PS3Q1
$$\frac{d(yu\phi)}{dx} = \frac{d}{dx} \left(\frac{r d\phi}{dx} \right)$$
 $\frac{fu}{r} \frac{d\theta}{dx} = \frac{d^{2}p}{dx^{2}}$
 $\frac{dx}{r} \frac{dx}{dx} = \frac{x}{r} \implies 0 \le x' \le 1$
 $\frac{fu}{r} \frac{d\theta}{d(x')} = \frac{d^{2}p}{f(x')^{2}}$

let
$$\phi_e = \frac{1+\alpha_e}{2}\phi_p + \frac{1-\alpha_e}{2}\phi_E$$

let
$$\phi_w = (\frac{1+\alpha_w}{2})\phi_w + (1-\alpha_w)\phi_p$$

recall that Po = jusx, ... all & will be the same \$\frac{\phi_p - \phi_w}{\pi_x} - \frac{\phi_E - \phi_p}{\pi_x} - \frac{\phi_E (1+\pi)}{2} \phi_w - \frac{\phi_E (1+\pi)}{2} \phi_p}{2} + \frac{\phi_E (1+\pi)}{2} \phi_p} + Pe (1-x) \$ = 0

At interior points
$$\begin{bmatrix}
1 & + & 1 & - & Pe(1-x) + Pe(1+x) & pp + & -1 & - & Pe(1+x) & pw \\
\Delta x & \Delta x & Z
\end{bmatrix}$$

$$+\left[-\frac{1}{\Delta x} + Pe\left(\frac{1-\alpha}{2}\right)\right] \oint_{E} = 0$$

At
$$x=0$$
, $\phi=1 = 2 \phi w + \phi p = 1 = 2 \phi w = 2 - \phi p$

At the interior points app + aw gw + ac ge = 0

now
$$appp + aw(z-pp) + aepe = 0$$

$$[(a_{\rho}-a_{w})\phi_{\rho}+a_{\epsilon}\phi_{\epsilon}=-2a_{w}]$$

at x'=1,
$$p = 0$$
 $p + q_6 = 0 => p_p = -q_6$

PS3 QI contid. Solving analytically.

$$d^{2}p = fedp$$

$$dx^{2} dx$$

$$let Y = dp = 7 dy = fe Y$$

$$dx = fe X$$

$$\int dY = fedx \Rightarrow ln Y = fex + C$$

$$Y = C, e^{fex}$$

$$\varphi = \int Y dx = \frac{1}{fe} Ce^{fex} + D$$

$$\varphi(x) = \int_{fe} e^{fex} + D$$

$$\varphi(0) = I \qquad \varphi(1) = 0$$

$$\varphi(0) = \int_{fe} e^{fe} + D = I \qquad \varphi(1) = \int_{fe} e^{fe} + D$$
Solve for C and D
$$C = \frac{-fe}{e^{fe}}, D = I + \frac{1}{e^{fe}}$$

$$\varphi(x) = \left(\frac{-1}{e^{fe}}\right)e^{fex} + \frac{1}{e^{fe}} + I$$

```
program PS3_Q1a
!************Begin Header*************************
!This program was written by Dr. Seth Dworkin on February 17, 2010.
!This program solves problem of 1D convection/diffusion and
!Dirichlet boundary conditions using finite volumes
!Variable declaration
implicit none
integer, parameter :: maxcvs=128
double precision, parameter :: pi = 3.1415926535897932384626433832795d0
double precision, dimension(maxcvs) :: e,f,g,b,T,x,T_exact,diff
integer :: numcvs,i,ii,osc
double precision :: length,ap,aw,ae,Pe,delx,alpha,L
!Variable initialization
Length = 1.d0
Pe = 50.d0
alpha = 0.d0 !Pe**2/(Pe**2+5.d0)
numcvs = 128
!do ii=1,32
!calculate the length of each cv
delx = Length/numcvs
!define the distance to the center of each c.v.
x(1) = delx/2.d0
do i=2, numcvs
   x(i) = x(i-1) + delx
end do
!determine the standard coefficients ap, aw, and ae
ap = (2.d0/delx) + Pe*alpha
aw = -1.d0/delx - Pe*(1.d0+alpha)/2.d0
ae = -1.d0/delx + Pe*(1.d0-alpha)/2.d0
!impose the west side boundary condition
e(1) = 0.d0
f(1) = ap-aw
g(1) = ae
b(1) = -2*aw
!impose the east side boundary condition
e(numcvs) = aw
f(numcvs) = ap-ae
g(numcvs) = 0.d0
b(numcvs) = 0.d0
!Enter the tridiagonal matrix A and rhs vector f to be solved
do i=2,numcvs-1
   e(i) = aw
   f(i) = ap
   g(i) = ae
   b(i) = 0.d0
end do
!solve the tridiagonal linear system using the Thomas algorithm
```

