



Autonomous RFID Drone For Inventory Tracking

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Introduction

- **Problem:** with the global rise of e-commerce, warehouses are growing much larger in size
 - Warehouse managers need access to inventory data (location, quantity, ship date, etc.)
 - Traditional approach: manually count and record all inventory via barcode readers
 - Need an improved method of taking inventory that is faster and more accurate
- **Solution:** autonomous RFID drone which can quickly and efficiently scan all inventory in a warehouse and then accurately display the locations of items on a three-dimensional map
 - Scan tall shelves and follow designated paths to avoid errors in counting inventory
 - Can also be used to track the exact locations and other data of cattle in a field



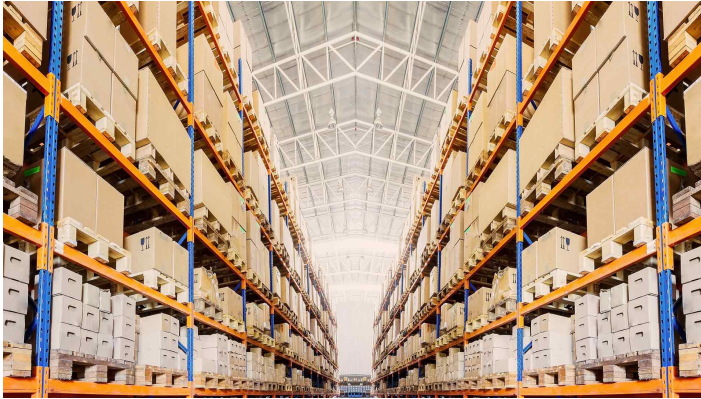
CAL POLY
College of Engineering



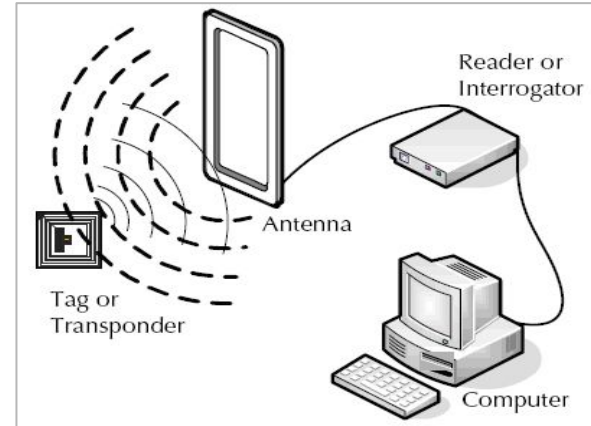
CAL POLY
Center
for Global Automatic
Identification Technologies

Application 1: Warehouse Inventory

- Improve accuracy, increase frequency of stock taking, reduce labor costs
- Warehouse drone industry expected to grow \$29 billion by 2026

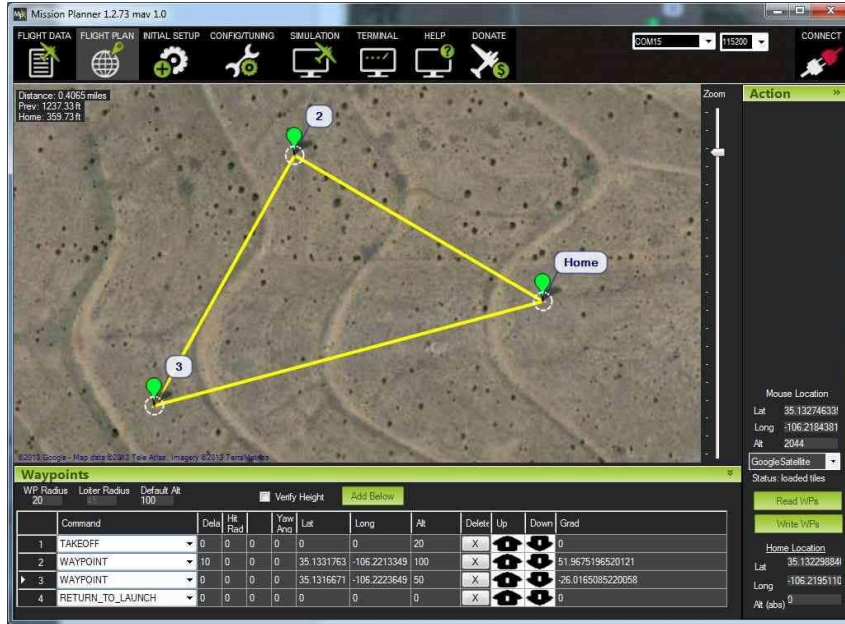


A typical warehouse in which the RFID drone would take inventory



Data transmission in a RFID system, from tag to computer via antenna and reader

Application 2: Cattle Tracking



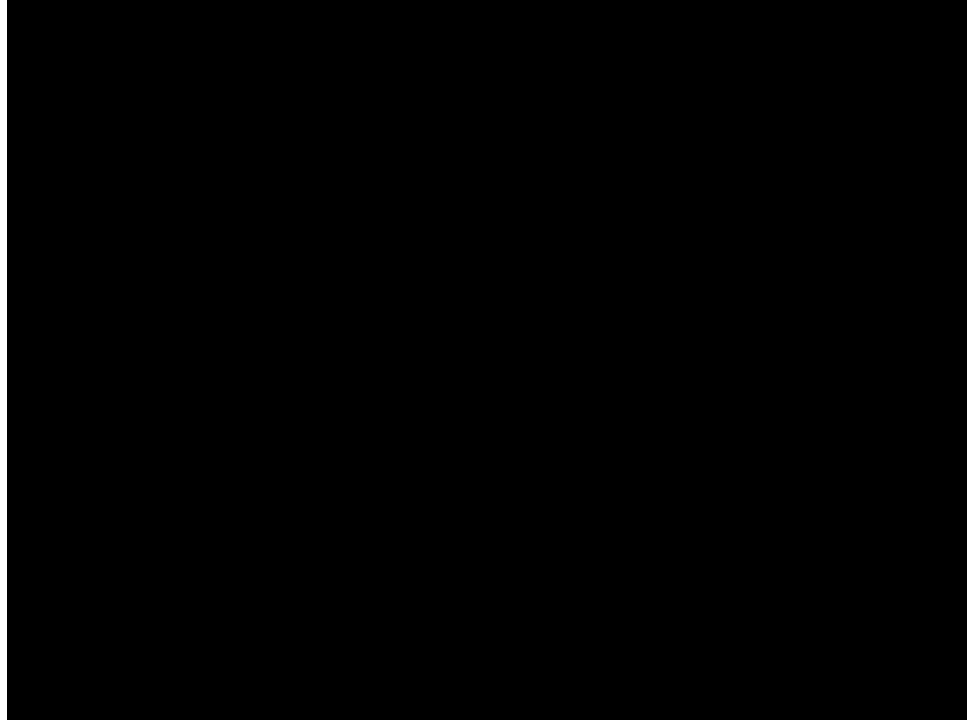
Autonomous flight plan in Mission Planner software



RFID drone doing a test flight at the Cal Poly airfield

Drone Flight Tests

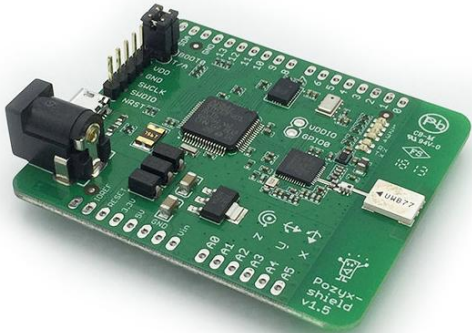
- DJI S900 and CPPG drones
- Autonomous flight mode
- Redesign to meet weight limit: 16.3 lb to 7.5 lb



Core Technologies

Pozyx Positioning System

- Indoor positioning system with tags and anchors
- Up to 10 cm of accuracy
- Low power consumption using UWB technology



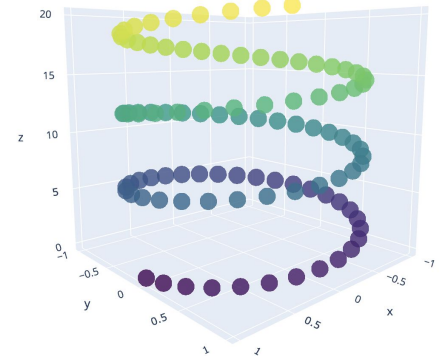
MiniStock RFID Reader

- Reads passive tags while connected to antenna
- Maximum range: 12 ft
- Saves the tag IDs and timestamps to a CSV file



Plotly Python Library

- Open source Python graphing library
- Support for interactive 2D and 3D scatter plots
- Highly customizable



