



# **An Introduction to Implicit Neural Representations for Image-Based Modeling**

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**Zhejiang University**

# Overview

Image-based modeling and rendering

Traditional methods and their limitations

Implicit Neural Representations

- Neural Radiance Fields (NeRF)
- Neural SDF for surface reconstruction
- Neural dynamic scene representations

# Image-based modeling and rendering



Input images

3D model

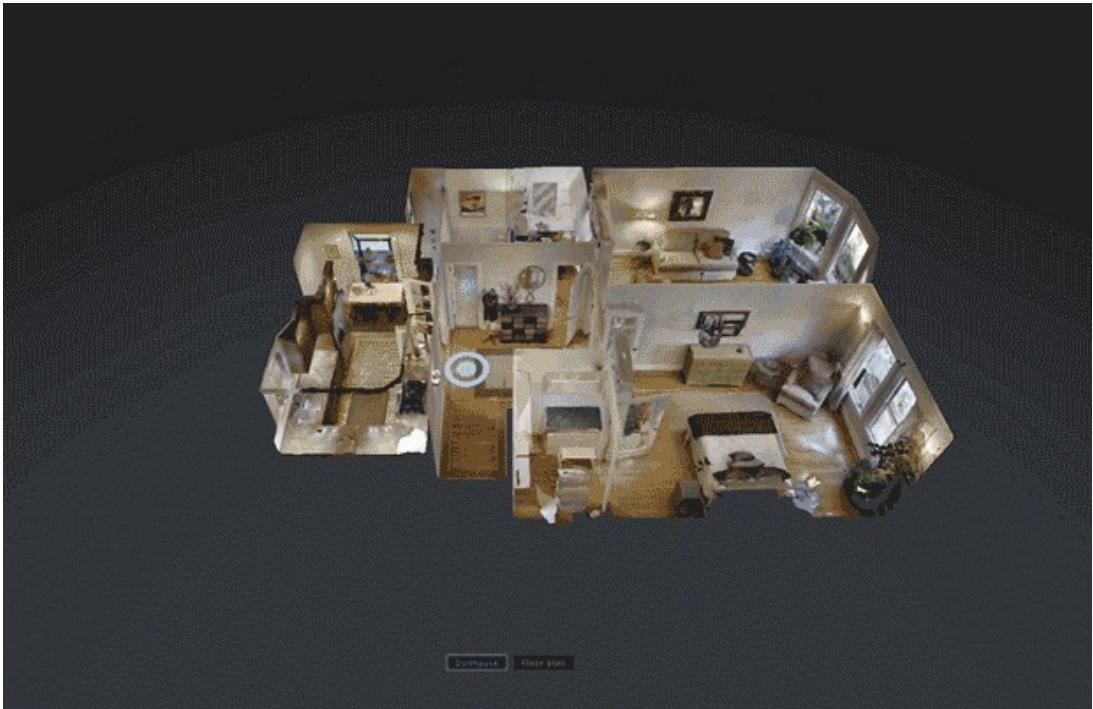
Novel views



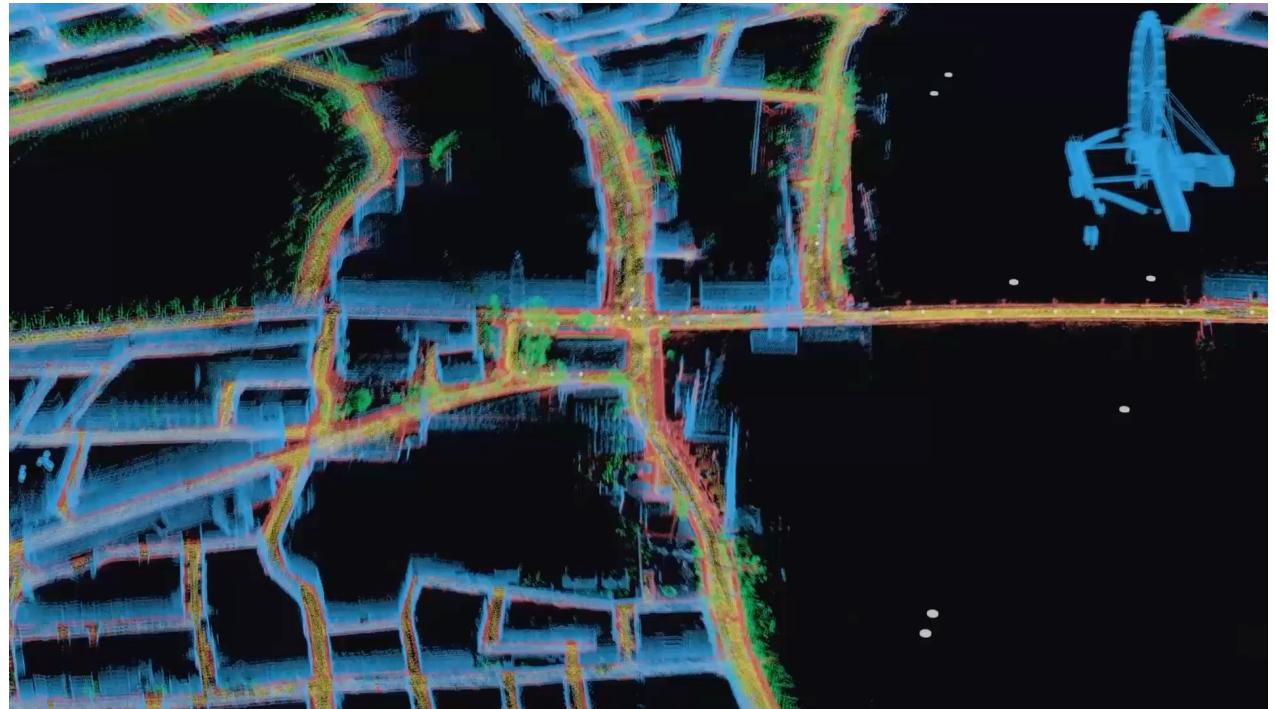
Nerf in the wild: Neural radiance fields for unconstrained photo collections. CVPR. 2021.

# Applications

## VR tour



Matterport



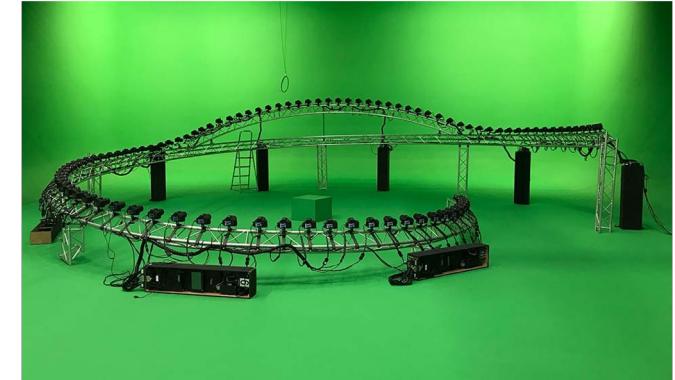
Google Immersive View

# Applications

## Bullet time effect



RED Lion movie shorts



Bullet time effect in "The Matrix"

# Applications

## Free-viewpoint video



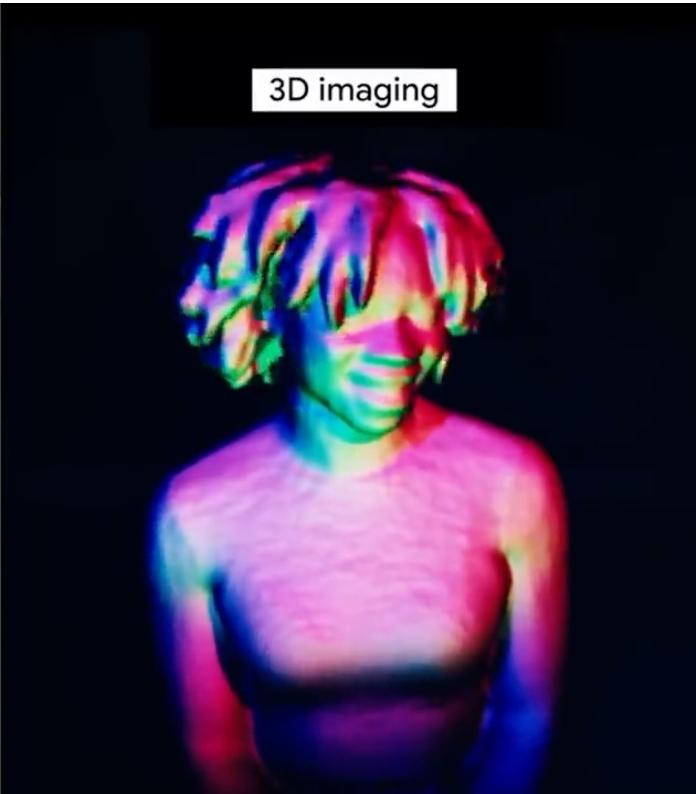
Intel TrueView



湖南卫视舞蹈风暴

# Applications

## Immersive telepresence

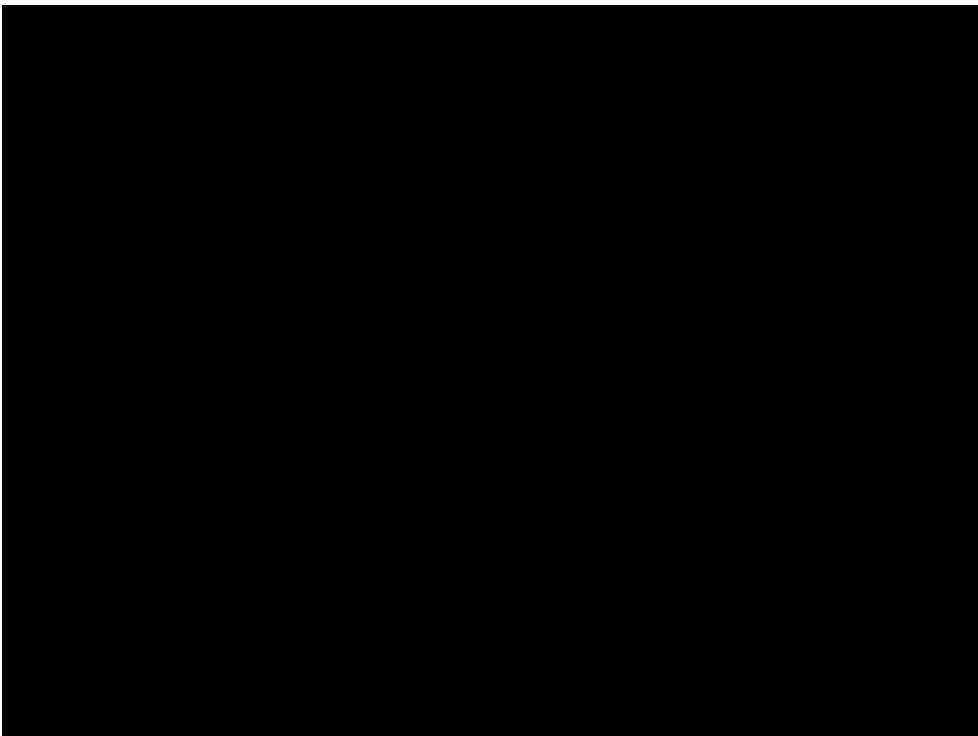


Google Project Starline

# Applications

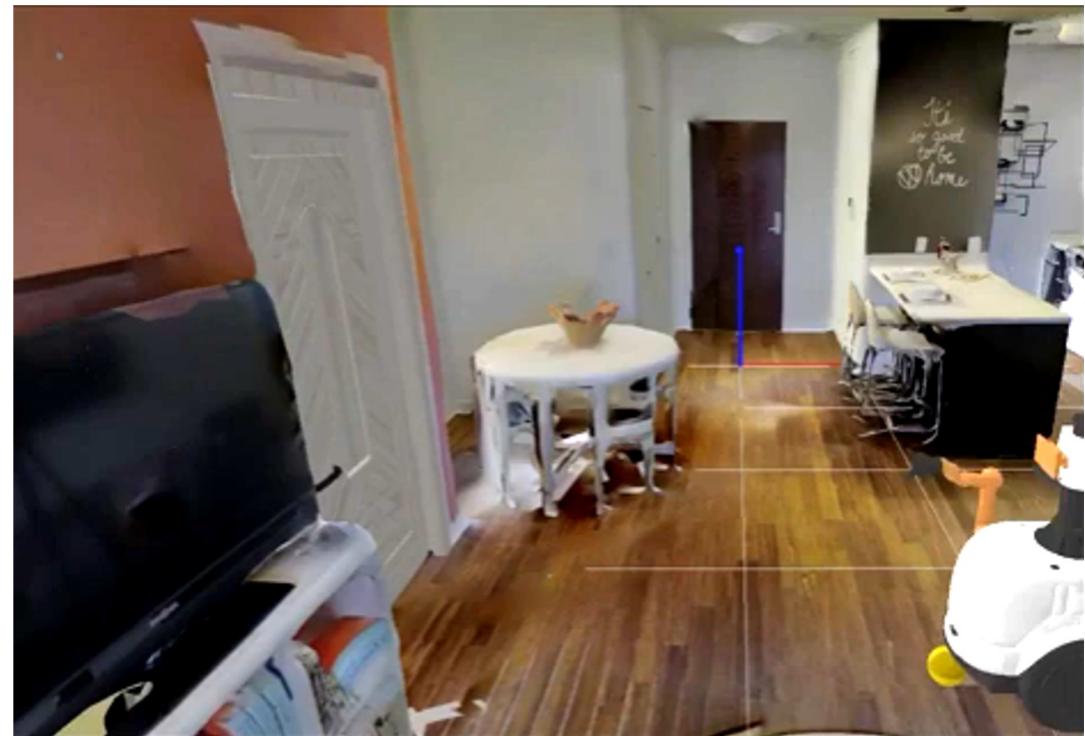
Embodied AI: training agents in simulated environments

