

yig_learning

May 8, 2022

0.1 Initialize HW and constants

```
[1]: import sys
sys.path.append("gpib_instrument_control")
import hp_3478a
import hp_8700_series_vna
import numpy as np
import time
import yig_controller_test
import matplotlib.pyplot as plt
import scipy.io as sio
import skrf.network
import yig_controller_test

plt.rcParams['figure.figsize'] = [15, 10]

#Instruments and devices
yigControllerPort='/dev/ttyUSB0'
vna = hp_8700_series_vna.Hp8753A()
curMeter = hp_3478a.Hp3478A()
yc = yig_controller_test.YigController(yigControllerPort)
```

Waiting for init... Done

```
[2]: #Constants and auxillary functions
fMin=np.array([0.6, 1, 2, 4, 8, 12])*1e9
fMax=np.array([1, 2, 4, 8, 12, 16])*1e9
yigDriver=yc.yigA
switch=yc.switchA

hardwareDescription='Yig filters moved to source side of transistor and 9v yig
↳voltage regulator'
hardwareRevision='2.2'
if yigDriver==yc.yigA:
    driverChannel='A'
if yigDriver==yc.yigB:
```

```

driverChannel='B'

def revFileName(baseName):
    global hardwareRevision
    return '%s_channel_%s_rev_%s.mat'%(baseName, driverChannel,hardwareRevision)

def saveData(baseName, baseData):
    global hardwareDescription
    global hardwareRevision
    dataToSave=baseData;
    dataToSave['hardwareDescription']=hardwareDescription
    sio.savemat(revFileName(baseName), dataToSave)

def loadData(baseName):
    global hardwareRevision
    return sio.loadmat(revFileName(baseName))

```

0.2 Measure current tuning ranges

```

[3]: wr = np.linspace(-32768, 32767, 128, dtype=np.int16)
yigChs = range(6)

zeros = []
channels=[]
currentMtx = None;
for c in yigChs:
    yigDriver.set(c, wr[0])
    time.sleep(5);
    current=[]
    for w in wr:
        yigDriver.set(c, w);
        time.sleep(0.5)
        for i in range(3):
            curMeter.readValue()
            current.append(curMeter.readValue())
    channels.append(current)
    currentMtx = yig_controller_test.stackVector(currentMtx, current)
    yigDriver.set(6, 0)
    time.sleep(3)
    zeros.append(curMeter.readValue())

saveData('current_sweep', {'current':currentMtx, 'yigChs':yigChs,'tuningWordRange': wr});

```

```

[4]: import scipy.io as sio
saveData('yig_filter_driver_current_data', {'zeros':zeros, 'channels':channels, ↴
    'wr':wr})

[5]: d=loadData('yig_filter_driver_current_data')
zeros=d['zeros'][0]
channels=d['channels']
wr=d['wr'][0]

[6]: print(zeros)

[-1.4e-05 -1.4e-05 -1.6e-05 -1.5e-05 -2.0e-05 -1.9e-05]

[7]: charr = np.array(channels)
def moving_average(x, w):
    return np.convolve(x, np.ones(w), 'valid') / w

class FilterParameters:
    def __init__(self, lc, hc, lw, hw):
        self.lc=lc
        self.hc=hc
        self.lw=lw
        self.hw=hw

fParams=[]
for i in range(len(zeros)):
    #avgd = moving_average(np.diff(charr[i,:]), 10)
    avgd = np.diff(charr[i,:])
    plt.plot(avgd)
    plt.grid(True)
    idxs = np.where(avgd>0.0002);
    mii=idxs[0][0]
    mai=idxs[0][-1]
    zc = zeros[i]
    mic=charr[i,mii]-zc
    mac=charr[i,mai]-zc
    #print(idxs[0])
    print("Filter %i has current from %f to %f [A] in control word range %d -" ↴
        "%d [LSB]"%(i, mic, mac, wr[mii], wr[mai]))
    fParams.append(FilterParameters(mic, mac, wr[mii], wr[mai]))

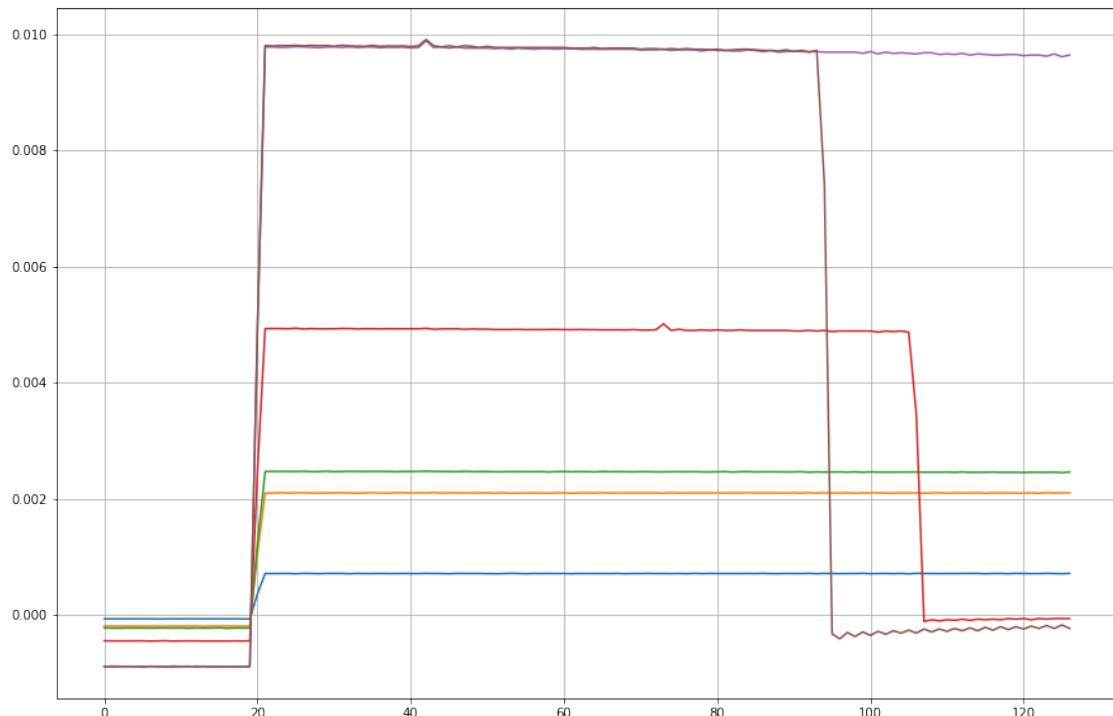
```

Filter 0 has current from 0.006467 to 0.081944 [A] in control word range -22448
- 32250 [LSB]
Filter 1 has current from 0.019049 to 0.240951 [A] in control word range -22448
- 32250 [LSB]

```

Filter 2 has current from 0.022388 to 0.282595 [A] in control word range -22448
- 32250 [LSB]
Filter 3 has current from 0.044662 to 0.464745 [A] in control word range -22448
- 21930 [LSB]
Filter 4 has current from 0.088594 to 1.114360 [A] in control word range -22448
- 32250 [LSB]
Filter 5 has current from 0.088834 to 0.806879 [A] in control word range -22448
- 15738 [LSB]

```



0.3 Coarse tuning

```
[8]: vna.setStartFrequency(130e6)
vna.setStopFrequency(20e9)
vna.setPoints(401)

fRanges=[]
for i in range(len(zeros)):
    #print("Filter", i )
    fp = fParams[i]
    switch.set(i+1)
    yigDriver.set(6, 0)
    fax = vna.frequencies()
    base = vna.readSParameter('S21')
    plt.plot(fax, 20*np.log10(np.abs(base)))
```

```

sr = np.linspace(fp.lw, fp.hw, 8)
freqs=[]

for w in sr:
    yigDriver.set(i, int(w))
    time.sleep(1)
    t = vna.readSParameter('S21')
    #traces.append(t)
    delt = np.abs(t)/np.abs(base)
    freqs.append(fax[np.argmax(delt)])
    plt.plot(fax, 20*np.log10(delt))

mif=np.min(freqs)
maf=np.max(freqs)
#print(freqs)
#print(np.diff(freqs))
fRanges.append((mif, maf))

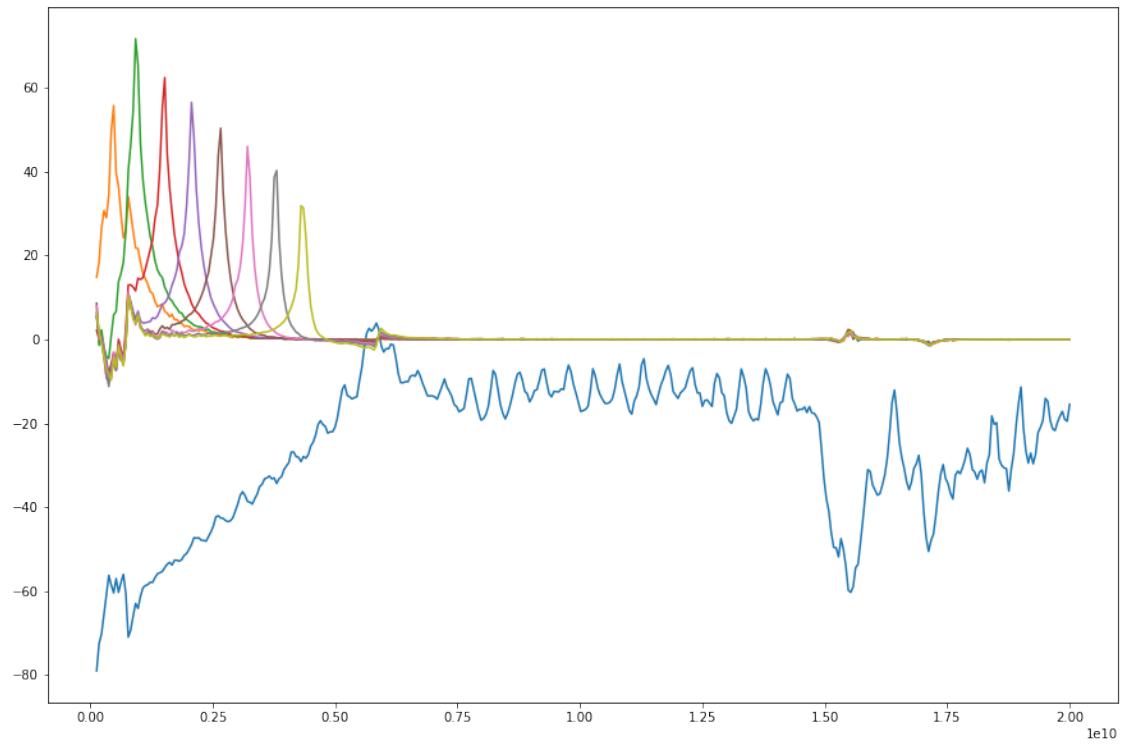
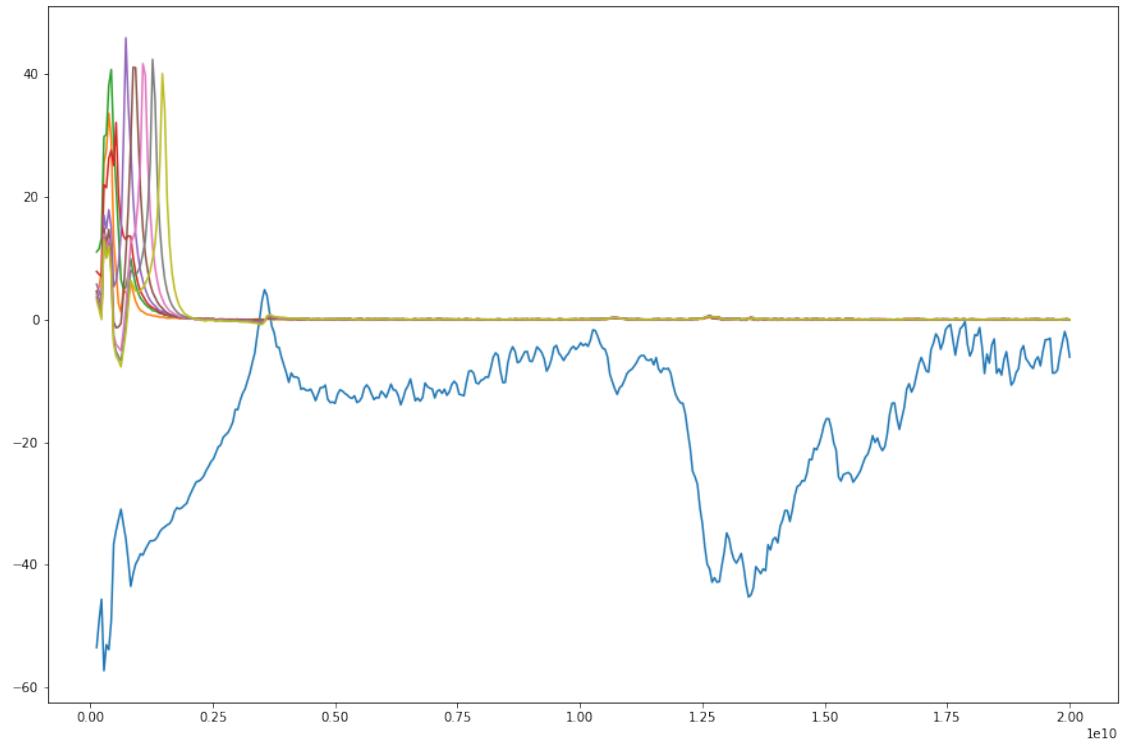
plt.figure()

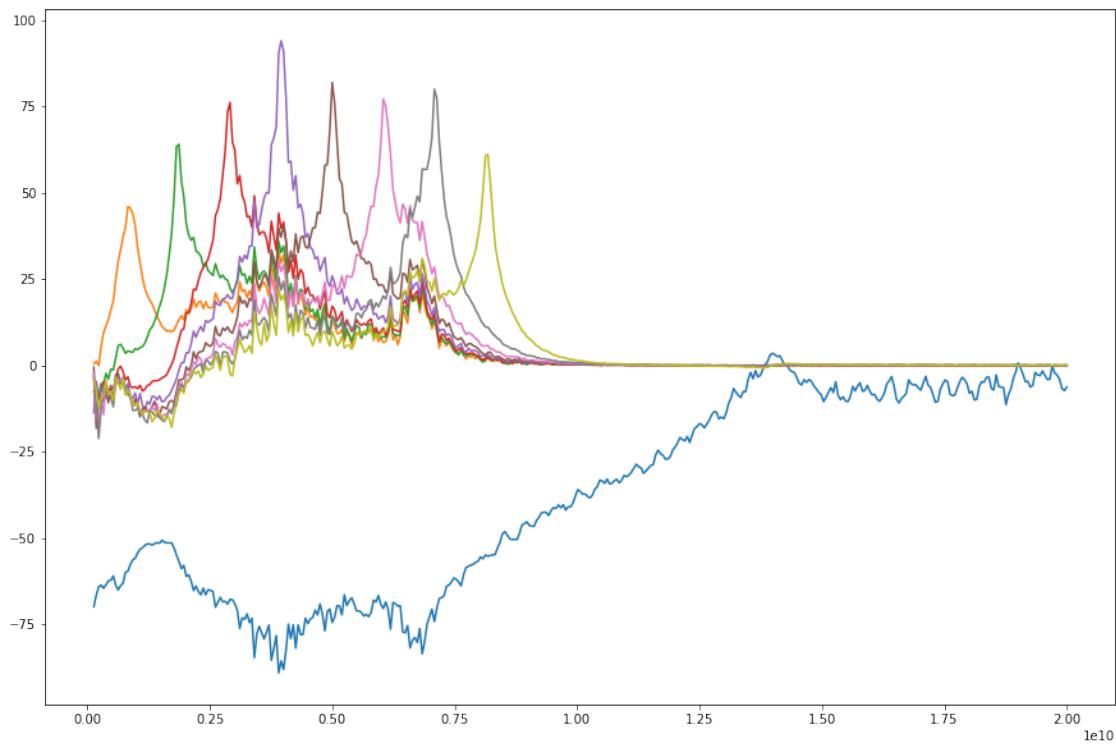
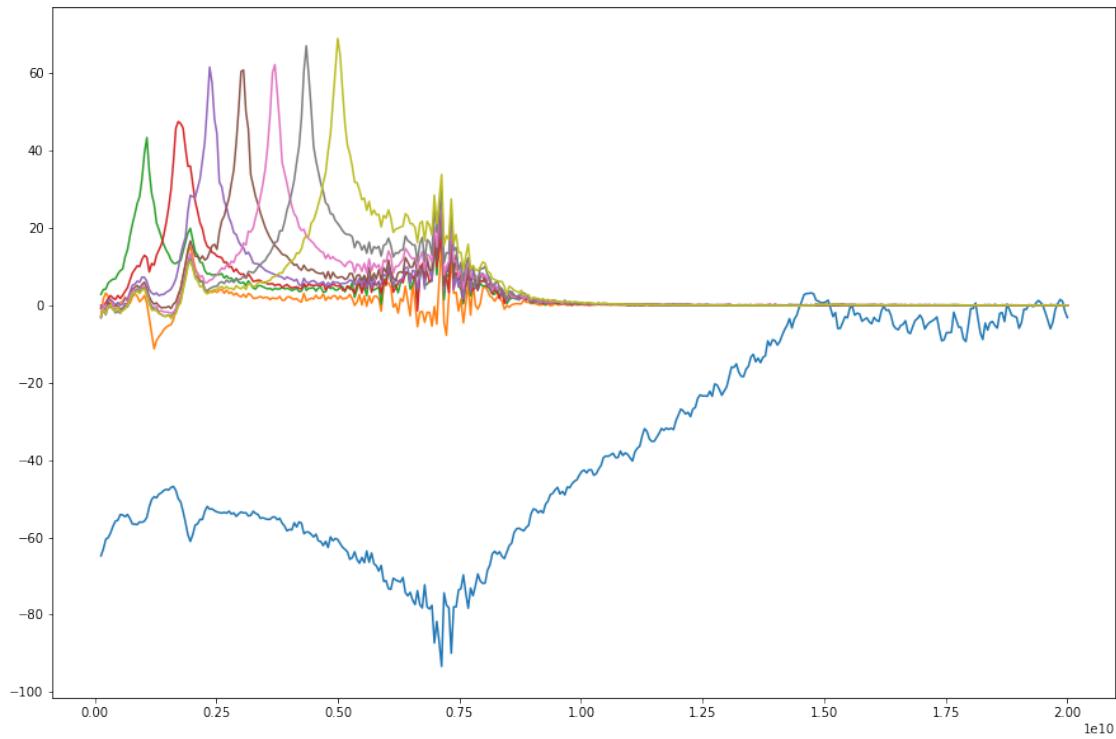
for fmi, fma in fRanges:
    print("%f to %f [GHz]"%(fmi/1e9, fma/1e9))

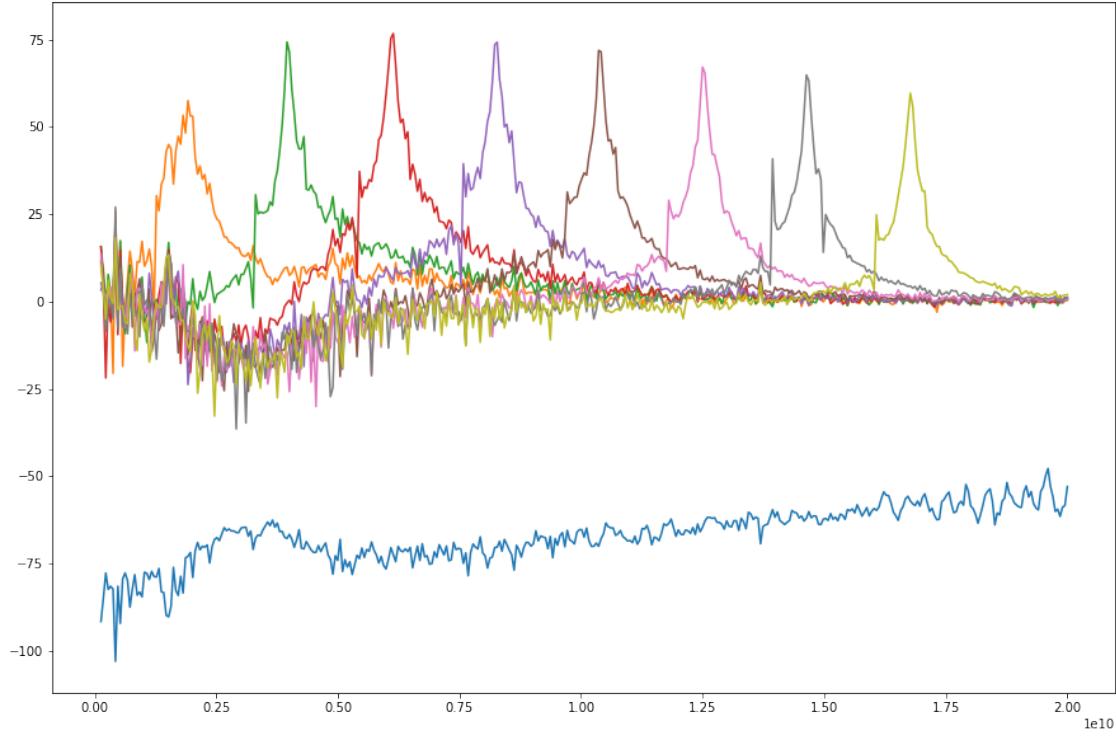
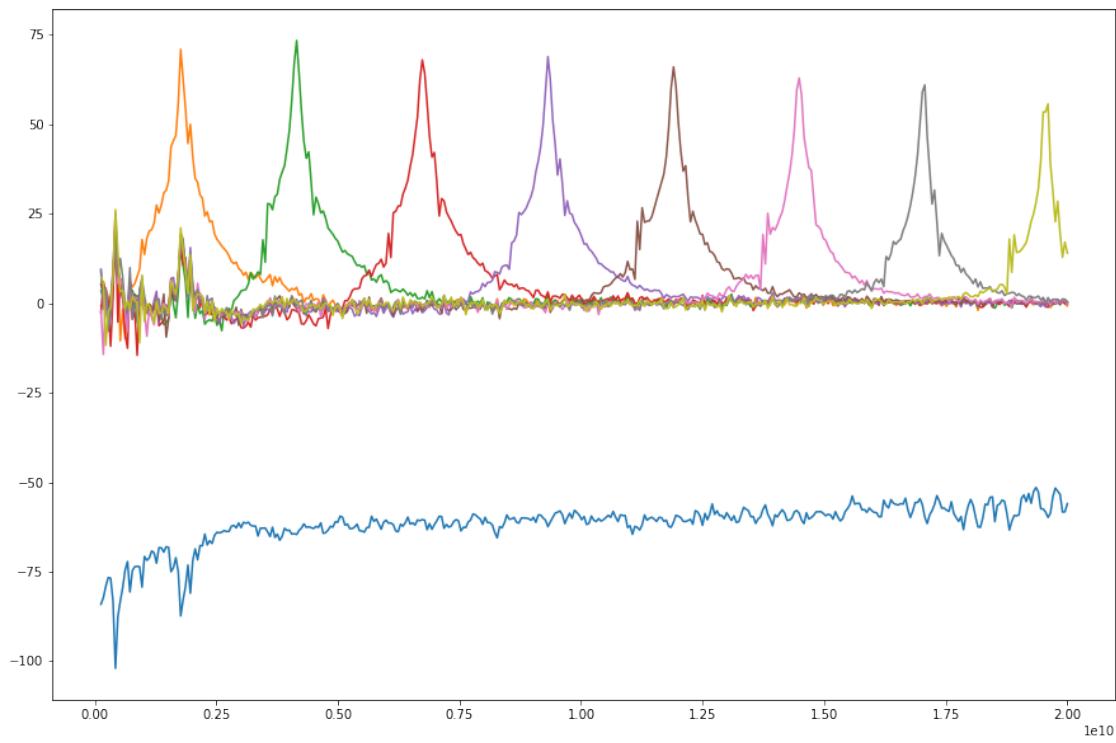
import scipy.io as sio
saveData('yig_filter_driver_coarse_frequency', {'fRanges':fRanges})