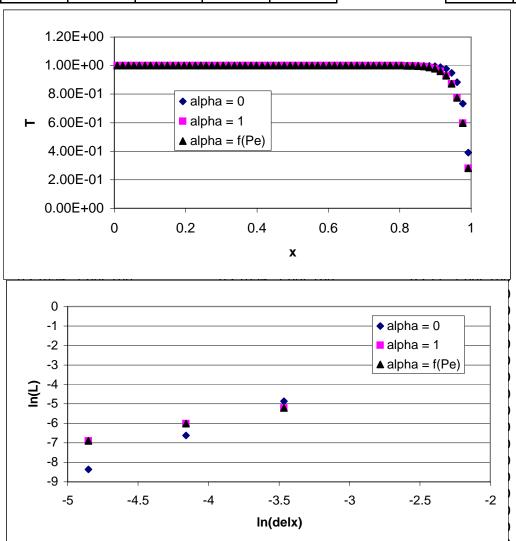
```
call Thomas(numcvs,e,f,g,b,T)
!Calculate the three errors, L1, L2, and L_inf
L = 0.d0
do i=1,numcvs
    T_{exact(i)} = (1.d0/(exp(Pe)-1.d0))*(1.d0-exp(Pe*x(i))) + 1.d0
   diff(i) = T_exact(i) - T(i)
   L = L + (T(i)-T_exact(i))**2
end do
L = \frac{dsqrt(L)}{numcvs}
!check for oscillations
osc = 0
do i=1,numcvs-1
   if(T(i+1)>T(i))then
    osc = osc + 1
    endif
end do
!if(numcvs==64)then
!write out the solution vector and error norms
write(*,*)' Solution vector:'
write(*,*)' x(i)
                      T(i)
                                 T_exact
                                              Diff'
do i=1, numcvs
   write(*,10)x(i),T(i),T_exact(i),T_exact(i)-T(i)
end do
!endif
write(*,*)
write(*,*)'For N = ',numcvs
write(*,12) L
!numcvs=numcvs+1
!if(osc.le.1)stop
!end do
10 format(1x,F7.5,4x,F7.5,4x,F7.5,4x,F9.5)
12 format(' L = ',E17.5)
end program PS3_Q1a
Subroutine Thomas(numcvs,e,f,g,b,x)
integer :: numcvs
double precision, dimension(numcvs) :: e,f,g,b,x
integer :: ii,jj,kk
!This subroutine solves a linear system using the thomas algorithm
!Part 1 (decomposition)
do kk=2, numcvs
    e(kk) = e(kk)/f(kk-1)
    f(kk) = f(kk) - e(kk)*g(kk-1)
end do
!Part 2 (forward substitution)
do kk=2, numcvs
   b(kk) = b(kk) - e(kk)*b(kk-1)
end do
```

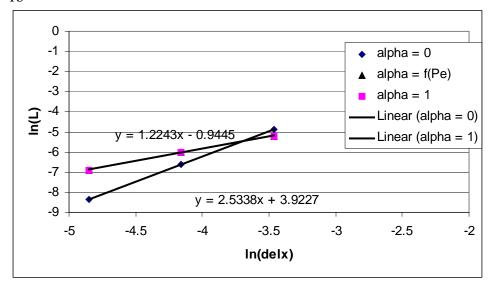
```
!Part 2 (backward substitution)
x(numcvs)=b(numcvs)/f(numcvs)
do kk=numcvs-1,1,-1
    x(kk) = (b(kk) - g(kk)*x(kk+1))/f(kk)
end do

End Subroutine Thomas
```

alpha delx Z 0 1 function 5.50E-03 0.03125 32 7.80E-03 5.52E-03 0.015625 1.33E-03 2.45E-03 2.44E-03 64 0.007813 128 2.32E-04 1.01E-03 1.01E-03

	In(L)		
In(deltx)	0	1	function
-3.46574	-4.85416	-5.19965	-5.20295
-4.15888	-6.62393	-6.01236	-6.01494
-4.85203	-8.36671	-6.89691	-6.89919





The two equations are depicted on the graph. They intercept at approx ln(delx) = -3.75 (delx = 0.0235) and $Pe_delta = 1.18$.

```
program PS3_Q1c
!************Begin Header*************************
!This program was written by Dr. Seth Dworkin on February 17, 2010.
!This program solves problem of 1D convection/diffusion and
!Dirichlet boundary conditions using finite volumes
!This program solves PS3 Qlc and determines the minimum number of grid points
!for which the solution no longer oscillates
!Variable declaration
implicit none
integer, parameter :: maxcvs=128
double precision, parameter :: pi = 3.1415926535897932384626433832795d0
double precision, dimension(maxcvs) :: e,f,g,b,T,x,T_exact,diff
integer :: numcvs,i,ii,osc
double precision :: length,ap,aw,ae,Pe,delx,alpha,L
!Variable initialization
Length = 1.d0
Pe = 50.d0
alpha = 0.d0 ! Pe**2/(Pe**2+5.d0)
numcvs = 8
do ii=1,32
!calculate the length of each cv
delx = Length/numcvs
!define the distance to the center of each c.v.
x(1) = delx/2.d0
do i=2, numcvs
   x(i) = x(i-1) + delx
end do
!determine the standard coefficients ap, aw, and ae
ap = (2.d0/delx) + Pe*alpha
aw = -1.d0/delx - Pe*(1.d0+alpha)/2.d0
ae = -1.d0/delx + Pe*(1.d0-alpha)/2.d0
!impose the west side boundary condition
e(1) = 0.d0
f(1) = ap-aw
g(1) = ae
b(1) = -2*aw
!impose the east side boundary condition
e(numcvs) = aw
f(numcvs) = ap-ae
g(numcvs) = 0.d0
b(numcvs) = 0.d0
!Enter the tridiagonal matrix A and rhs vector f to be solved
do i=2,numcvs-1
   e(i) = aw
   f(i) = ap
   g(i) = ae
   b(i) = 0.d0
end do
```

```
!solve the tridiagonal linear system using the Thomas algorithm
call Thomas(numcvs,e,f,g,b,T)
!Calculate the three errors, L1, L2, and L_inf
L = 0.d0
do i=1,numcvs
    T_{exact(i)} = (1.d0/(exp(Pe)-1.d0))*(1.d0-exp(Pe*x(i))) + 1.d0
    diff(i) = T_exact(i)-T(i)
    L = L + (T(i)-T_exact(i))**2
end do
L = \frac{dsqrt(L)}{numcvs}
!check for oscillations
osc = 0
do i=1,numcvs-1
    if(T(i+1)>T(i))then
    osc = osc + 1
    endif
end do
!if(numcvs==64)then
!write out the solution vector and error norms
write(*,*)' Solution vector:'
write(*,*)' x(i)
                                               Diff'
                        T(i)
                                  T exact
do i=1, numcvs
   write(*,10)x(i),T(i),T_exact(i),T_exact(i)-T(i)
end do
!endif
write(*,*)
write(*,*)'For N = ',numcvs
write(*,12) L
numcvs=numcvs+1
if(osc.le.1)then
    write(*,*)'Pe_delta = ',Pe/numcvs
    stop
endif
end do
10 format(1x,F7.5,4x,F7.5,4x,F7.5,4x,F9.5)
12 format(' L = ',E17.5)
end program PS3_Q1c
! *********************************
Subroutine Thomas(numcvs,e,f,g,b,x)
integer :: numcvs
double precision, dimension(numcvs) :: e,f,g,b,x
integer :: ii,jj,kk
!This subroutine solves a linear system using the thomas algorithm
!Part 1 (decomposition)
do kk=2, numcvs
    e(kk) = e(kk)/f(kk-1)
```

```
f(kk) = f(kk) - e(kk)*g(kk-1)
end do

!Part 2 (forward substitution)
do kk=2,numcvs
    b(kk) = b(kk) - e(kk)*b(kk-1)
end do

!Part 2 (backward substitution)
x(numcvs)=b(numcvs)/f(numcvs)
do kk=numcvs-1,1,-1
    x(kk) = (b(kk) - g(kk)*x(kk+1))/f(kk)
end do

End Subroutine Thomas
```

