Le Réseau neuronal convolutif

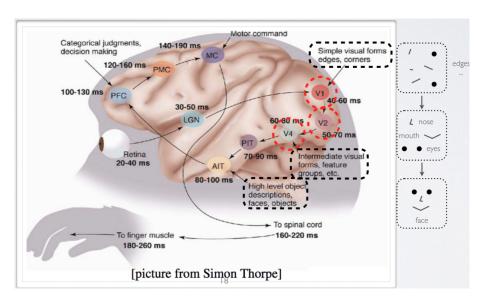
Chaolei CAI

Paris VIII

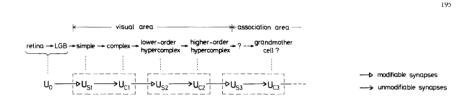
April 28, 2020

- Le néocognitron
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 - Lien avec Hubel et Wiesel
 - Formule de la sortie d'une cellule S
 - Exemple de detection numérique
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Le modèle vivant



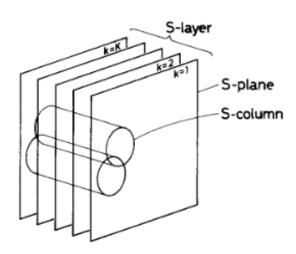
Correspondance avec le modèle de Hubel et Wiesel et le Néocognitron



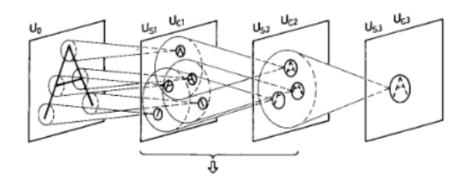
Formule de la sortie d'une cellule S

$$u_{Sl}(k_{l}, \mathbf{n}) = r_{l} \cdot \varphi \left[\frac{1 + \sum_{k_{l-1}=1}^{K_{l-1}} \sum_{\mathbf{v} \in S_{l}} a_{l}(k_{l-1}, \mathbf{v}, k_{l}) \cdot u_{Cl-1}(k_{l-1}, \mathbf{n} + \mathbf{v})}{1 + \frac{2r_{l}}{1 + r_{l}} \cdot b_{l}(k_{l}) \cdot v_{Cl-1}(\mathbf{n})} - 1 \right],$$