```

0.378375 to 1.471225 [GHz]
0.477725 to 4.302700 [GHz]
1.073825 to 7.134175 [GHz]
0.825450 to 8.177350 [GHz]
1.769275 to 19.602600 [GHz]
1.918300 to 16.771125 [GHz]







<Figure size 1080x720 with 0 Axes>

```
[9]: #Get calibration data
import os.path

if not os.path.exists('cal_through.s2p'):
    calPar=vna.getHighResolutionNetwork(130e6, 20e9, 1e6)
    calPar.plot_s_db()
    calPar.write_touchstone('cal_through.s2p')
```

```
[10]: import skrf.network

calPar=skrf.network.Network('cal_through.s2p')
d=loadData('yig_filter_driver_current_data')
zeros=d['zeros'][0]
channels=d['channels']
wr=d['wr'][0]

d2=loadData('yig_filter_driver_coarse_frequency')
fRanges=d2['fRanges']
#print(fRanges)
#print(channels)
#print(wr)

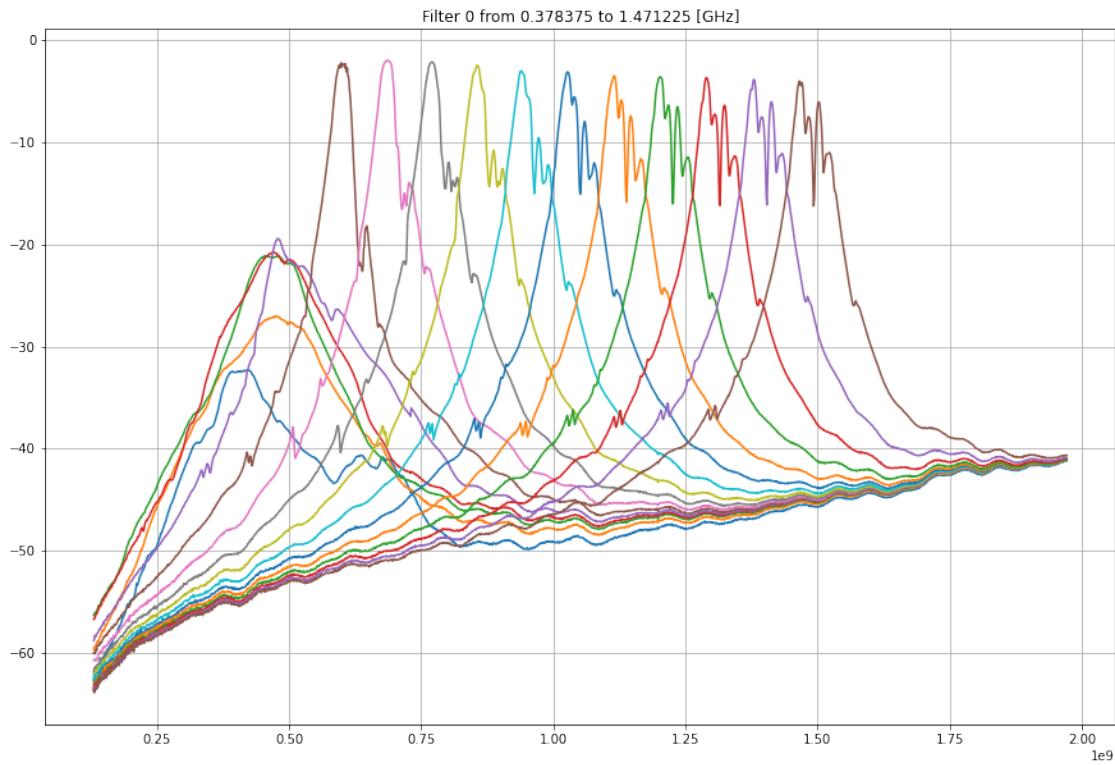
def inter(fd, fa, a):
    afd=np.interp(fd, fa, a)
    return afd

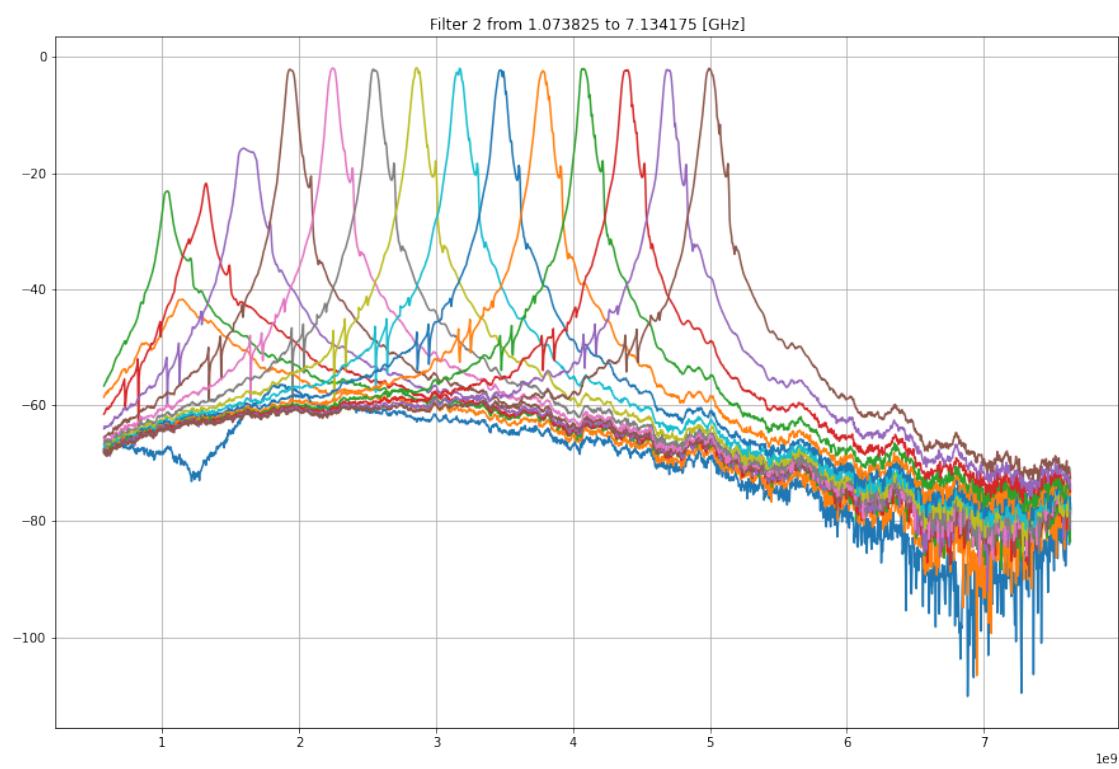
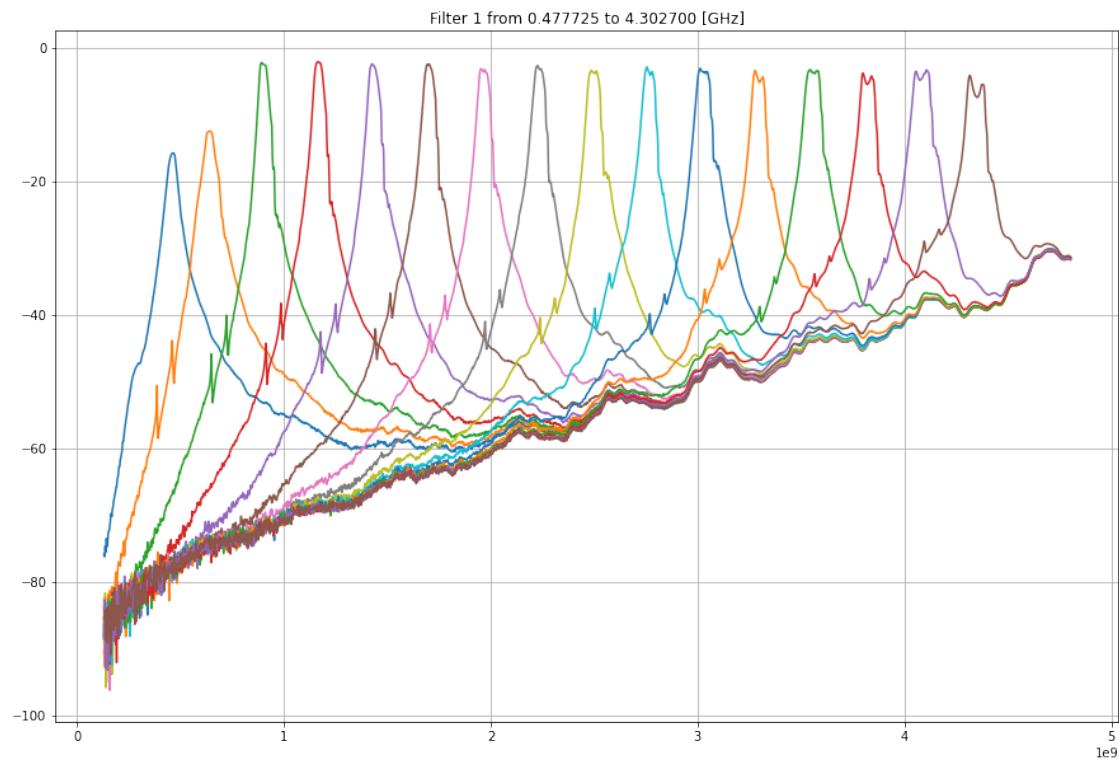
filterMeas={}
for i in range(len(zeros)):
    switch.set(i+1)
    fsta=fRanges[i,0]-500e6
    fsta=np.max((fsta, 130e6))
    fsto=fRanges[i,1]+500e6
    fsto=np.min((fsto, 20e9))
    vna.setStartFrequency(fsta)
    vna.setStopFrequency(fsto)
    vna.setPoints(1601)
    vwr = np.linspace(fParams[i].lw, fParams[i].hw, 16)
    plt.figure()
    plt.title("Filter %d from %f to %f [GHz]"%(i, fRanges[i,0]/1e9,
    ↪fRanges[i,1]/1e9))
    thisFilterMeas={}
    thisFilterMeas['words']=[]
    thisFilterMeas['traces']=[]
    thisFilterMeas['frequencies']=[]
    thisFilterMeas['calData']=[]
```

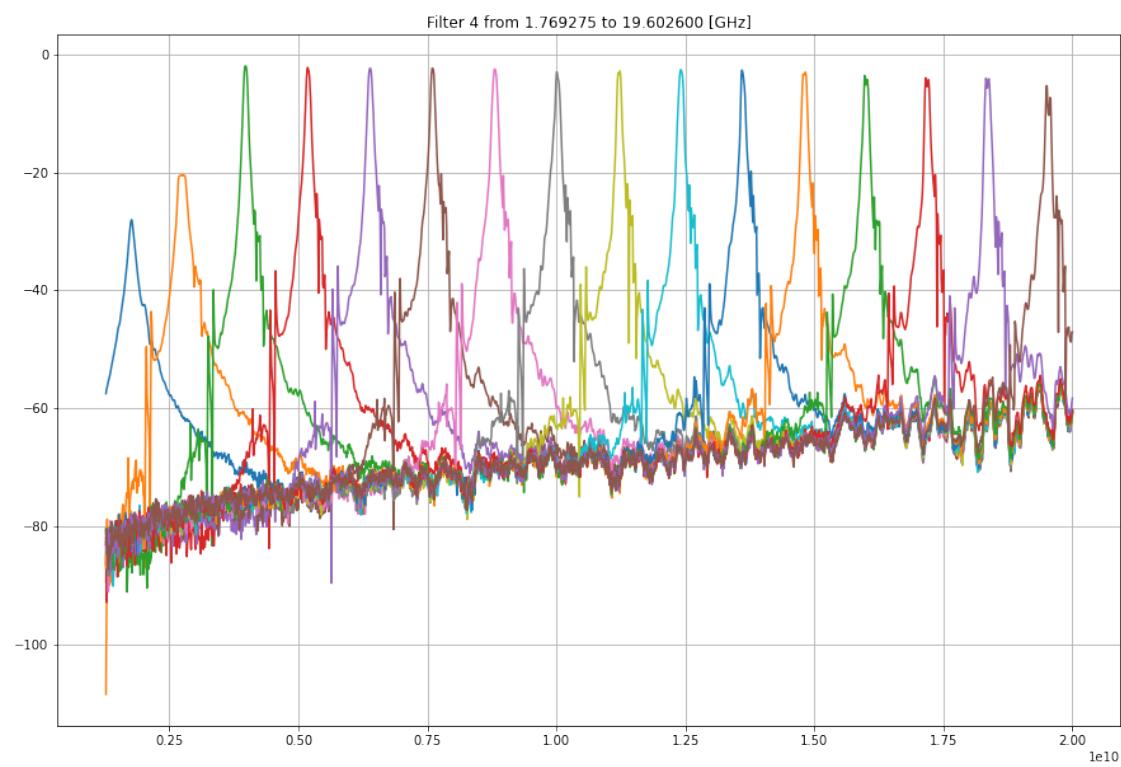
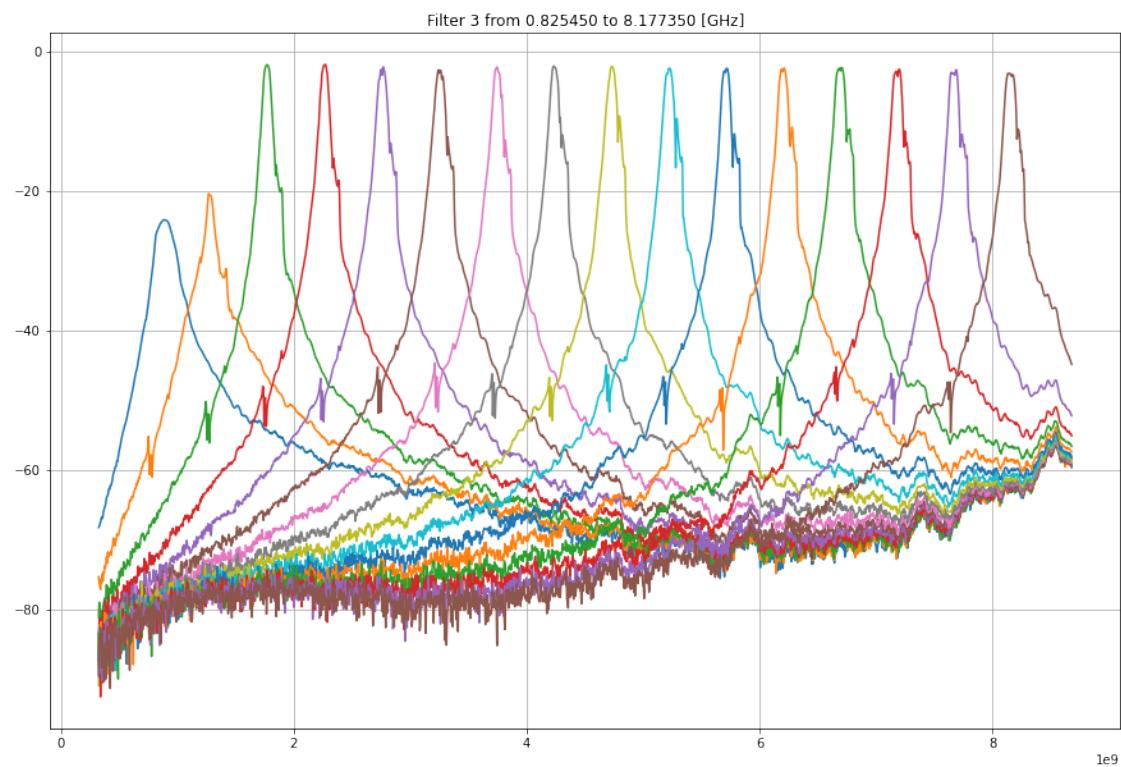
```

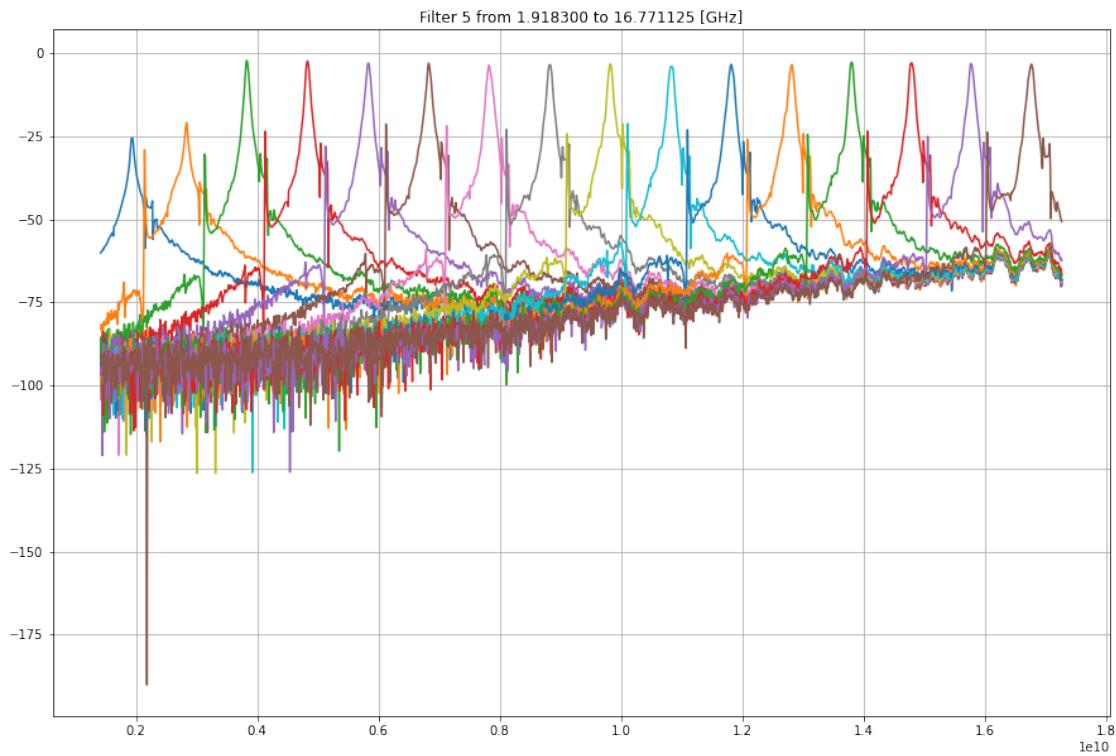
for w in vwr:
    yigDriver.set(i, int(w))
    time.sleep(0.5)
    tr = vna.readSParameter('S21')
    fr = vna.frequencies()
    cai=inter(fr, calPar.f, np.abs(calPar.s[:,1,0]))
    #nf, npar = norm(calPar.f, np.abs(calPar.s[:,0,1]), fr, np.abs(tr))
    #plt.plot(nf, npar)
    plt.plot(fr, 20*np.log10(np.abs(tr)/cai))
    thisFilterMeas['words'].append(w)
    thisFilterMeas['traces'].append(tr)
    thisFilterMeas['frequencies'].append(fr)
    thisFilterMeas['calData'].append(cai)
    #plt.plot(fr, cai)
filterMeas[i] = thisFilterMeas
plt.grid(True)
plt.show()
yigDriver.set(6, 0)

