

**FACE RECOGNITION SYSTEM USING
LOCAL BINARY PATTERN BASED ON ONE
SAMPLE
PER PERSON PROBLEM**

**THESIS SUBMITTED IN PARTIAL FULFILLMENT OF
THE REQUIREMENT FOR THE DEGREE OF**

**MASTER OF SCIENCE
IN
COMPUTER SCIENCE**

**By
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**UNDER THE GUIDANCE
OF**

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DECLARATION

I **Bipul Kalita**, Roll No **137/16**, a M.Sc. student of the department of Computer Science, Gauhati University hereby declares that I have compiled this thesis reflecting all my works during the semester long full time project as part of my M.Sc curriculum.

I declare that I have included the descriptions etc. of my project work, and nothing has been copied/replicated from other's work. The facts, figures, analysis, results, claims etc. depicted in my thesis are all related to my full time project work.

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CERTIFICATE

This is to certify that **Bipul Kalita** bearing Roll No: **137/16** has carried out the project work ***face recognition system using local binary pattern based on one sample per person problem*** under my supervision and has compiled this thesis reflecting the candidate's work in the semester long project. The candidate did this project full time during the whole semester under my supervision, and the analysis, results, claims etc. are all related to his/her studies and works during the semester.

I recommend submission of this thesis as the project report as a part for partial fulfillment of the requirements for the degree of Master of Science in Computer Science of Gauhati University.

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External Examiners Certificate

This is to certify that ***Bipul Kalita***, bearing Roll No ***137/16*** has delivered his project presentation on ***29/06/2018*** and I examined his thesis entitled ***face recognition system using local binary pattern based on one sample per person problem*** and recommend this thesis as the project report as a part for partial fulfillment of the requirements for the degree of Master of Technology in Computer Science of Gauhati University.

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ABSTRACT

In a face recognition system the system has to identify an unknown face based on its stored database. There are several techniques used in face recognition system. However most of them needs large databases of faces per one person to identify a face. In this project using Local Binary Pattern as features and Euclidean distance as classifier are used. A classifier is a system which classifies object. It can classify a face, this classifier is build from existing data so its called supervised learning. In this project the aim is to identify an unknown person by its face using less number of existing images. For the experiment different datasets have been used and obtained the accuracy of the recognition system, Also later possible matching faces are computed.

PROJECT DESCRIPTION

Title : Face recognition system using local binary pattern based on one sample per person problem

Category : Image Processing

Project Guide : Dr. Pranamika Kakati

Aim : To recognize an unknown face of a person

Language : C++

Library : OpenCV 3.4

Platform : Linux

Duration : 1 Semester

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CHAPTER 1. INTRODUCTION AND OVERVIEW

1.1 Introduction:

The face recognition system has two parts : face verification and face identification (simply recognition) but at the beginning stage the faces are extracted from images and preprocessing them. Then comes recognition part, it includes feature extraction and the matching. The face recognition system can be classified in to following parts mainly -

- **Holistic Methods:** face image is used as the raw input to the system. Example : Local Binary Pattern(LBP), PCA-based technique etc.
- **Local Feature-based Methods:** features such as eyes, nose and mouth are extracted and then their locations and appearances are the input to system. Example : Elastic Bunch Graph Matching (EBGM).

In this project Local Binary Pattern (LBP) is used for feature extraction.

1.2 Local Binary Pattern(LBP)

[1]It was first described in 1994. It is a simple and very efficient texture operator which labels the pixels of an image by thresholding the neighborhood of each pixel and considers the result as a binary number. LBP operator has become a popular approach in various applications. The most important property of the LBP operator in real-world applications is its robustness to monotonic gray-scale changes caused, for example, by illumination variations, example :

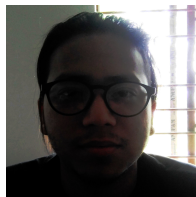


Image 1 (dark)



LBP image of 1

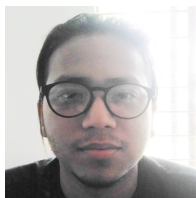


Image 2 (bright)



LBP image of 2

Also LBP computational cost is low which makes it possible to analyze images in challenging real-time.

