#### Embedded Software

Resource Handling - Improving our programs



# Challenge - Resource Handling

- Brainstorm What do you consider a Resource Handling challenge?
  - What is a resource?
  - In which situations do you foresee challenges?
- Team up 2 & 2 for 3 minutes



# The Challenge

- Design and implement a system that
  - That garbage collects a resource when no one uses it (multi parties may share a resource)
  - It must be thread-safe
    - ▶ The resource itself is *NOT* protected, but its destruction must be



- Following usage scenario must work
  - Allocate resource in Thread A
  - Pass it to Thread B while keeping it in A
  - Relinquish usage in Thread A followed by Thread B
  - Resource is hereafter relinquished
- Could be ported to our Message Queues



#### The exercises this lecture

- RAII and SmartPointer
- Counted Smart Pointer
- Templated Counted Smart Pointer (OPTIONAL)
- boost::shared\_ptr<>



# Resource Handling



RAII for short repetition



# RAII



#### RAII

- Managing memory is often a problem or challenge,
  - ensuring correctness forgetting to deallocate (message etc.)
  - dealing with exceptions



#### RAII

- Managing memory is often a problem or challenge,
  - ensuring correctness forgetting to deallocate (message etc.)
  - dealing with exceptions
- Idiom : Resource Acquisition Is Initialization
  - Wrap up all resources in their own object that handles their lifetime and put object on stack



Simple RAII class which also is a SmartPointer

```
template<typename T>
class RAII
{
public:
    explicit RAII( T* p = 0 ) : p_(p) {}
    ~RAII() { delete p_; }
    T& operator*() const { return p_; }
    T* operator->() const { return p_; }
};
```

```
RAII<std::vector<int> > r( new std::vector<int>() );
std::cout << r->size() << std::endl;
} // The std::vector<int> is automatically deallocated
```



• Simple RAII class which also is a **SmartPointer** 

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Simple RAII class which also is a SmartPointer

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template<typename T>
                                                      RAII in effect
  class RAII
  public:
      explicit RAII( T* p = 0 ) : p_(p) {}
                                                        Resource is
                                                        deallocated
      ~RAII() { delete p_; }
      T& operator*() const { return p ;
      T* operator->() const { return p_;
                                   Accessing handled
Usage example
                                        resource
      RAII<std::vector<int> / r( new std::vector<int>() );
      std::cout <<(r->size())<< std::endl;</pre>
    // The std::vector<int> is automatically deallocated
```



boost::shared\_ptr<T>



# Classic problem

• What is the problem here?

```
void f()
{
    Client* c = new Client;
    Data* d = acquireData(c);
    if(...)
       return;

    delete d;
    delete c;
}
```



# Classic problem

• What is the problem here?

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void f()
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### Classic problem

• What is the problem here?

```
void f()
{
    Client* c = new Client;
    Data* d = acquireData(c);
    if(...)
        return;
    delete d;
    delete c;
}
Bad, where is the deallocation?
```



## Simple example

- std::string is automatically deallocated
  - Where exception is thrown
  - End of scope

```
void f()
{
    boost::shared_ptr<std::string> stringPtr(new std::string("Hello"));
    if (...) throw std::some_error("Bad number");
    std::cout << *stringPtr << std::endl;
}</pre>
Exit points
```



```
Stdout readout:
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                                                                              Value Use Count
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                                                                               42
                                                      2) 003756D0
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1) std::cout << aa << "\t" << *aa << "\t" << aa.use_count() << std::endl;
       boost::shared_ptr<int> bb(aa);
       ++(*bb);
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       std::cout << bb << "\t" << *bb << "\t" <<bb.use count()<<std::endl;</pre>
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Copy code and verify!



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I L L ENGINEE

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#### boost::shared\_ptr<T> - Properties

- A wrapping created with new T
- Reference counted
- delete is guaranteed called when the last reference to the object dies or when the member function reset() is called
- The same thread safety as build-in types
- It is possible to supply an alternative functor that handles the "deallocation"
- May be used in a container
- Implements the comparison operators
- Allows conversion from shared\_ptr<T> to shared\_ptr<U> if T\* implicit can be converted to U\* or if T is a specialization of U or U is void



boost::weak\_ptr<T> - Cyclic dependencies



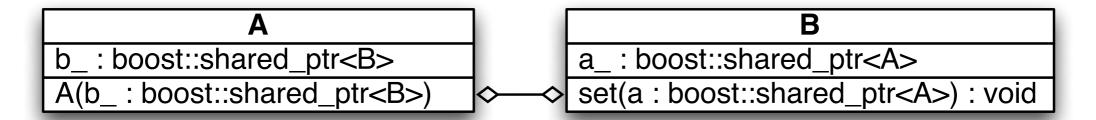
# Cyclic dependency - What?