```









```
[11]: kvec=[]
mvec=[]
for i in range(len(zeros)):
    thisFilter=filterMeas[i]
    words = thisFilter['words']
    traces = thisFilter['traces']
    frequencies = thisFilter['frequencies'][0]
    cals = thisFilter['calData']
    fildata=[]
    for trace, w, cal in zip(traces, words, cals):
        tDat = 20*np.log10(np.abs(trace)/np.abs(cal))
        i=np.argmax(tDat)
        if(tDat[i]>-5):
            fildata.append((int(w), frequencies[i]/1e6, tDat[i]))
    j=int(len(fildata)/5.0)
    jj=int(4*len(fildata)/5.0)
    m=int((j+jj)/2)
    dw=fildata[jj][0]-fildata[j][0]
    df=fildata[jj][1]-fildata[j][1]
```

```

filK=df/dw
ms=[]
for m in range(len(fildat)):
    filM=fildat[m][1]-fildat[m][0]*filK
    ms.append(filM)
filM=np.mean(ms)
print("Filter parameter for filter %d is k %.3f [MHz/LSB] m is %.
      .3f[LSB]"%(i, filK, filM))
kvec.append(filK)
mvec.append(filM)

coarseFilter={'k':kvec, 'm':mvec}
saveData('coarse_filter_parameters', coarseFilter)

```

Filter parameter for filter 1161 is k 0.024 [MHz/LSB] m is 696.557[LSB]
 Filter parameter for filter 1434 is k 0.072 [MHz/LSB] m is 2001.056[LSB]
 Filter parameter for filter 1002 is k 0.085 [MHz/LSB] m is 2278.379[LSB]
 Filter parameter for filter 1496 is k 0.166 [MHz/LSB] m is 4524.629[LSB]
 Filter parameter for filter 1557 is k 0.329 [MHz/LSB] m is 8980.192[LSB]
 Filter parameter for filter 1550 is k 0.391 [MHz/LSB] m is 10632.053[LSB]

0.4 Measure drift

```
[12]: import time
coarseFilter=loadData('coarse_filter_parameters')
mvec=coarseFilter['m'][0]
kvec=coarseFilter['k'][0]

def computeWord(fTarget, k, m):
    return (fTarget/1e6-m)/k

s21Drift=None
currentDrift=None

dataDict={}

def measureDrifts():
    for a in range(10):
        curMeter.readValue()
    t0=time.time()
    t00=t0
    fmax=[]
    curr=[]
    phase=[]
    sFreq = None
```

```

sMat = None
timeVec = []
for j in range(10):

    t0=t00+10*j
    while time.time() < t0:
        pass
    f=vna.frequencies()
    curr.append(curMeter.readValue())
    t=vna.readSParameter('S21')
    fmax.append(f[np.argmax(np.abs(t))])
    phase.append(np.angle(t[int(len(t)/2)]))
    sFreq = f;
    sMat = yig_controller_test.stackVector(sMat, t)
    timeVec.append(t0)
return timeVec, f, curr, phase, sMat, fmax

for i in range(6):
    print("Measuring filter", i)
    k = kvec[i]
    m = mvec[i]
    switch.set(i+1)
    keyBase = 'yigFilter%d'%(i)
    for tf, keySub in zip([fMin[i], fMax[i], fMin[i]], ['Low', 'High', ↴'LowAgain']):
        yigDriver.set(i, int(computeWord(tf, k, m)))
        vna.setStartFrequency(tf-100e6)
        vna.setStopFrequency(tf+100e6)
        timeVec, f, curr, phase, sMat, fmax = measureDrifts()
        dataDict[keyBase+keySub+'Current']=curr
        dataDict[keyBase+keySub+'Time']=timeVec
        dataDict[keyBase+keySub+'Frequency']=f
        dataDict[keyBase+keySub+'Phase']=phase
        dataDict[keyBase+keySub+'SMatrix']=sMat
        dataDict[keyBase+keySub+'MinimumLossFrequency']=fmax

saveData('filter_drift', dataDict)

```

```

Measuring filter 0
Measuring filter 1
Measuring filter 2
Measuring filter 3
Measuring filter 4
Measuring filter 5

```

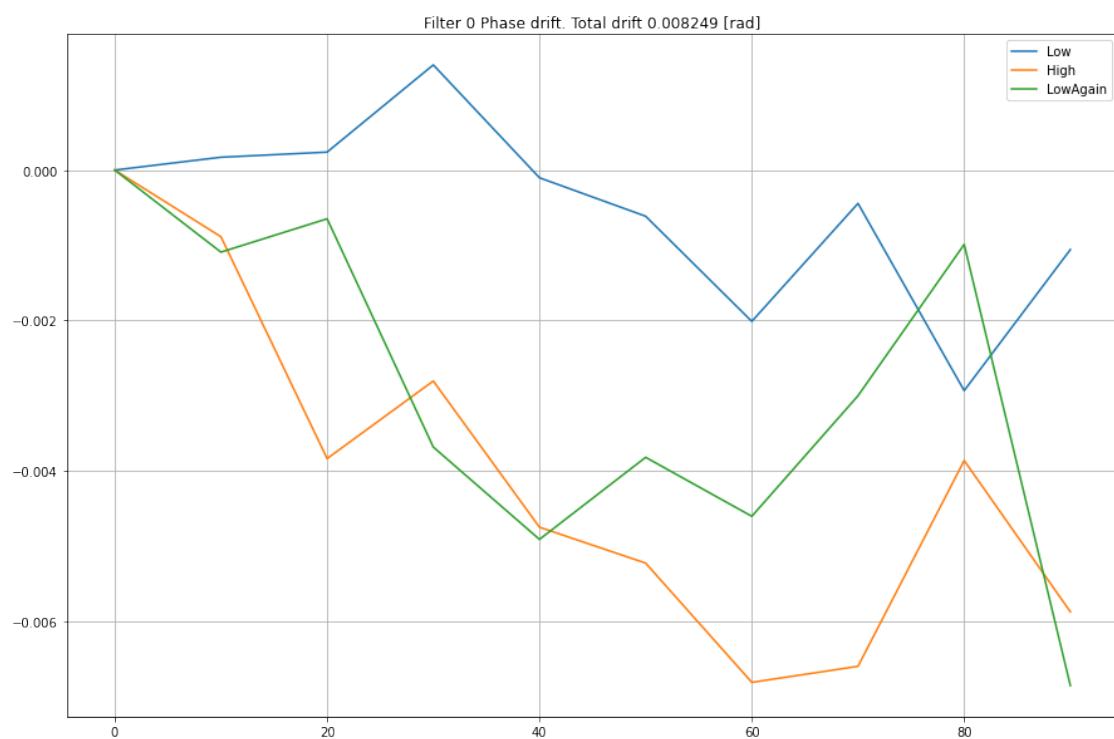
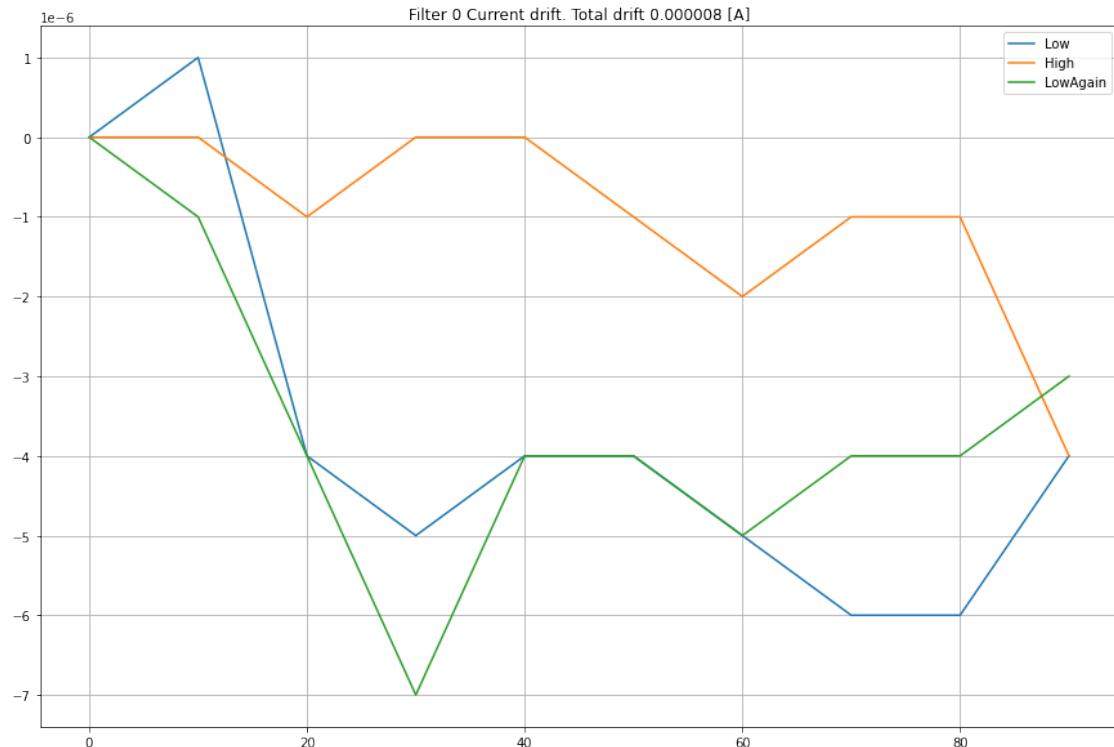
```
[13]: dd = loadData('filter_drift')

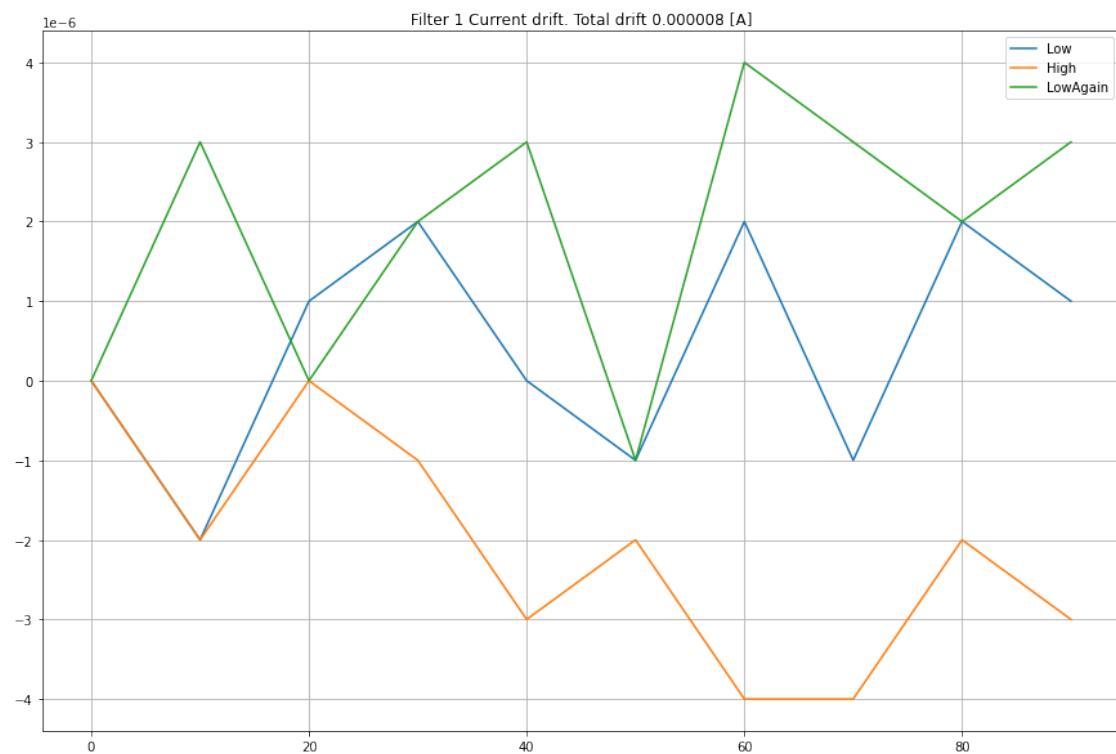
def plotParameter(i, par, unit):
    keyBase = 'yigFilter%d'%(i)
    plt.figure()

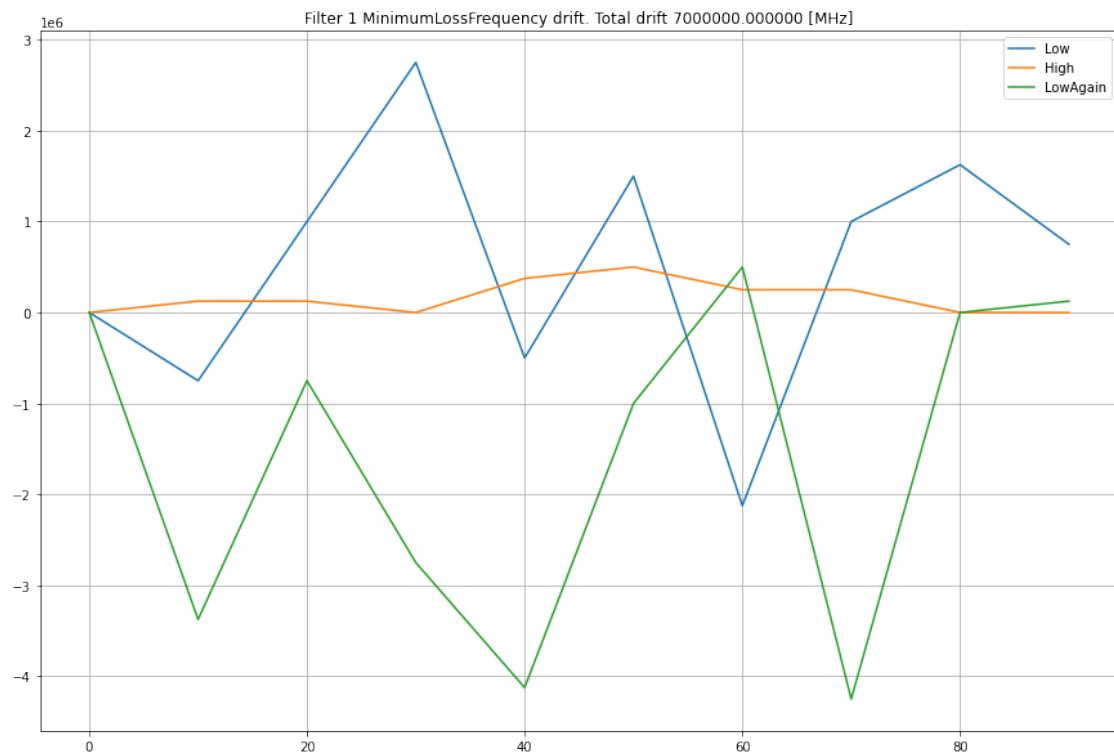
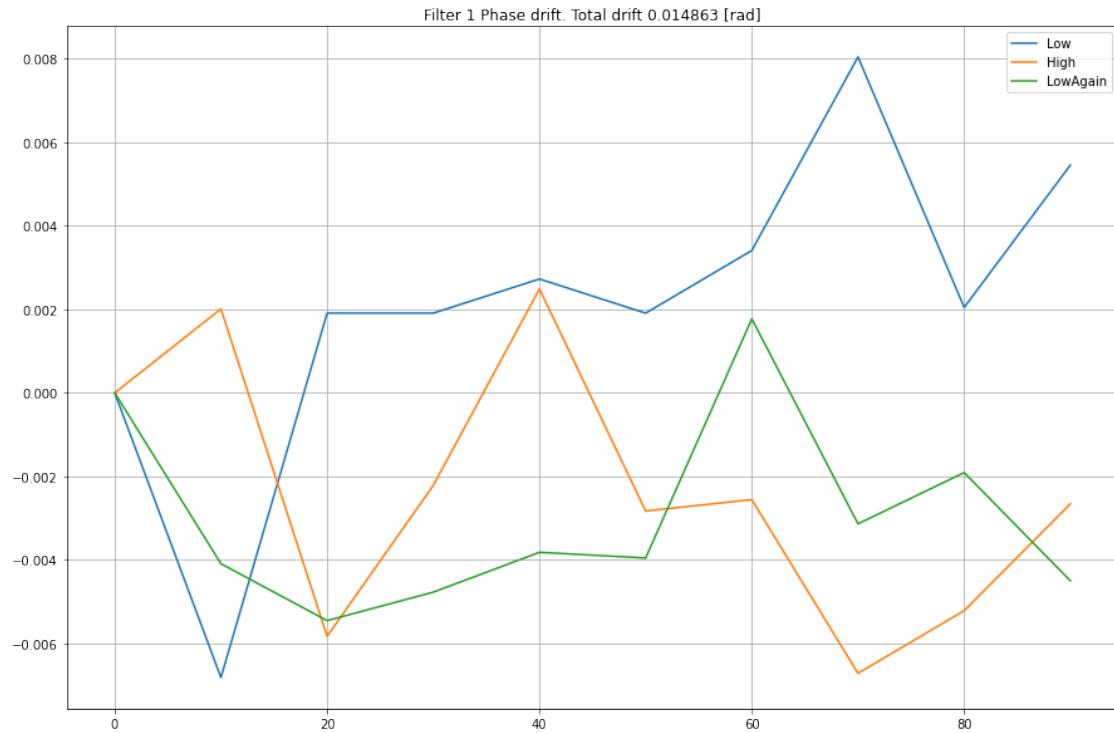
    minVal=None
    maxVal=None
    for keySub in ['Low', 'High', 'LowAgain']:
        data=dd[keyBase+keySub+par][0]
        timeData=dd[keyBase+keySub+'Time'][0]
        timeData=timeData-timeData[0]
        data=data-data[0]
        plt.plot(timeData, data, label=keySub)
        if minVal is None:
            minVal=min(data)
        else:
            minVal = min(minVal, min(data))
        if maxVal is None:
            maxVal=max(data)
        else:
            maxVal=max(maxVal, max(data))

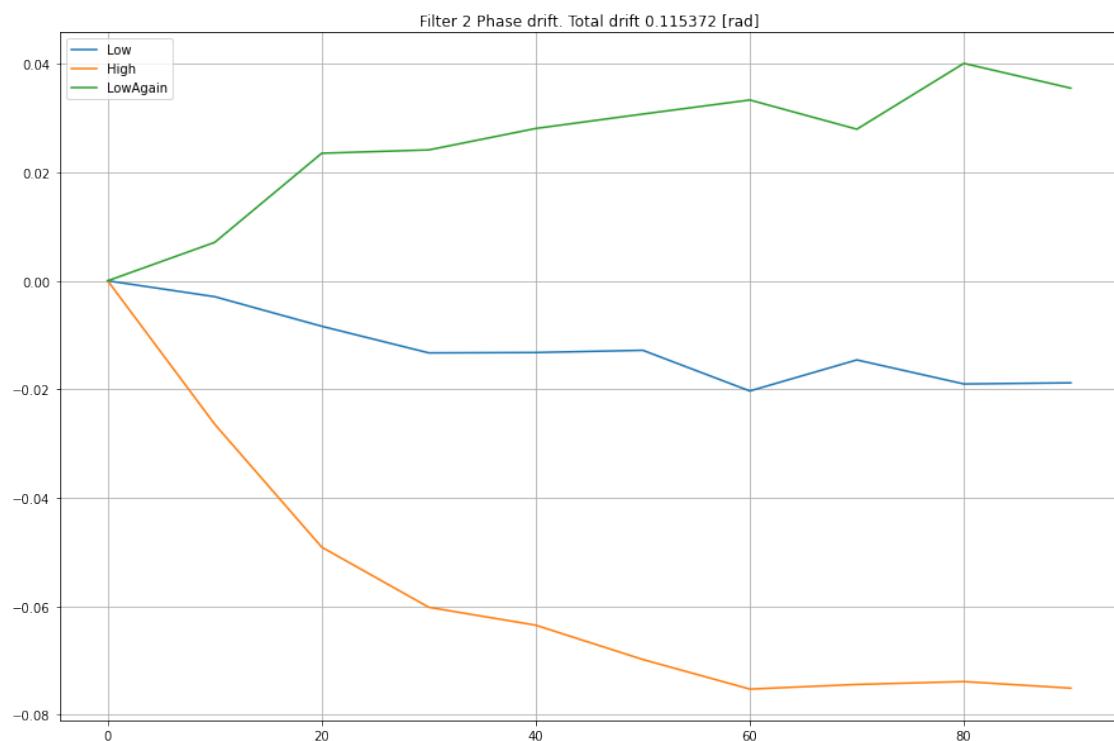
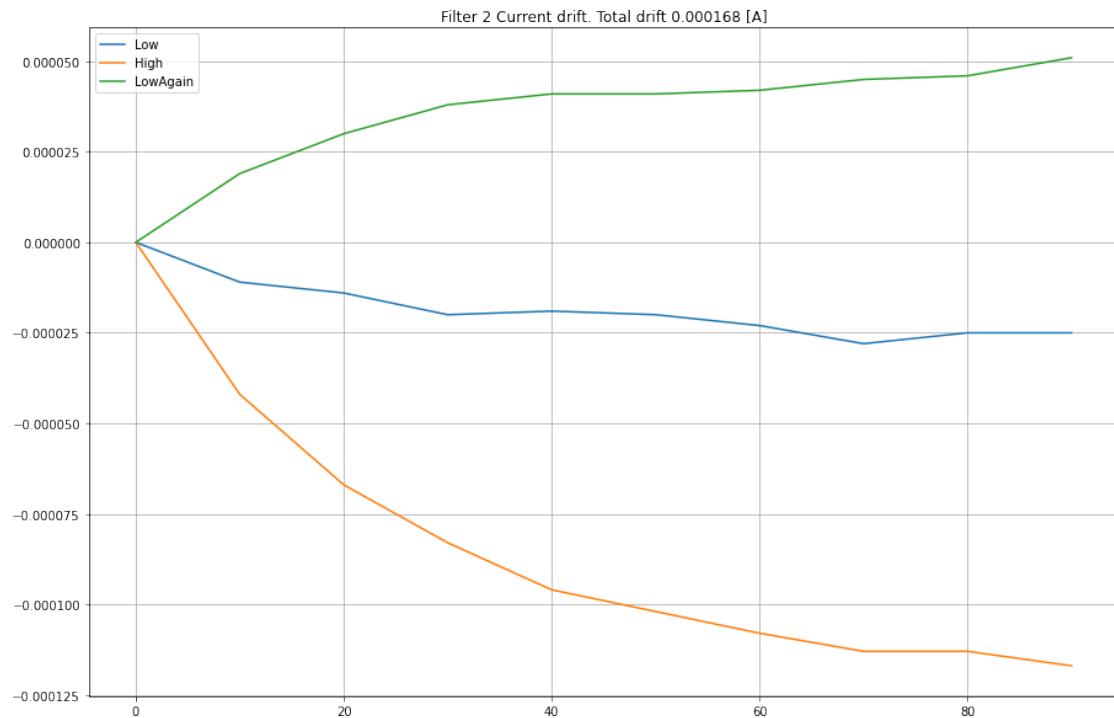
    plt.title("Filter %d %s drift. Total drift %f [%s]"%(i, par, maxVal-minVal, unit))
    plt.grid(True)
    plt.legend()
    plt.show()

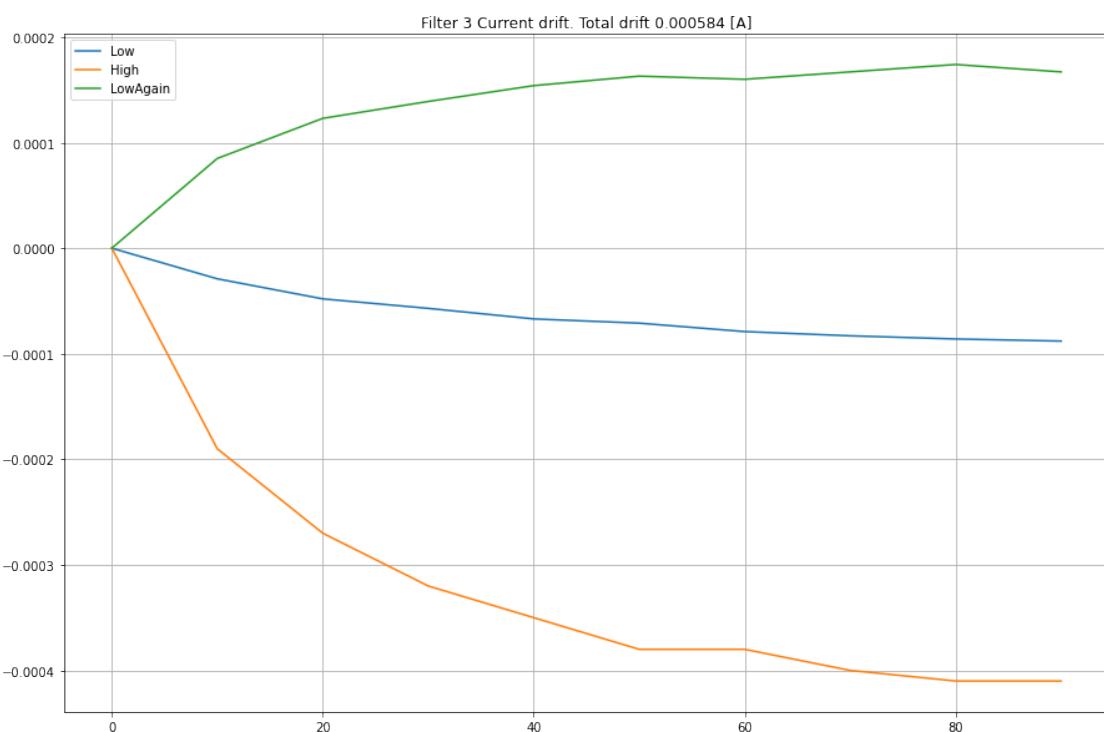
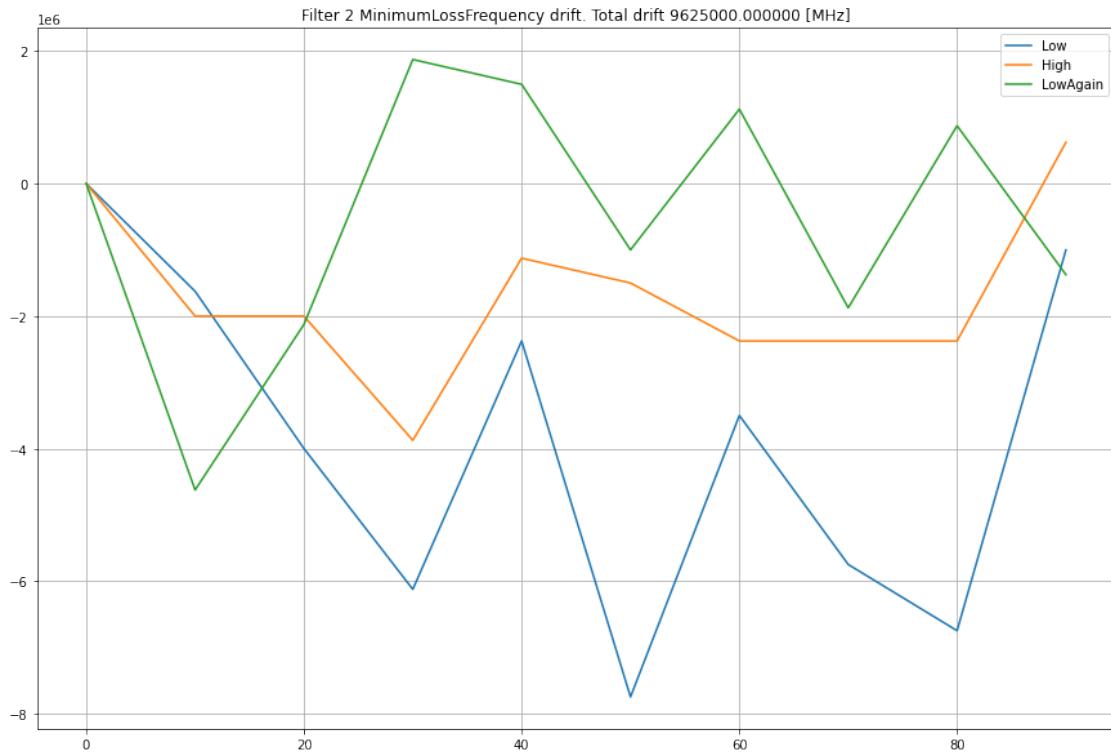
for i in range(6):
    plotParameter(i, 'Current', 'A')
    plotParameter(i, 'Phase', 'rad')
    plotParameter(i, 'MinimumLossFrequency', 'MHz')
```