Autonomous driving



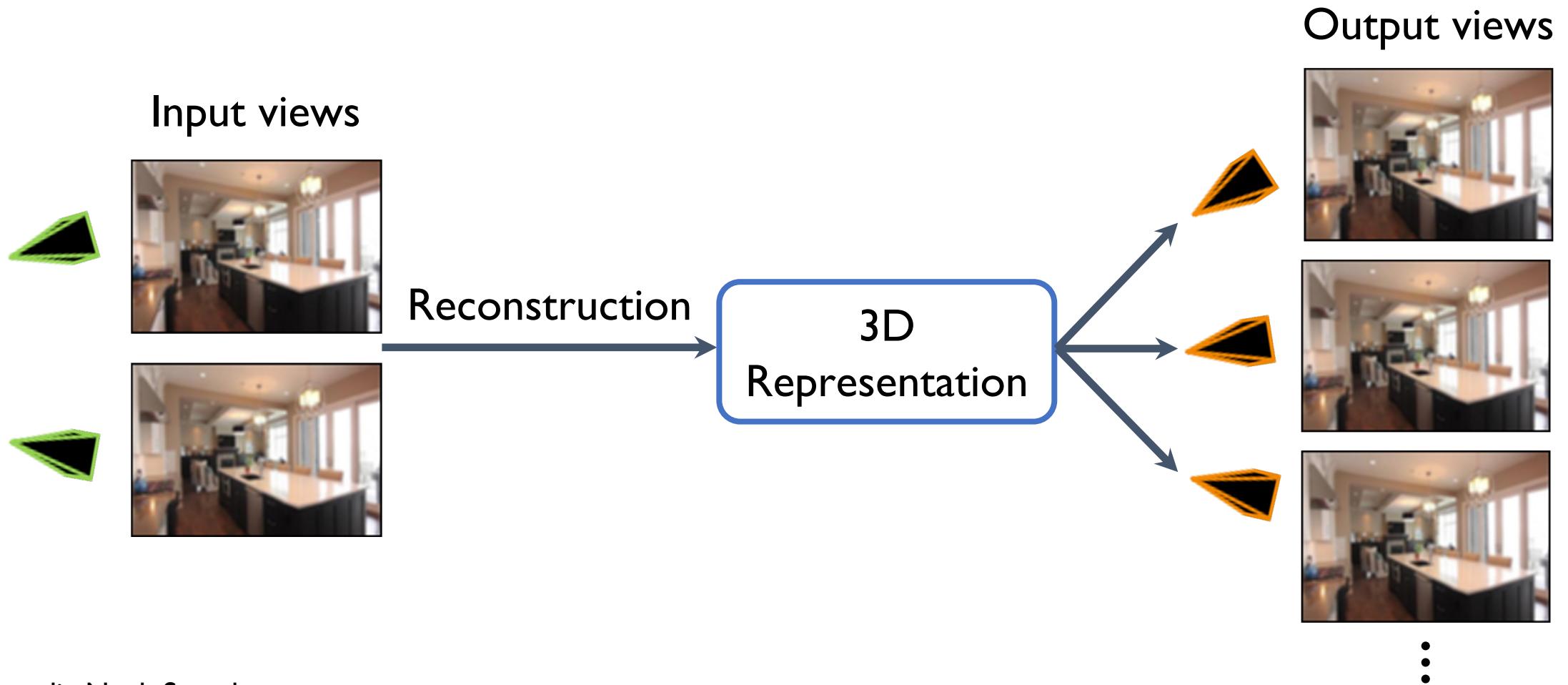
Block NeRF

Robots

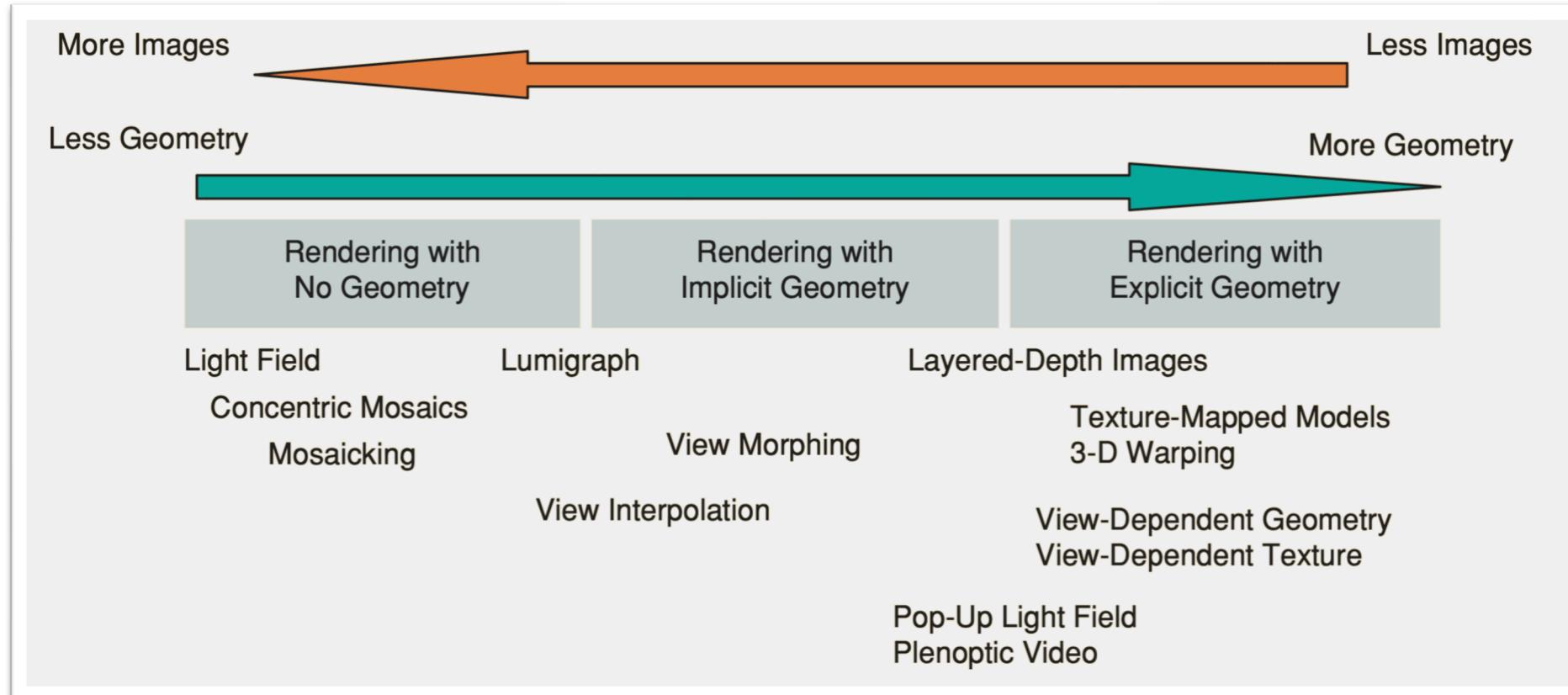


iGibson

# Image-based modeling and rendering

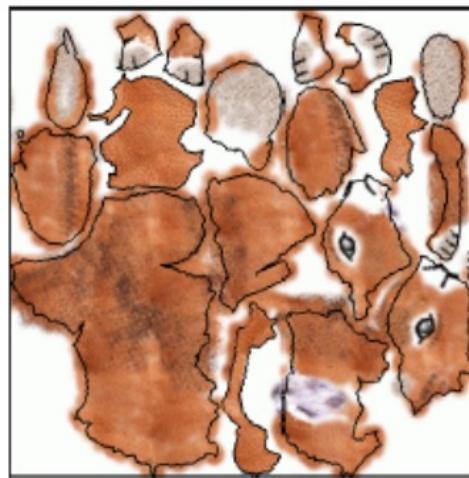
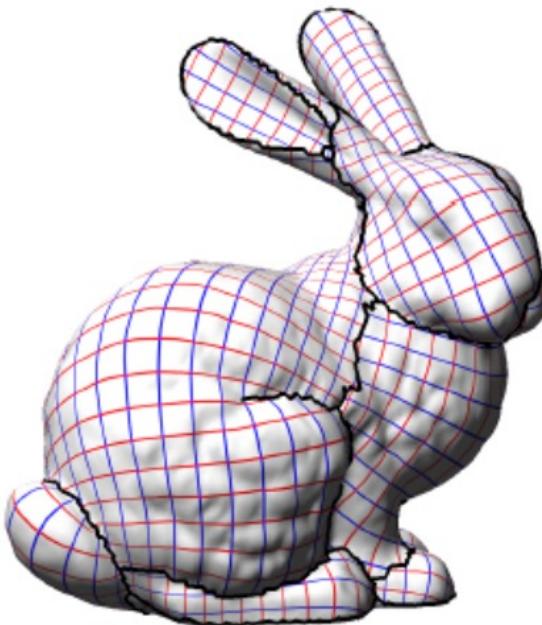


# Traditional methods



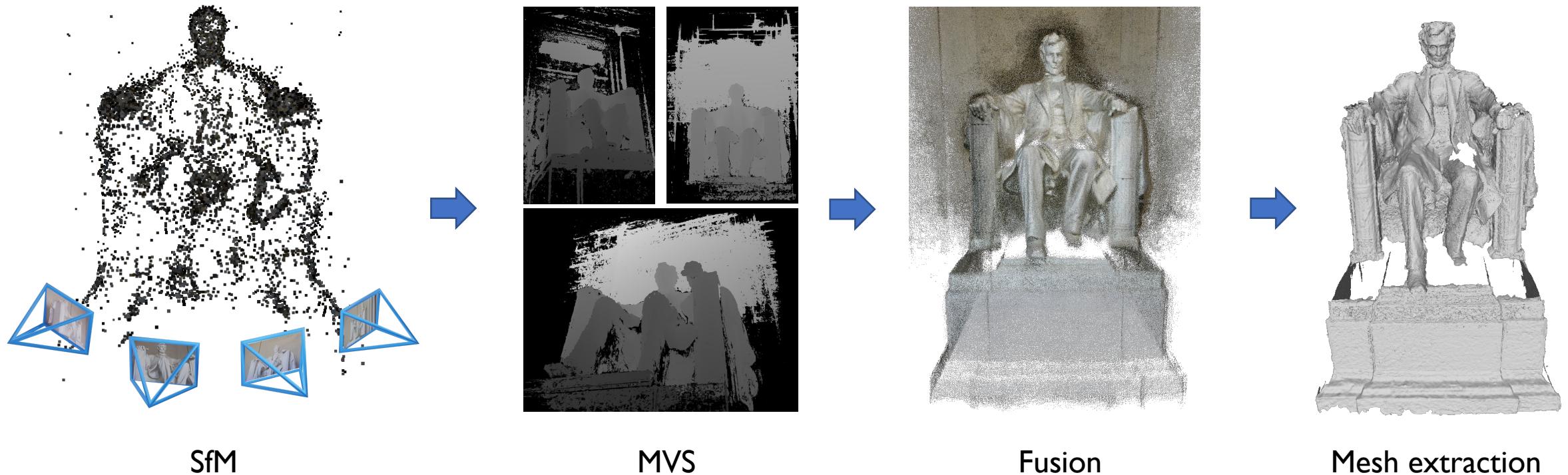
# Surface-based representations

3D mesh with texture map



# Surface-based representations

Mesh reconstruction pipeline



# Surface-based representations

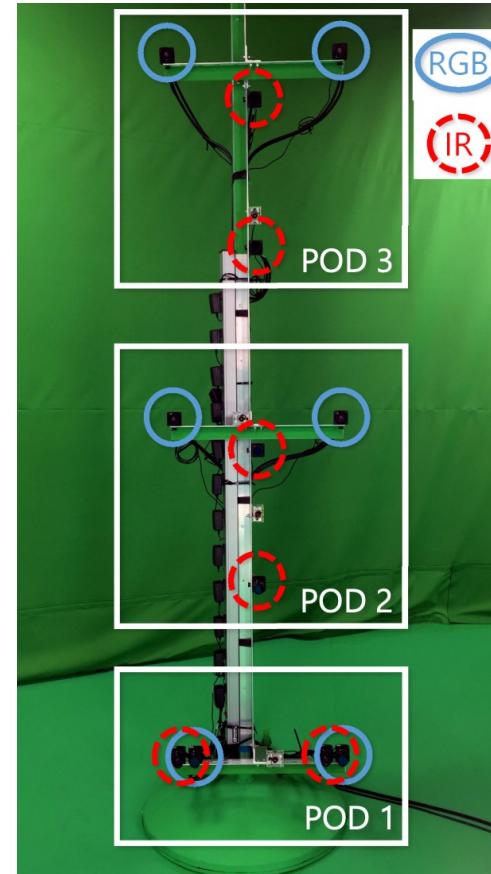


High-Quality Streamable Free-Viewpoint Video, SIGGRAPH 2015.

# Surface-based representations

Capture system

53 RGB cameras and 53 IR cameras



High-Quality Streamable Free-Viewpoint Video, SIGGRAPH 2015.

# Surface-based representations

Limitations:

- High-quality mesh reconstruction is difficult in many cases
- Cannot represent very complex scenes

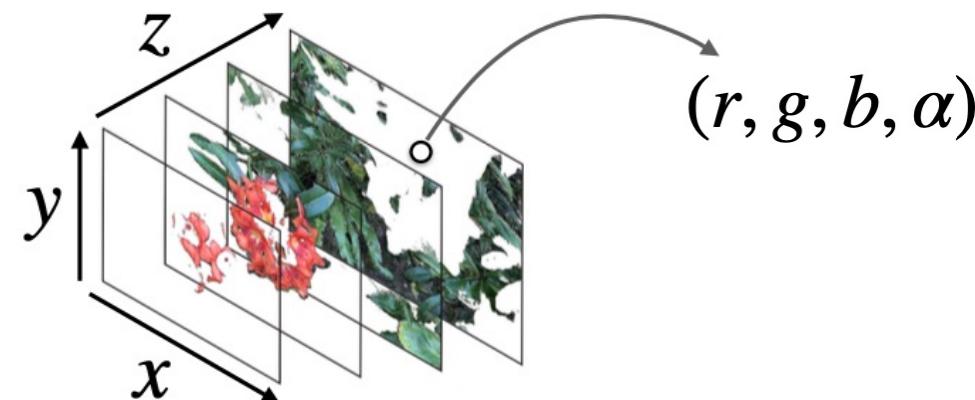


# Volume-based representations

## Multi-Plane Image (MPI)

A set of front-parallel planes at a fixed range of depths

Each plane encodes an RGB color image  $C_d$  and an alpha/transparency map  $\alpha_d$



$$\sum \left( \begin{array}{c} \text{Target RGB} \\ \times \\ \text{Target alpha} \end{array} \right) = \text{Rendered Target}$$

Blend RGBA renderings together  
to render final output image

# Volume-based representations

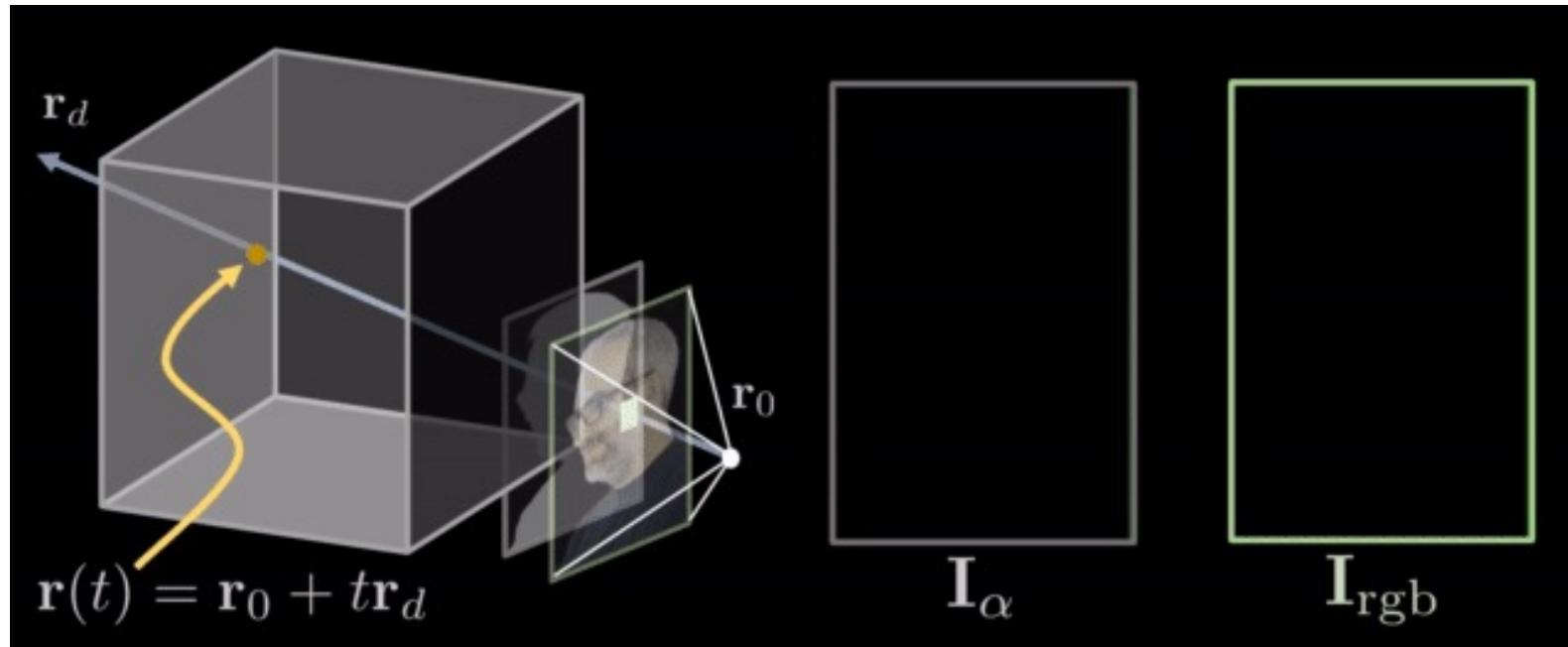
## Multi-Plane Image (MPI)



DeepView: View synthesis with learned gradient descent. CVPR, 2019.

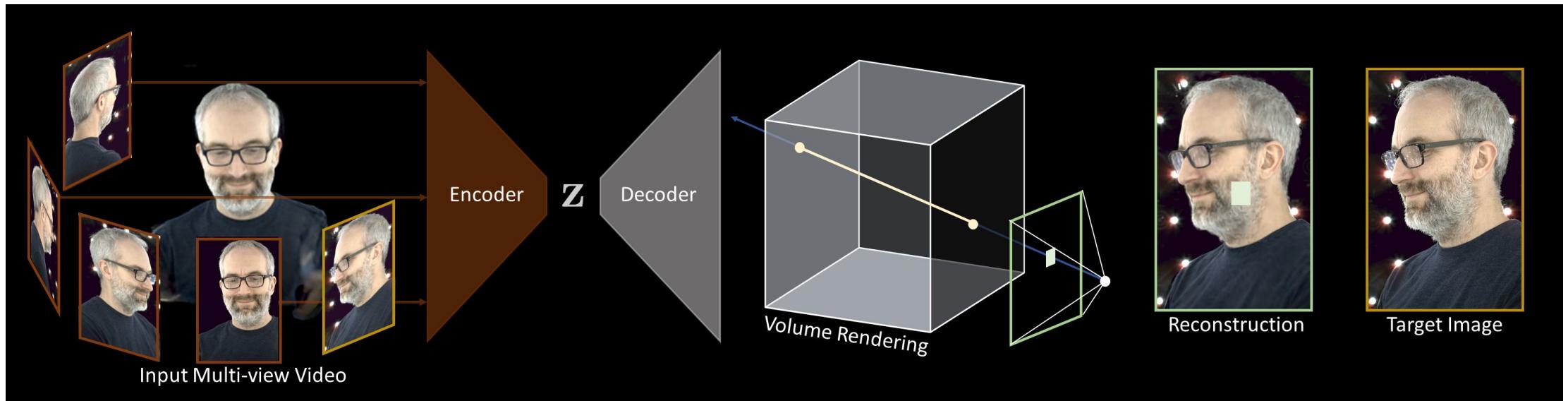
# Volume-based representations

## RGB- $\alpha$ volume



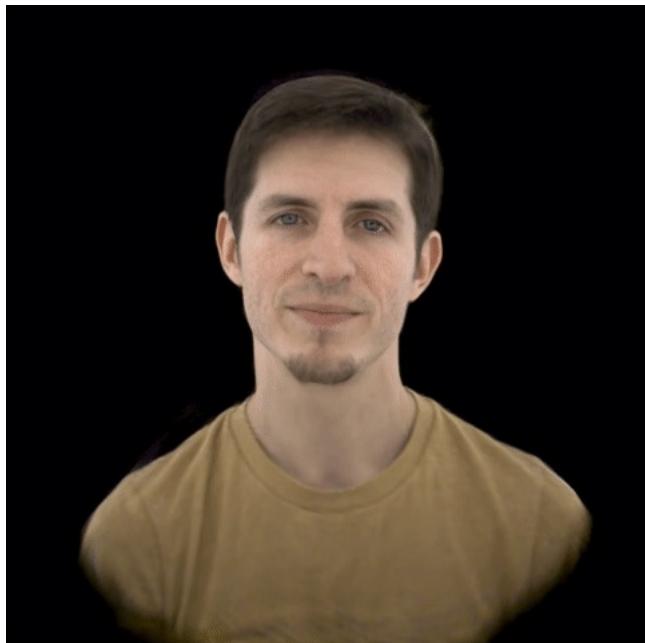
# Volume-based representations

Neural volumes: an encoder-decoder network that transforms input images into a 3D volume representation



# Volume-based representations

Neural volumes: an encoder-decoder network that transforms input images into a 3D volume representation