CHAPTER 2. LITERATURE REVIEW

Face recognition based on one sample per person problem:

In a survey[2], several feature extraction methods are used to result which method is best for one sample per person face recognition problem, and they have found LBP as it gave more accuracy.

In the research paper [3], they have used a tree based data structure which divides the face image to some sub-grids and then extracted LBP features. For different types of grid different accuracies are obtained.

[4] contains works using LBP where image is partitioned into 7x7 grid and then calculated histogram and concatenate them, then the recognition result was obtained by using chi-square distance from histograms of test images and training images. The results was surprising, using only one training image per person the system gave 85.81% accuracy.

CHAPTER 3. THE PHASES OF THE PROJECT

3.1. Preparing face images:

For training datasets i have taken equal number of images for each person. Then, I extracted faces and resizes them to 100x100 pixels. Images of each person have been stored in separate folder.

Similarly for 1 face image to be tested, the same face extraction and resizing is done.

Accessing images in the program:

Two text files are created, one contains locations(file path) of all training images and other one contains path to test images.

3.2. Finding LBP(local binary pattern) from image:

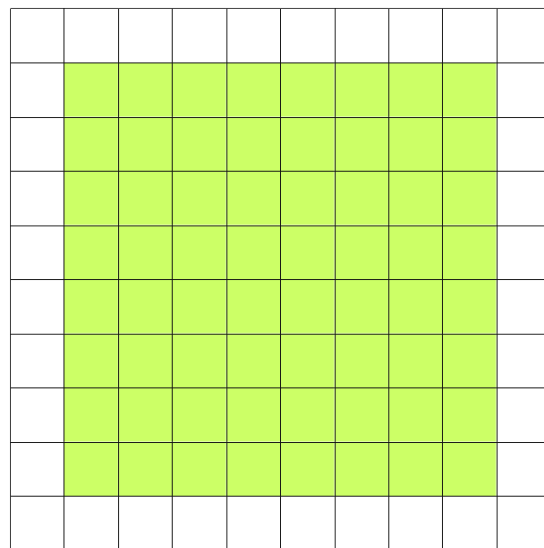
The size of the image is $100 \times 100 = 10,000$ pixels.

Then next, the image is converted to gray scale image. Where each pixel has a value between 0-255, 0 for pure black and 255 for pure white.

Next the image is partitioned into 10×10 blocks,
where each block contains $10 \times 10 = 100$ pixels,
then from each block LBP is calculated and stored in an array with associated block position as index.

Calculating LBP for a block:

To calculate LBP for a block we have to select centers where each center has 8 neighboring pixel and then calculate LBP for each center.



10x10
A block



center



Discarded to be a center

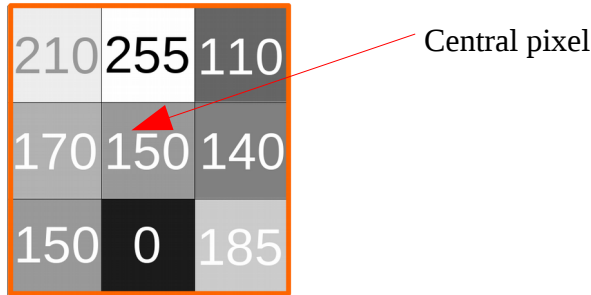
Total centers for one block = 8×8
= 64

Total centers for 1 image = $10 \times 10 \times 64$
= 6400

i.e. 6,400 LBP features for one image

Calculating LBP for a center:

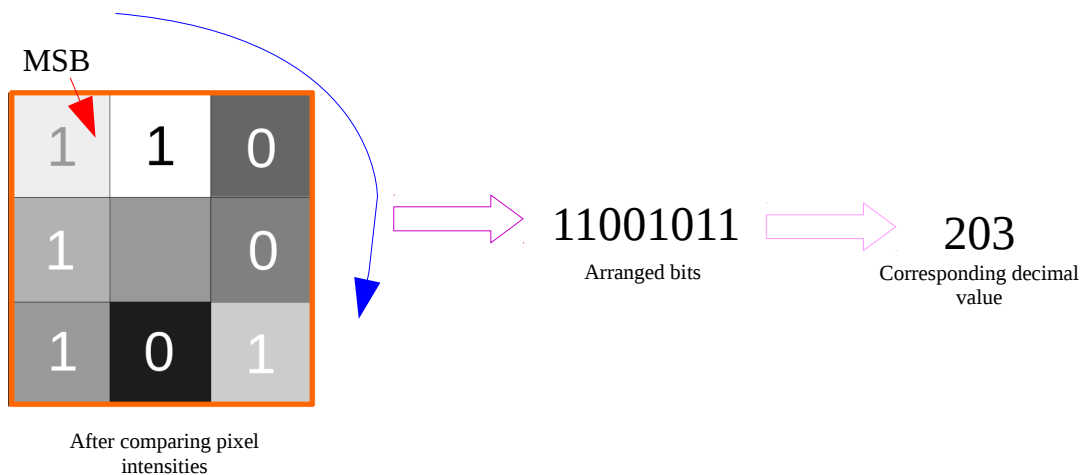
To illustrate how to find the LBP, the following picture with pixel intensities is considered.



Selected pixel as center to calculate LBP with 8 neighboring pixels

Now, compare each neighbor pixel with center, if the neighbor pixel has higher or equal intensity than central pixel then consider 1 for that position else consider 0.

Then, we will have 8 numbers for 8 neighbors pixel, each one is either 0 or 1, so arrange those 8 bits by selecting any one bit as most significant bit(MSB) and then select other bits by moving either clockwise or anticlockwise. It is noted that, selecting bits can be in any order but the same order must be maintain for all centers in every block in every image. Then calculate the corresponding Decimal value of that 8 bit binary number and then store it in the array in corresponding center location as index.



The algorithm to find LBP of a central pixel C as follows:
(consider that the pixel C has 8 neighbors as we selected)

```
begin
step 1: initialize i=7,result=0
step 2: for each neighbor pixel p of C do:
step 3:     if intensity(p)>=intensity(C) then
step 4:         result = result + 2i
step 5:         i--
step 6:     end if
step 7: end for
end
```

3.3. Calculating Histogram Data from LBP features:

After calculating LBP features of an image, we have now 6,400 LBP features from $10 \times 10 = 100$ blocks, now each block contains 64 LBP features which is 8×8 features in a block.

Now from that 8×8 features from each block we have to calculate histogram data.

In LBP features, every LBP value is in range from 0 to 255.

Next we select a range of intensity, say 5,

now we can make $255/5 = 51 + 1 = 52$ number of bars in histogram (from 0 to 51)
each bar will represent frequency of intensity in a block in its corresponding intensity range.

Bar sl no	Intensity range	Bar sl no	Intensity range
0	0-4	26	130-134
1	5-9	27	135-139
2	10-14	28	140-144
3	15-19	29	145-149
4	20-24	30	150-154
5	25-29	31	155-159
6	30-34	32	160-164
7	34-39	33	165-169
8	40-44	34	170-174
9	45-49	35	175-179
10	50-54	36	180-184
11	55-59	37	185-189
12	60-64	38	190-194
13	65-69	39	195-199
14	70-74	40	200-204
15	75-79	41	205-209
16	80-84	42	210-214
17	85-89	43	215-219
18	90-94	44	220-224
19	95-99	45	225-229
20	100-104	46	230-234

21	105-109	47	235-239
22	110-114	48	240-244
23	115-119	49	245-249
24	120-124	50	250-254
25	125-129	51	255

It is to be noted that the last bar (i.e. sl no 51) got only 255
so, now there will be 52 histogram features for each block,
Total will be $52 \times 10 \times 10 = 5,200$ features for an image.
To calculate histogram data for an image the algorithm will be:

begin

Step 1: initialize an 3d array (say bar) of size 10, 10, 52 and assign 0 to every location
(i.e. = bar[10][10][52])