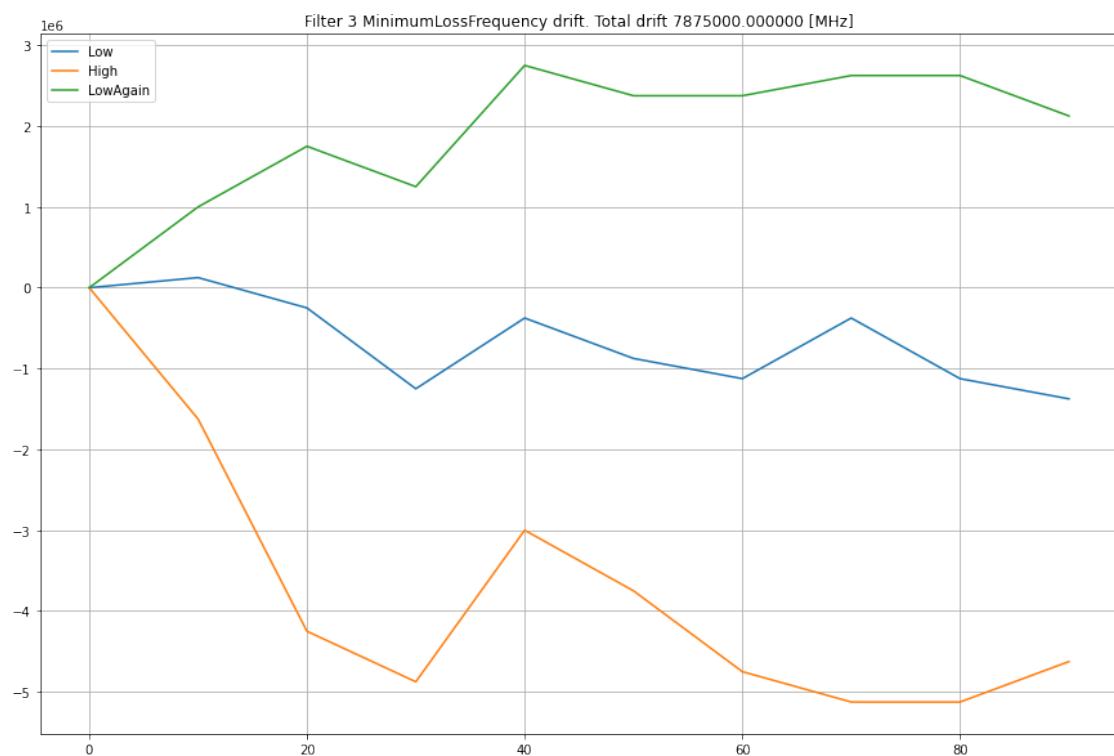
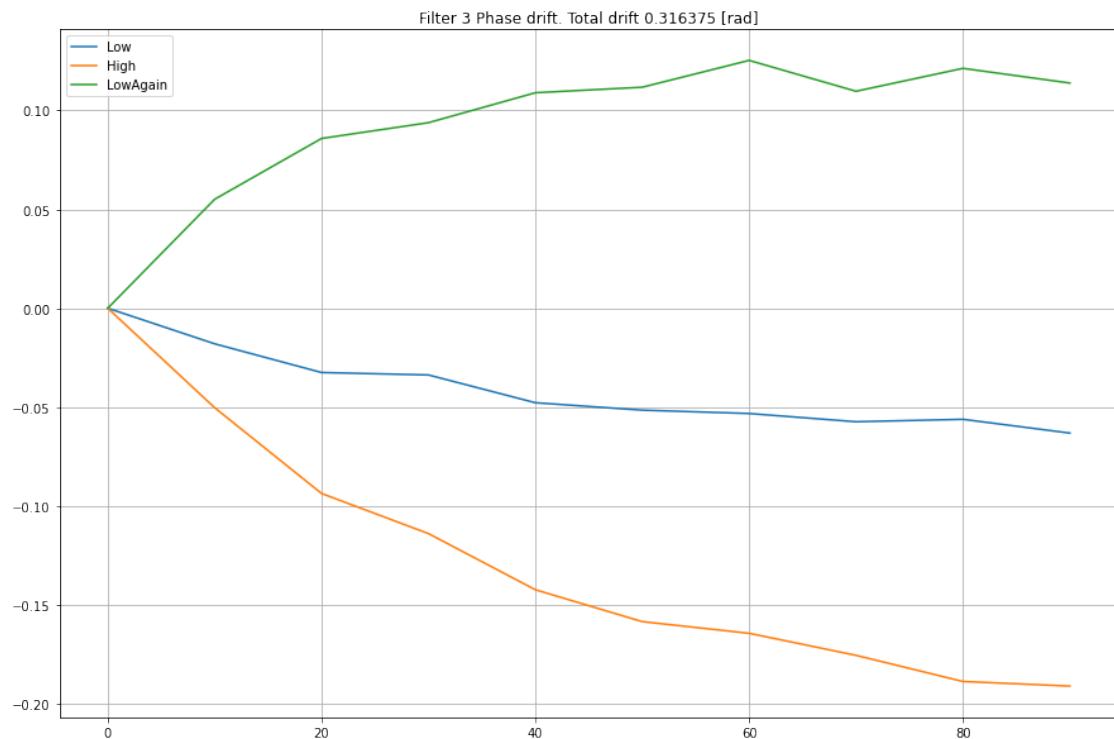


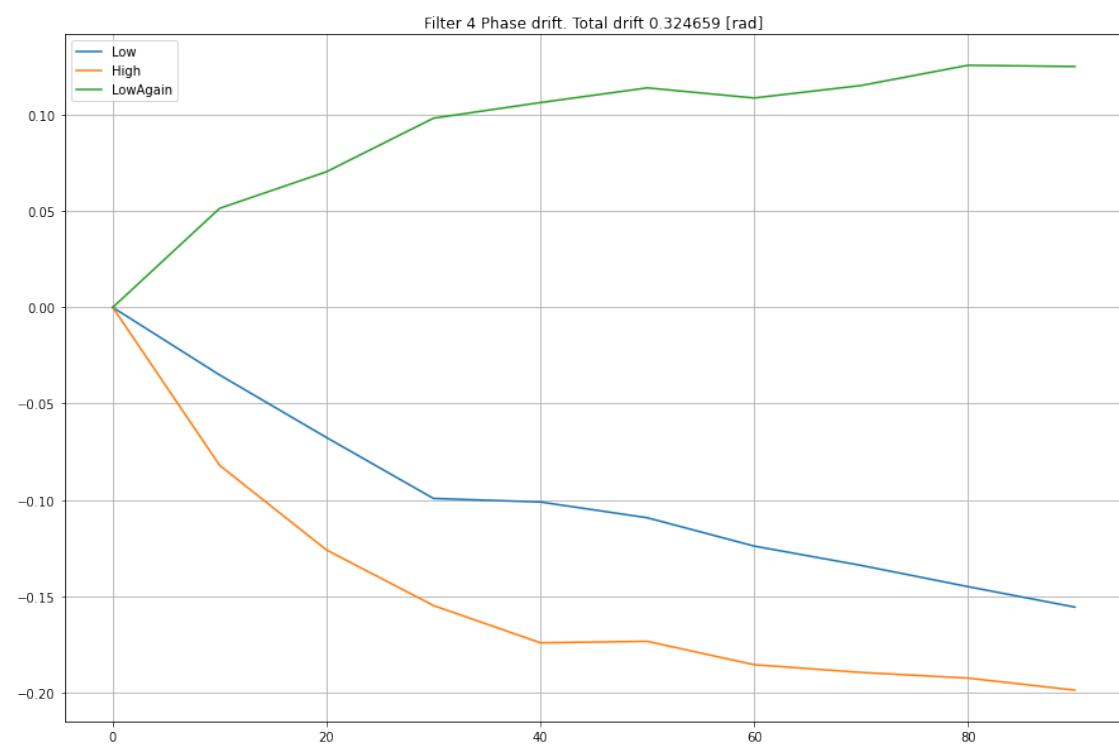
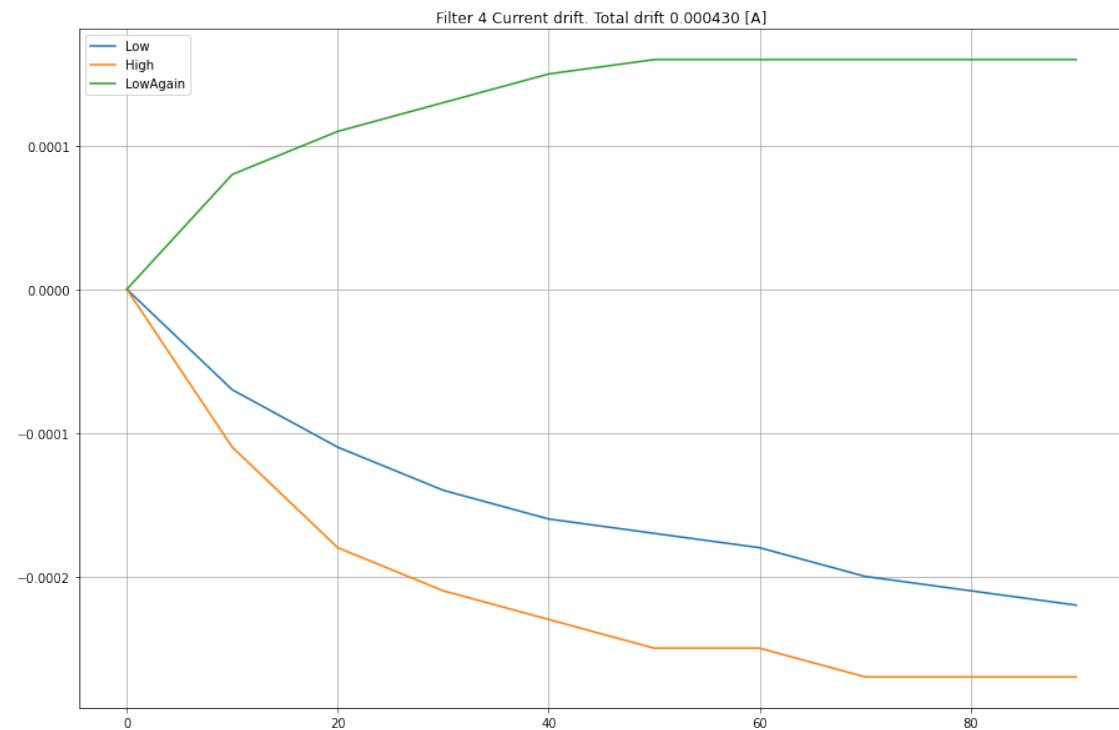