# Volume-based representations

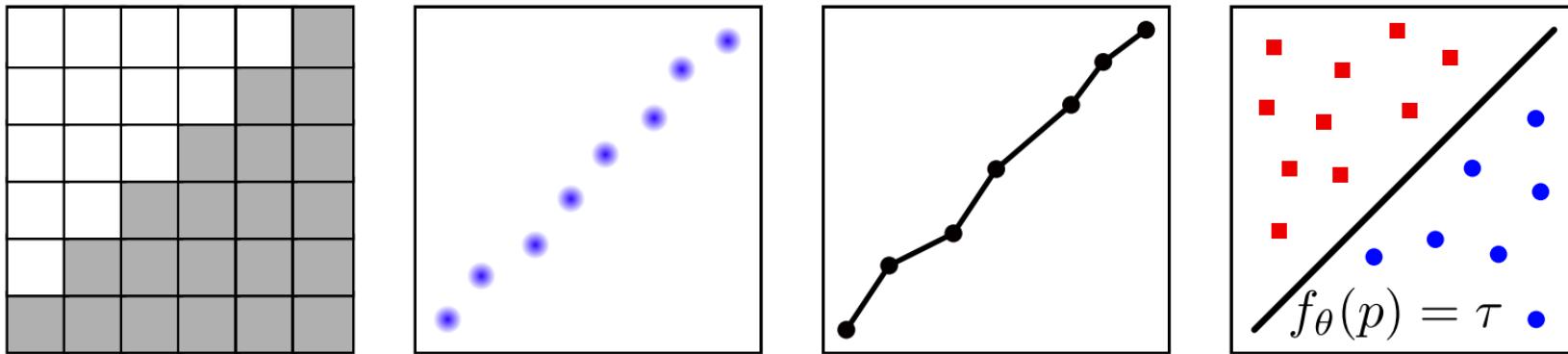
## Advantages:

- Can represent very complex scenes
- Realistic reflections / specularity / transparency

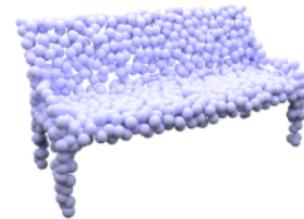
## Limitations:

- Discrete 3D volume requires **large storage** size for high-resolution rendering

# Implicit Representations



Volume



Point cloud



Mesh



Implicit function

Explicit & discrete

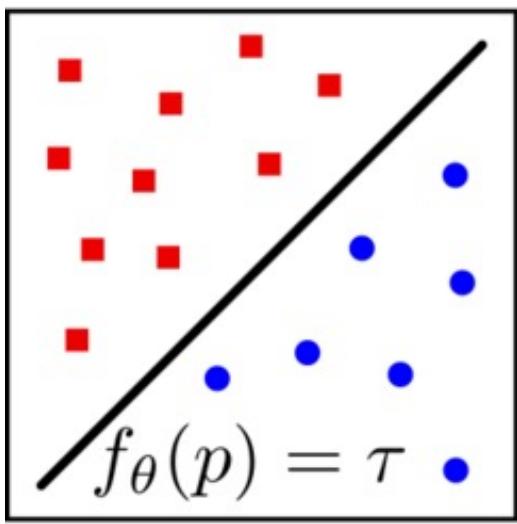
Implicit & continuous



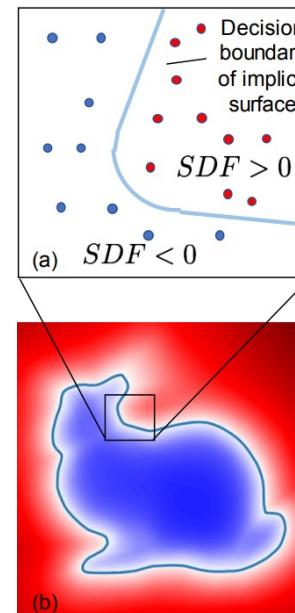
# Implicit Representations

The implicit function can be:

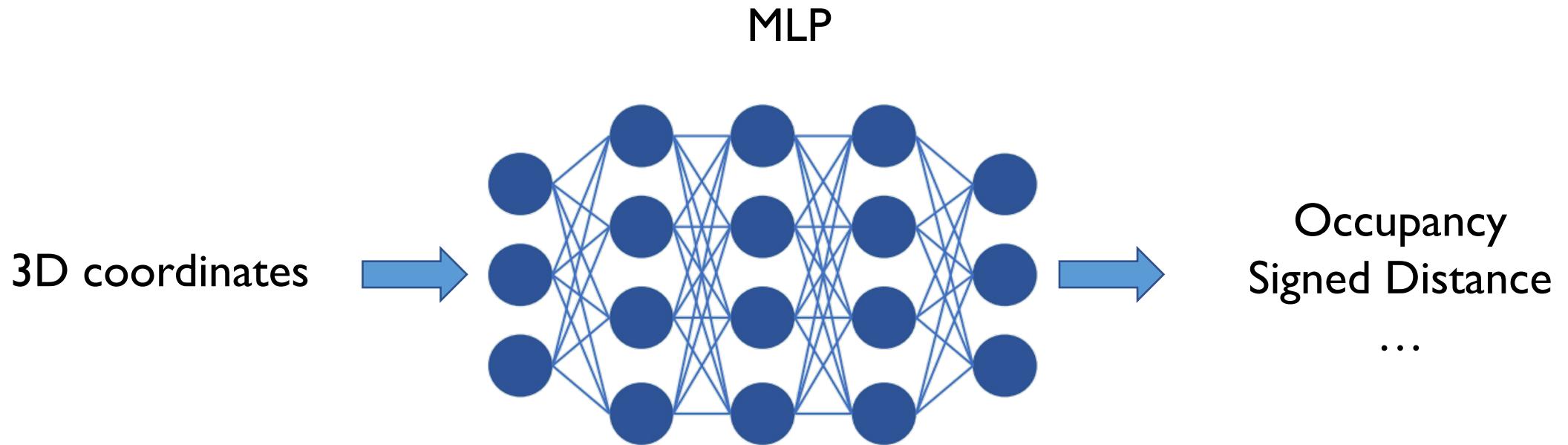
Occupancy



Signed distance function (SDF)



# Implicit Neural Representations



Occupancy Networks: Learning 3D Reconstruction in Function Space, CVPR 2019.

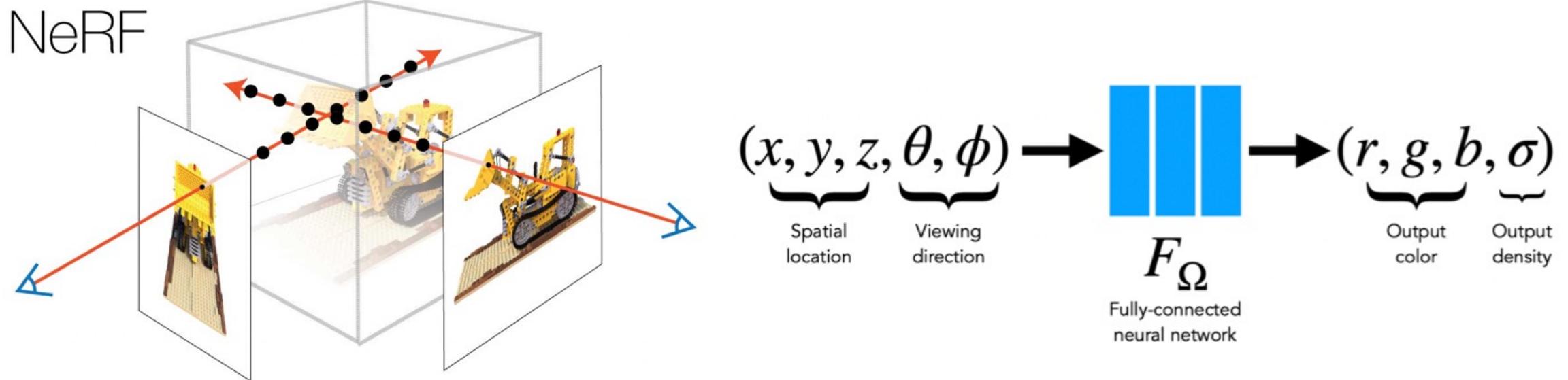
DeepSDF: Learning Continuous Signed Distance Functions for Shape Representation, CVPR 2019.

Learning implicit fields for generative shape modeling, CVPR 2019.

Scene Representation Networks: Continuous 3D-Structure-Aware Neural Scene Representations, NeurIPS 2019.

# Neural Radiance Fields (NeRF)

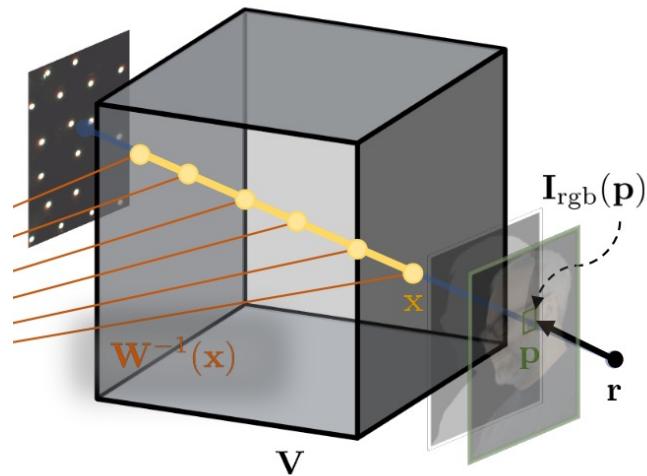
Representing scenes as **continuous density and color fields**



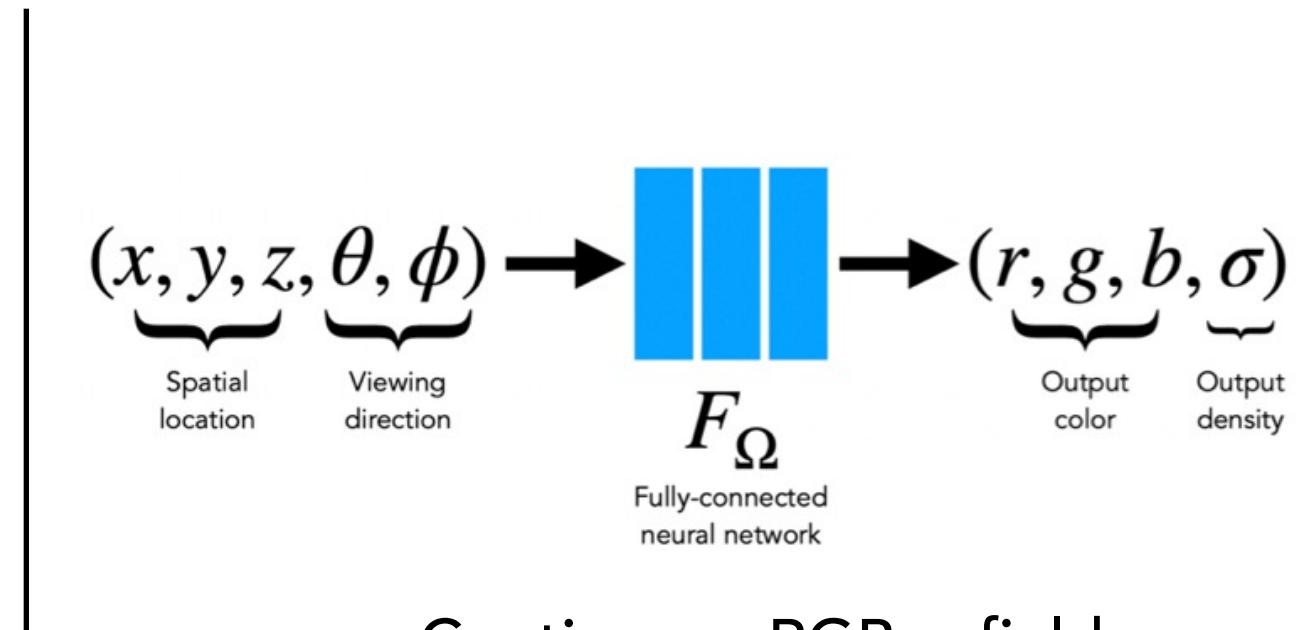
NeRF: Representing scenes as neural radiance fields for view synthesis, ECCV 2020.

# Neural Radiance Fields (NeRF)

Representing scenes as **continuous density and color fields**



Discrete RGB- $\alpha$  volume



Continuous RGB- $\alpha$  field



Neural Volumes: Learning Dynamic Renderable Volumes from Images, *SIGGRAPH* 2019.

NeRF: Representing scenes as neural radiance fields for view synthesis, *ECCV* 2020.

# Neural Radiance Fields (NeRF)

Volume rendering, which is **differentiable**

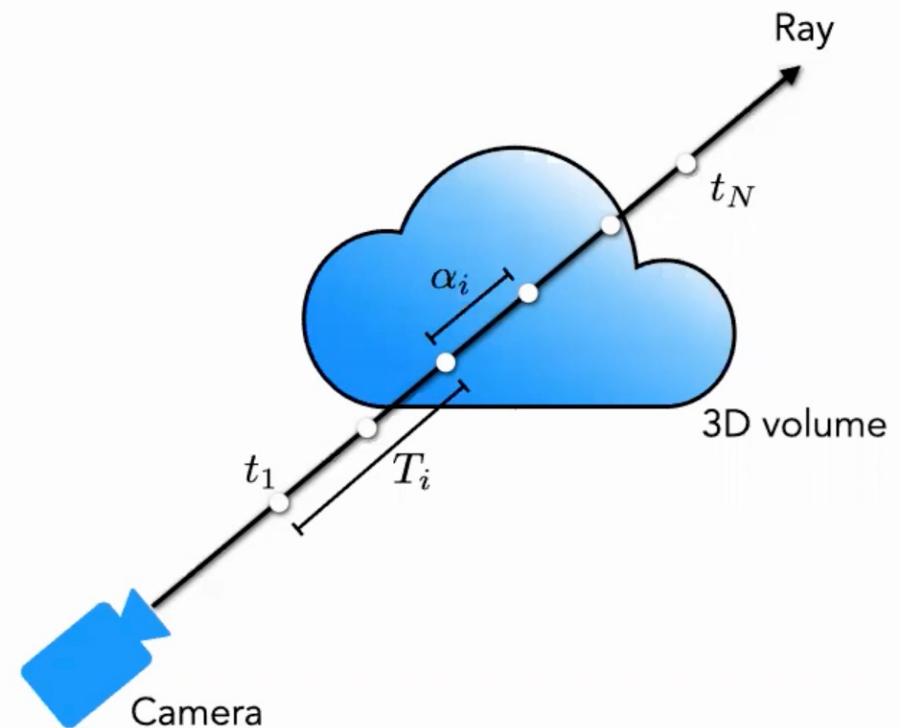
Rendering model for ray  $r(t) = o + td$ :

$$C \approx \sum_{i=1}^N T_i \alpha_i c_i$$

weights                      colors

How much light is blocked earlier along ray:

$$T_i = \prod_{j=1}^{i-1} (1 - \alpha_j)$$



# Neural Radiance Fields (NeRF)

Learning NeRF from images



Input multi-view images



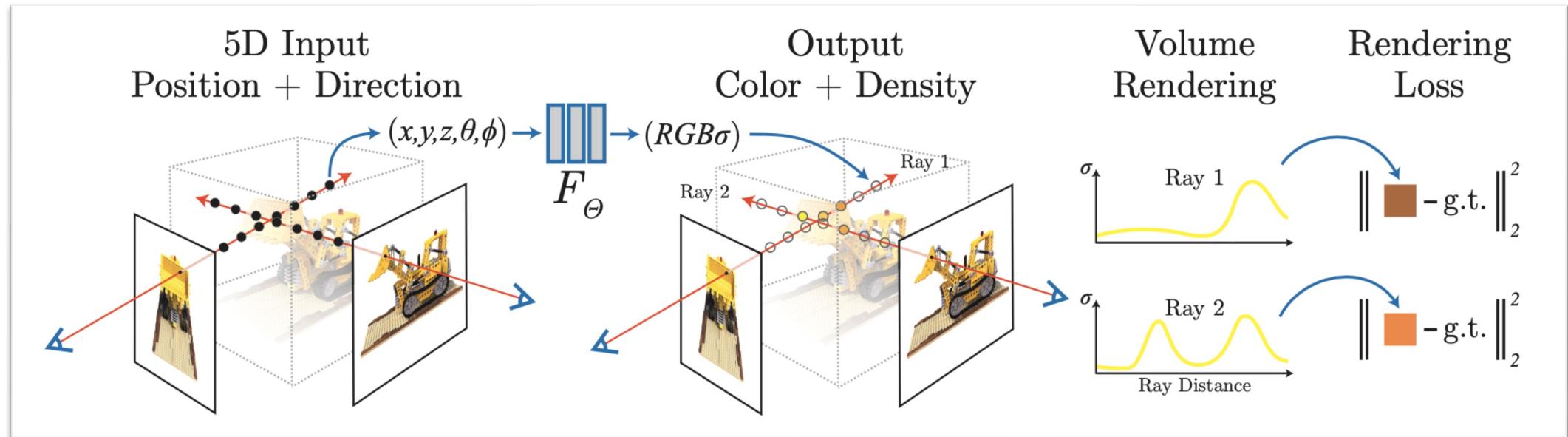
Optimizing NeRF



NeRF: Representing scenes as neural radiance fields for view synthesis, ECCV 2020.

# Neural Radiance Fields (NeRF)

Learning NeRF from images



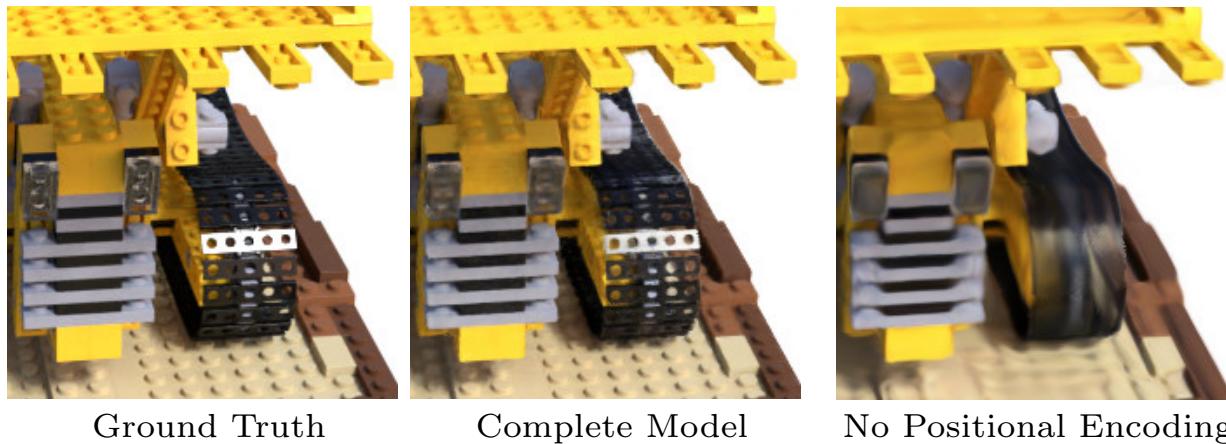
NeRF: Representing scenes as neural radiance fields for view synthesis, ECCV 2020.