Step 2: for each block_row_no in block in all rows do:

step 3: for each block_col_no in block_row_no do:

step 4: for each lbp_val in LBP features within the selected block do:

step 5: bar[block_row_no] [block_col_no] [lbp_val/5]++

step 6 end for

step 7 end for

step 8 end for

end

For example, the histogram data for the following 8x8 LBP features as follows:

200	100	0	5	255	45	78	120
99	255	189	156	222	243	24	64
32	46	245	56	245	26	2	1
57	37	120	153	12	75	47	46
74	36	88	246	24	67	24	16
183	166	76	210	88	46	53	84
36	63	37	3	78	35	45	84
36	99	34	253	255	0	25	45

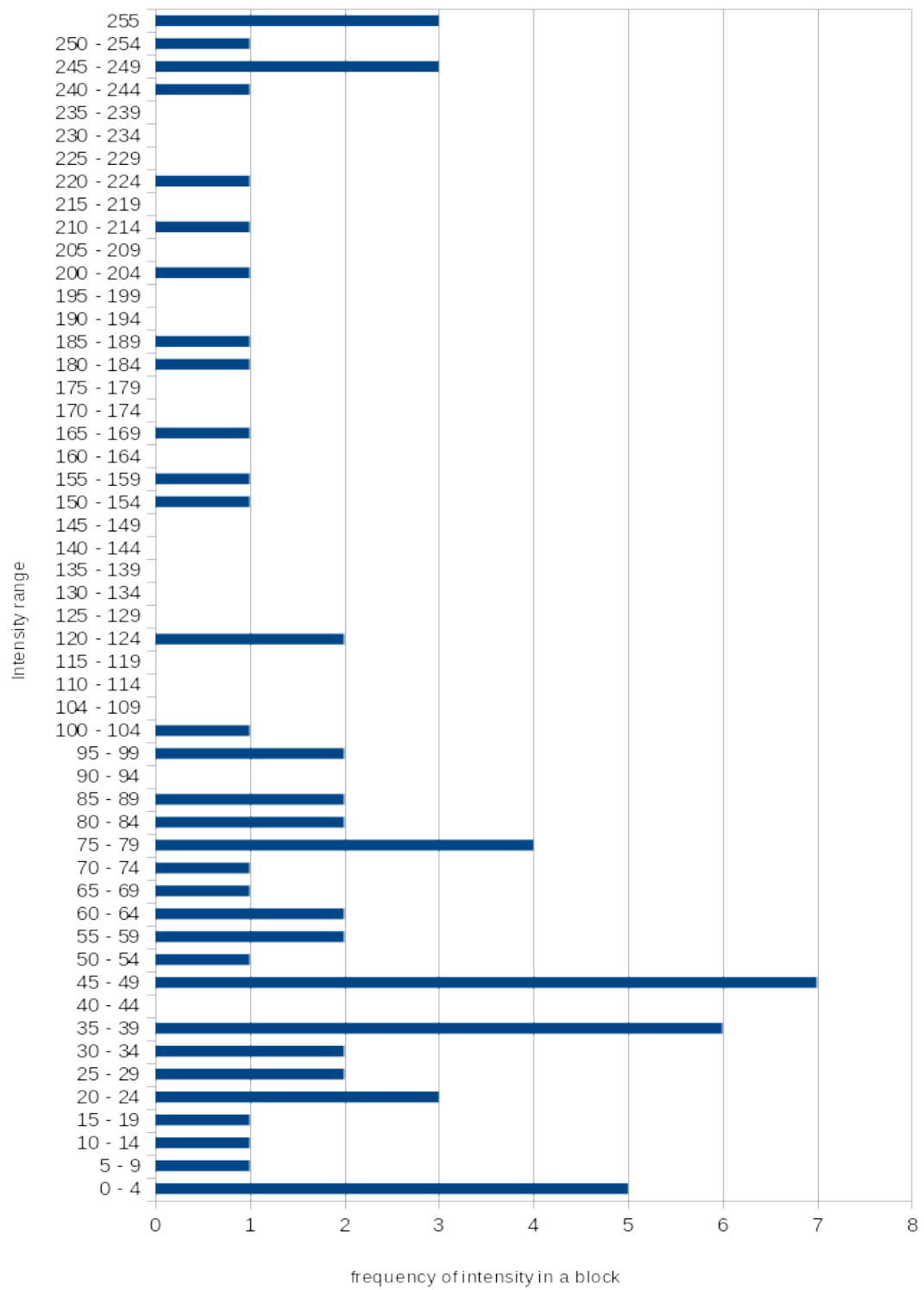


Fig: Histogram of the above LBP features

3.4. Calculating Euclidean distance:

The euclidean distance of any two value is computed as

$$\text{eu_distance} = \sqrt{(val_1 - val_2)^2}$$

For two 1D arrays A_1 and A_2 with n number of values is computed as:

$$\text{eu_distance} = \sum_{i=1}^n \sqrt{(A_1[i] - A_2[i])^2}$$

Now, we have Histogram data of images, contains 5,200 features per image. Now to find euclidean distance between histogram data of two images, the algorithm is:

```
begin
step 1: initialize eu_distance = 0
step 2: for each block_row_no in block in all rows do:
step 3:     for each block_col_no in block_row_no do:
step 4:         for each h_val1 in histogram features within the selected block of
                    image1 and h_val2 in histogram features within the selected block
                    of image2 do:
step 5:             eu_distance = eu_distance + sqrt(square(h_val1 - h_val2))
step 6:         end for
step 7:     end for
step 8: end for
end
```

3.5. Producing Result:

The purpose of the system in this project is to identify a person from face image using already stored minimum number of face images.

The euclidean distance can now tell the difference of images, higher the euclidean distance lower the chance of match, and lower the euclidean distance higher the chance of match.

If we have n number of images stored and we want to identify a person face, then there will be n number of euclidean distances between image to be tested and stored images. Now the stored image with lowest euclidean distance will be the result, and may be the person to be identified. This is done when there is only one image stored per person.