ABb\_: boost::shared\_ptr<B>a\_: boost::shared\_ptr<A>A(b\_: boost::shared\_ptr<B>)⇒ set(a: boost::shared\_ptr<A>): void



# Cyclic dependency - What?

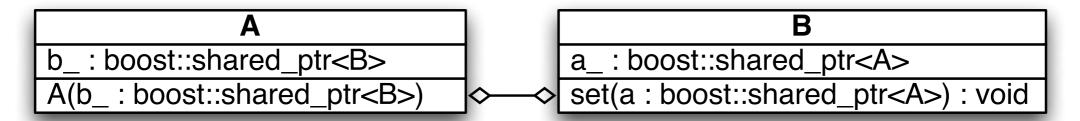
Problem simple



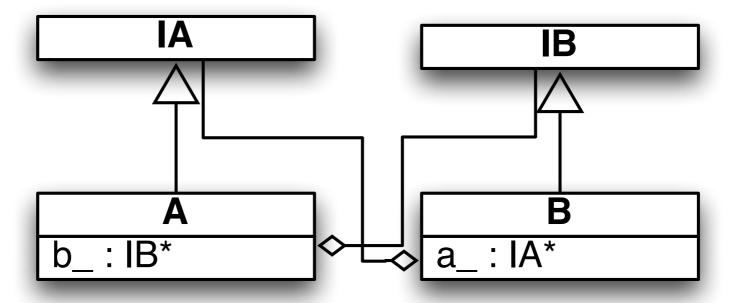


# Cyclic dependency - What?

Problem simple



More complex





# Usage – boost::weak\_ptr

Breaking cyclic dependencies

```
struct A {
    A(boost::shared_ptr<B> b)
    : b_(b) {}
    boost::shared_ptr<B> b_;
};
```

```
struct B {
    void set(boost::shared_ptr<A> a)
    { a_ = a; }

    boost::shared_ptr<A> a_;
};
```

```
Test harnish
boost::shared_ptr<B> tmpB(new B);
boost::shared_ptr<A> tmpA(new A(tmpB));
tmpB->set(tmpA); // Cyclic dependency introduced
```



## Usage – boost::weak\_ptr

Breaking cyclic dependencies

```
struct A {
    A(boost::shared_ptr<B> b)
    : b_(b) {}
    boost::shared_ptr<B> b_;
};
```

```
struct B {
   void set(boost::shared_ptr<A> a)
   { a_ = a; }

   boost::weak_ptr<A> a_;

   void doStuff() {
      boost::shared_ptr<A> a = a_.lock();
      if(a) {
            // Do stuff
      }
   };
};
```

```
Test harnish
boost::shared_ptr<B> tmpB(new B);
boost::shared_ptr<A> tmpA(new A(tmpB));
tmpB->set(tmpA); // Cyclic dependency introduced
```



### Properties – boost::weak\_ptr

- Typical usage is breaking cyclic dependencies
- Must call .lock() to determine whether the object pointed to still lives before trying to access it
- Must be converted to a shared\_ptr when access the object again
- Implements a "a less important" shared\_ptr
- A shared\_ptr without reference counting.
- Can be used in containers



scoped\_ptr<T>



# Usage

# boost::scoped\_ptr

- Simpel usage
  - std::string is automatically deallocated
    - Where exception is thrown
    - End of scope

```
void f()
{
    boost::scoped_ptr<std::string>
    stringPtr(new std::string("Hello"));

    if (...) throw std::some_error("Bad number");

    std::cout << *stringPtr << std::endl;
}</pre>
```



# Usage

# boost::scoped\_ptr

- Simpel usage
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void f()
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   if (...) throw std::some_error("Bad number");
   std::cout << *stringPtr << std::endl;
}</pre>
Exit points
```



# Properties

boost::scoped\_ptr

- Holds a pointer to an element allocated with new
- Guarantees that delete is called at destruction time
- Calls delete via a call to the member function reset()
- Cannot be used in a container, not copyable
- Alternative
  - std::auto\_ptr const but it cannot be reset



Boost::SmartPointer - Summary



#### Boost SmartPointer summary

#### boost::scoped\_ptr & boost::scoped\_array

- Objects with short lifespan confined to function/object
- Single object or an array of objects
- Non-copyable (whole point)

#### • boost::shared\_ptr & boost::shared\_array

- A more general wrapping used in containers
- Single object or an array of objects
- You want it all and you are willing to pay for it

#### boost::weak\_ptr

- Typically used to break circular references
- boost::intrusive\_ptr
  - Where OS or framework implement reference counting



#### Understandable or NOT

- Team up 2 and 2 for 2 mins
- Write down 1 thing that you
  - understood
  - did not quite get

• It will then be brought up on friday!