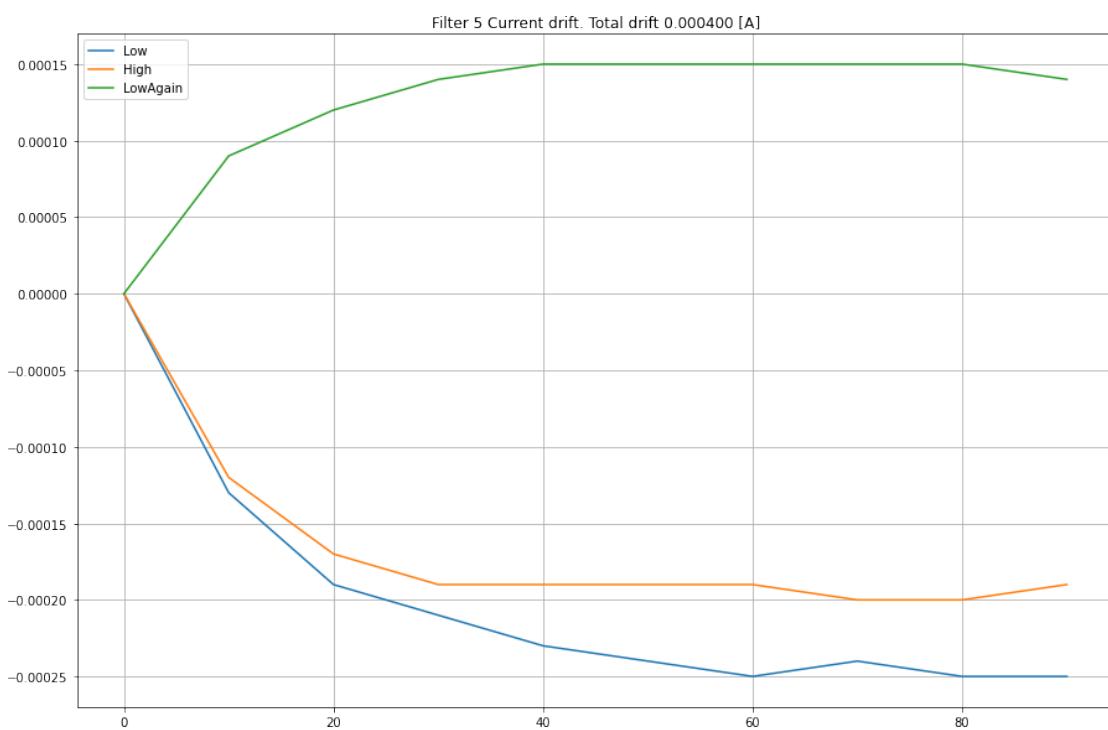
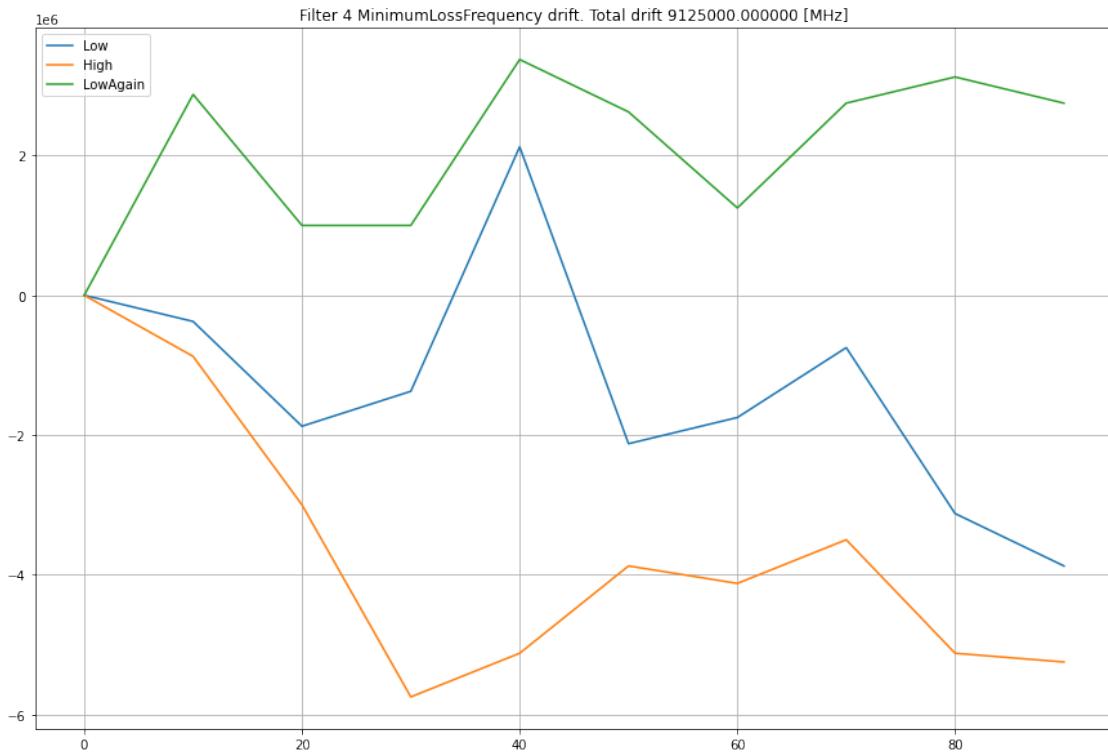


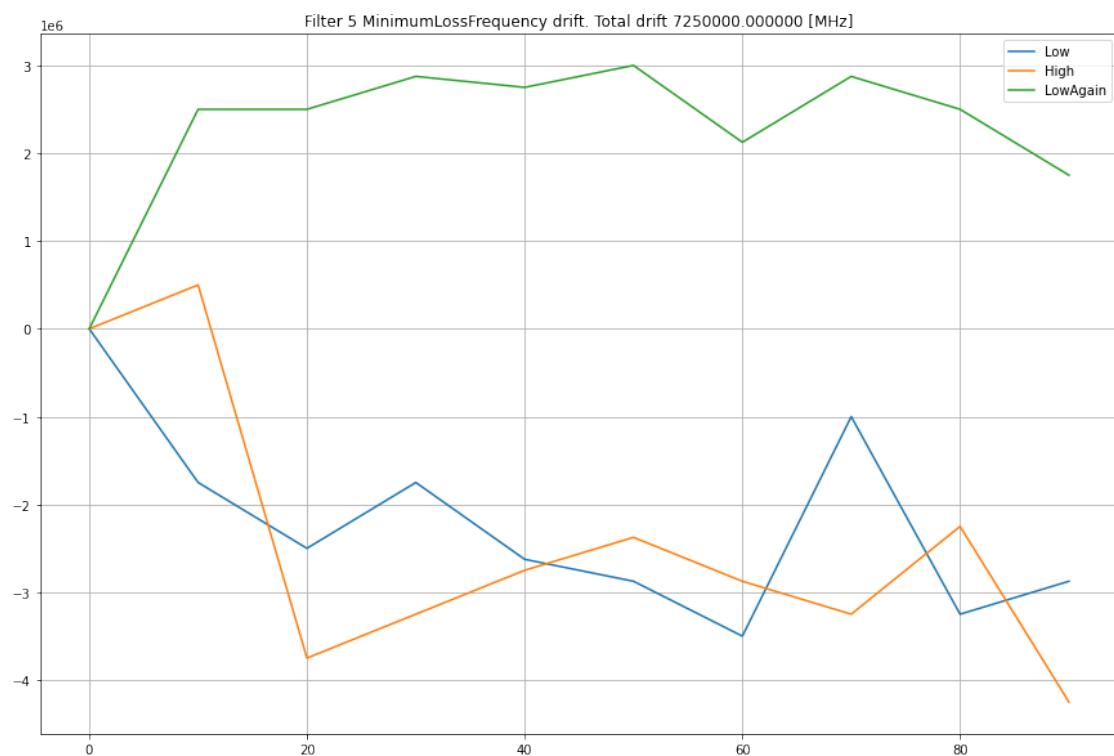
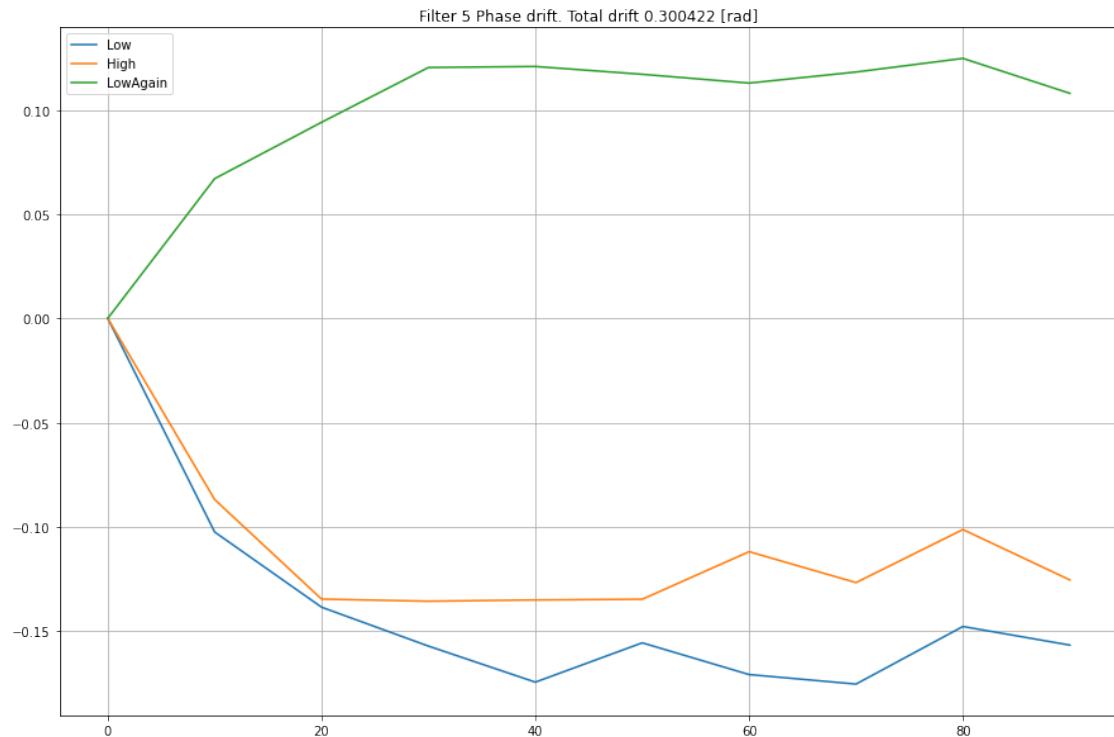












0.5 Fine tuning of filter tuning parameters

```
[14]: a = loadData('coarse_filter_parameters')
import yig_controller_test
import yig_filter_model

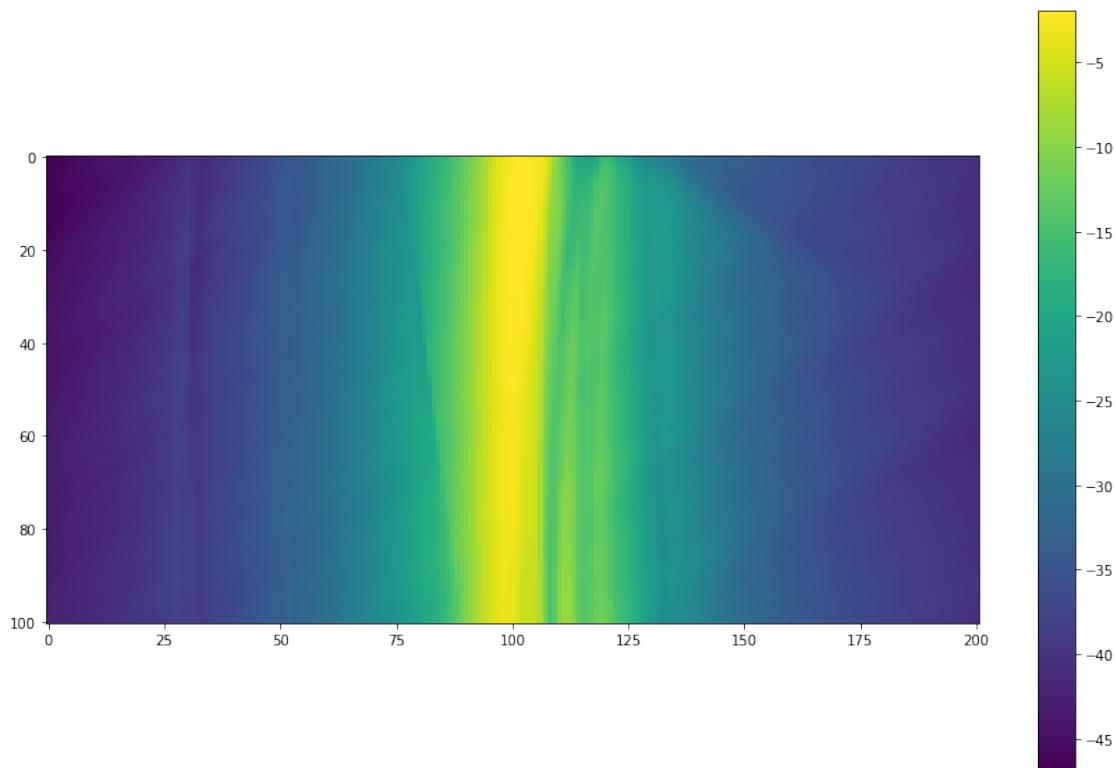
ks = a['k'][0]
ms = a['m'][0]
filterBank = []
for i in range(len(ks)):
    filterBank.append(yig_controller_test.YigFilter(fMin[i], fMax[i], ms[i]*1e6, ks[i]*1e6, yc, i))

calMeas = skrf.network.Network('cal_through.s2p')

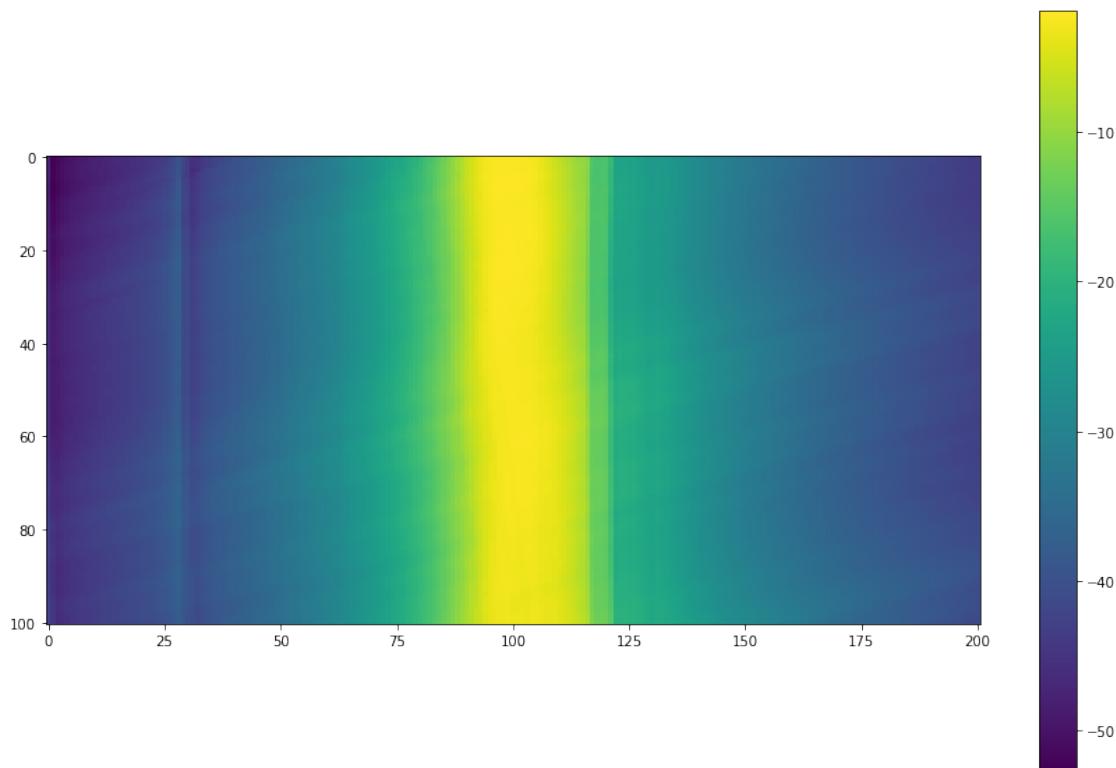
fix = yig_filter_model.SimpleS21Fixture(calMeas.f, calMeas.s[:, 1, 0])

def measureYigFilter(f):
    frequencies = np.linspace(f.flow, f.fhigh, 101)
    vna.setPoints(201)
    filterMap=None
    spanMap=None
    tuningWords=[]
    for fr in frequencies:
        f.tuneTo(fr)
        tuningWords.append(f.computeTuningWord(fr))
        vna.setStartFrequency(fr-250e6)
        vna.setStopFrequency(fr+250e6)
        spar=vna.readSParameter('S21')
        fax = vna.frequencies()
        spanMap = yig_controller_test.stackVector(spanMap, fax)
        dePar=fix.deembedFrom(fax, spar)
        filterMap=yig_controller_test.stackVector(filterMap, dePar)
    plt.figure()
    plt.imshow(20*np.log10(np.abs(filterMap)))
    plt.colorbar()
    plt.show()
    return filterMap, tuningWords, frequencies, spanMap
```

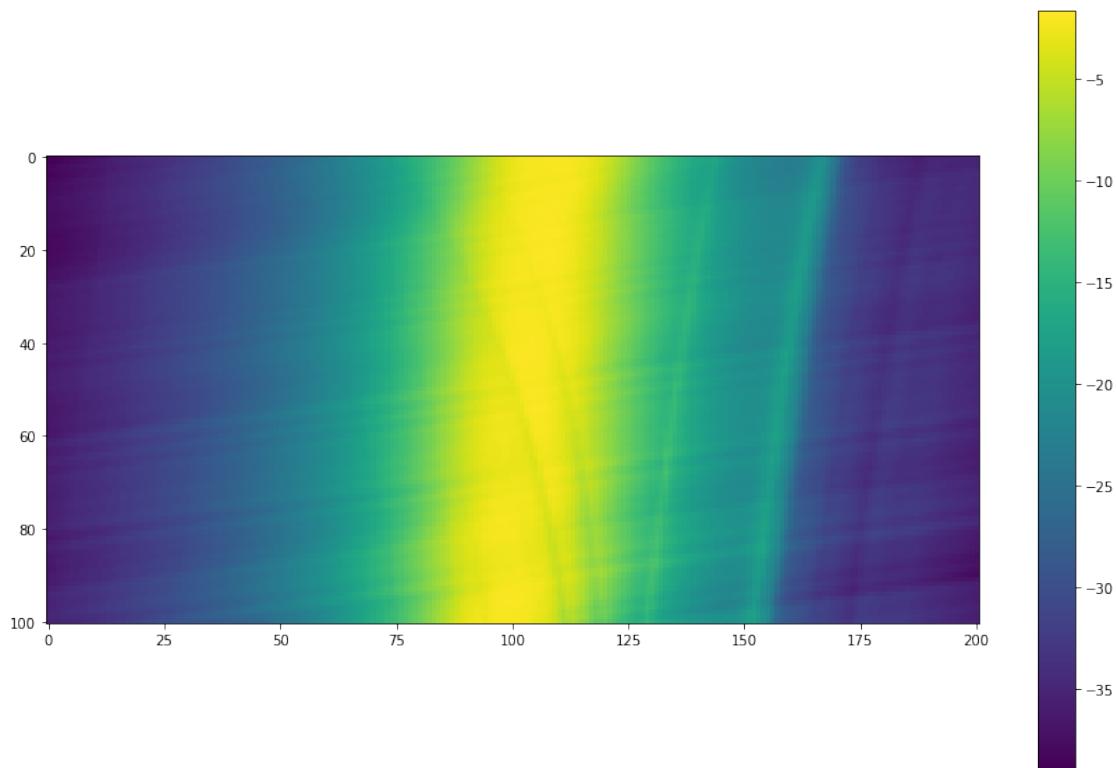
```
[17]: filter0Map, filter0TuningWords, filter0Frequencies, filter0SpanMap =
    measureYigFilter(filterBank[0])
```



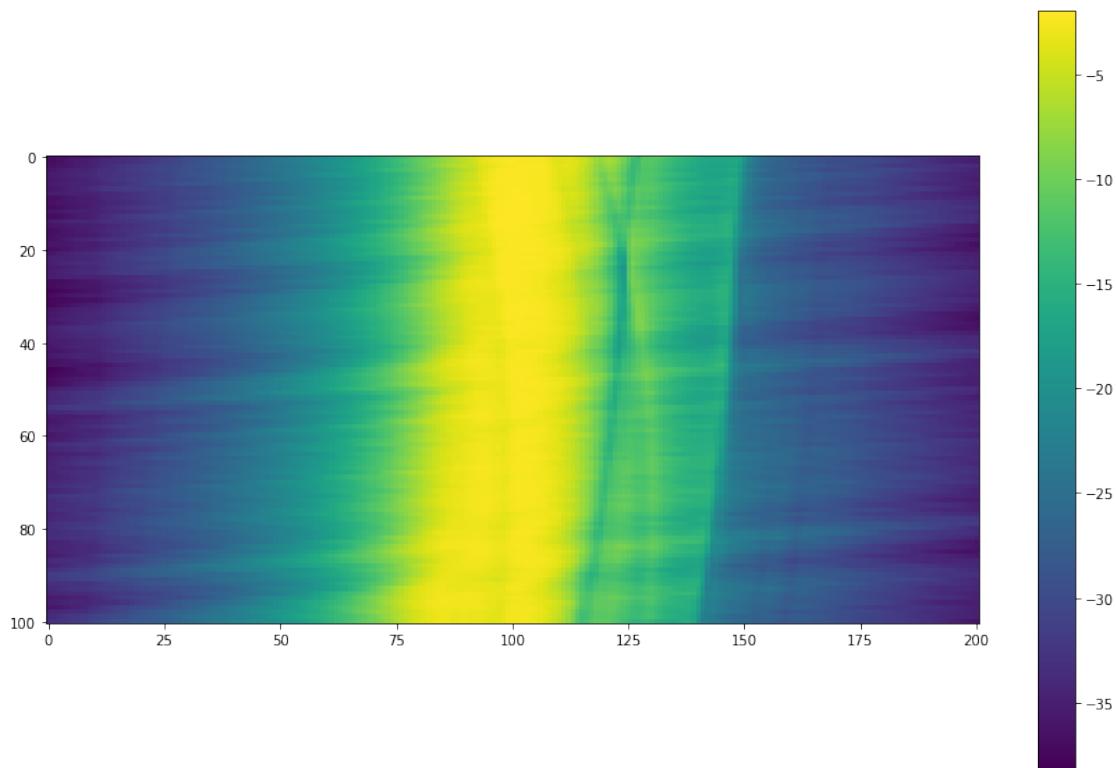
```
[18]: filter1Map, filter1TuningWords, filter1Frequencies, filter1SpanMap =  
      ↪measureYigFilter(filterBank[1])
```