But when there is more than one image stored per person, then euclidean distance between one person images with tested image will be sum of all euclidean distances between each images of that person with the tested image. Then the minimum euclidean distance will be the resulted person to be identified. The algorithm is as follows :

```
begin
step 1: initialize min_eu = +inf, eu_distance = 0,resulted_person = person[0]
step 2: for each person p in person_images_database:
step 3:     for each image i in p do:
step 4:         eu_distance = eu_distance + euclidean_distance(i,test_image)
step 5:     end for
step 6:     if min_eu > eu_distance then
step 7:         min_eu = eu_distance
step 8:         resulted_person = p
step 9:     end if
step 10:     eu_distance = 0
step 11: end for
end
```

But sometimes, the matched person is not correct. This happens with a less differences of euclidean distances. To make it better, 2 other possibilities of matching result is computed. This is done by simply sorting all euclidean distances in ascending order and took the 2nd and 3rd results as other possibilities.

Computing accuracy of recognition:

This is computed simply by dividing number of matched by number of tests and multiplied by 100 to produce percentage.

$$\text{Accuracy} = \frac{\text{number of match}}{\text{number of tests}} \times 100$$

The number of match is computed by matching the test image label and resulted person name.

For this test training datasets have person with different name. I have taken 3 databases, one is friends database which contains 7 persons and 5 images per person, this database is created by myself.

Next one is ORL database, which contains 40 persons and 10 images per person. The images of this database have variant poses.

ORL face database source from :

<http://www.cl.cam.ac.uk/research/dtg/attarchive/facedatabase.html>

thanks to AT&T Laboratories Cambridge.

And the 3rd database is faces94 which contains 151 individuals and 20 images per person.

These databases have male and female persons faces.

Faces94 source from: <http://cswww.essex.ac.uk/mv/allfaces/faces94.html>

For the testing purpose from each individual one image is moved to other directories and stored in a directory with a label as the directory name.

CHAPTER 4. IMPLEMENTATION

4.1 LBP function

The following function reads an image from location 'str' and then calculate it's LBP and store it in an array 'ar[]' by sending arguments starting row=i,ending row = row, starting column = v, ending column = col

```
void lbp(unsigned char *ar,string str,int i,int v,int row,int col){
    int k = 0;
    Mat img = imread(str,CV_LOAD_IMAGE_GRAYSCALE);
    for ( ;i<row;i++) {
        for(int j = v ;j<col;j++) {
            int t = 0;
            t = img.at<uchar>(i-1,j-1) >= img.at<uchar>(i,j) ? (t<<1)|1:t<<1;
            t = img.at<uchar>(i-1,j) >= img.at<uchar>(i,j) ? (t<<1)|1:t<<1;
            t = img.at<uchar>(i-1,j+1) >= img.at<uchar>(i,j) ? (t<<1)|1:t<<1;
            t = img.at<uchar>(i,j+1) >= img.at<uchar>(i,j) ? (t<<1)|1:t<<1;
            t = img.at<uchar>(i+1,j+1) >= img.at<uchar>(i,j) ? (t<<1)|1:t<<1;
            t = img.at<uchar>(i+1,j) >= img.at<uchar>(i,j) ? (t<<1)|1:t<<1;
            t = img.at<uchar>(i+1,j-1) >= img.at<uchar>(i,j) ? (t<<1)|1:t<<1;
            t = img.at<uchar>(i,j-1) >= img.at<uchar>(i,j) ? (t<<1)|1:t<<1;
            ar[k++] = t;
        }
    }
}
```

4.2 Histogram function

This function calculates histogram features from lbp features from `ar[]` and stored it in `his[]`, where `pixels` is the size of the array `ar[]`, size of `ar[]` and `his[]` are same.

```
void histogram(unsigned char *ar,unsigned char *his,int pixels){
    for (int i = 0;i<pixels;i++)
        his[ar[i]/5]++;
}
```

4.3 Euclidean function

This following function return the euclidean distance between values in two arrays `a1[]` and `a2[]` where `size` is the size of those array.

```
double g_his_euclidean_distance(unsigned char a1[],unsigned char a2[],int size){
    double result = 0;
    for (int i=0;i<size;i++)
        result+=pow(a1[i]-a2[i],2);
    return sqrt(result);
}
```

4.4 Accuracy measure

Following statement will compute accuracy of the system and assign it to accuracy in terms of percentage. Where `test_count` is the total number of tests and `false_count` is total number of wrong output.