Output

Solution x(i) 0.06250 0.18750 0.31250 0.43750 0.56250 0.68750 0.81250	vector: T(i) 0.98442 1.04490 0.92750 1.15539 0.71302 1.57173 09517	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99992	Diff 0.01558 -0.04490 0.07250 -0.15539 0.28698 -0.57173 1.09508
0.93750 For N = L =	3.14058 8 0.31653E+00	0.95606	-2.18451
Solution x(i) 0.05556 0.16667 0.27778 0.38889 0.50000 0.61111 0.72222 0.83333 0.94444		T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99976 0.93782	Diff -0.00314 0.01021 -0.01816 0.04211 -0.08596 0.18619 -0.39212 0.83655 -1.83681
For N = L = Solution x(i) 0.05000 0.15000 0.25000 0.35000 0.45000 0.55000 0.65000 0.75000 0.85000 0.95000	9 0.22965E+00 vector: T(i) 0.99948 1.00192 0.99622 1.00951 0.97852 1.05082 0.88211 1.27578 0.35722 2.50052	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99945 0.91792	Diff 0.00052 -0.00192 0.00378 -0.00951 0.02148 -0.05082 0.11789 -0.27578 0.64223 -1.58261
For N = L = Solution x(i) 0.04545 0.13636 0.22727 0.31818 0.40909 0.50000 0.59091 0.68182 0.77273 0.86364 0.95455	10 0.17350E+00 vector: T(i) 1.00007 0.99971 1.00064 0.99826 1.00437 0.98865 1.02908 0.92512 1.19244 0.50503 2.27266	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99999 0.99891 0.89697	Diff -0.00007 0.00029 -0.00064 0.00174 -0.00437 0.01135 -0.02908 0.07488 -0.19246 0.49387 -1.37569
For N = L = Solution x(i) 0.04167 0.12500 0.20833 0.29167 0.37500 0.45833 0.54167 0.62500 0.70833 0.79167 0.87500 0.95833	11 0.13423E+00 vector: T(i) 0.99999 1.00003 0.99992 1.00026 0.99929 1.00204 0.99420 1.01651 0.95302 1.13374 0.61937 2.08334	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99997 0.99807 0.87549	Diff 0.00001 -0.00003 0.00008 -0.00026 0.00071 -0.00204 0.00580 -0.01651 0.04698 -0.13377 0.37870 -1.20786
For N =	12		