# Neural Radiance Fields (NeRF)

## Positional encoding:

- Standard coordinate-based MLPs perform poorly at representing high frequency details
- Passing input coordinates through a high frequency mapping

$$\gamma(p) = (\sin(2^0\pi p), \cos(2^0\pi p), \dots, \sin(2^{L-1}\pi p), \cos(2^{L-1}\pi p))$$



# Neural Radiance Fields (NeRF)

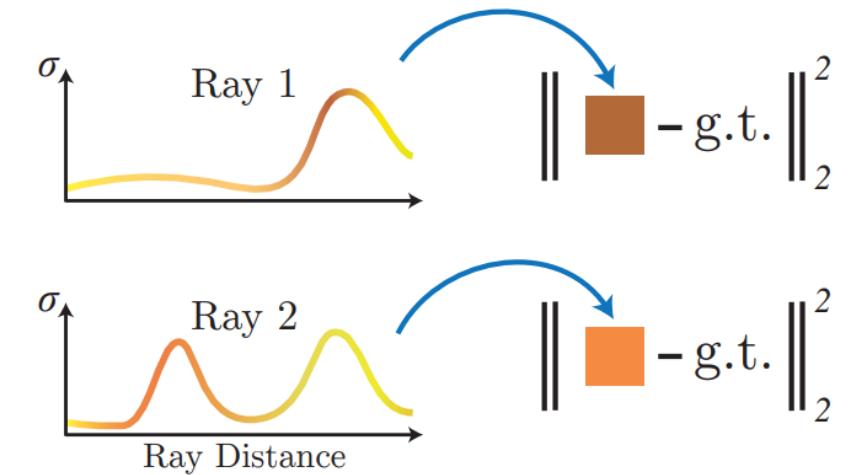
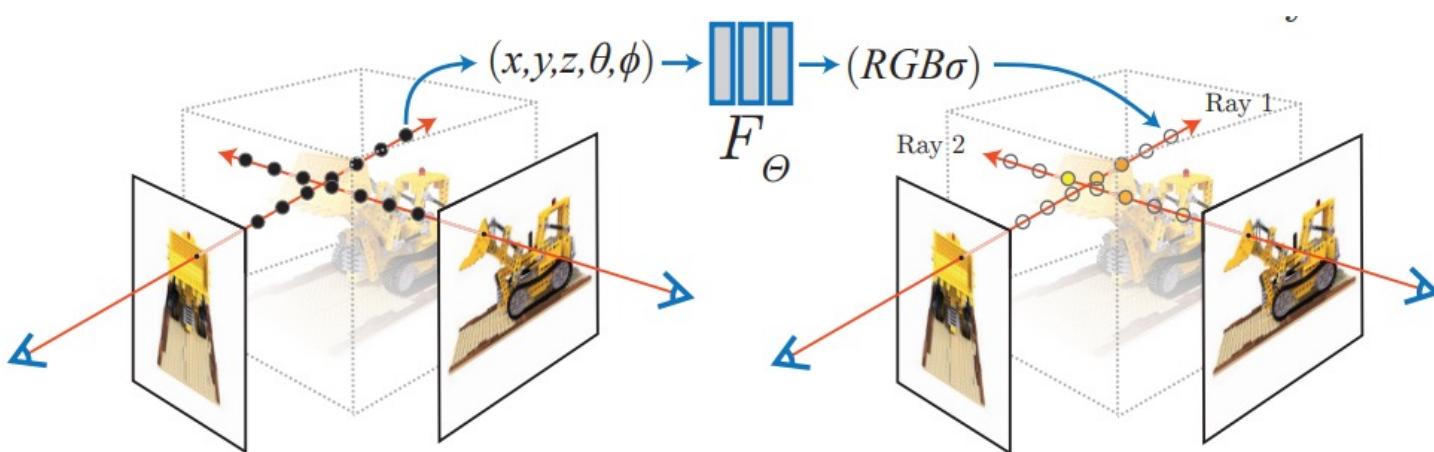


NeRF: Representing scenes as neural radiance fields for view synthesis, ECCV 2020.

# Neural Radiance Fields (NeRF)

## Why better?

- The representation is continuous and flexible
- Optimizing rendering quality end-to-end



# Neural Radiance Fields (NeRF)

## Limitations:

- Computationally inefficient in terms of training and inference  
Optimizing a MLP network needs about **1 day**  
Render one novel view needs **30 seconds**
- Cannot model dynamic scenes
- Poor surface reconstruction quality

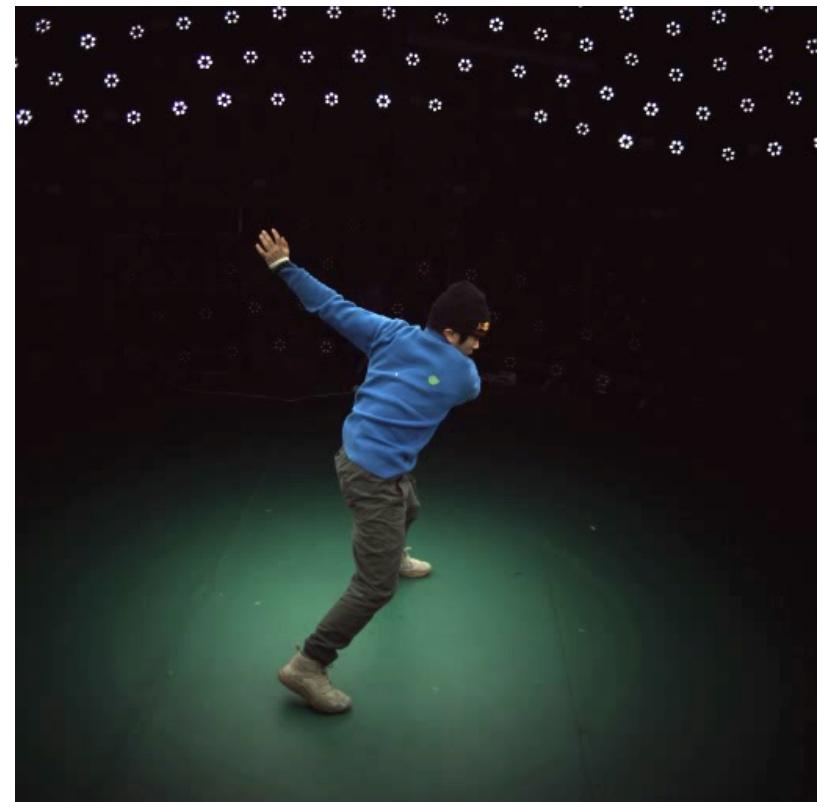
**NeRF**  
1.6 days  
31.15 dB



# Neural Radiance Fields (NeRF)

## Limitations

- Computationally inefficient in terms of training and inference
- Cannot model dynamic scenes
- Poor surface reconstruction quality



# Neural Radiance Fields (NeRF)

## Limitations

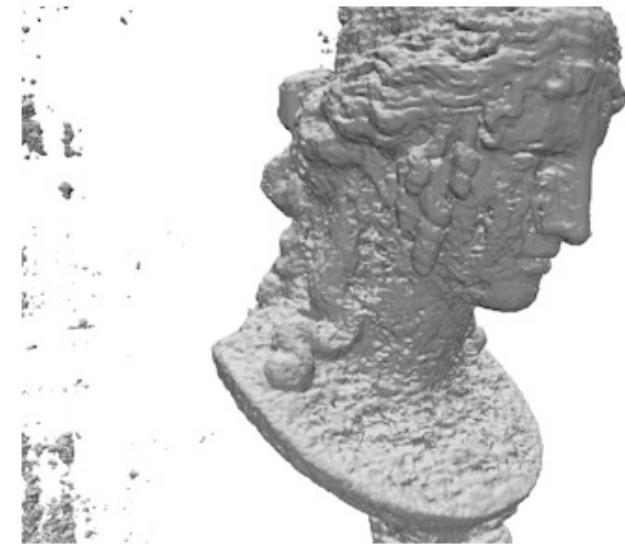
- Computationally inefficient in terms of training and inference
- Cannot model the motion of dynamic scenes
- Poor surface reconstruction quality



Reference image



COLMAP

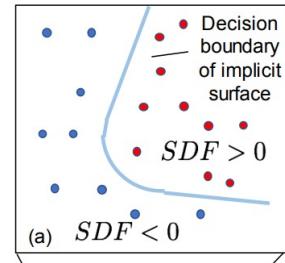


NeRF

# Neural SDFs for Surface Reconstruction

Surface reconstruction vs. Volumetric reconstruction

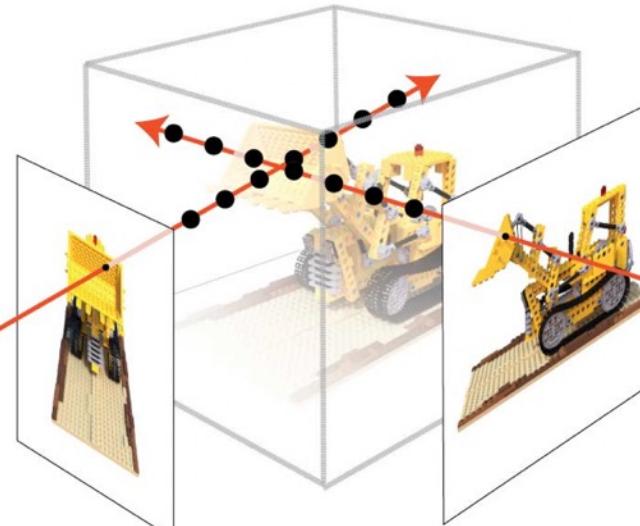
$(x, y, z)$



(c)

Signed distance

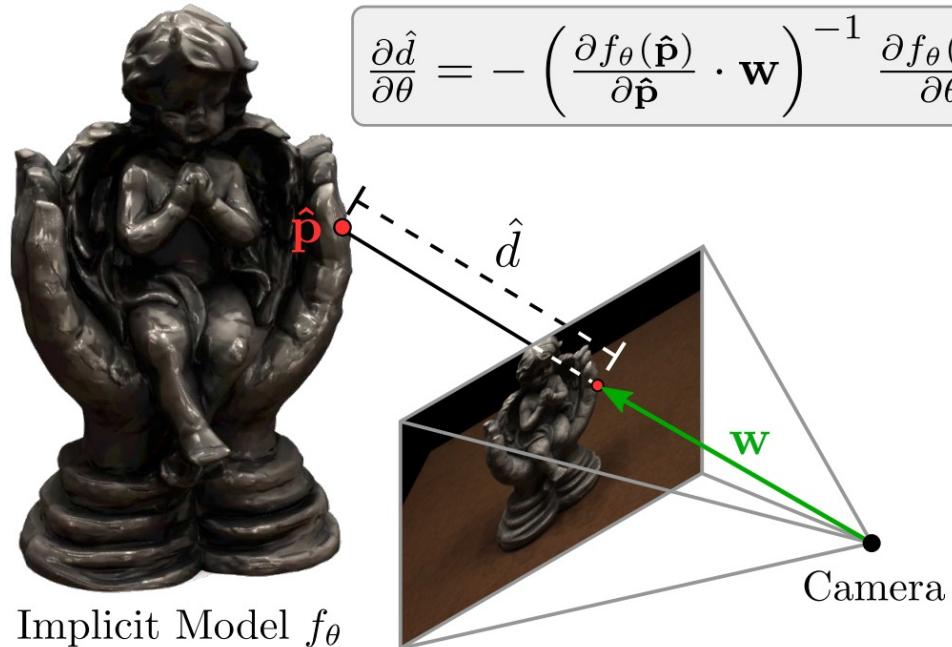
$(x, y, z)$



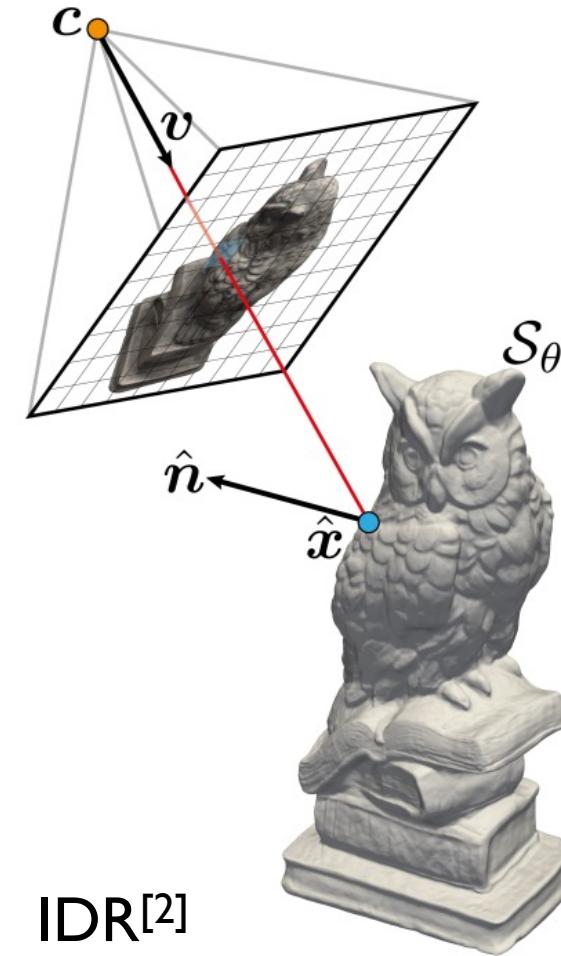
RGB + density

# Neural SDFs for Surface Reconstruction

Differentiable surface rendering



DVR<sup>[1]</sup>



IDR<sup>[2]</sup>



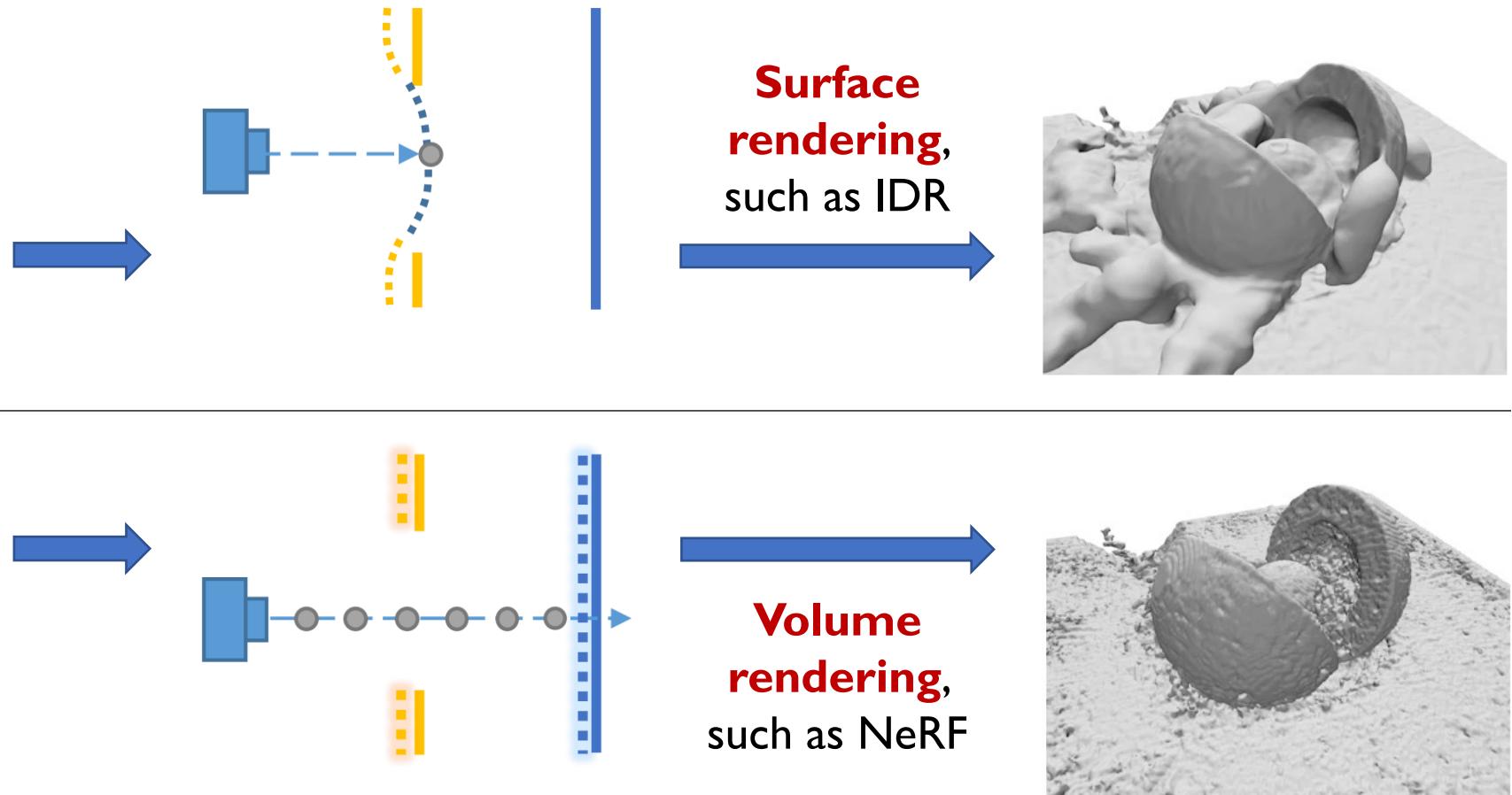
[1] Differentiable Volumetric Rendering: Learning Implicit 3D Representations without 3D Supervision, CVPR 2020.

[2] Multiview Neural Surface Reconstruction by Disentangling Geometry and Appearance, NeurIPS 2020.

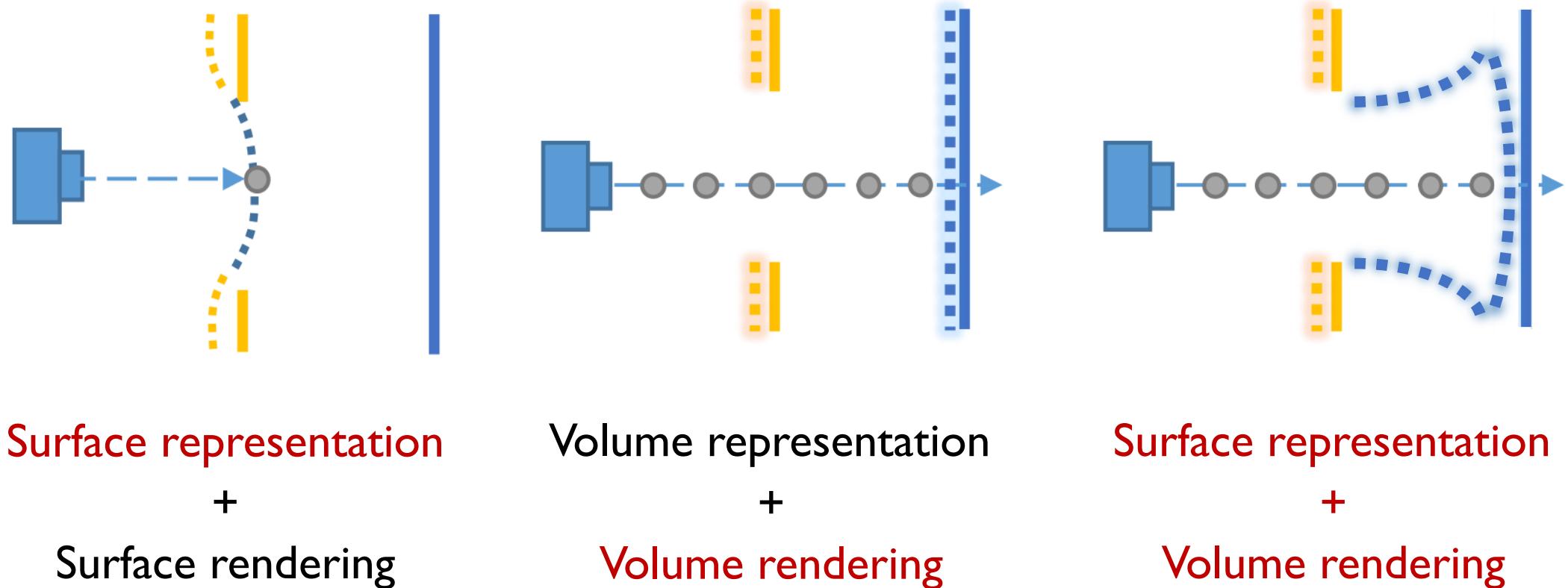
# Limitation of surface rendering



Reference image

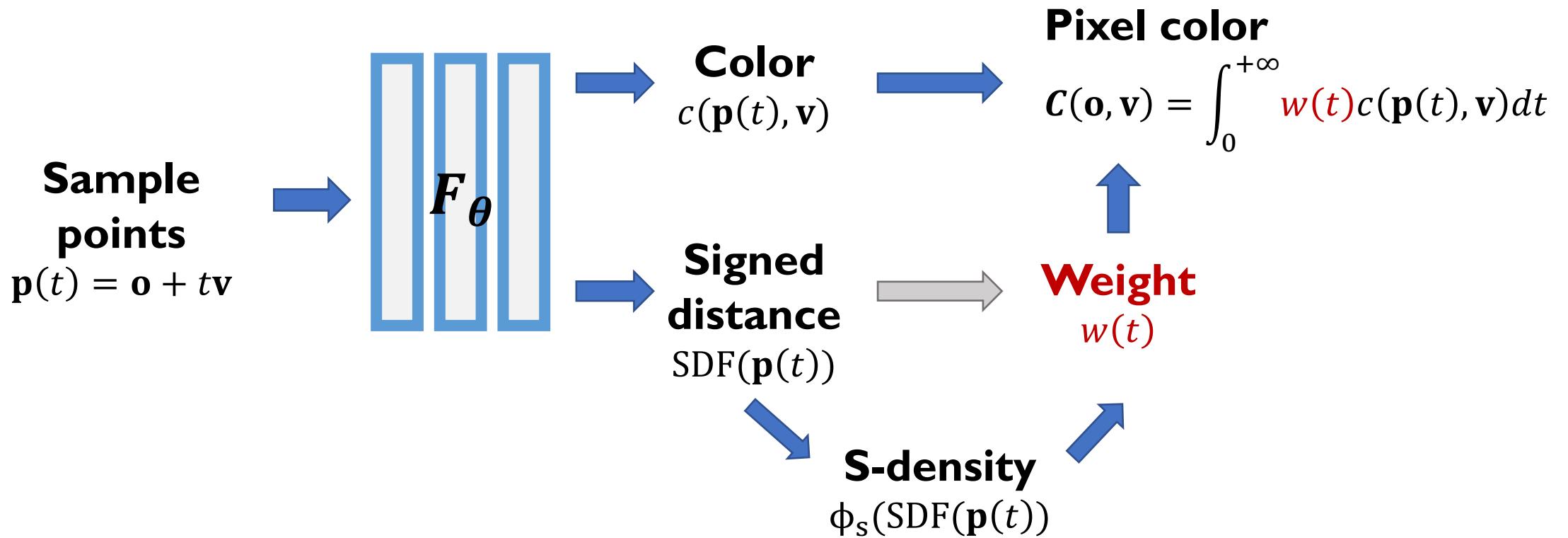


NeuS: Learning Neural Implicit Surfaces by Volume Rendering for Multi-view Reconstruction, NeurIPS 2021.



# NeuS

Optimizing SDF in a volumetric rendering framework



# NeuS

## Advantages:

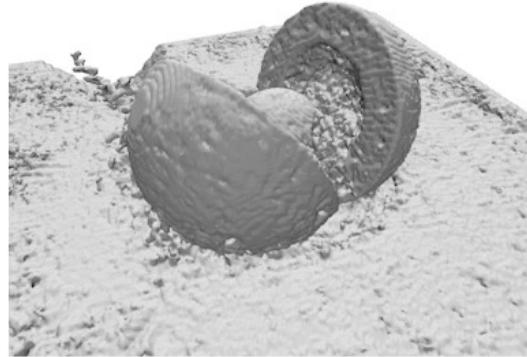
- Accurate 3D implicit surface reconstruction
- No need for depth or mask supervision



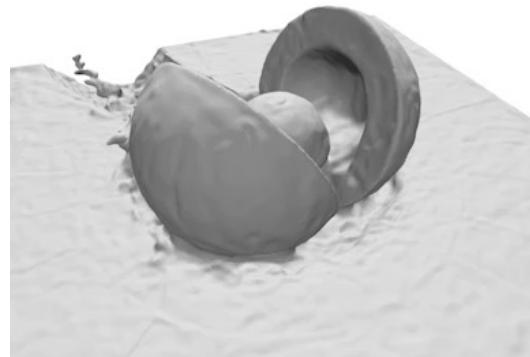
Reference image



IDR



NeRF

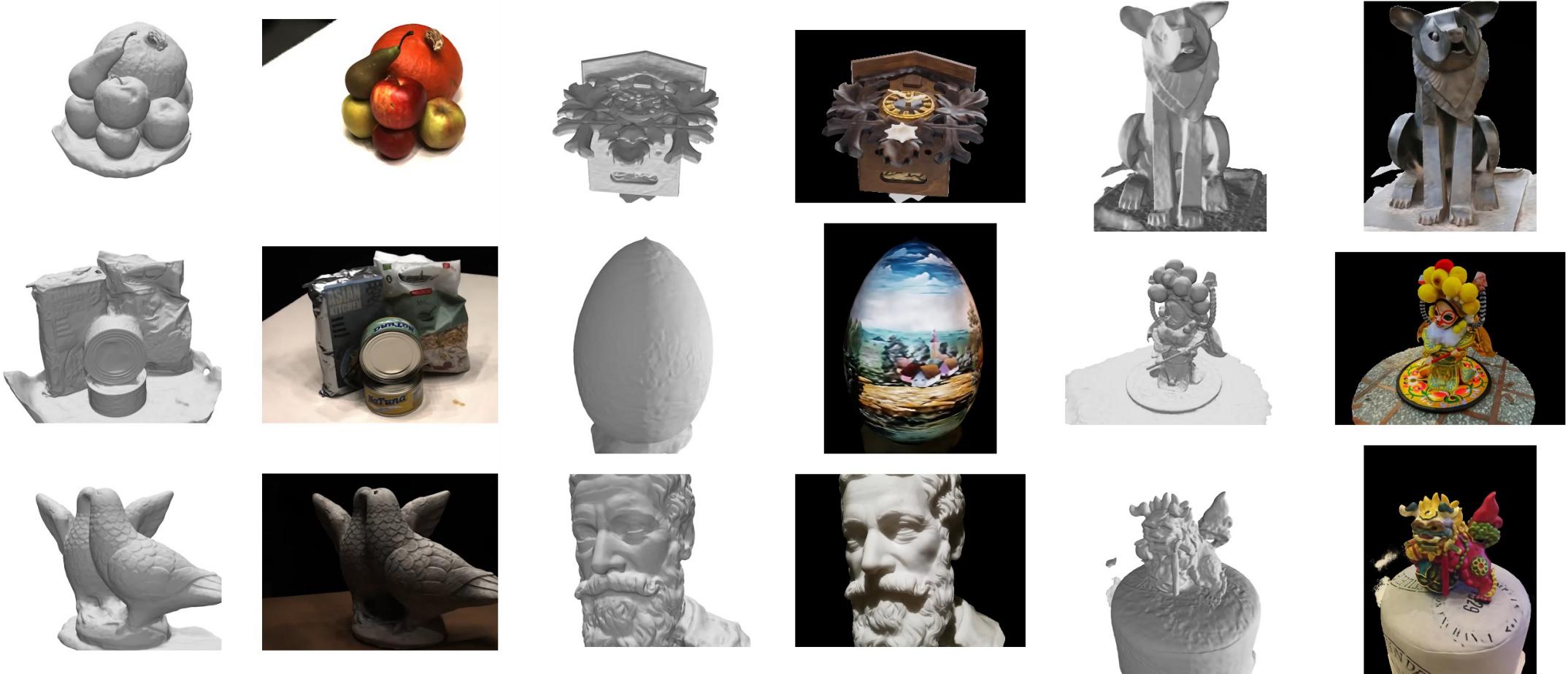


NeuS



NeuS: Learning Neural Implicit Surfaces by Volume Rendering for Multi-view Reconstruction, *NeurIPS* 2021.

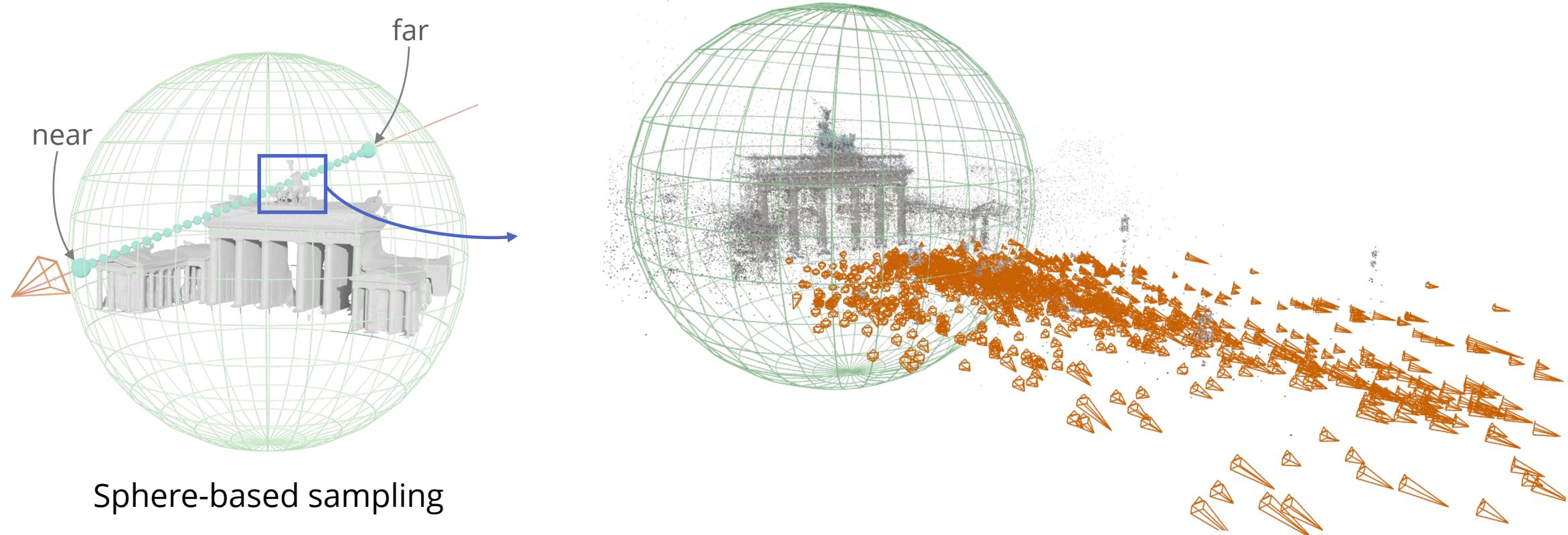
# NeuS



NeuS: Learning Neural Implicit Surfaces by Volume Rendering for Multi-view Reconstruction, NeurIPS 2021.

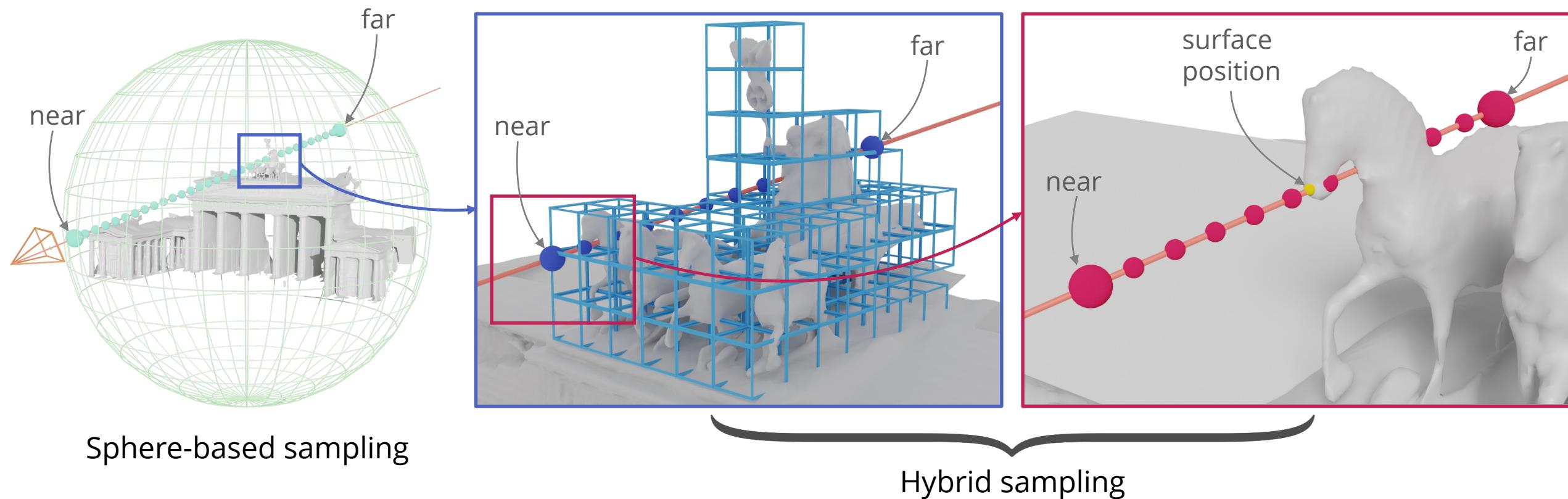
# Large-scale scene reconstruction

Challenge: large-scale scene with thousands of images



# Large-scale scene reconstruction

Improving sampling efficiency by surface-guided sampling



Sphere-based sampling

Hybrid sampling



Neural Reconstruction in the Wild, SIGGRAPH 2022.

# Large-scale scene reconstruction



Credits: Flickr



Neural Reconstruction in the Wild, SIGGRAPH 2022.

