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#include "rk4_solver.hh"
#include <cstdlib>
#include <ctime>
#include <cstdio>
#include <iostream>
#include <math.h>
#include <omp.h>

int main(){
    double T_final = 100.0;
    double hi_step = 0.001;
    double tolerance = 0.000001;
    double J = 0.1;
    double K = 1;
    double N_intrvls = 2;

    rk4 myRk4_1(1250, hi_step, tolerance, J, K, N_intrvls, 0.7, 1);
    double t1 = omp_get_wtime();
    myRk4_1.compute_solution(T_final);
    double t2 = omp_get_wtime();
    myRk4_1.terminate();

    /*
    for (double N_pwr=3.00; N_pwr<4.10; N_pwr += 0.05 ){
        int NN = (int) pow(10, N_pwr);
        rk4 myRk4_norm(NN, hi_step, tolerance, J, K, N_intrvls,0.1,0);
        double t1 = omp_get_wtime();
        myRk4_norm.compute_solution(T_final);
        double t2 = omp_get_wtime();
        myRk4_norm.terminate();
        rk4 myRk4_bh(NN, hi_step, tolerance, J, K, N_intrvls,0.1,1);
        double t3 = omp_get_wtime();
        myRk4_bh.compute_solution(T_final);
        double t4 = omp_get_wtime();
        myRk4_bh.terminate();
        printf("%d %f %f\n",NN, t2-t1, t4-t3);
    }
    */
    /*
    for (double pwr=-2; pwr<-0.2; pwr+=0.02){
        double theta = pow(10,pwr);
        rk4 myRk4_1(hi_step, tolerance, J, K, N_intrvls,theta);
        double t1 = omp_get_wtime();
        myRk4_1.compute_solution(T_final);
        double t2 = omp_get_wtime();
        myRk4_1.terminate();
        rk4 myRk4_2(hi_step, tolerance, J, K, N_intrvls,theta);
        double t3 = omp_get_wtime();
        myRk4_2.compute_solution(T_final);
        double t4 = omp_get_wtime();
        myRk4_2.terminate();
        rk4 myRk4_3(hi_step, tolerance, J, K, N_intrvls,theta);
        double t5 = omp_get_wtime();
        myRk4_3.compute_solution(T_final);
        double t6 = omp_get_wtime();
        myRk4_3.terminate();
        rk4 myRk4_4(hi_step, tolerance, J, K, N_intrvls,theta);
        double t7 = omp_get_wtime();
        myRk4_4.compute_solution(T_final);
        double t8 = omp_get_wtime();
        myRk4_4.terminate();
        rk4 myRk4_5(hi_step, tolerance, J, K, N_intrvls,theta);
        double t9 = omp_get_wtime();
        myRk4_5.compute_solution(T_final);
        double t10 = omp_get_wtime();
        myRk4_5.terminate();
        printf("%f %f %f %f %f %f\n",theta,t2-t1,t4-t3,t6-t5,t8-t7,t10-t9);
    }
    */
    printf("Total Computation Time: %f\n", t2-t1);
    return 0;
}

```