1

```
0.10616E+00
T, =
  Solution vector:
  x(i)
              T(i)
                        T_exact
                                      Diff
 0.03846
            1.00000
                        1.00000
                                     0.00000
0.11538
            1.00000
                        1.00000
                                     0.00000
0.19231
            1.00001
                        1.00000
                                    -0.00001
            0.99997
                                     0.00003
0.26923
                        1.00000
0.34615
            1.00009
                        1.00000
                                    -0.00009
0.42308
            0.99971
                        1.00000
                                     0.00029
0.50000
            1.00092
                        1.00000
                                    -0.00092
            0.99710
                                    0.00290
0.57692
                       1.00000
0.65385
            1.00918
                        1.00000
                                    -0.00918
0.73077
            0.97093
                        1.00000
                                    0.02907
0.80769
            1.09205
                        0.99993
                                    -0.09212
            0.70850
0.88462
                        0.99688
                                     0.28838
0.96154
            1.92308
                        0.85384
                                    -1.06923
For N =
           0.85514E-01
L =
  Solution vector:
            T(i)
                        T_exact
  x(i)
                                      Diff
0.03571
            1.00000
                        1.00000
                                     0.00000
                                     0.00000
0.10714
            1.00000
                       1.00000
0.17857
            1.00000
                        1.00000
                                     0.00000
0.25000
            1.00000
                        1.00000
                                     0.00000
0.32143
            0.99999
                       1.00000
                                     0.00001
            1.00003
                       1.00000
0.39286
                                    -0.00003
0.46429
            0.99989
                        1.00000
                                    0.00011
            1.00040
                                    -0.00040
0.53571
                       1.00000
0.60714
            0.99860
                       1.00000
                                    0.00140
                       1.00000
0.67857
            1.00497
                                    -0.00497
0.75000
            0.98237
                        1.00000
                                     0.01763
0.82143
            1.06251
                        0.99987
                                    -0.06264
0.89286
            0.77839
                        0.99529
                                    0.21690
            1.78571
                        0.83232
                                    -0.95339
0.96429
For N =
                   14
           0.69995E-01
T, =
Press any key to continue
  Solution vector:
              T(i)
                         T exact
                                      Diff
  x(i)
0.03333
            1.00000
                        1.00000
                                     0.00000
                       1.00000
0.10000
            1.00000
                                     0.00000
0.16667
            1.00000
                        1.00000
                                     0.00000
                                     0.00000
0.23333
            1.00000
                        1.00000
 0.30000
            1.00000
                       1.00000
                                     0.00000
            1.00000
                       1.00000
0.36667
                                     0.00000
0.43333
            1.00001
                        1.00000
                                    -0.00001
0.50000
            0.99996
                        1.00000
                                     0.00004
0.56667
            1.00016
                       1.00000
                                    -0.00016
0.63333
            0.99935
                       1.00000
                                    0.00065
0.70000
            1.00260
                        1.00000
                                    -0.00260
0.76667
            0.98958
                       0.99999
                                    0.01041
0.83333
            1.04167
                        0.99976
                                    -0.04191
0.90000
            0.83333
                       0.99326
                                     0.15993
0.96667
            1.66667
                        0.81112
                                    -0.85554
For N =
                   15
L =
           0.58096E-01
  Solution vector:
  x(i)
              T(i)
                        T_exact
                                      Diff
 0.03125
            1.00000
                        1.00000
                                     0.00000
                        1.00000
0.09375
            1.00000
                                     0.00000
0.15625
            1.00000
                        1.00000
                                     0.00000
0.21875
            1.00000
                        1.00000
                                     0.00000
                                     0.00000
0.28125
            1.00000
                        1.00000
            1.00000
                       1.00000
                                     0.00000
0.34375
0.40625
            1.00000
                        1.00000
                                     0.00000
0.46875
                                     0.00000
            1,00000
                        1.00000
0.53125
            0.99999
                        1.00000
                                     0.00001
            1.00006
0.59375
                                    -0.00006
                       1.00000
 0.65625
            0.99971
                        1.00000
                                     0.00029
                                    -0.00131
0.71875
            1.00131
                        1.00000
 0.78125
            0.99405
                        0.99998
                                    0.00593
0.84375
            1.02710
                       0.99960
                                    -0.02751
0.90625
            0.87652
                        0.99079
                                    0.11427
```

0.96875	1.56250	0.79039	-0.77211
For N = L = Solution x(i) 0.02941 0.08824 0.14706 0.20588 0.26471 0.32353 0.38235 0.44118 0.50000 0.55882 0.61765 0.67647 0.73529 0.79412 0.85294 0.91176 0.97059	16 0.48814E-01 vector: T(i) 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00002 0.99988 1.00062 0.99675 1.01707 0.91036 1.47059	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99997 0.99936 0.98787 0.77021	Diff 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 -0.00002 0.00012 -0.00062 0.00322 -0.01771 0.07750 -0.70038
For N = L = Solution x(i) 0.02778 0.08333 0.13889 0.19444 0.25000 0.30556 0.36111 0.41667 0.47222 0.52778 0.58333 0.63889 0.69444 0.75000 0.80556 0.86111 0.91667 0.97222	17 0.41464E-01 vector: T(i) 1.00000	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99994 0.99904 0.98450 0.75065	Diff 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 -0.00001 0.00004 -0.00028 0.00162 -0.01127 0.04780 -0.63824
For N = L = Solution x(i) 0.02632 0.07895 0.13158 0.18421 0.23684 0.28947 0.34211 0.39474 0.44737 0.50000 0.55263 0.60526 0.65789 0.71053 0.76316 0.81579 0.86842 0.92105 0.97368	18 0.35563E-01 Vector: T(i) 1.00000	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99999 0.99861 0.98069 0.73174	Diff 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00001 -0.0012 0.0070 -0.00726 0.02376 -0.58405
<pre>For N = L = Solution x(i) 0.02500</pre>	19 0.30767E-01 vector: T(i) 1.00000	T_exact 1.00000	Diff 0.00000

0.07500 0.12500 0.12500 0.17500 0.22500 0.27500 0.32500 0.37500 0.42500 0.47500 0.52500 0.52500 0.62500 0.72500 0.72500 0.72500 0.72500 0.82500 0.87500 0.82500 0.92500 0.97500 For N = L = Solution x(i) 0.02381 0.07143 0.11905	1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00309 0.97222 1.25000 20 0.26827E-01 Vector: T(i) 1.00000 1.00000 1.00000	1.00000 1.00000	0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00005 0.00005 0.00018 -0.0502 0.00426 -0.53650
0.16667 0.21429 0.26190 0.30952 0.35714 0.40476 0.45238 0.50000 0.54762 0.59524 0.64286 0.69048 0.73810 0.78571 0.83333 0.88095 0.92857 0.97619	1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00001 0.99987 1.00144 0.98344 1.19048	1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99998 0.99740 0.97188 0.69592	0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 -0.00003 -0.00012 -0.00404 -0.01155 -0.49455
For N = L = Solution x(i) 0.02273 0.06818 0.11364 0.15909 0.255000 0.25545 0.34091 0.38636 0.43182 0.47727 0.52273 0.56818 0.61364 0.65909 0.70455 0.75000 0.79545 0.84091 0.88636 0.93182 0.97727	21 0.23557E-01 vector: T(i) 1.00000	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99996 0.99659 0.96693 0.67902	Diff 0.00000

For N = 22 L = 0.20819E-01Solution vector:

D 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
or N = = Solution x(i) .02000 .06000 .10000 .14000 .22000 .26000 .30000 .34000 .42000 .46000 .50000 .54000 .58000 .62000 .70000	or N = Solution x(i) .02083 .06250 .10417 .14583 .18750 .22917 .27083 .31250 .35417 .39583 .43750 .47917 .52083 .56250 .60417 .64583 .68750 .72917 .77083 .81250 .85417 .89583 .93750 .97917	x(i) .02174 .06522 .10870 .15217 .19565 .23913 .28261 .32609 .36957 .41304 .45652 .50000 .54348 .58696 .63043 .67391 .71739 .76087 .80435 .84783 .89130 .93478
24 0.16538E-01 vector: T(i) 1.00000	23 0.18506E-01 Vector: T(i) 1.00000	T(i) 1.00000
T_exact 1.00000	T_exact 1.00000 0.99999 0.99992 0.999932 0.99453 0.95606 0.64713	T_exact 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 1.00000 0.99999 0.99950 0.99564 0.96164 0.66276
Diff 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000	Diff 0.00000	Diff 0.00000 0.00001 -0.000451 -0.03473 -0.42420

0.74000	1.00000	1.00000	0.00000
0.78000	1.00000	0.99998	-0.00002
0.82000	1.00000	0.99988	-0.00012
0.86000	1.00000	0.99909	-0.00091
0.90000	1.00000	0.99326	-0.00674
0.94000	1.00000	0.95021	-0.04979
0.98000	1.00000	0.63212	-0.36788

0.98000 1.00000 0.63212 -0.36788

For N = 25
L = 0.14852E-01
Pe_delta = 1.92307692307692

Press any key to continue

$$\begin{cases}
dT dt = 2 \begin{cases}
\nabla T. \hat{n} dA dt + \begin{cases}
\frac{S}{gc_p}
\end{cases}$$

$$t \neq A$$

since our CV is 20

This xay - Thoxay = xat Te-Te ay - xat Te-Tw ay

Ax

+xat Tr-Te ax - 2at Te-Ts ax

Ay

+ 5, + 5, Tp n+1

[DA + 2D+ AY + 2D+AY + 2D+AX + 2D+AX - S2] Tpn+1

- LAtay TE - & Stay Tw - & Stax TN - & Stax TN - & Stax Ts

= 5, + 7 "AX AY

PS3Q2 cont'd

rewrite the discretized egn at interior pts as

$$\begin{array}{l}
0 \text{ ApTp}^{n+1} + A \in Te^{n+1} + A_N T_N^{n+1} + A_W T_W^{n+1} + A_S T_S^{N+1} = b \\
\text{at } x = 0, \quad T_W = h T_W - \left[\frac{-\lambda}{\Delta x} + \frac{h}{2} \right] T_P \\
\text{at } x = 5 \text{cm}; \quad \lambda \left[\frac{1}{12} - \frac{1}{12} + \frac{h}{12} \right] T_P = h T_W \\
\text{at } x = \frac{1}{12} - \frac{1}{12} + \frac{h}{12} T_P = h T_W \\
\text{at } y = 0: \quad T_S + T_P = 150 + 273.15

\end{aligned}$$

$$\begin{array}{l}
T_S = 846.3 - T_P & 4 \\
\text{at } y = 5 \text{cm};
\end{array}$$

at
$$y = 5cm$$
:
$$\lambda \left[\frac{T_N - T_P}{\Delta y} \right] = h \left(\frac{T_N - T_P}{2} \right)$$

$$\begin{bmatrix} \lambda + h \end{bmatrix} T_N + \begin{bmatrix} -\lambda + h \end{bmatrix} T_p = h T_{\infty}$$

$$\begin{bmatrix} \lambda y & z \end{bmatrix} T_{\infty} = h T_{\infty}$$

PS3 QZ contid

$$T_N = h T_{\infty} - \left[\frac{\lambda}{2} + \frac{h}{2} \right] T_P$$
 (4)
 $\left[\frac{\lambda}{2} + \frac{h}{2} \right]$