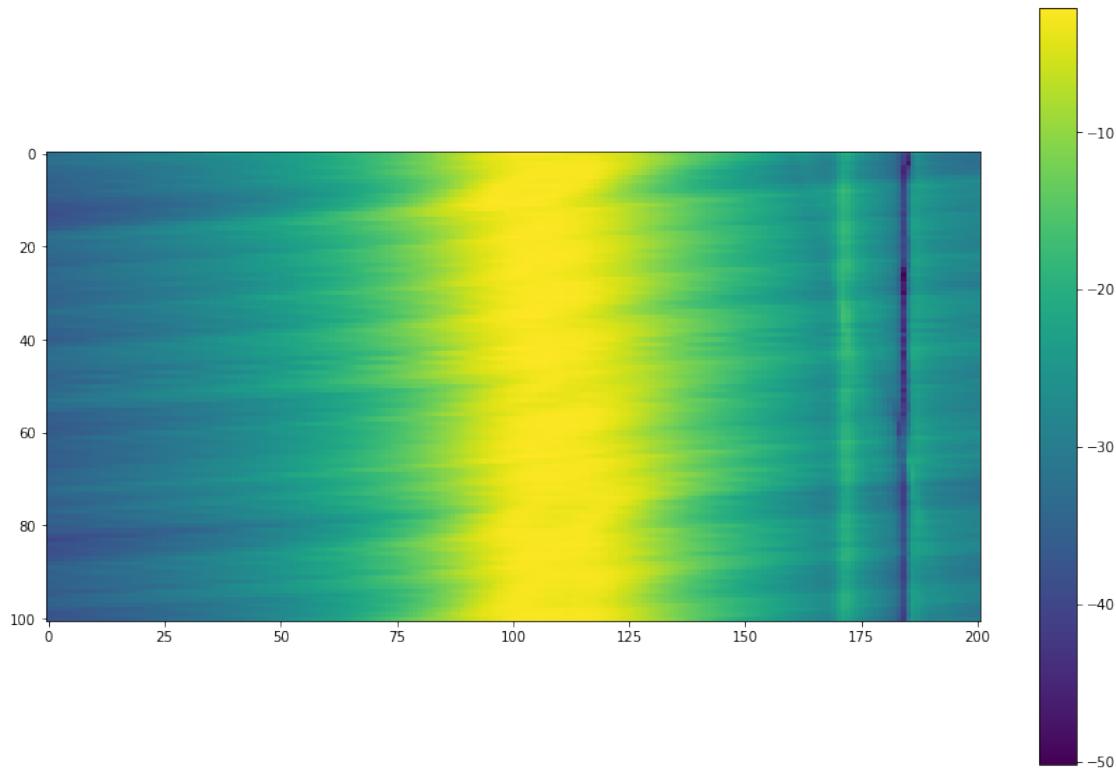
```
[20]: filter2Map, filter2TuningWords, filter2Frequencies, filter2SpanMap =  
      ↵measureYigFilter(filterBank[2])
```



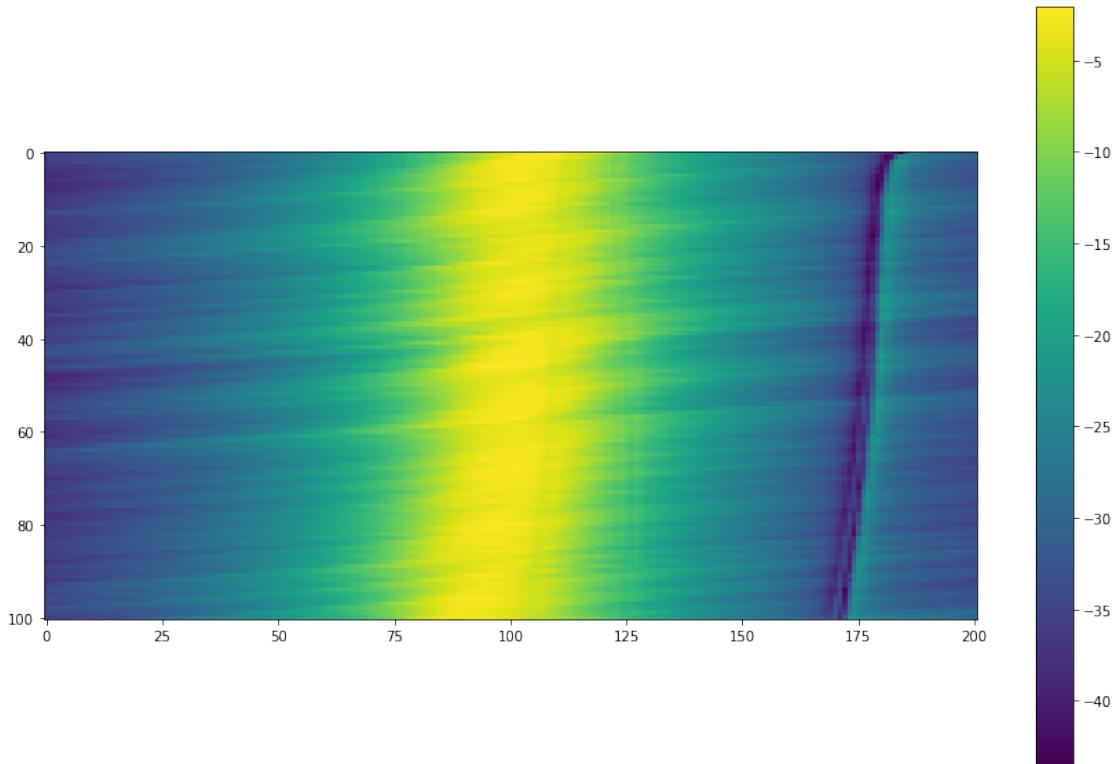
```
[21]: filter3Map, filter3TuningWords, filter3Frequencies, filter3SpanMap =  
      ↵measureYigFilter(filterBank[3])
```



```
[24]: filter4Map, filter4TuningWords, filter4Frequencies, filter4SpanMap =  
      ↵measureYigFilter(filterBank[4])
```



```
[25]: filter5Map, filter5TuningWords, filter5Frequencies, filter5SpanMap =  
    ↪measureYigFilter(filterBank[5])
```



```
[26]: saveDict={'filter0Map':filter0Map, 'filter0TuningWords':filter0TuningWords, □
    ↵'filter0Frequencies':filter0Frequencies, 'filter0SpanMap':filter0SpanMap,
    'filter1Map':filter1Map, 'filter1TuningWords':filter1TuningWords, □
    ↵'filter1Frequencies':filter1Frequencies, 'filter1SpanMap':filter1SpanMap,
    'filter2Map':filter2Map, 'filter2TuningWords':filter2TuningWords, □
    ↵'filter2Frequencies':filter2Frequencies, 'filter2SpanMap':filter2SpanMap,
    'filter3Map':filter3Map, 'filter3TuningWords':filter3TuningWords, □
    ↵'filter3Frequencies':filter3Frequencies, 'filter3SpanMap':filter3SpanMap,
    'filter4Map':filter4Map, 'filter4TuningWords':filter4TuningWords, □
    ↵'filter4Frequencies':filter4Frequencies, 'filter4SpanMap':filter4SpanMap,
    'filter5Map':filter5Map, 'filter5TuningWords':filter5TuningWords, □
    ↵'filter5Frequencies':filter5Frequencies, 'filter5SpanMap':filter5SpanMap, }
saveData('coarse_tuning_fine_measurements', saveDict)
```

```
[27]: ftm = loadData('coarse_tuning_fine_measurements')

def dB(data):
    return 20*np.log10(np.abs(data))

def fineTuneAnalysis(meas, i):
    baseKey='filter%d'%(i)
    filterMap = meas[baseKey+'Map']
```

```

tuningWords = meas[baseKey+'TuningWords'][0]
frequencies = meas[baseKey+'Frequencies'][0]
spanMap = meas[baseKey+'SpanMap']
dBfilt=dB(filterMap)
peaksIdx=np.argmax(dB(filterMap),axis=1)
peaksVal=np.max(dB(filterMap),axis=1)

x = np.arange(peaksIdx.shape[0])
bestLineCoeff=np.polyfit(x, peaksIdx-100, deg=1)
k, m =bestLineCoeff

span=spanMap[0]
deltaF=(max(span)-min(span))/float(len(span)-1)
deltaW =(max(tuningWords)-min(tuningWords))/float(len(tuningWords)-1)

kcorr=k*(deltaF/1e6)*(1/deltaW)
mcorr=m*deltaF/1e6
lineFunc=np.poly1d(bestLineCoeff)

filterNorm = (dBfilt.T-peaksVal).T;
plt.figure();
plt.title("Filter %d"%(i))

plt.imshow(filterNorm)

yr = np.array(range(filterMap.shape[0]))

plt.plot(peaksIdx, yr)
peaksIdxFilter=np.convolve(peaksIdx, np.ones((10,))/10, mode='same')

plt.plot(peaksIdxFilter, yr)
plt.plot(lineFunc(x)+100,x)
plt.contour(filterNorm, [-10, -6, -3])
plt.figure()
plt.title("Filter %d"%(i))
plt.plot(np.arange(10,91), peaksIdxFilter[10:-10]-100)
plt.plot(peaksIdx-100)
plt.grid(True)

plt.plot(x, lineFunc(x))
return kcorr, mcorr
# plt.contourf(db(filterMap), []

```

```

coarseData = loadData('coarse_filter_parameters')

kcoarse = coarseData['k'][0]
mcoarse = coarseData['m'][0]
kfine = kcoarse
mfine = mcoarse

for i in range(6):
    k, m = fineTuneAnalysis(ftm, i)
    print("filter", i, "Coarse k", kcoarse[i], "[MHZ/lsb]", "coarse m", mcoarse[i], "[MHz]")
    kfine[i] = kcoarse[i] + k
    mfine[i] = mcoarse[i] + m
    print("filter", i, "fine k", kfine[i], "[MHZ/lsb]", "cfine m", mfine[i], "[MHz]")

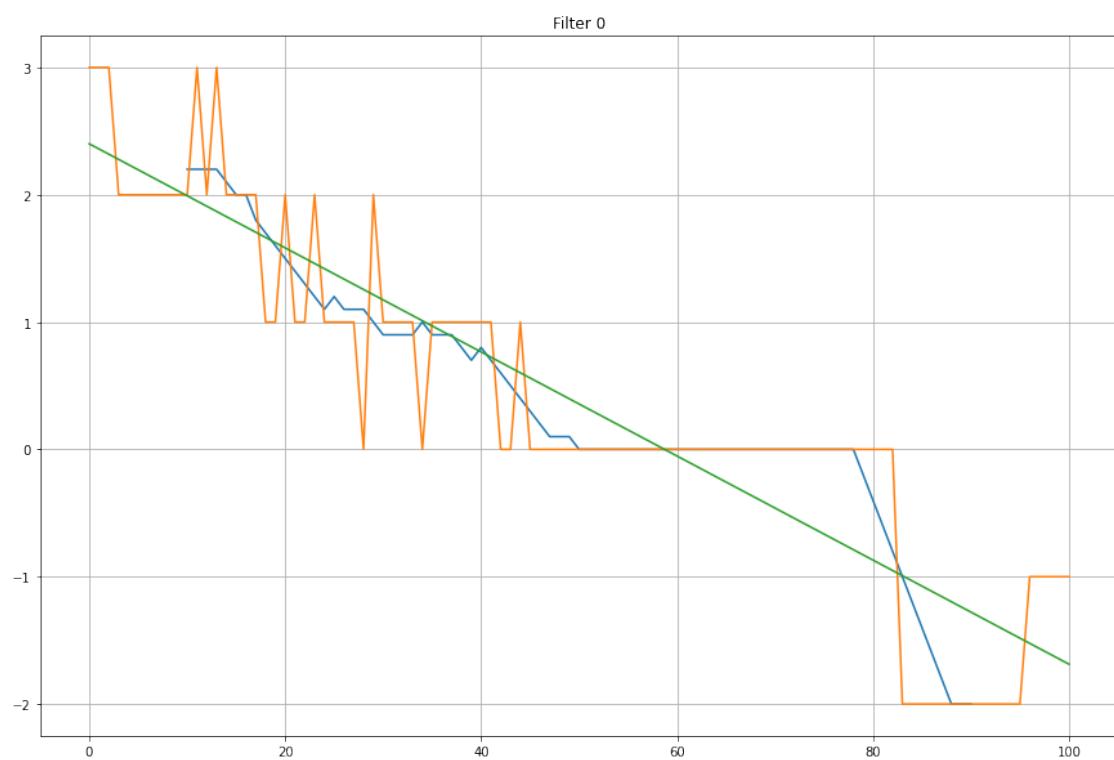
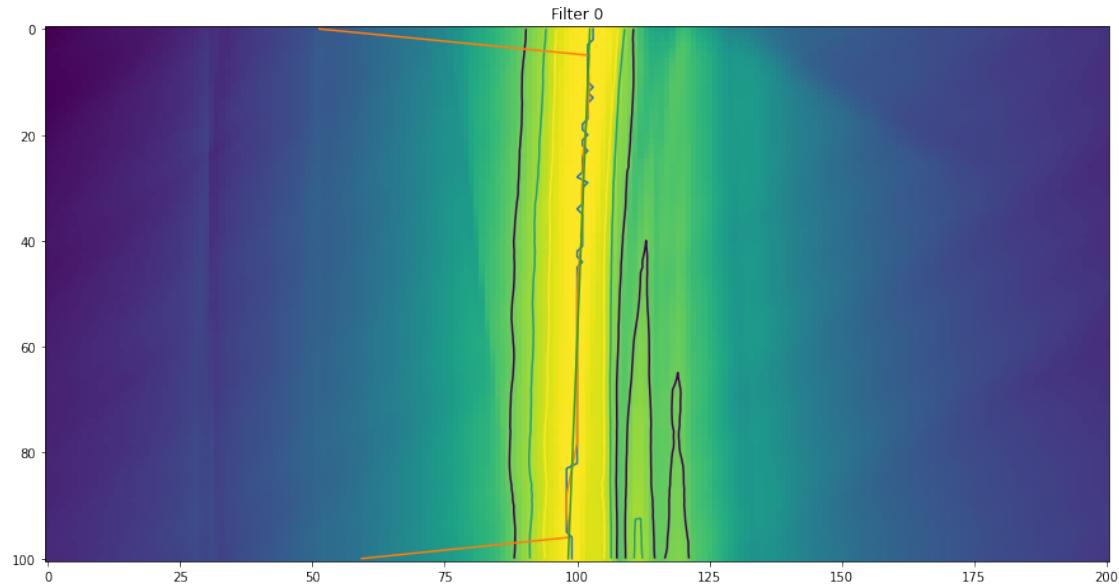
fineTuned={'k':kfine, 'm':mfine}
saveData('fine_filter_parameters', fineTuned)

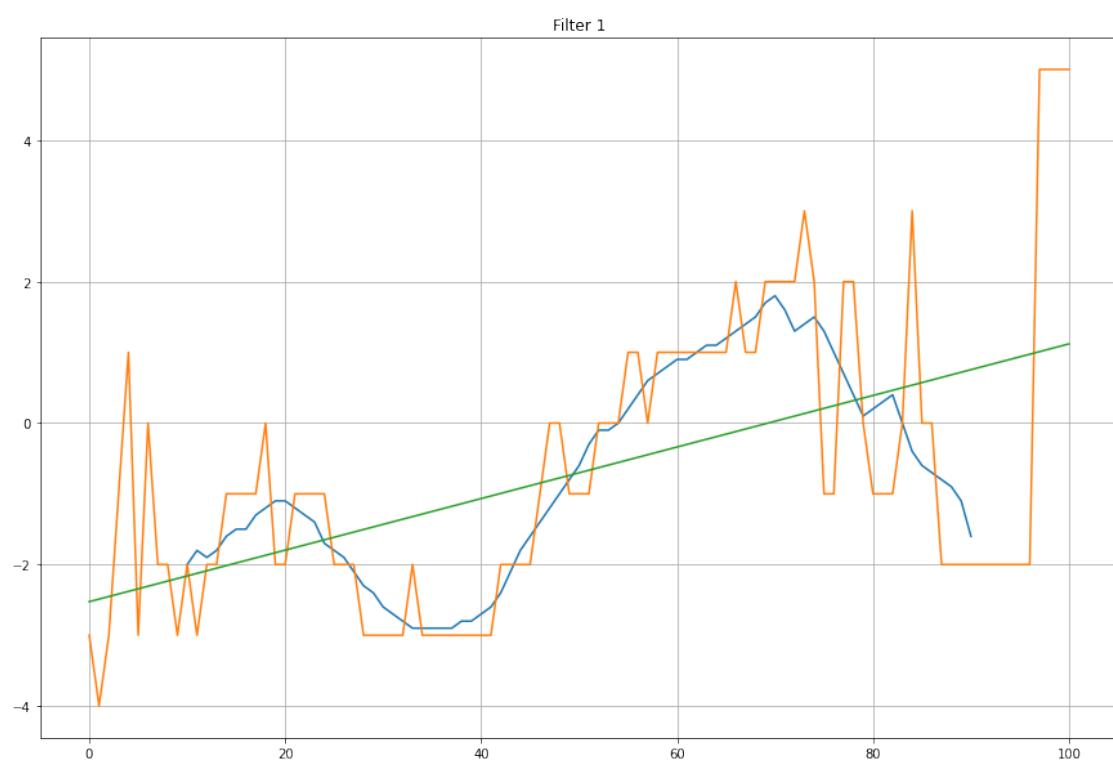
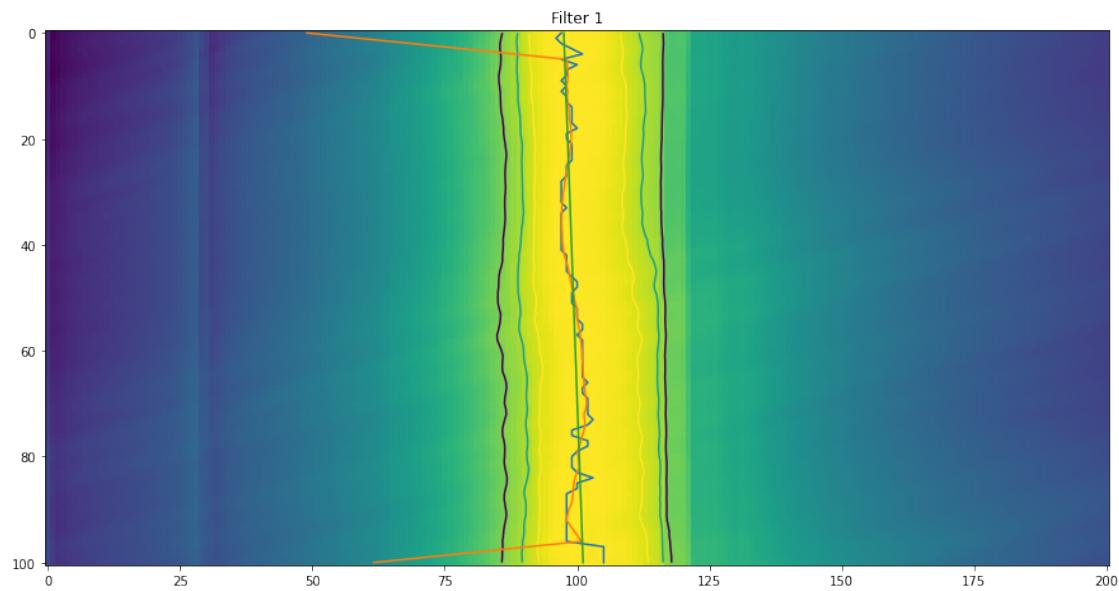
```

