping)

$$\Psi \vdash A \lesssim B \stackrel{\text{def}}{=} \Psi \vdash A <: A', \ A' \sim B' \ \text{and} \ \Psi \vdash B' <: B \ \text{for some} \ A' \ \text{and} \ B'.$$

Two sources of non-determinism:

1. Two intermediate types A' and B'

Non-Determinism

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$$\Psi \vdash A \lesssim B \stackrel{\text{def}}{=} \Psi \vdash A <: A', \ A' \sim B' \ \text{and} \ \Psi \vdash B' <: B \ \text{for some} \ A' \ \text{and} \ B'.$$

Two sources of non-determinism:

1. Two intermediate types A' and B'

$$\frac{\Psi \vdash \tau \qquad \Psi \vdash A[a \mapsto \tau] <: B}{}$$

2. Guessing monotypes $\Psi \vdash \forall a. A <: B$

Non-Determinism

Definition (Generalized Consistent Subtyping)

 $\Psi \vdash A \lesssim B \stackrel{\mathit{def}}{=} \Psi \vdash A <: A', \ A' \sim B' \ \mathsf{and} \ \Psi \vdash B' <: B \ \mathsf{for \ some} \ A' \ \mathsf{and} \ B'.$

Two sources of non-determinism:

- 1. Two intermediate types A' and B'
 - We can derive a syntax-directed inductive definition without resorting to subtyping or consistency at all!

Consistent Subtyping Without Existentials

Notice
$$\Psi \vdash \star \lesssim A$$
 always holds $(\star <: \star \sim A <: A)$, and vise versa $(\Psi \vdash A \lesssim \star)$

Consistent Subtyping Without Existentials: First Step

$$\begin{array}{c|c} \Psi \vdash A <: B \\ \hline \\ \hline \\ \Psi \vdash a <: a \end{array} \qquad \begin{array}{c} \hline \\ \Psi \vdash Int <: Int \end{array} \qquad \begin{array}{c} \Psi \vdash B_1 <: A_1 \quad \Psi \vdash A_2 <: B_2 \\ \hline \\ \Psi \vdash A_1 \rightarrow A_2 <: B_1 \rightarrow B_2 \end{array} \\ \hline \\ \hline \\ \Psi \vdash \forall a. A <: B \end{array} \qquad \begin{array}{c} \Psi, a \vdash A <: B \\ \hline \\ \Psi \vdash A <: \forall a. B \end{array}$$

$$\Psi \vdash \star <: \star$$

Consistent Subtyping Without Existentials: First Step

$$\Psi \vdash \star \lesssim \star$$

Consistent Subtyping Without Existentials: Second Step

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$$\begin{array}{c|c} \hline \Psi \vdash A \lesssim B \\ \hline \\ \hline A \in \Psi \\ \hline \Psi \vdash A \lesssim A \end{array} \qquad \begin{array}{c} \hline \Psi \vdash B_1 \lesssim A_1 & \Psi \vdash A_2 \lesssim B_2 \\ \hline \Psi \vdash A_1 \to A_2 \lesssim B_1 \to B_2 \end{array} \\ \hline \\ \hline \\ \Psi \vdash \Psi = A[a \mapsto \tau] \lesssim B \\ \hline \\ \Psi \vdash A \lesssim A \lesssim B \end{array} \qquad \begin{array}{c} \hline \Psi, a \vdash A \lesssim B \\ \hline \Psi \vdash A \lesssim \forall a, B \end{array}$$

$$\overline{\Psi \vdash \star \lesssim A} \qquad \overline{\Psi \vdash A \lesssim \star}$$

Definition Meets Specification

Theorem

 $\Psi \vdash A \lesssim B \text{ iff } \Psi \vdash A <: A', A' \sim B' \text{ and } \Psi \vdash B' <: B \text{ for some } A' \text{ and } B'.$

Declarative Type System

Type System

Ψ ⊢ *e* : *A*

$$\frac{\Psi, a \vdash e : A}{\Psi \vdash e : \forall a. A} \text{ U-GEN}$$

$$\frac{\Psi, x: \tau \vdash e: B}{\Psi \vdash \lambda x. \, e: \tau \to B} \stackrel{\text{\tiny{U-LAM}}}{}$$

(Typing, selected rules)

$$\frac{\Psi, x: A \vdash e: B}{\Psi \vdash \lambda x: A.\, e: A \rightarrow B} \stackrel{\text{\tiny U-LAMANN}}{}$$

$$\begin{split} \frac{\Psi \vdash e_1 : A & \Psi \vdash A \triangleright A_1 \rightarrow A_2}{\Psi \vdash e_2 : A_3 & \Psi \vdash A_3 \lesssim A_1} \\ \frac{\Psi \vdash e_2 : A_3 & \Psi \vdash A_3 \lesssim A_1}{\Psi \vdash e_1 e_2 : A_2} \end{split}$$
 U-APP

Type System

$$\begin{array}{c|c} \Psi \vdash e_1 : A & \Psi \vdash A \triangleright A_1 \rightarrow A_2 \\ \hline \Psi \vdash e_2 : A_3 & \Psi \vdash A_3 \lesssim A_1 \\ \hline \Psi \vdash e_1 e_2 : A_2 & & \text{U-APP} \end{array}$$

$$\begin{array}{c|c} \Psi \vdash A \triangleright A_1 \to A_2 \end{array} \qquad \qquad \begin{array}{c} (\textit{Matching}) \\ \hline \\ \Psi \vdash \tau \qquad \Psi \vdash A[a \mapsto \tau] \triangleright A_1 \to A_2 \\ \hline \\ \Psi \vdash \forall a. \ A \triangleright A_1 \to A_2 \end{array} \xrightarrow{\text{M-INKNOWN}} \\ \hline \\ \frac{\Psi \vdash A_1 \to A_2 \triangleright A_1 \to A_2}{\Psi \vdash A_2 \triangleright A_1 \to A_2} \xrightarrow{\text{M-INKNOWN}} \end{array}$$

Dynamic Semantics

- Type-directed translation into an intermediate language with runtime casts $(\Psi \vdash e : A \leadsto s)$
- We translate to the Polymorphic Blame Calculus (PBC)
 [Ahmed et al., 2011]

PBC terms²
$$s := x \mid n \mid \lambda x : A. s \mid \Lambda a. s \mid s_1 s_2 \mid \langle A \hookrightarrow B \rangle s$$

²Only a subst of PBC terms are used

Correctness Criteria

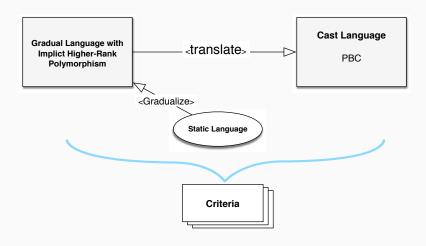
- Conservative extension: for all static Ψ , e, and A,
 - if $\Psi \vdash^{OL} e : A$, then there exists B, such that $\Psi \vdash e : B$, and $\Psi \vdash B <: A$.
 - if $\Psi \vdash e : A$, then $\Psi \vdash^{OL} e : A$
- Monotonicity w.r.t. precision: for all Ψ, e, e', A , if $\Psi \vdash e : A$, and $e' \sqsubseteq e$, then $\Psi \vdash e' : B$, and $B \sqsubseteq A$ for some B.
- Type Preservation of cast insertion: for all Ψ , e, A, if $\Psi \vdash e : A$, then $\Psi \vdash e : A \leadsto s$, and $\Psi \vdash^B s : A$ for some s.
- Monotonicity of cast insertion: for all Ψ , e_1 , e_2 , s_1 , s_2 , A, if $\Psi \vdash e_1 : A \leadsto s_1$, and $\Psi \vdash e_2 : A \leadsto s_2$, and $e_1 \sqsubseteq e_2$, then $\Psi \vdash \Psi \vdash s_1 \sqsubseteq^B s_2$.

Correctness Criteria

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Proved in Coq!

Recap



More in the Paper

- A bidirectional account of the algorithmic type system (inspired by [Dunfield and Krishnaswami, 2013])
- Extension to top types
- Discussion and comparison with other approaches (AGT [Garcia et al., 2016], Directed Consistency [Jafery and Dunfield, 2017])
- Discussion of dynamic guarantee

Future Work

- Fix the issue with dynamic guarantee (partially)
- More features: mutable state, fancy types, etc.

References

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Backup Slides

Dynamic Guarantee

- Changes to the annotations of a gradually typed program should not change the dynamic behaviour of the program.
- The declarative system breaks it...

$$(\lambda f: \forall a. a \to \mathsf{Int}. \, \lambda x: \mathsf{Int}. \, f \, x) \, (\lambda x. \, 1) \, 3 \, \Downarrow \, 3$$
$$(\lambda f: \forall a. \, a \to \mathsf{Int}. \, \lambda x: \star. \, f \, x) \, (\lambda x. \, 1) \, 3 \, \Downarrow \, ?$$

- A common problem in gradual type inference, see [Garcia and Cimini 2015]. Static and gradual type parameters may help.
- A more sophisticated term precision is needed in PBC.
 [Igarashi et al. 2017]