Note that since DK=Dy, (3, and (5) can be withten as

where
$$C_1 = h T a$$
 and $C_2 = -\frac{\lambda}{2} + \frac{h}{2}$

$$\begin{bmatrix} \lambda + h \\ \Delta x & 2 \end{bmatrix}$$

$$\begin{bmatrix} \lambda + h \\ \Delta x & 2 \end{bmatrix}$$

For the source term

PS3 QZ cont'd along the bottom sub (1) into (1) APTP+AETE+ANTN+AWTW+As(706.3-TP)=6 (Ap-As)Tp + AST+ + ANTN+ ANTW= b- As 706.3 at bottom right, sub (3) and (1) into (1) APTP + AE (C.+CZTP) + ANTN + ANTN + AS (706.3-TP) = b (Ap + At (z - As) Tp + ANTN + ANTN = b-Atc. - As 706.3 left side: sub (2) into (1) APTP + AFTE + ANTN + AW (C.+(ZTP)+ASTS = b (Ap+Aw(2)Tp+AeTe+ANTN+Asts=b-Aw(, right side: sub (3) into (1) (Ap+AECz)Tp+AWTW+ANTN+AsTs=b-AEC, upper left (Ap + Aw(z + AN(z) Tp + AsTs + AETE = b - AWC, -ANC, (Ap+AN(z)Tp + AsTs + AETz+ AWTw=b-Anl. ap + AcCz + ANCZ)Tp + AsTs + ANTW = b - AcC, - ANC,

```
program PS3_Q2
!************Begin Header******
!This program was written by Dr. Seth Dworkin on February 19, 2010.
!This program solves the problem of 2D diffusion in a heat sink
!using finite volumes
!Variable declaration
implicit none
integer, parameter :: NX = 80
integer, parameter :: NY = 80
double precision, parameter :: pi = 3.1415926535897932384626433832795d0
double precision, parameter :: rho = 1716.d0 !Kg/m^3
double precision, parameter :: cp = 4817.d0 !J/kg*K
double precision, parameter :: lambda = 14.6d0 !W/m*K
double precision, parameter :: T_CPU = 423.15d0 !K
double precision, parameter :: h = 472.d0 \cdot W/m^2*K
double precision, parameter :: hside = 36.4d0 !W/m^2*K
double precision, parameter :: Tinf = 298.15d0 !K
double precision, parameter :: thickness = 0.0035d0
double precision, dimension(NX*NY) :: e,f,g,b,Tn,Tnpl,x,y
double precision, dimension(NX*NY) :: ld,ud !lower and upper diagonal of the lin sys
integer :: i,j,ii,iii,numcvs,ind
double precision :: length,height,alpha,Ap,Ae,Aw,An,As,T_center_np1,T_center_n
double precision :: delx,dely,delA,delV,delt,S1,S2,C1,C2,soldiff
!open a file to write the computed solutions to
open(UNIT=21,STATUS='replace',FORM='FORMATTED',FILE='T_plate.dat')
!Variable initialization
Length = 0.05d0 !meters
height = 0.05d0 !meters
delt = 0.01d0
numcvs = NX*NY
alpha = lambda/(rho*cp)
                          !in units of m^2/s
!calculate the length of each cv
delx = Length/NX
!calculate the height of each cv
dely = height/NY
!calculate the area of each cv
delA = delx*dely
!calculate the volume of each cv
delV = delA*thickness
!define the distance to the center of each c.v.
x(1) = delx/2.d0
do i=2,NX
   x(i) = x(i-1) + delx
!define the distance to the center of each c.v.
y(1) = dely/2.d0
do i=2,NY
   y(i) = y(i-1) + dely
end do
!set an initial guess
do ind=1, numcvs
   Tn(ind) = 298.15d0
!set the constant parameters of the problem
S1 = 2.d0*hside*Tinf*delA*delt/(rho*cp*thickness) !2.d0*hside*delA*Tinf/(rho*cp)
S2 = -2.d0*hside*delA*delt/(rho*cp*thickness) !-2.d0*hside*delA/(rho*cp)
Ap = delA + 4.d0*alpha*delt - S2
Ae = -alpha*delt
Aw = -alpha*delt
An = -alpha*delt
As = -alpha*delt
C1 = h*Tinf/((lambda/delx) + (h/2.d0))
C2 = -((h/2.d0) - (lambda/delx))/((lambda/delx) + (h/2.d0))
```

```
!initialize a timestep number counter
!enter the main timestepping loop
222 continue
ii=ii+1
!consider the bottom left hand point (ind = 1)
ind = 1
ld(ind) = 0.d0
e(ind) = 0.d0
f(ind) = Ap + Aw*C2 - As
g(ind) = Ae
ud(ind) = An
b(ind) = (S1 + Tn(ind)*delA) - Aw*C1 - As*2.d0*T_CPU
!consider the points along the bottom between the corners
do ind = 2,NX-1
    ld(ind) = 0.d0
    e(ind) = Aw
    f(ind) = Ap - As
    g(ind) = Ae
    ud(ind) = An
    b(ind) = (S1 + Tn(ind)*delA) - As*2.d0*T_CPU
!consider the bottom left hand point (ind = 1)
ind = NX
ld(ind) = 0.d0
e(ind) = Aw
f(ind) = Ap + Ae*C2 - As
g(ind) = 0.d0
ud(ind) = An
b(ind) = (S1 + Tn(ind)*delA) - Ae*C1 - As*2.d0*T_CPU
!consider the points along left side between the corners
do j = 2,NY-1
    ind = (j-1)*NX+1
    ld(ind) = As
    e(ind) = 0.d0
   f(ind) = Ap + Aw*C2
    g(ind) = Ae
    ud(ind) = An
    b(ind) = (S1 + Tn(ind)*delA) - Aw*C1
!consider the interior points
do j = 2,NY-1
    do i = 2,NX-1
        ind = (j-1)*NX+i
        ld(ind) = As
        e(ind) = Aw
        f(ind) = Ap
        g(ind) = Ae
        ud(ind) = An
        b(ind) = (S1 + Tn(ind)*delA)
    end do
end do
!consider the points along right side between the corners
do j = 2,NY-1
    ind = j*NX
    ld(ind) = As
    e(ind) = Aw
    f(ind) = Ap + Ae*C2
    g(ind) = 0.d0
    ud(ind) = An
    b(ind) = (S1 + Tn(ind)*delA) - Ae*C1
!consider the upper left hand point
ind = (NY-1)*NX + 1
ld(ind) = As
e(ind) = 0.d0
f(ind) = Ap + An*C2 + Aw*C2
```