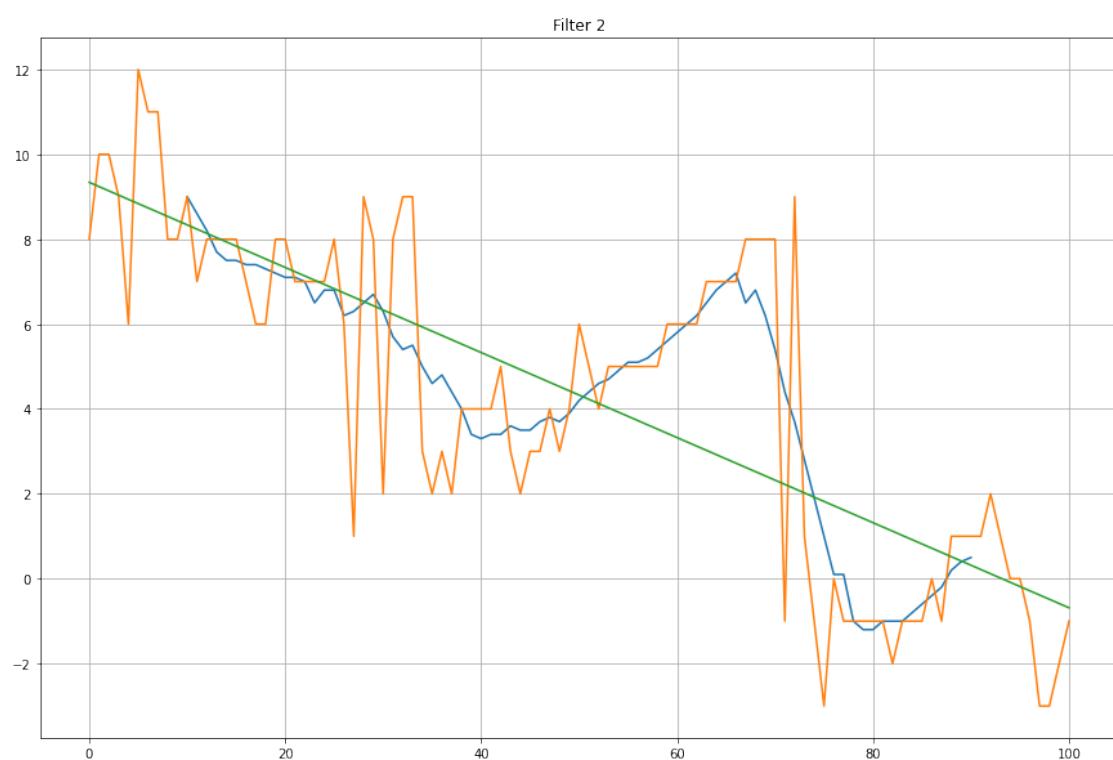
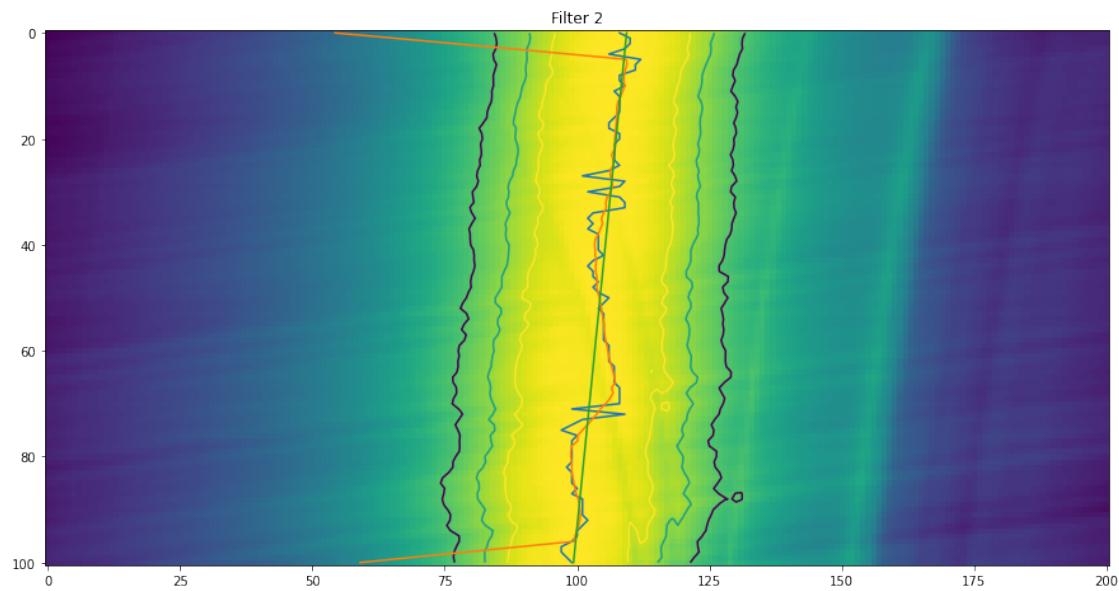
```

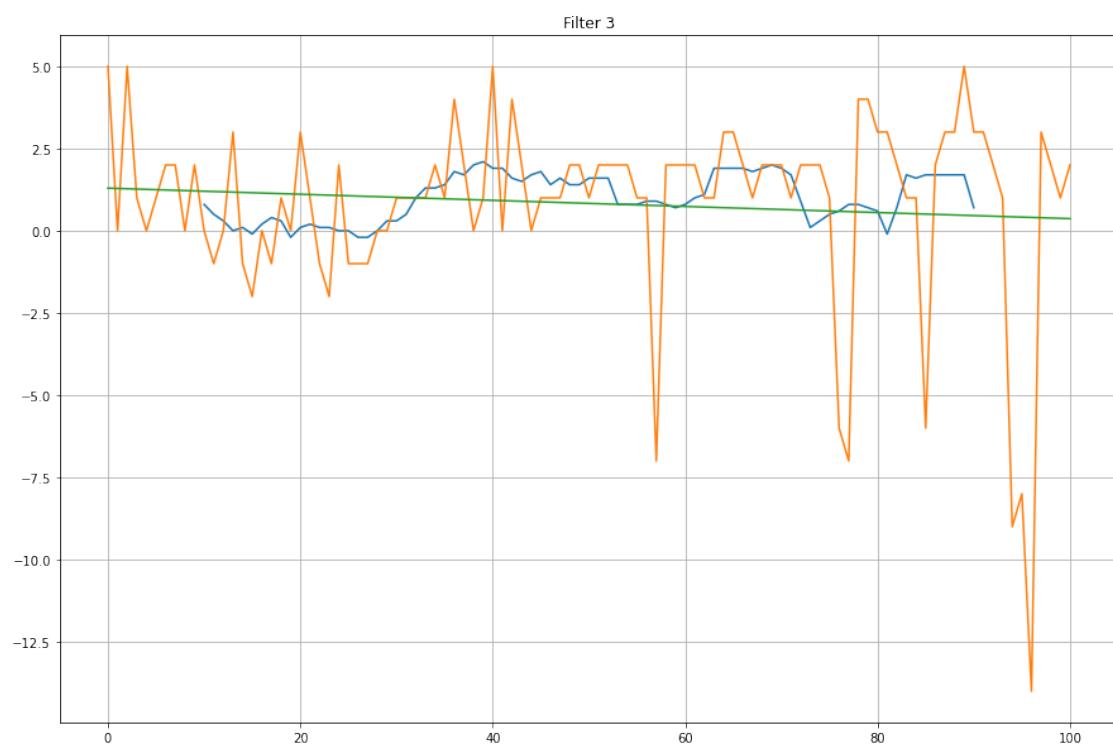
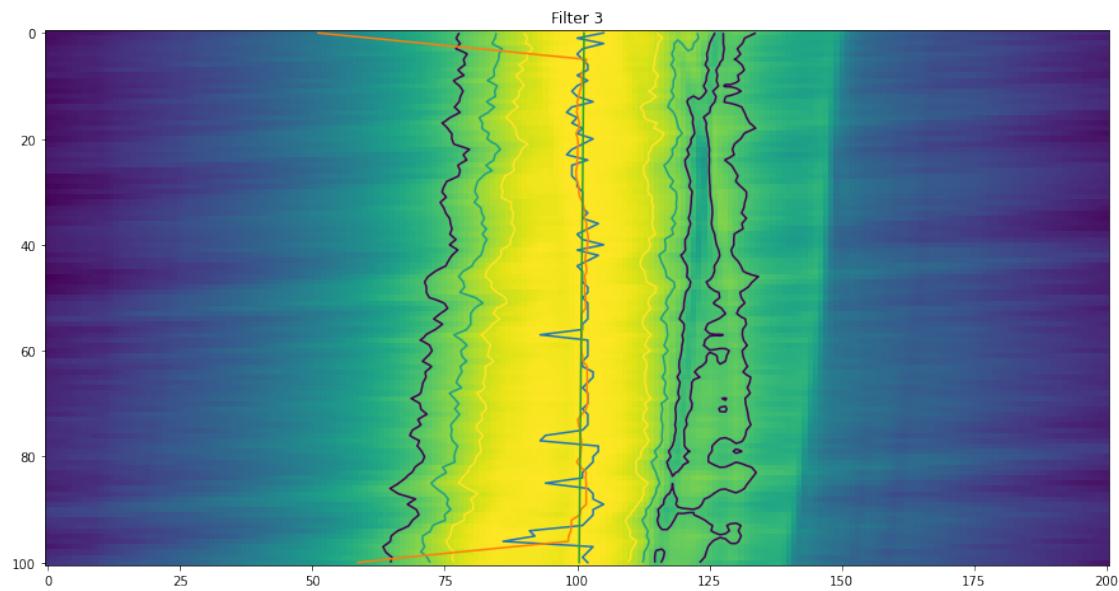
filter 0 Coarse k 0.0237737585127291 [MHZ/lsb] coarse m 696.557330620258 [MHz]
filter 0 fine k 0.023166387840275433 [MHZ/lsb] cfine m 702.5576218258491
[MHz]
filter 1 Coarse k 0.07235017483316573 [MHZ/lsb] coarse m 2001.0564145545754
[MHz]
filter 1 fine k 0.07300940091817518 [MHZ/lsb] cfine m 1994.7430773385008
[MHz]
filter 2 Coarse k 0.08491039781297136 [MHZ/lsb] coarse m 2278.379453855581 [MHz]
filter 2 fine k 0.08384636549546866 [MHZ/lsb] cfine m 2301.7268621258195
[MHz]
filter 3 Coarse k 0.16625378403755867 [MHZ/lsb] coarse m 4524.629401062039 [MHz]
filter 3 fine k 0.16615743770123825 [MHZ/lsb] cfine m 4527.8676072355975
[MHz]
filter 4 Coarse k 0.32867539197747764 [MHZ/lsb] coarse m 8980.19173952352 [MHz]
filter 4 fine k 0.3290628205682144 [MHZ/lsb] cfine m 8993.601756995855 [MHz]
filter 5 Coarse k 0.39094086355898916 [MHZ/lsb] coarse m 10632.052962911413
[MHz]
filter 5 fine k 0.3885476892745918 [MHZ/lsb] cfine m 10644.889305369188 [MHz]

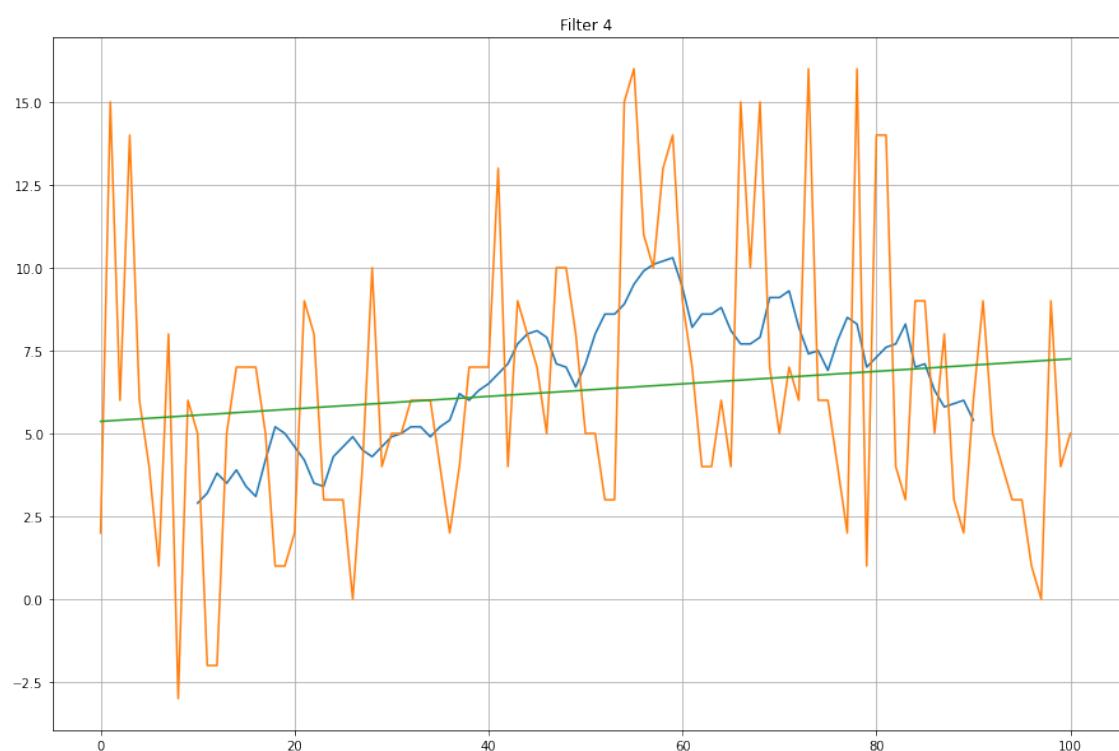
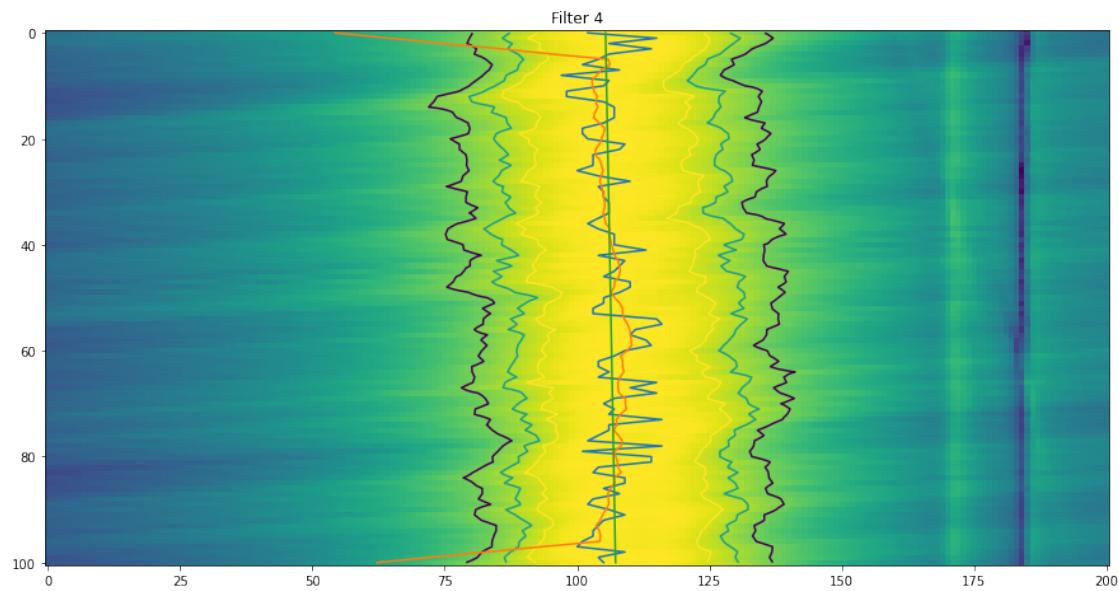
```

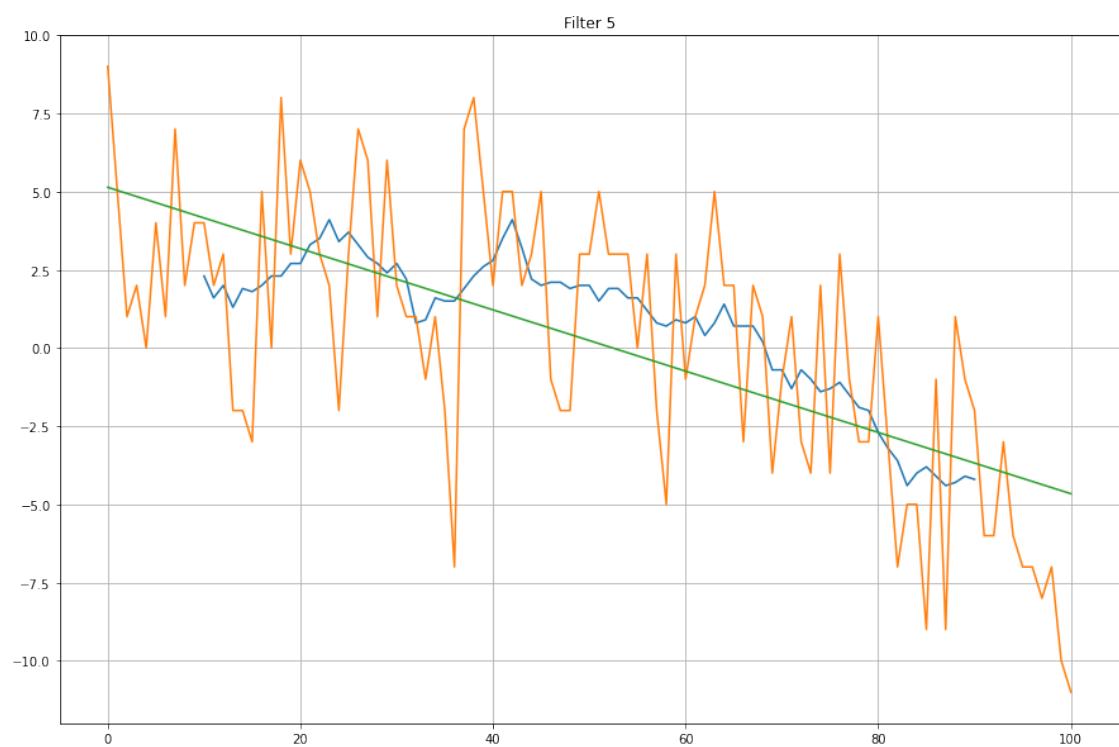
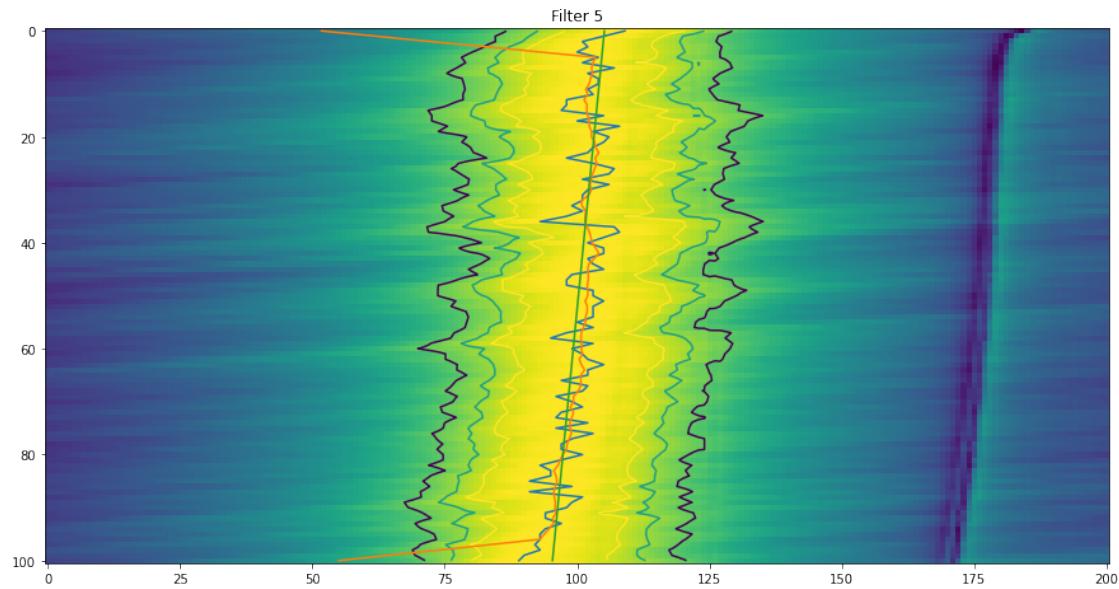