Accompanying Software

Using Python, we designed software that allows a warehouse worker to document incoming and outgoing inventory.

```
Would you like to Build from CSV or Create from scratch? (B or C): b
Please enter the name of the file (without the extension): inventory

Please enter a command (enter 'help' to list options): help
    Type 'add' to add a new tag
    Type 'del' to delete an existing tag
    Type 'pos' to update an existing tag's positional arguments
    Type 'q' to update the csv file then quit
    Type 'quit without saving' to quit WITHOUT saving

Please enter a command (enter 'help' for options): add
Enter tag ID: 123213ab3d00002
Enter the tag description (ex: Produce, Power Tools, etc): Printer Paper
Enter the weight of the shipment (in lbs): 50
Enter the time this tag entered the warehouse (ex: June 20, 2020 = 6/20/2020): 6/30/2020
Enter a ship date for the shipment (ex: December 1, 2020 = 12/1/2020): 7/30/2020

Please enter a command (enter 'help' for options): add
Enter tag ID: 000300da0021288
Enter the tag description (ex: Produce, Power Tools, etc): Printer Ink
Enter the weight of the shipment (in lbs): 20
Enter the time this tag entered the warehouse (ex: June 20, 2020 = 6/20/2020): 6/30/2020
Enter a ship date for the shipment (ex: December 1, 2020 = 12/1/2020): 12/30/2020

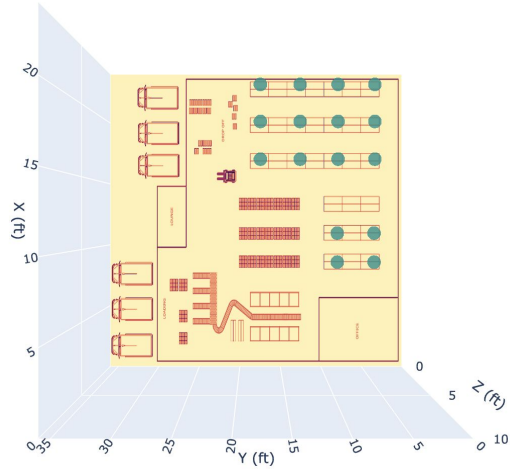
Please enter a command (enter 'help' for options): q
Enter the name of the output csv file to make: output
```

CSV/Excel Spreadsheet

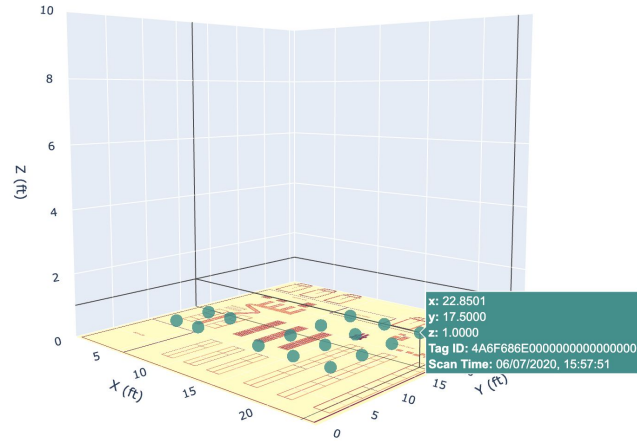
A warehouse worker can input new inventory information into the system, then the drone flight will update positional data for each piece of inventory.

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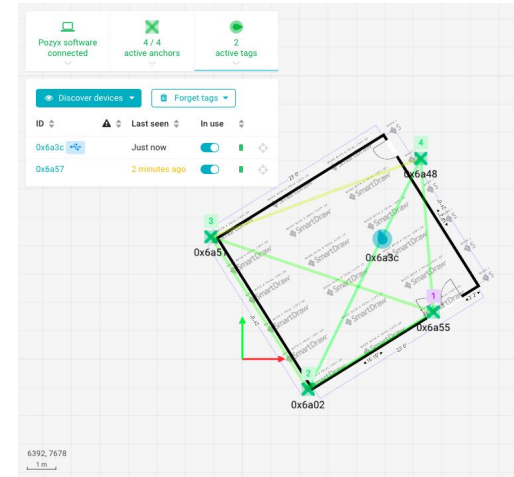
Pozyx/Plotly Demo



Top Down Plotly Warehouse Image



Side View Plotly Warehouse Image



Pozyx Positioning Software

Reflection/Conclusion

- Achieved results
 - Flying the Cal Poly drone autonomously via GPS
 - Scanning and reading tags with the MiniStock RFID reader
 - Developing Python software for a warehouse worker to input inventory data
 - Integrating the Pozyx system with Plotly to visualize tag locations
- Due to COVID-19 and the closure of the RFID lab, our team was unable to run an indoor test flight or fully integrate all components into a single product
- It is hoped that our work can be continued by future senior projects and will help spur the adoption of autonomous RFID drones in inventory management