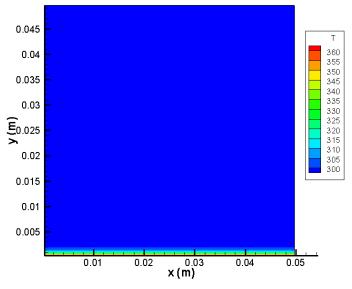
```
g(ind) = Ae
    ud(ind) = 0.d0
   b(ind) = (S1 + Tn(ind)*delA) - An*C1 - Aw*C1
    !consider the upper points between the corners
    do i = 2,NX-1
        ind = (NY-1)*NX + i
        ld(ind) = As
        e(ind) = Aw
        f(ind) = Ap + An*C2
        g(ind) = Ae
        ud(ind) = 0.d0
       b(ind) = (S1 + Tn(ind)*delA) - An*C1
    !consider the upper right hand point
    ind = NY*NX
    ld(ind) = As
    e(ind) = Aw
   f(ind) = Ap + An*C2 + Ae*C2
    g(ind) = 0.d0
   ud(ind) = 0.d0
   b(ind) = (S1 + Tn(ind)*delA) - An*C1 - Ae*C1
    !solve the tridiagonal linear system using the Thomas algorithm
   call P_Bi_CGSTAB(NX,numcvs,e,f,g,b,ud,ld,Tnp1)
    !check the stop criteria
   soldiff=0.d0
   do j=1,NY
        do i=1,NX
        ind=(j-1)*NX+1
            soldiff = soldiff + (Tn(ind) - Tnp1(ind))**2
    end do
    soldiff = dsqrt(soldiff)/numcvs
    write(*,*)delt*ii,soldiff
    !the ss value in the centre of the plate is first calculated as 352K
    !since it starts at 298.15 K
   T_center_n = 0.d0
    T_center_np1 = 0.d0
   do j=40,41
        do i=40.41
        ind=(j-1)*NX+1
            T_center_n = T_center_n + Tn(ind)
            T_center_np1 = T_center_np1 + Tnp1(ind)
        end do
    end do
    T_center_n = T_center_n/4.d0
   T_center_np1 = T_center_np1/4.d0
    if (T_center_n.lt.((375.7+298.15)/2.d0) .and. T_center_npl.gt.((375.7+298.15)/2.d0))then
   write(*,*)'Centre half time = ',delt*ii
   endif
    !update the solution so that the next timestep can proceed
   do ind=1, numcvs
        Tn(ind) = Tnp1(ind)
    !move to the next time step
    if(soldiff.gt.5d-10)goto 222
write(*,*)'Solution Complete'
write(21,*)'TITLE ="Temp"'
write(21,34)'VARIABLES = "x (m)", "y (m)", "T"'
write(21,*) ' ZONE T=', '"' ,'Species', '"' , ',', ' i =', NX,',' , ' J =', NY, ',' ,' F =POINT'
DO j=1,NY
   DO i=1.NX
       ind=(j-1)*NX+i
        write(21,33)x(i),y(j),Tnpl(ind)
    enddo
enddo
```

```
33 FORMAT(1X,1P120E13.4)
34 FORMAT(1X,A4000)
CLOSE(21)
write(*,*)
!write(*,*)'Temp profile at j=5'
!do i=1.NX
           ind=(j-1)*NX+i
           write(*,*)x(i),Tnpl(ind)
!end do
10 format(F9.1, 4x, F6.2, 1x, F6.2, 
11 format(F14.8,4x,F13.4)
end program PS3_Q2
Subroutine P_Bi_CGSTAB(NX,numcvs,e,f,g,b,ud,ld,x)
integer :: numcvs,NX
double precision, dimension(numcvs) :: e,f,g,b,x,r,v,p,r_bar,viml,piml,riml,ximl,ld,ud
double precision, dimension(numcvs) :: y,K,z,s,t,kinvs,kinvt,esym,fsym,gsym,bsym
integer :: ii,jj,kk
double precision :: errsum,rho,alpha,omega,CGTOL,rhoiml,omegaiml,beta
!This subroutine solves a tri-diagonal linear system using preconditioned Bi-CGSTAB
!The algorithm was taken from
!Van Der Vorst Siam J. Sci. Stat. Comput. 13 (1992) 631-644
!and was adapted for a nonsymmetric tridiagonal linear system
!Set the Bi-CGSTAB tolerance
CGTOL = 1.d-9
!Generate the initial guess
do ii=1, numcvs
            xim1(ii)=b(ii)/f(ii)
 !define the preconditioner as the diagonal of A
do ii=1.numcvs
            K(ii)=f(ii)
end do
!calculate r0
ii=1
rim1(ii)=b(ii)-ud(ii)*xim1(ii+NX)-f(ii)*xim1(ii)-q(ii)*xim1(ii+1)
           rim1(ii)=b(ii)-ud(ii)*xim1(ii+NX)-e(ii)*xim1(ii-1)-f(ii)*xim1(ii)-g(ii)*xim1(ii+1)
do ii=NX+1,numcvs-NX
             \\ \text{riml(ii)=b(ii)-ld(ii)*ximl(ii-NX)-ud(ii)*ximl(ii+NX)-e(ii)*ximl(ii-1)-f(ii)*ximl(ii)-g(ii)*ximl(ii+1) \\ \\ \text{riml(ii)=b(ii)-ld(ii)*ximl(ii)-g(ii)*ximl(ii+1) \\ \\ \text{riml(ii)=b(ii)-ld(ii)*ximl(ii)-g(ii)*ximl(ii+1) \\ \\ \text{riml(ii)=b(ii)-ld(ii)*ximl(ii)-g(ii)*ximl(ii+1) \\ \\ \text{riml(ii)=b(ii)-ld(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)*ximl(ii)-g(ii)-g(ii)*ximl(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii)-g(ii
do ii=numcvs-NX+1,numcvs-1
            rim1(ii)=b(ii)-ld(ii)*xim1(ii-NX)-e(ii)*xim1(ii-1)-f(ii)*xim1(ii)-q(ii)*xim1(ii+1)
end do
ii=numcvs
rim1(ii)=b(ii)-ld(ii)*xim1(ii-NX)-e(ii)*xim1(ii-1)-f(ii)*xim1(ii)
 !set r0_bar equal to r0
do ii=1,numcvs
            r_bar(ii)=rim1(ii)
!initialize the constants
kk=0
rhoim1 = 1.d0
alpha = 1.d0
omegaim1 = 1.d0
do ii=1, numcvs
            vim1(ii) = 0.d0
            pim1(ii) = 0.d0
end do
!begin main loop
errsum=1.d0
2001 continue
if(errsum.gt.CGTOL)then
```