0.6 Check fine tuned parameters

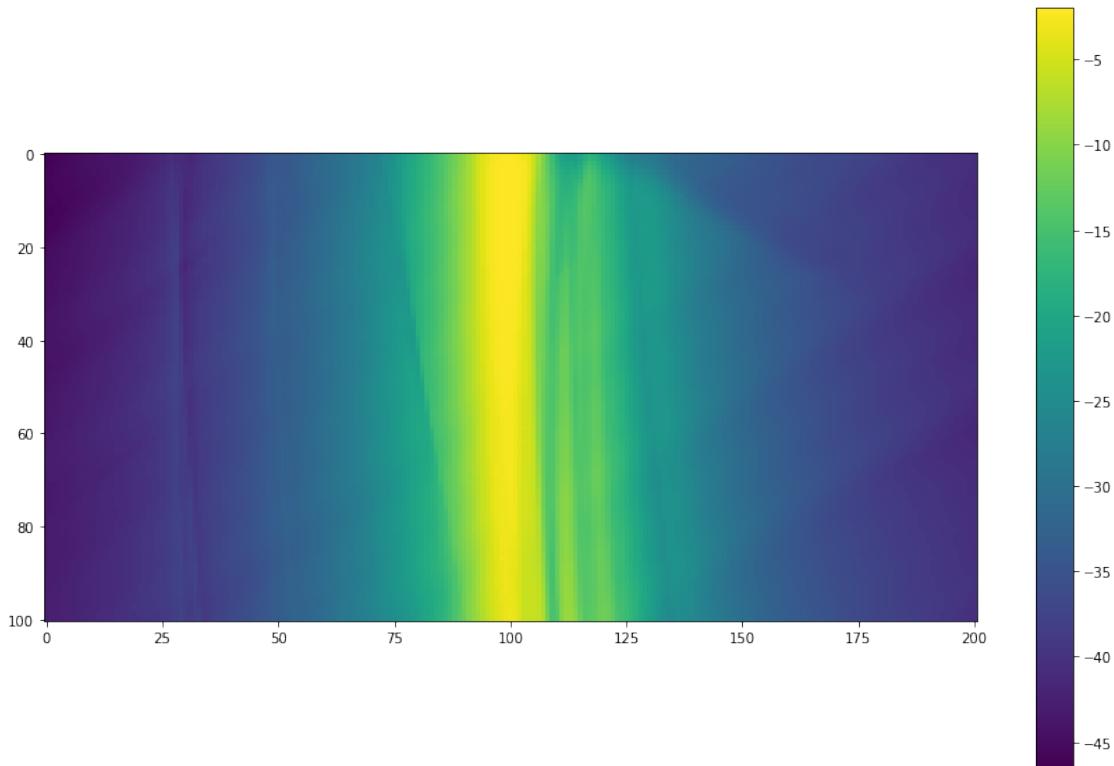
```
[28]: a = loadData('fine_filter_parameters')

ks = a['k'][0]
ms = a['m'][0]
filterBank = []
for i in range(len(ks)):
    filterBank.append(yig_controller_test.YigFilter(fMin[i], fMax[i], ms[i]*1e6, ks[i]*1e6, yc, i))

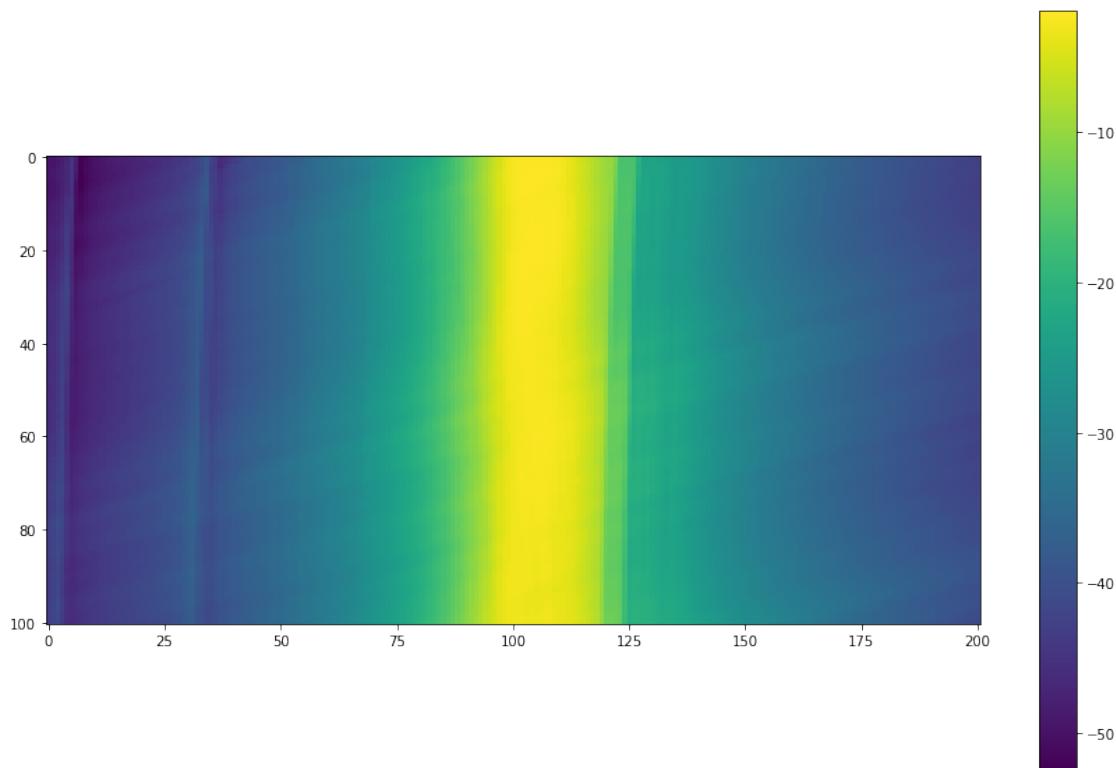
calMeas = skrf.network.Network('cal_through.s2p')

fix = yig_filter_model.SimpleS21Fixture(calMeas.f, calMeas.s[:, 1, 0])
```

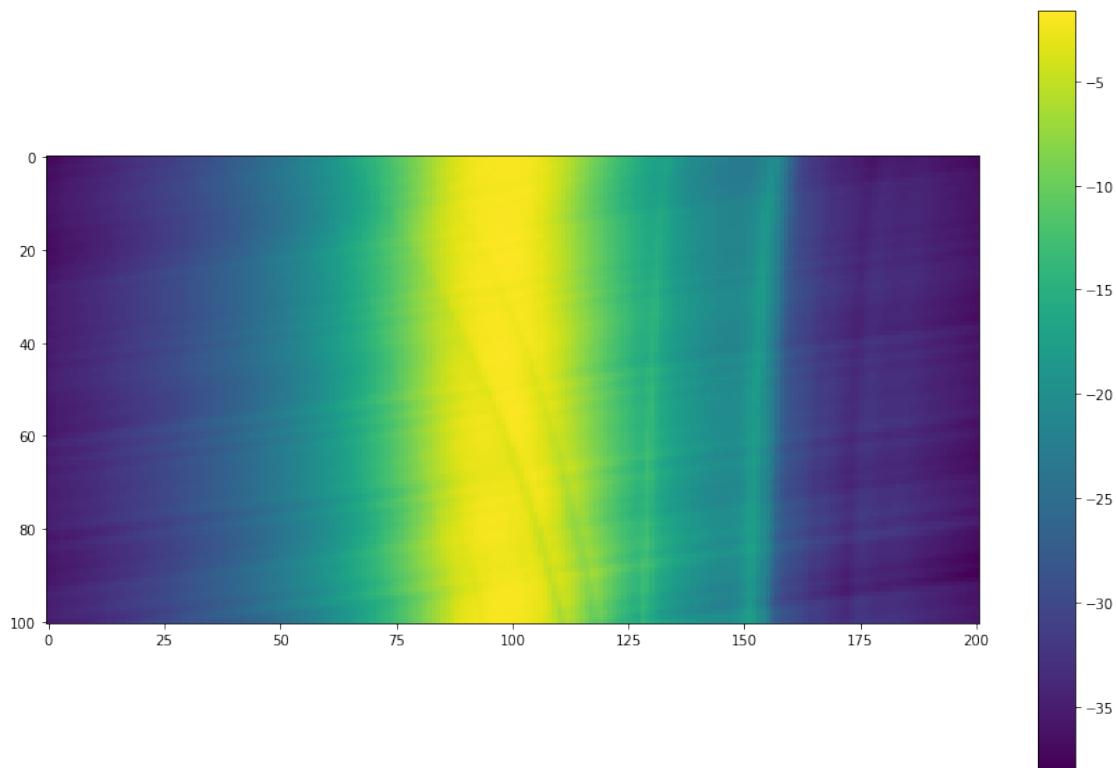
```
[29]: filter0Map, filter0TuningWords, filter0Frequencies, filter0SpanMap = measureYigFilter(filterBank[0])
```



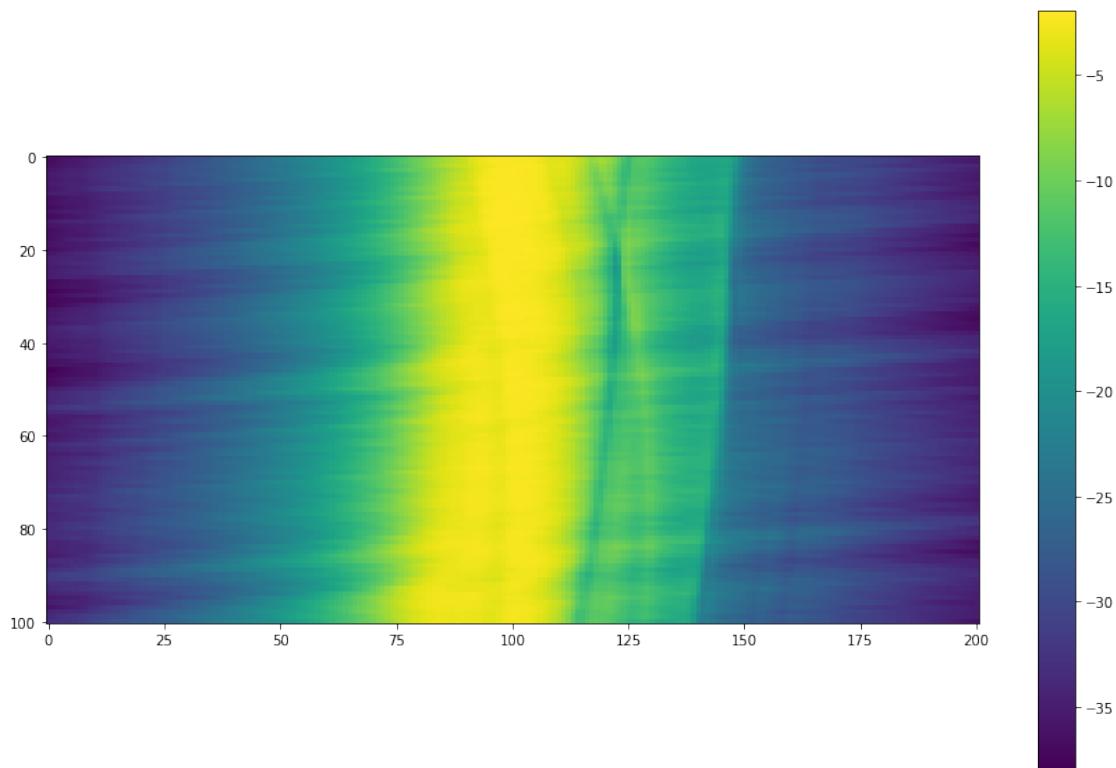
```
[31]: filter1Map, filter1TuningWords, filter1Frequencies, filter1SpanMap = measureYigFilter(filterBank[1])
```



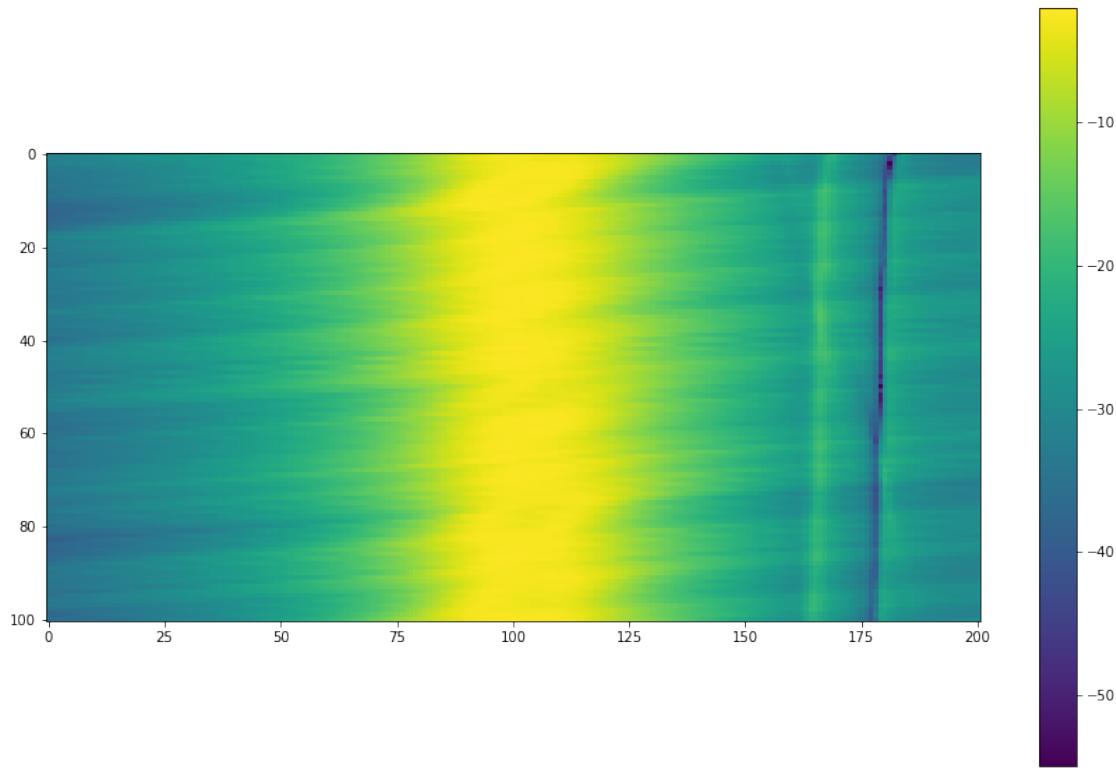
```
[32]: filter2Map, filter2TuningWords, filter2Frequencies, filter2SpanMap =  
      ↵measureYigFilter(filterBank[2])
```



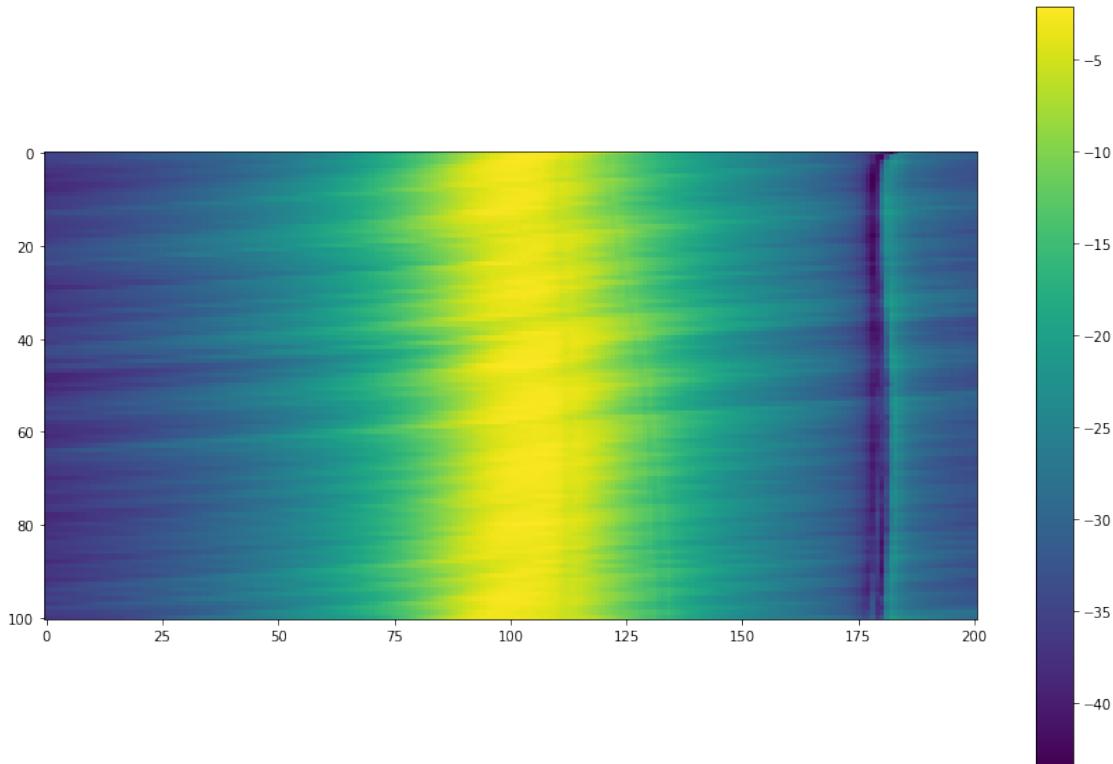
```
[33]: filter3Map, filter3TuningWords, filter3Frequencies, filter3SpanMap =  
      ↵measureYigFilter(filterBank[3])
```



```
[34]: filter4Map, filter4TuningWords, filter4Frequencies, filter4SpanMap =  
      ↵measureYigFilter(filterBank[4])
```



```
[35]: filter5Map, filter5TuningWords, filter5Frequencies, filter5SpanMap =  
    measureYigFilter(filterBank[5])
```



```
[36]: saveDict={'filter0Map':filter0Map, 'filter0TuningWords':filter0TuningWords, □
    ↵'filter0Frequencies':filter0Frequencies, 'filter0SpanMap':filter0SpanMap,
    'filter1Map':filter1Map, 'filter1TuningWords':filter1TuningWords, □
    ↵'filter1Frequencies':filter1Frequencies, 'filter1SpanMap':filter1SpanMap,
    'filter2Map':filter2Map, 'filter2TuningWords':filter2TuningWords, □
    ↵'filter2Frequencies':filter2Frequencies, 'filter2SpanMap':filter2SpanMap,
    'filter3Map':filter3Map, 'filter3TuningWords':filter3TuningWords, □
    ↵'filter3Frequencies':filter3Frequencies, 'filter3SpanMap':filter3SpanMap,
    'filter4Map':filter4Map, 'filter4TuningWords':filter4TuningWords, □
    ↵'filter4Frequencies':filter4Frequencies, 'filter4SpanMap':filter4SpanMap,
    'filter5Map':filter5Map, 'filter5TuningWords':filter5TuningWords, □
    ↵'filter5Frequencies':filter5Frequencies, 'filter5SpanMap':filter5SpanMap, }
saveData('fine_tuning_fine_measurements', saveDict)
```

```
[37]: ftm = loadData('fine_tuning_fine_measurements')

coarseData = loadData('fine_filter_parameters')

kcoarse = coarseData['k'][0]
mcoarse = coarseData['m'][0]
kfine = kcoarse
mfine = mcoarse
```

```

for i in range(6):
    k, m = fineTuneAnalysis(ftm, i)
    print("filter", i, "Coarse k", kcoarse[i], "[MHZ/lsb]", "coarse m", m,
          "mcoarse[i], [MHz]")
    kfine[i] = kcoarse[i] + k
    mfine[i] = mcoarse[i] + m
    print("filter", i, "fine k", kfine[i], "[MHZ/lsb]", "cfine m", mfine[i],
          " [MHz]")
    #print("filter", i, "fine k", kfine[i], "[MHZ/lsb]", "cfine m", mfine[i],
    #      " [MHz]")

fineTuned={'k':kfine, 'm':mfine}
#saveData('fine_filter_parameters', fineTuned)

```

```

filter 0 Coarse k 0.023166387840275433 [MHZ/lsb] coarse m 702.5576218258491
[MHz]
filter 0 fine k 0.023197252327232437 [MHZ/lsb] cfine m 700.7565152446027
[MHz]
filter 1 Coarse k 0.07300940091817518 [MHZ/lsb] coarse m 1994.7430773385008
[MHz]
filter 1 fine k 0.07302683583236479 [MHZ/lsb] cfine m 2003.3118018580117
[MHz]
filter 2 Coarse k 0.08384636549546866 [MHZ/lsb] coarse m 2301.7268621258195
[MHz]
filter 2 fine k 0.08390374711036018 [MHZ/lsb] cfine m 2297.97322205593 [MHz]
filter 3 Coarse k 0.16615743770123825 [MHZ/lsb] coarse m 4527.8676072355975
[MHz]
filter 3 fine k 0.16623123107553198 [MHZ/lsb] cfine m 4526.484380677647 [MHz]
filter 4 Coarse k 0.3290628205682144 [MHZ/lsb] coarse m 8993.601756995855 [MHz]
filter 4 fine k 0.32885007637657404 [MHZ/lsb] cfine m 8997.196690018569 [MHz]
filter 5 Coarse k 0.3885476892745918 [MHZ/lsb] coarse m 10644.889305369188 [MHz]
filter 5 fine k 0.38867865400378193 [MHZ/lsb] cfine m 10652.457738683108
[MHz]

```