# Large-scale scene reconstruction



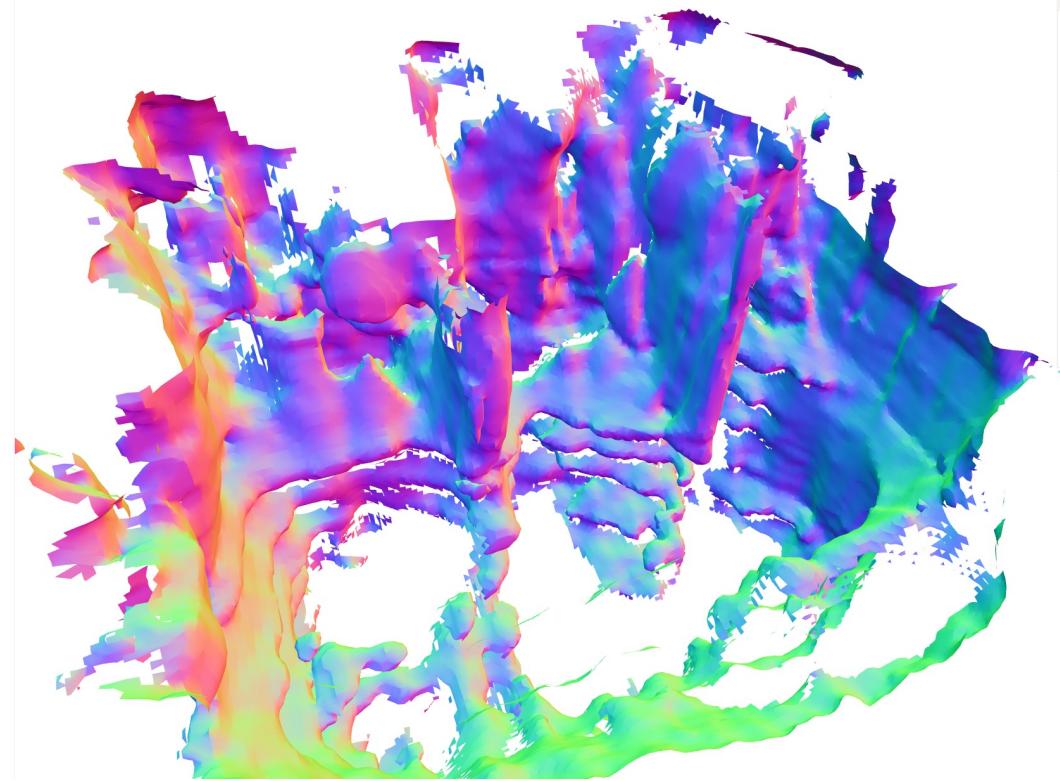
Credits: Flickr



Neural Reconstruction in the Wild, SIGGRAPH 2022.

# Indoor scene reconstruction

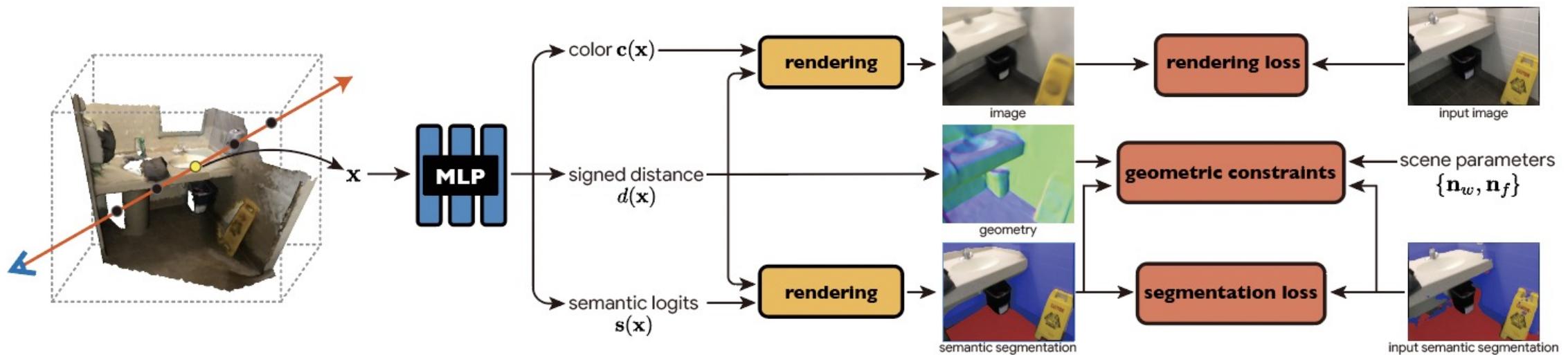
Challenge: texture-low regions



# Indoor scene reconstruction

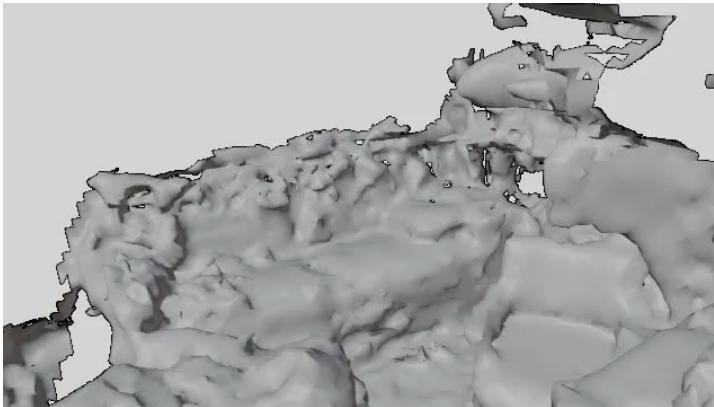
Manhattan-world assumption

Can be easily integrated when optimizing implicit neural representations

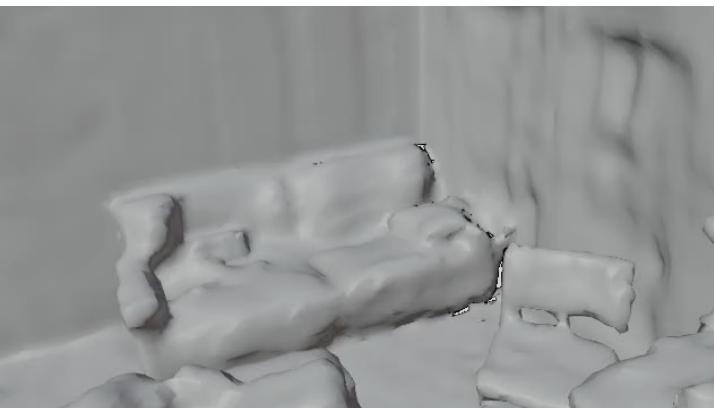


Neural 3D Scene Reconstruction with the Manhattan-world Assumption, CVPR 2022.

# Indoor scene reconstruction



COLMAP



Ours



VoISDF



GT

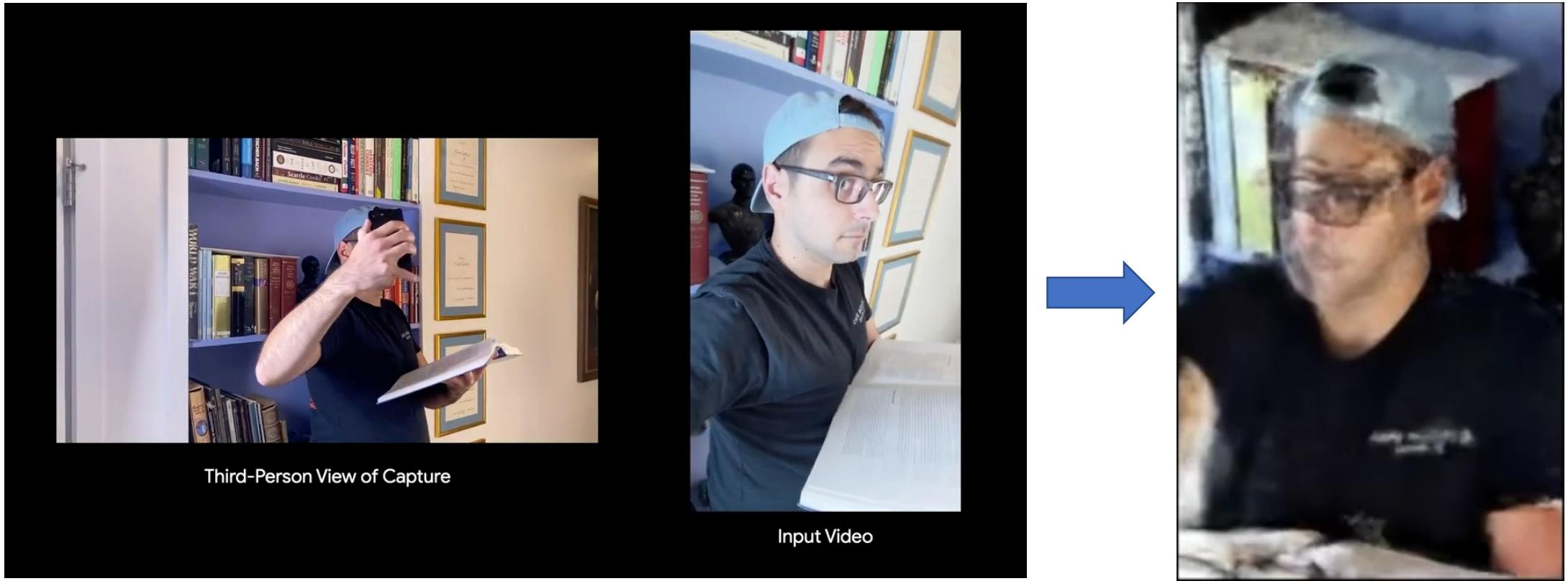


Neural 3D Scene Reconstruction with the Manhattan-world Assumption, CVPR 2022.

Volume Rendering of Neural Implicit Surfaces, NeurIPS 2021.

# Neural dynamic scene representations

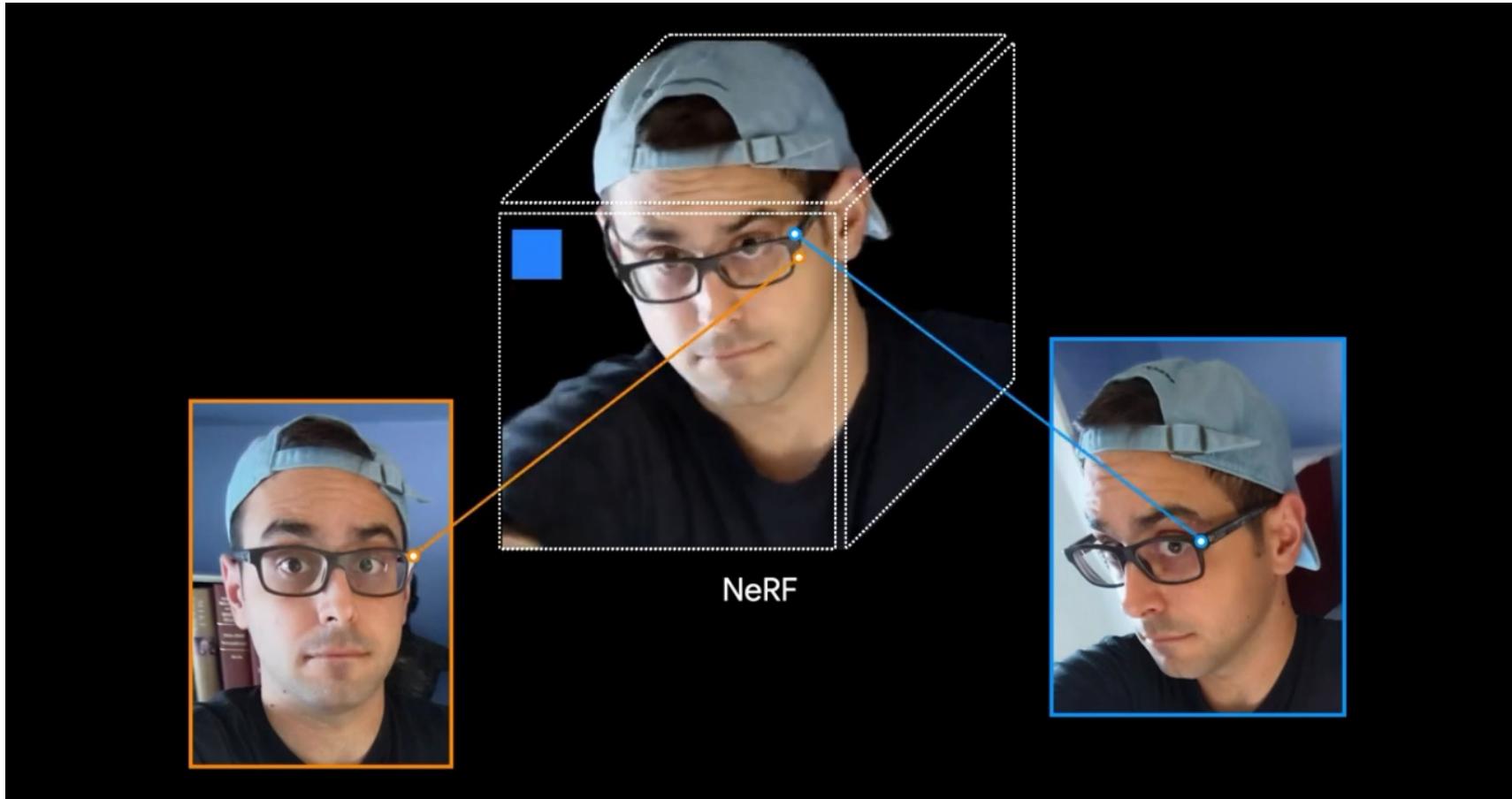
NeRF cannot model dynamic scenes



Nerfies: Deformable neural radiance fields, ICCV 2021.

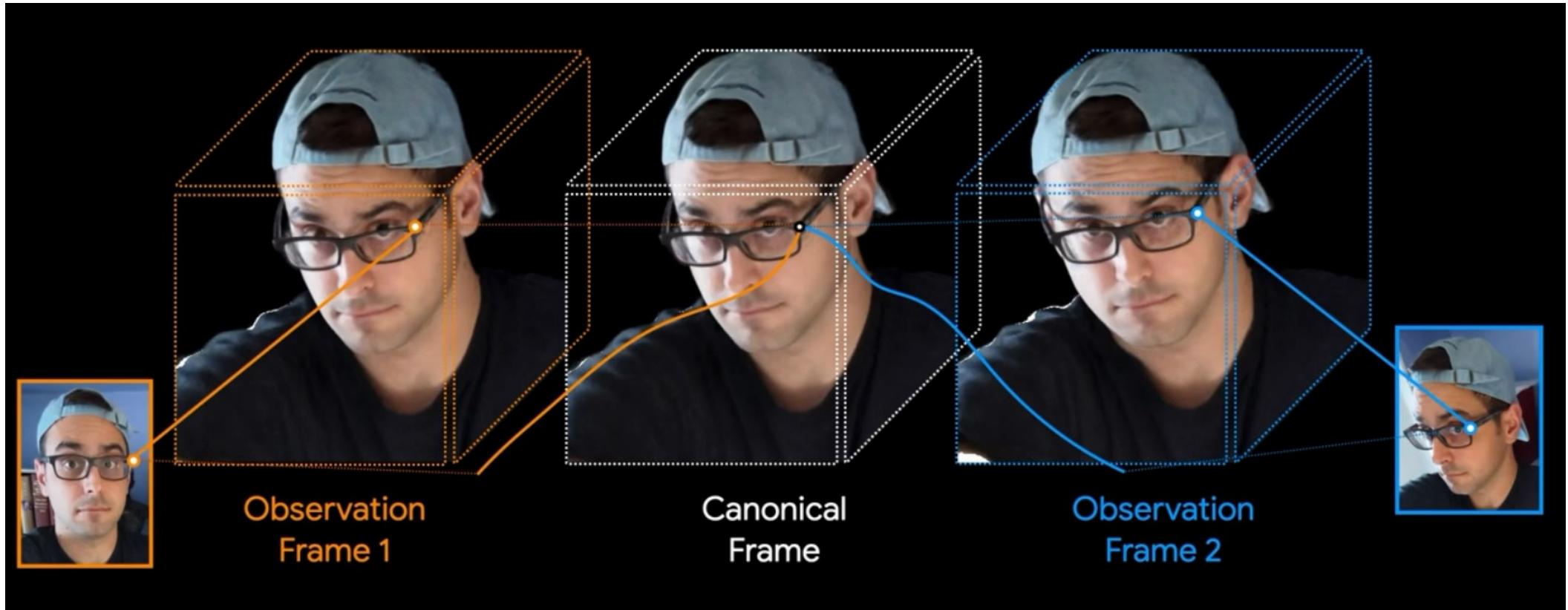
# Neural dynamic scene representations

Problem: scene movements cause the rays of different frames of the same observed point do not intersect



# General dynamic scenes – Deformable NeRF

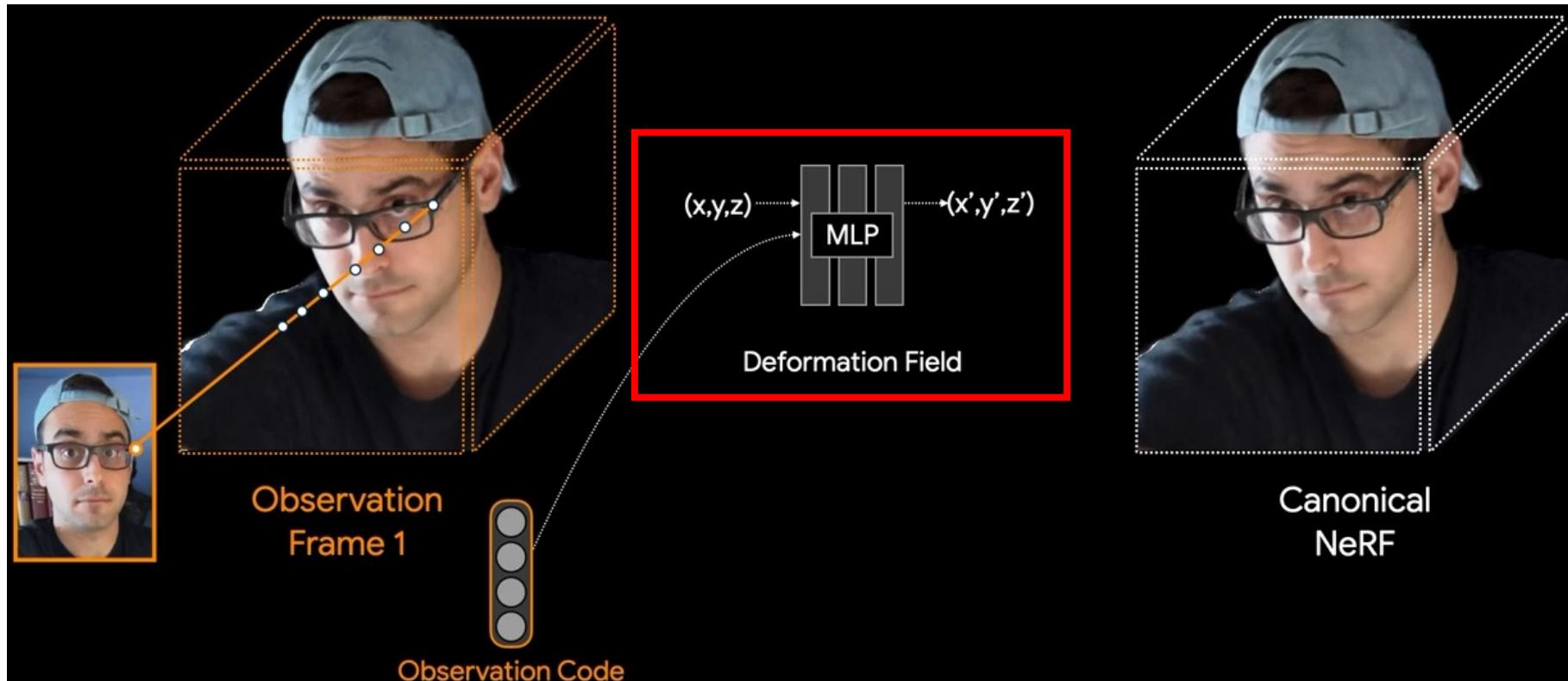
Deformable NeRF: a canonical NeRF + deformation fields



Nerfies: Deformable neural radiance fields, ICCV 2021.