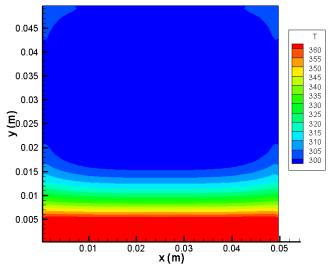
```
kk=kk+1
!check the progress
if(mod(kk,1000)==0)write(*,*)' BiCGSTAB itn = ',kk,' Resid = ',errsum
rho=dotprod(numcvs,rim1,r_bar)
beta=rho*alpha/(rhoim1*omegaim1)
do ii=1, numcvs
          p(ii)=rim1(ii)+beta*(pim1(ii)-omegaim1*vim1(ii))
!solve for y from Ky=pi
do ii=1, numcvs
          y(ii)=p(ii)/K(ii)
end do
!perform the matrix vector multiplication vi = Ay
v(ii) = f(ii)*y(ii) + g(ii)*y(ii+1) + ud(ii)*y(ii+NX)
do ii=2,NX
          v(ii) = e(ii)*y(ii-1) + f(ii)*y(ii) + g(ii)*y(ii+1) + ud(ii)*y(ii+NX)
do ii=NX+1,numcvs-NX
          v(ii) = e(ii)*y(ii-1) + f(ii)*y(ii) + g(ii)*y(ii+1) + ld(ii)*y(ii-NX) + ud(ii)*y(ii+NX)
end do
do ii=numcvs-NX+1,numcvs-1
          v(ii) = e(ii)*y(ii-1) + f(ii)*y(ii) + q(ii)*y(ii+1) + ld(ii)*y(ii-NX)
end do
ii=numcvs
v(ii) = e(ii)*y(ii-1) + f(ii)*y(ii) + ld(ii)*y(ii-NX)
alpha=rho/dotprod(numcvs,r_bar,v)
do ii=1, numcvs
          s(ii)=rim1(ii)-alpha*v(ii)
end do
!solve for z from Kz=s
do ii=1,numcvs
          z(ii)=s(ii)/K(ii)
!perform the matrix vector multiplication t = Az
t(ii)=f(ii)*z(ii)+g(ii)*z(ii+1)+ud(ii)*z(ii+NX)
do ii=2,NX
          t(ii)=e(ii)*z(ii-1)+f(ii)*z(ii)+g(ii)*z(ii+1)+ud(ii)*z(ii+NX)
end do
do ii=NX+1, numcvs-NX
          \texttt{t(ii)} = \texttt{e(ii)} * \texttt{z(ii-1)} + \texttt{f(ii)} * \texttt{z(ii)} + \texttt{g(ii)} * \texttt{z(ii+1)} + \texttt{ld(ii)} * \texttt{z(ii-NX)} + \texttt{ud(ii)} * \texttt{z(ii+NX)} + \texttt{ud(ii)} * \texttt{z(ii+NX)} + \texttt{ud(ii)} * \texttt{z(ii+NX)} + \texttt{ud(ii)} * \texttt{ud(iii)} * \texttt{ud(ii)} * \texttt{ud(iii)} * \texttt{ud(ii)}
end do
do ii=numcvs-NX+1,numcvs-1
          t(ii) = e(ii) *z(ii-1) + f(ii) *z(ii) + g(ii) *z(ii+1) + Id(ii) *z(ii-NX)
end do
t(ii) = e(ii) *z(ii-1) + f(ii) *z(ii) + ld(ii) *z(ii-NX)
do ii=1, numcvs
          kinvs(ii)=s(ii)/K(ii)
           kinvt(ii)=t(ii)/K(ii)
omega = (dotprod(numcvs,kinvt,kinvs))/(dotprod(numcvs,kinvt,kinvt))
do ii=1, numcvs
          x(ii)=xim1(ii)+alpha*y(ii)+omega*z(ii)
do ii=1.numcvs
         r(ii)=s(ii)-omega*t(ii)
!calculate the remaining error
errsum=0
ii=1
errsum = errsum + (b(ii) - f(ii) *x(ii) - g(ii) *x(ii+1) - ud(ii) *x(ii+NX)) **2
do ii=2,NX
           \verb|errsum+|(b(ii)-e(ii)*x(ii-1)-f(ii)*x(ii)-g(ii)*x(ii+1)-ud(ii)*x(ii+NX))**2|
end do
do ii=NX+1, numcvs-NX
           errsum = errsum + (b(ii) - e(ii) * x(ii-1) - f(ii) * x(ii) - g(ii) * x(ii+1) - ld(ii) * x(ii-NX) - ud(ii) * x(ii+NX)) * *2
do ii=numcvs-NX+1,numcvs-1
```

```
errsum = errsum + (b(ii) - e(ii) *x(ii-1) - f(ii) *x(ii) - q(ii) *x(ii+1) - ld(ii) *x(ii-NX)) **2
    end do
    ii=numcvs
    errsum=errsum+(b(ii)-e(ii)*x(ii-1)-f(ii)*x(ii)-ld(ii)*x(ii-NX))**2
    errsum = dsqrt(errsum)/numcvs
    !update all of the variables to prepare for the next iteration
    omegaim1 = omega
    do ii=1, numcvs
        rim1(ii)=r(ii)
        vim1(ii)=v(ii)
        pim1(ii)=p(ii)
        xim1(ii)=x(ii)
    end do
    goto 2001
else
    return
endif
12 format(1x, i5, 3x, E17.5E3)
End Subroutine P_Bi_CGSTAB
double precision function dotprod(n,a,b)
!this function calculates the dot product of two vectors \boldsymbol{a} and \boldsymbol{b}, of a given length \boldsymbol{n}
integer :: n,i
double precision, dimension(n) :: a,b
dotprod = 0.d0
do i=1,n
    dotprod = dotprod + a(i)*b(i)
end do
end function dotprod
```

After the stop criteria has been met, the temp distribution in the plate at 0.12s looks like:



However, the distribution using a stop criteria of 5e-5 is



The distribution at steady state using a stop criteria of 5e-8 (the same with 5e-10) is:

