

A POMDP

- discount
- eps
- finalStates
- initBelief
- numActions
- numStates
- obsLength
- timehorizon

- BeliefDynamics()
- GenerateObservation()
- ObservationLikelihood()
- Reward()
- Simulate()
- UpdateBelief()

C IPOMDP

- d
- mapsize
- obstype
- obstypelist
- r0
- r1
- sigma
- tmat

- IPOMDP()
- BeliefDynamics()
- GenerateObservation()
- ObservationLikelihood()
- Reward()
- GetDiscriminability()
- GridDistance()
- GridLoc()
- InitBelief()
- InitDiscriminability()