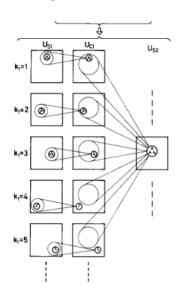
Auto-organisation du réseau



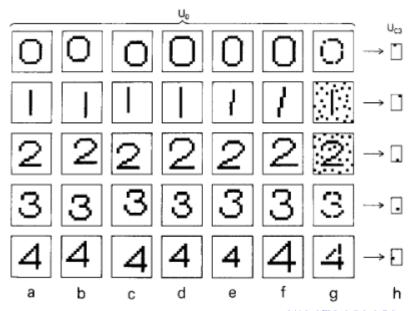
Auto-organisation du réseau



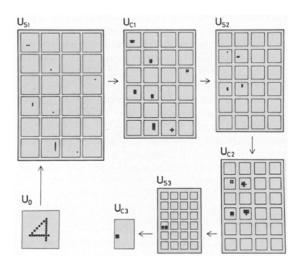
Auto-organisation du réseau



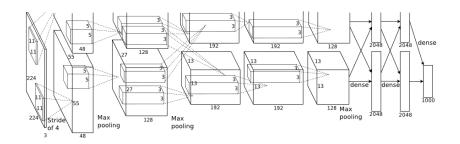
Exemple de detection numérique



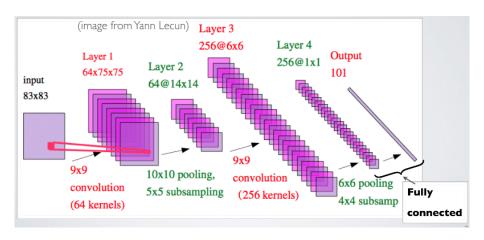
Exemple de detection numérique



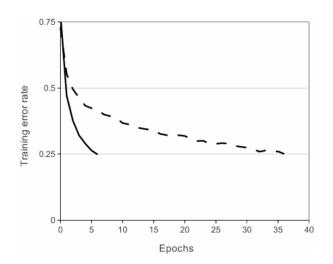
Architecture du réseau



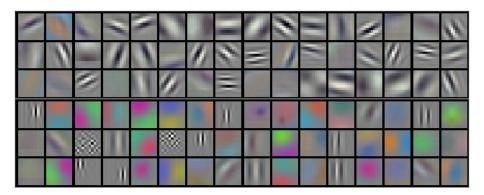
Architecture du réseau | modèle initial



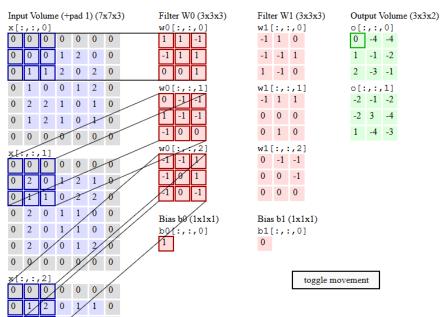
Rectified Linear Unites ReLUs



Couches de convolution

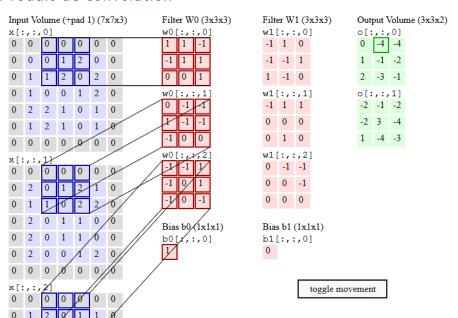


Produit de convolution

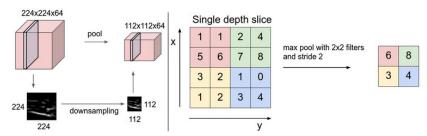


Chaolei CAI (Paris 8)

Produit de convolution

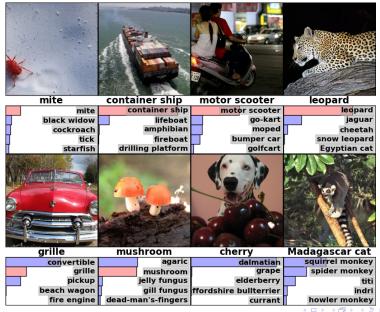


Couches de pooling

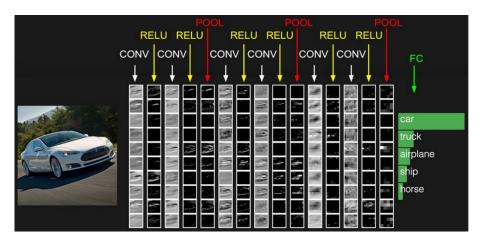


Pooling layer downsamples the volume spatially, independently in each depth slice of the input volume. **Left:** In this example, the input volume of size [224x224x64] is pooled with filter size 2, stride 2 into output volume of size [112x112x64]. Notice that the volume depth is preserved. **Right:** The most common downsampling operation is max, giving rise to **max pooling**, here shown with a stride of 2. That is, each max is taken over 4 numbers (little 2x2 square).

Présentation des résultats



Présentation des résultats



Et après...

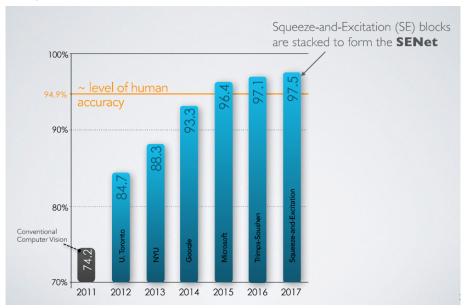
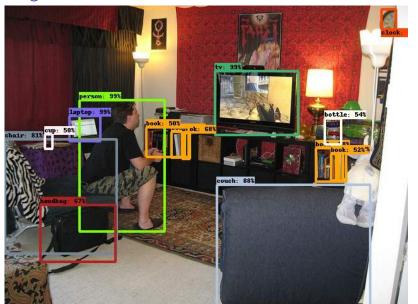
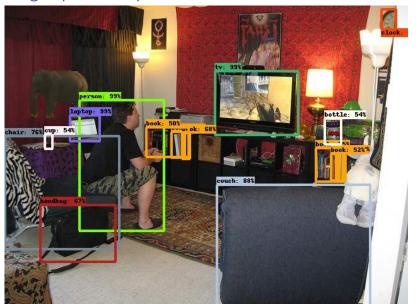
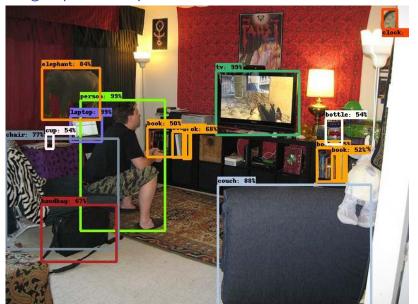


Image initial







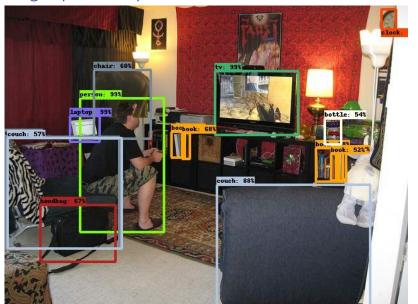
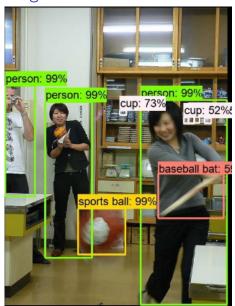


Image initial







[2] [3] [4] [6] [7] [5] [1]

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