Appendix B

Finding Linearly Independent Solutions

Algorithm B.1: Finds a maximal set of linearly independent solutions for $A\vec{x} \geq \vec{0}$, and expresses them as rows of matrix B.

INPUT: An $m \times n$ matrix A.

OUTPUT: A matrix B of linearly independent solutions to $A\vec{x} \ge \vec{0}$.

METHOD: The algorithm is shown in pseudocode below. Note that X[y] denotes the yth row of matrix X, X[y:z] denotes rows y through z of matrix X, and X[y:z][u:v] denotes the rectangle of matrix X in rows y through z and columns u through v. \square

```
M = A^T;
r_0 = 1;
c_0 = 1;
B = I_{n \times n}; /* an n-by-n identity matrix */
while (true) {
     /* 1. Make M[r_0:r'-1][c_0:c'-1] into a diagonal matrix with
               positive diagonal entries and M[r':n][c_0:m]=0.
               M[r':n] are solutions. */
     r' = r_0;
     c' = c'_0;
     while ( there exists M[r][c] \neq 0 such that
               r - r' and c - c' are both \geq 0) {
          Move pivot M[r][c] to M[r'][c'] by row and column
                    interchange;
          Interchange row r with row r' in B;
          if (M[r'][c'] < 0) {
               M[r'] = -1 * M[r'];
               B[r'] = -1 * B[r'];
          for (row = r_0 \text{ to } n) {
               if (row \neq r' \text{ and } M[row][c'] \neq 0  {
                    u = -(M[row][c']/M[r'][c']);
                    M[row] = M[row] + u * M[r'];
                    B[row] = B[row] + u * B[r'];
               }
          }
          r' = r' + 1;
          c' = c' + 1;
     }
```

```
/* 2. Find a solution besides M[r':n]. It must be a
           nonnegative combination of M[r_0:r'-1][c_0:m] */
Find k_{r_0}, \ldots, k_{r'-1} \geq 0 such that
          k_{r_0}M[r_0][c':m] + \cdots + k_{r'-1}M[r'-1][c':m] \ge 0;
if (there exists a nontrivial solution, say k_r > 0) {
     M[r] = k_{r_0}M[r_0] + \cdots + k_{r'-1}M[r'-1];
     NoMoreSoln =  false;
}
        else /* M[r':n] are the only solutions */
     NoMoreSoln = true;
/* 3. Make M[r_0:r_n-1][c_0:m] \geq 0 */
if (NoMore Soln) { /* Move solutions M[r':n] to M[r_0:r_n-1] */
     for (r = r' \text{ to } n)
           Interchange rows r and r_0 + r - r' in M and B;
     r_n = r_0 + n - r' + 1;
else { /* Use row addition to find more solutions */
     r_n = n + 1;
     for (col = c' \text{ to } m)
           if (there exists M[row][col] < 0 such that row \ge r_0)
                if (there exists M[r][col] > 0 such that r \ge r_0)
                     for (row = r_0 \text{ to } r_n - 1)
                           if ( M[row][col] < 0 ) {
                                u = \lceil (-M[row][col]/M[r][col]) \rceil;
                                M[row] = M[row] + u * M[r];
                                B[row] = B[row] + u * B[r];
                           }
                else
                     for (row = r_n - 1 \text{ to } r_0 \text{ step } -1)
                           if (M[row][col] < 0 {
                                r_n = r_n - 1;
                                Interchange M[row] with M[r_n];
                                Interchange B[row] with B[r_n];
                           }
}
/* 4. Make M[r_0:r_n-1][1:c_0-1] \ge 0 */
for (row = r_0 \text{ to } r_n - 1)
     for ( col = 1 \text{ to } c_0 - 1 )
          if ( M[row][col] < 0 {
                Pick an r such that M[r][col] > 0 and r < r_0;
                u = \lceil (-M[row][col]/M[r][col]) \rceil;
                M[row] = M[row] + u * M[r];
                B[row] = B[row] + u * B[r];
          }
```

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/* 5. If necessary, repeat with rows M[r_n:n] */

if ( (NoMoreSoln \text{ or } r_n > n \text{ or } r_n == r_0) {

Remove rows r_n to n from B;

return B;
}

else {

c_n = m+1;

for ( col = m \text{ to } 1 \text{ step } -1 )

if ( there is no M[r][col] > 0 such that r < r_n {

c_n = c_n - 1;

Interchange column col with c_n in M;

}

r_0 = r_n;

c_0 = c_n;
}
```