# General dynamic scenes – Deformable NeRF

The deformation field from other frames to canonical frame is learned by another MLP

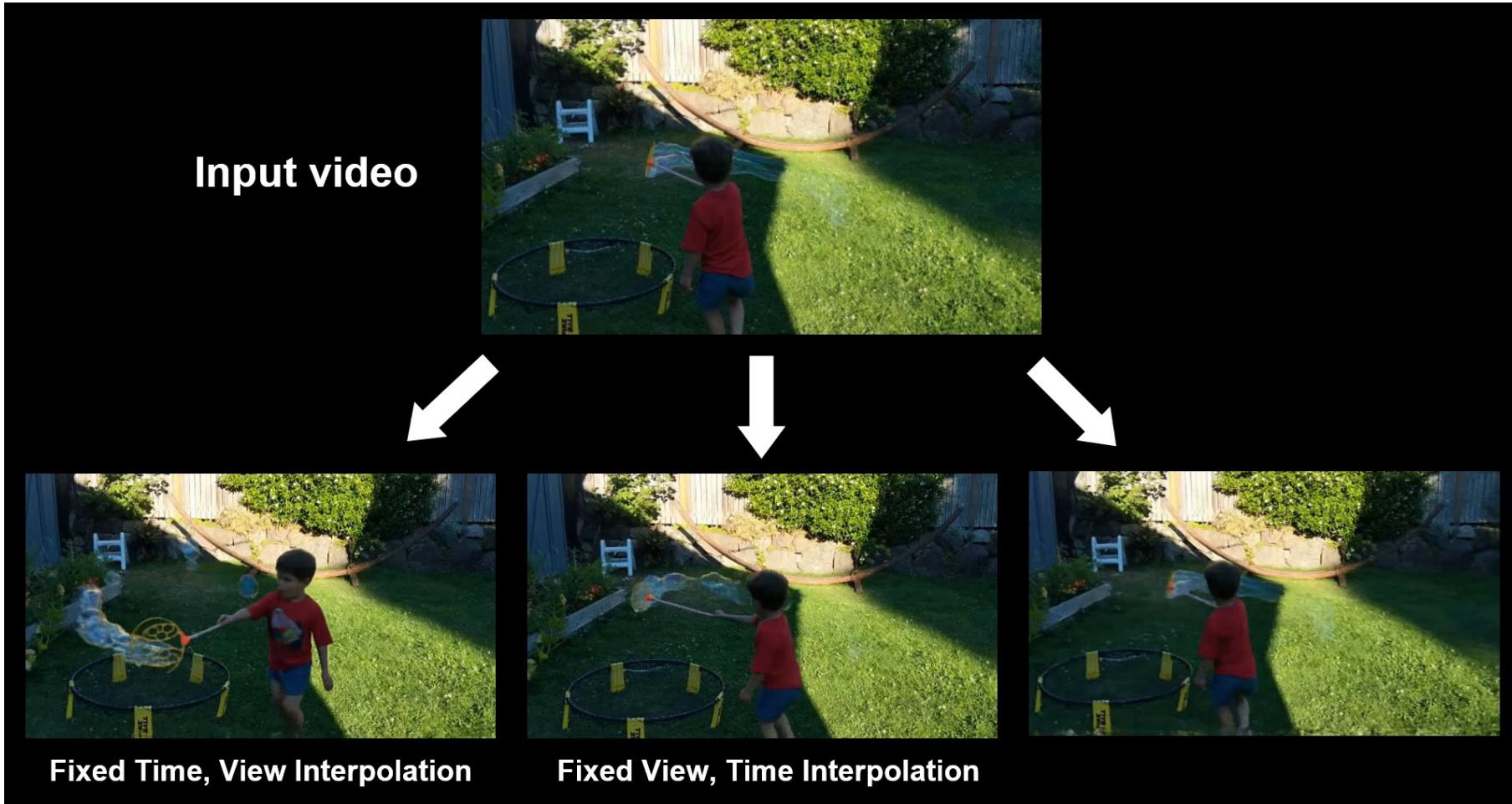


# General dynamic scenes – Deformable NeRF



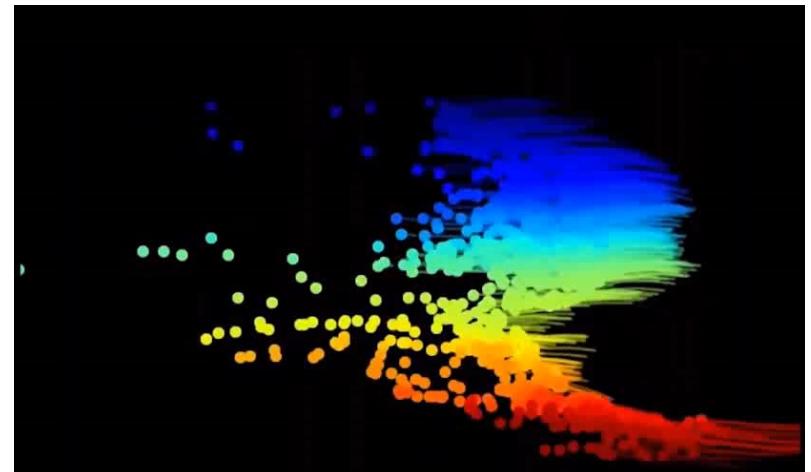
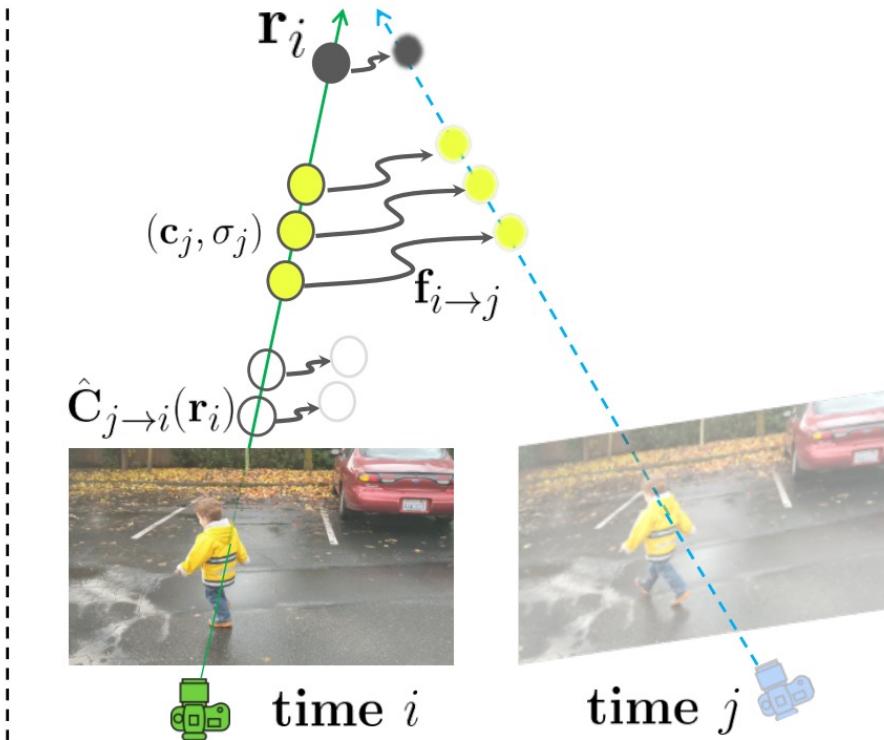
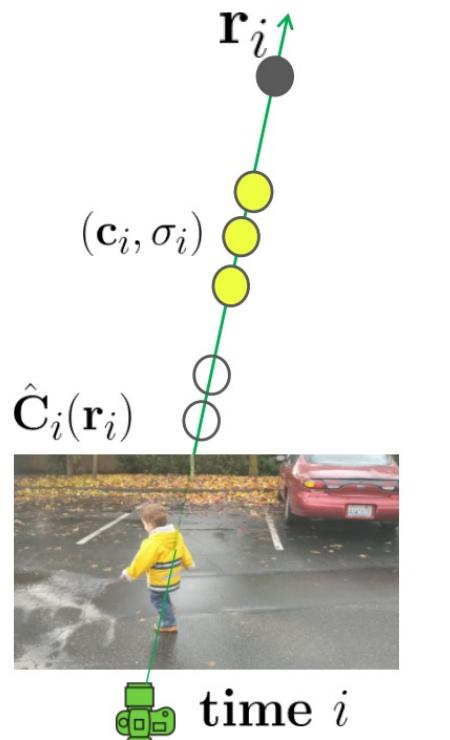
Nerfies: Deformable neural radiance fields, ICCV 2021.

# General dynamic scenes – NSFF



NSFF: Neural Scene Flow Fields for Space-Time View Synthesis of Dynamic Scenes, CVPR 2021

# General dynamic scenes – NSFF



3D scene flow visualization



NSFF: Neural Scene Flow Fields for Space-Time View Synthesis of Dynamic Scenes, CVPR 2021

# General dynamic scenes

Advantages:

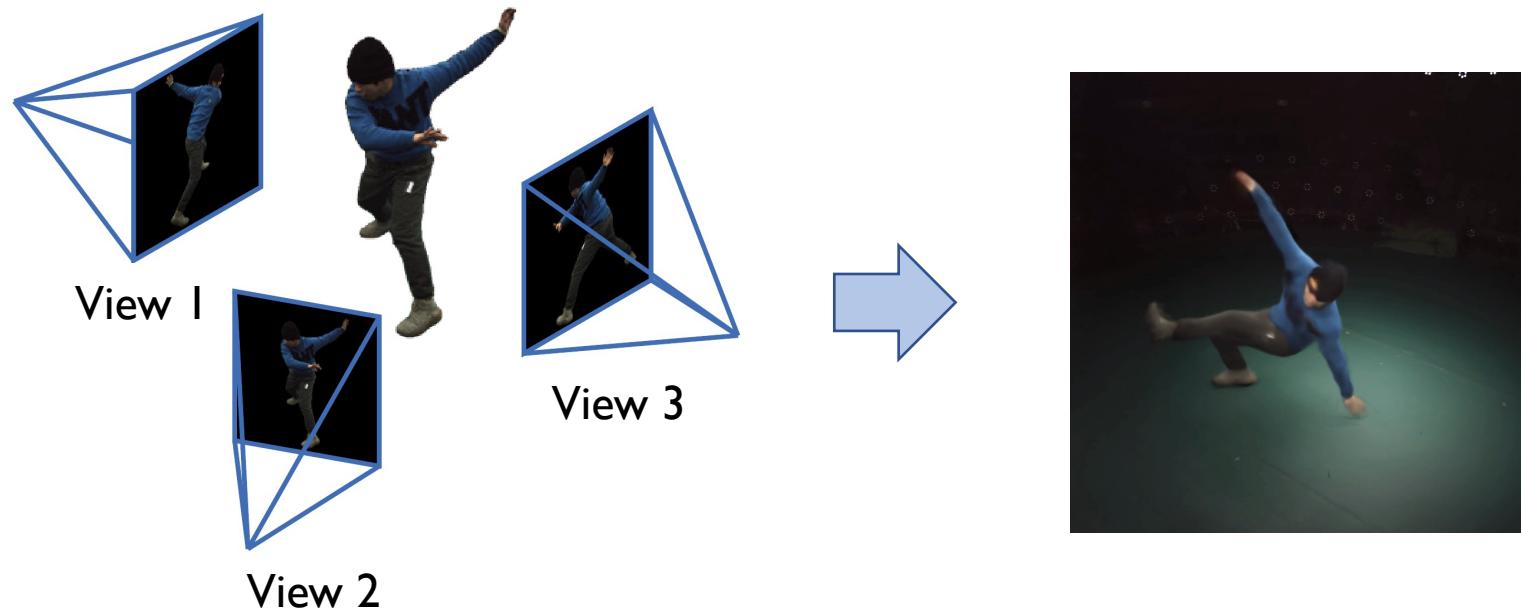
- Can model general objects and scenes, not restricted to human

Limitations:

- Need to optimize canonical NeRF and motion field simultaneously, which is prone to local optima
- It is very hard to recover large and long-range motion, e.g. fast moving human bodies

# Dynamic humans – Neural body

Reconstructing dynamic human from sparse views

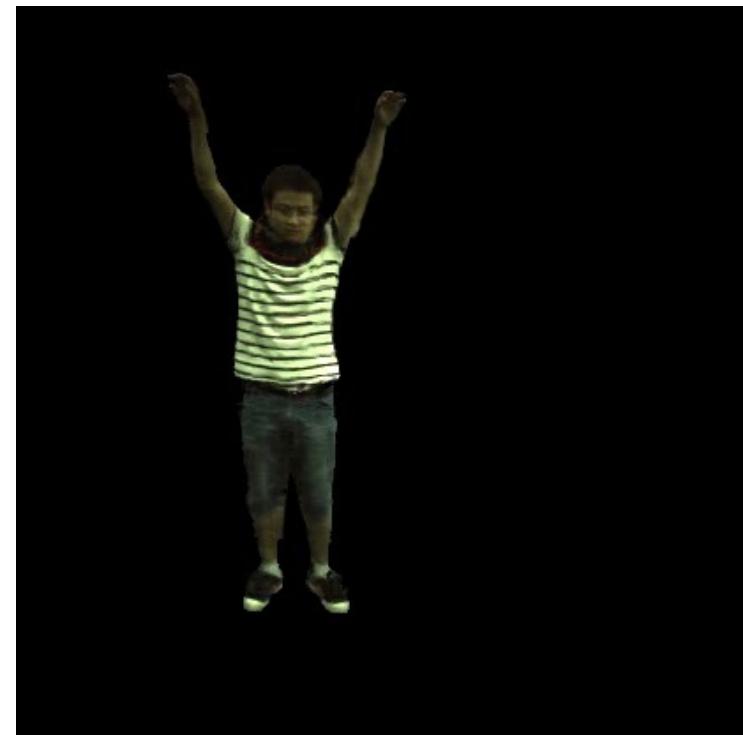


# Dynamic humans – Neural body

Reconstruction from sparse views is ill-posed



4 input views



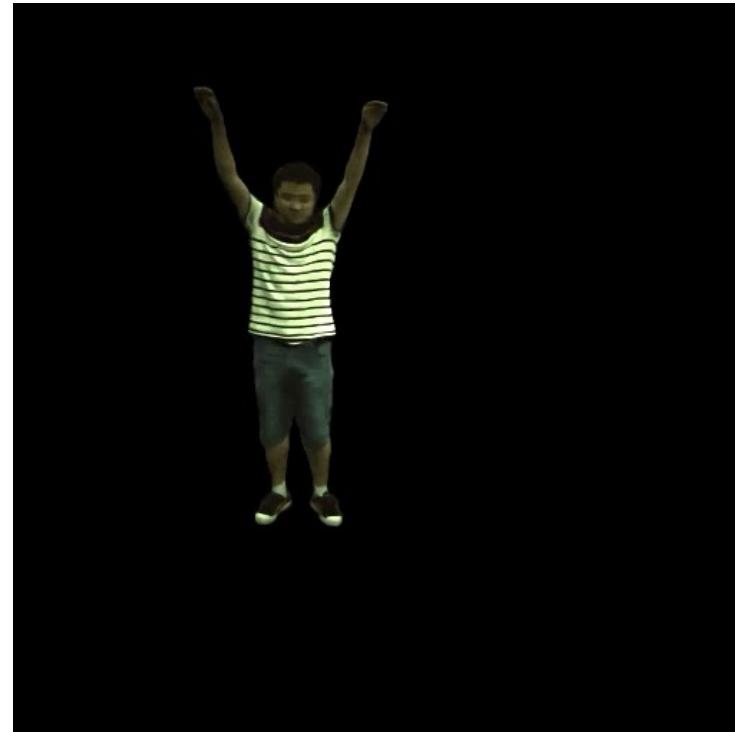
NeRF reconstruction

# Dynamic humans – Neural body

Integrating observations from multiple frames



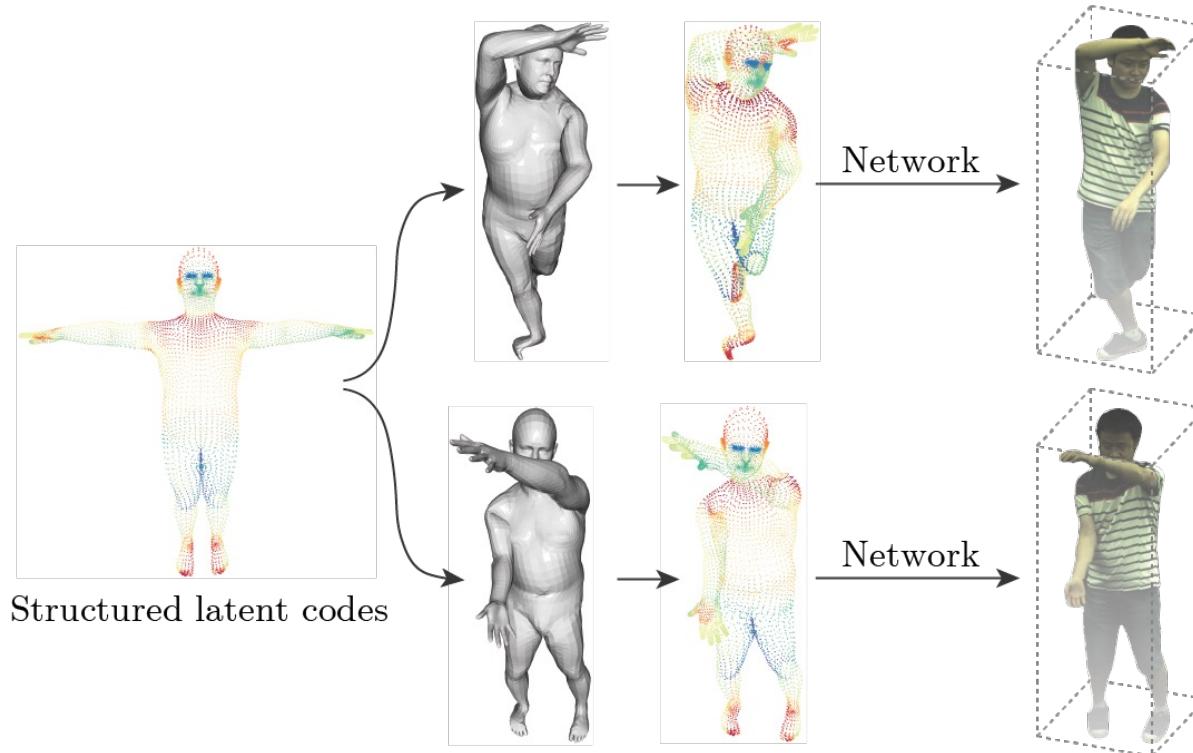
4 input views



Our reconstruction

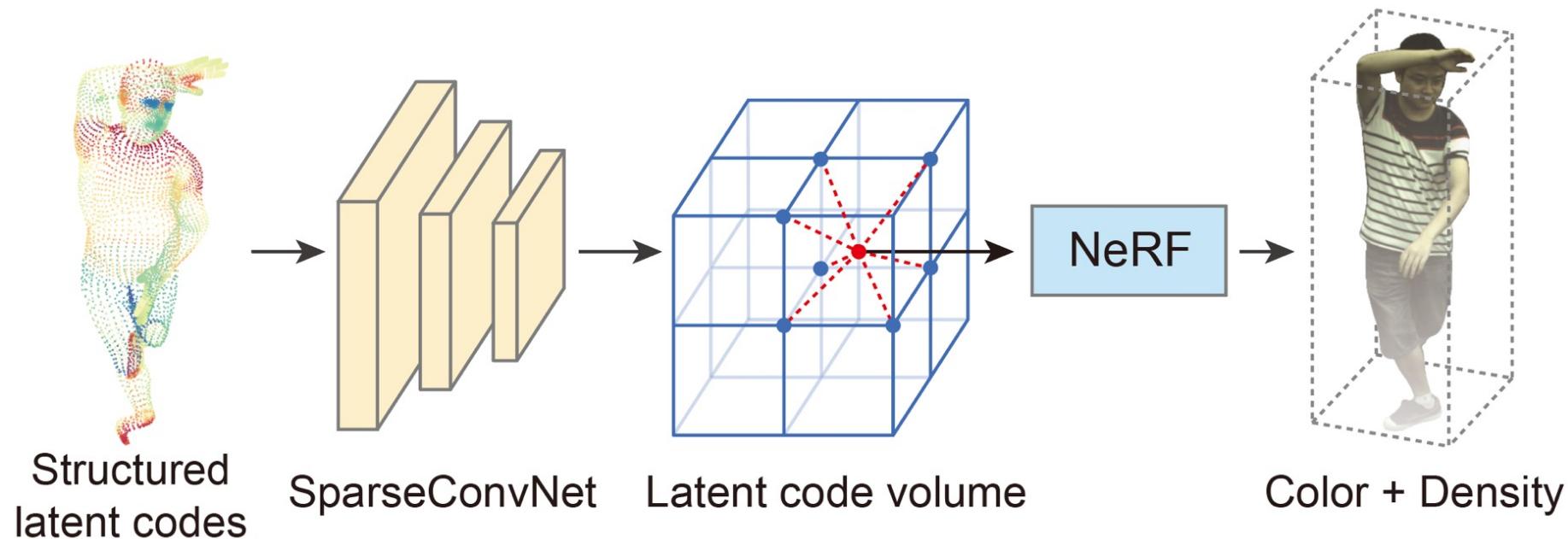
# Dynamic humans – Neural body

Assume NeRFs at different frames are decoded from the same set of latent codes, whose locations are pose dependent

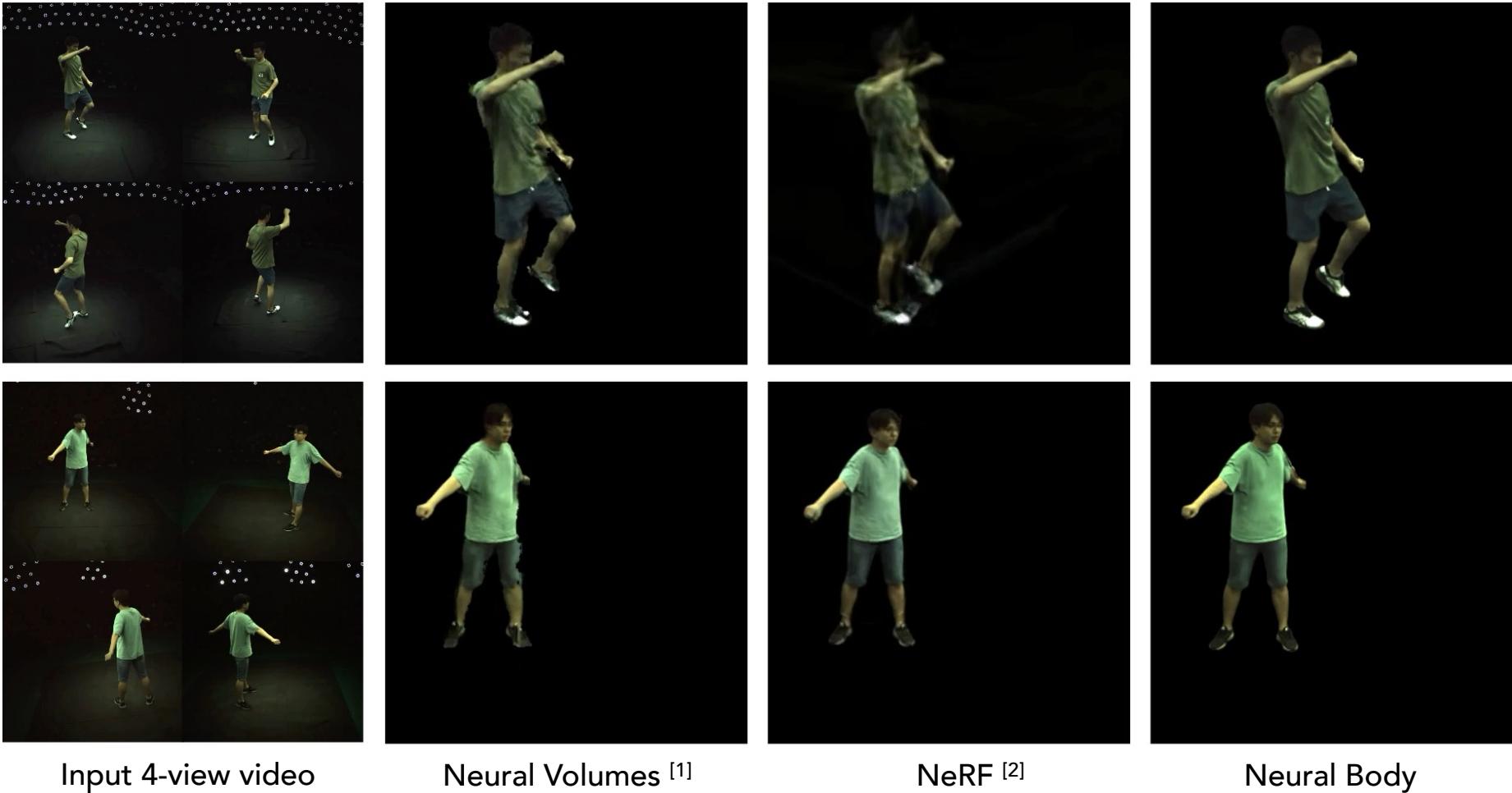


# Dynamic humans – Neural body

The latent codes are decoded into NeRF by sparse convolution



# Dynamic humans – Neural body

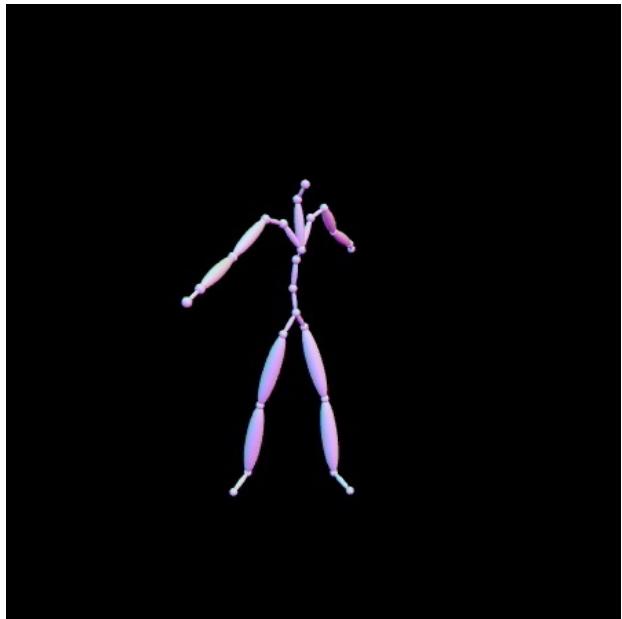


[1] Neural volumes: Learning dynamic renderable volumes from images, *SIGGRAPH* 2019.

[2] Nerf: Representing scenes as neural radiance fields for view synthesis, *ECCV* 2020.

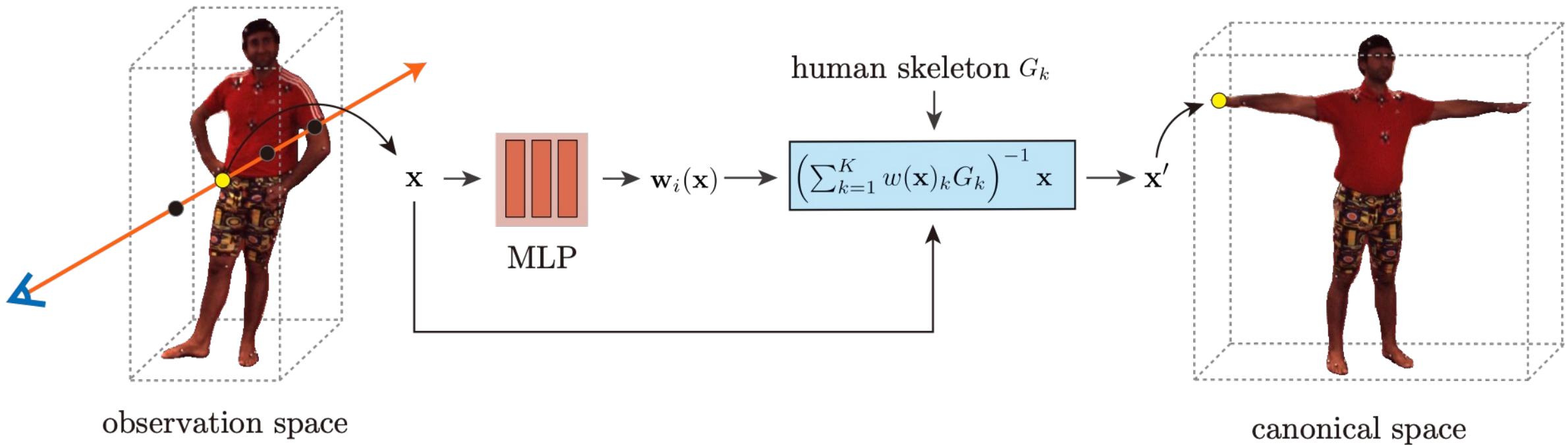
# Dynamic humans – Animatable NeRF

Neural Body cannot synthesize images of novel human poses as the 3D convolution is **not equivariant** to pose changes



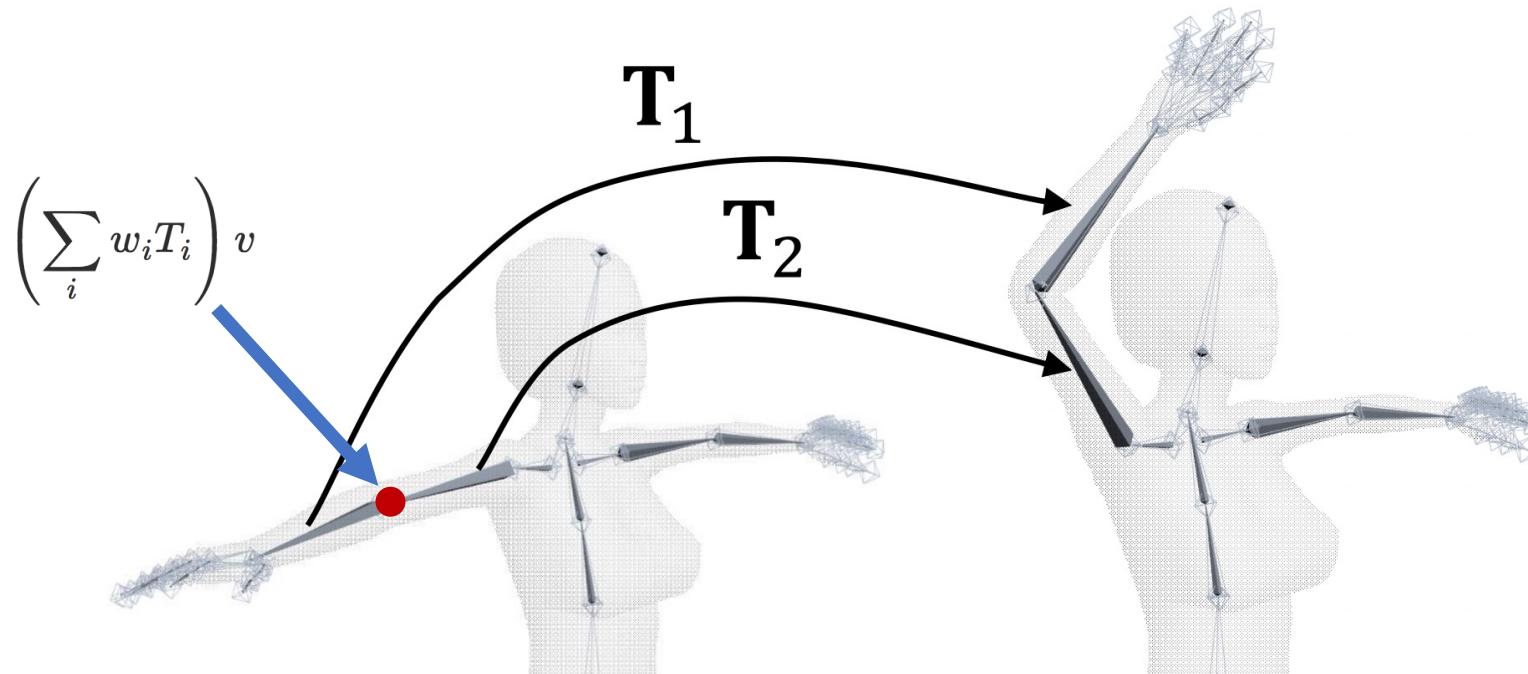
# Dynamic humans – Animatable NeRF

Key idea: deform NeRF with the linear blend scheme

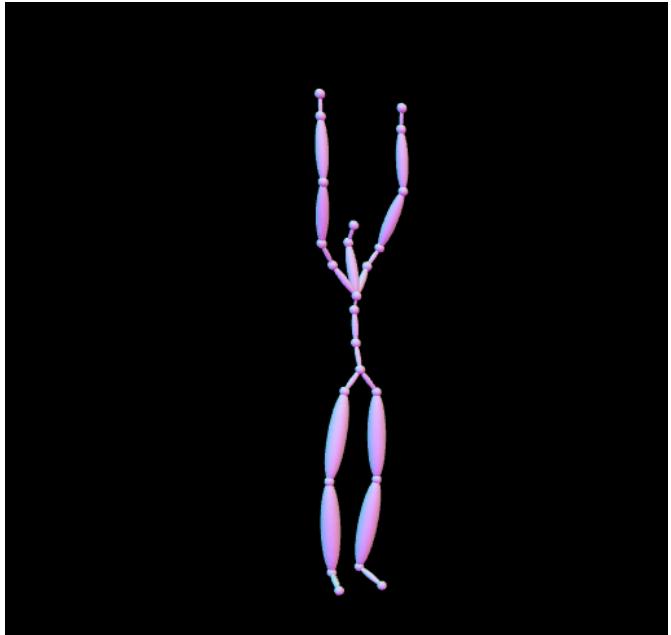


# Dynamic humans – Animatable NeRF

Key idea: deform NeRF with the linear blend scheme



# Dynamic humans – Animatable NeRF



# Dynamic humans – Animatable NeRF

Replace NeRF with Neural SDF (NeuS)



Animatable  
NeRF



Animatable  
NeuS



Animatable Implicit Neural Representations for Creating Realistic Avatars from Videos, arXiv 2022.

# Dynamic humans – Animatable NeRF

Monocular video  $\Rightarrow$  detailed surface





**VALSE**

**Thanks !**