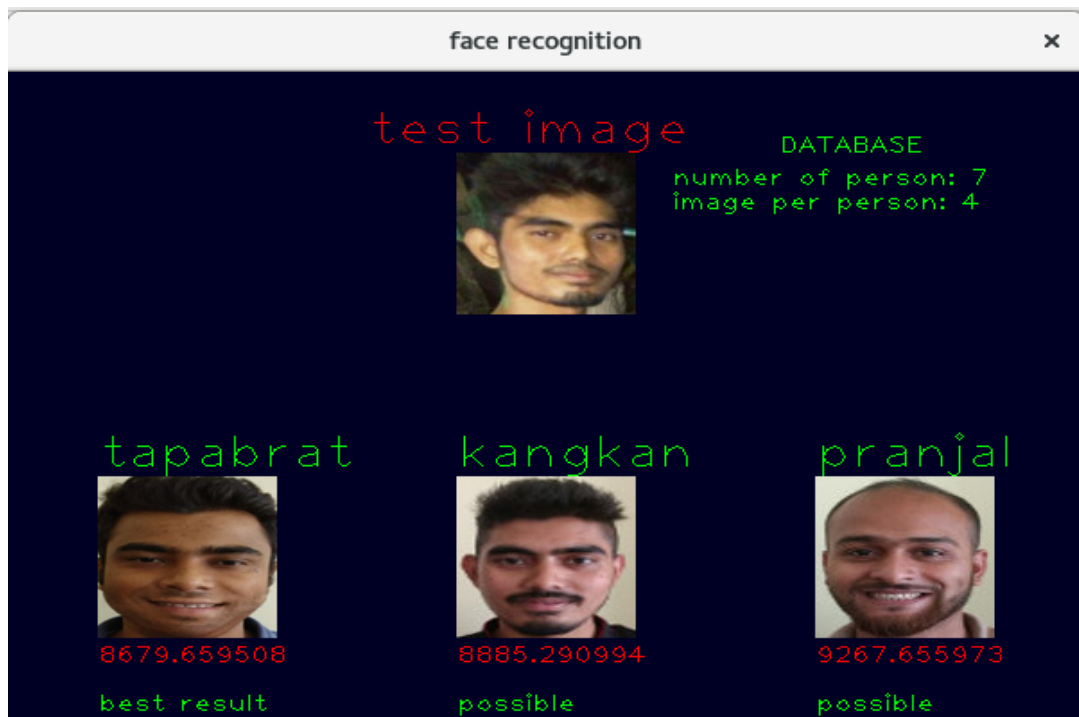
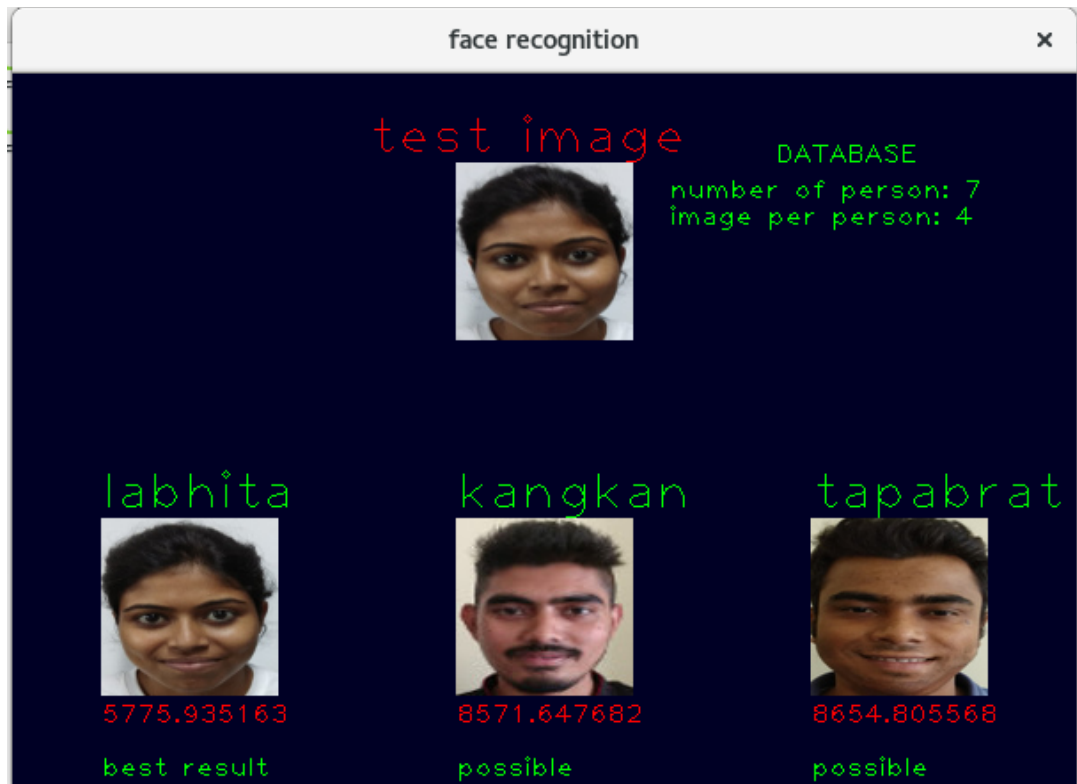
```
double accuracy = ((double)(test_count-false_count)/test_count)*100;
```

CHAPTER 5. OUTCOMES

Accuracy of recognition:

Database	Individuals	Image per person	Number of test images	Miss	Match	Accuracy %
ORL	30	1	30	11	19	63.333
		2	30	8	22	73.333
		3	30	7	23	76.6667
		4	30	9	21	70
		5	30	8	22	73.333
		6	30	7	23	76.6667
		7	30	7	23	76.6667
		8	30	5	25	83.3333
		9	30	3	27	90
	40	1	40	18	22	55
		2	40	14	26	65
		3	40	13	27	67.5
		4	40	14	26	65
		5	40	12	28	70
		6	40	12	28	70
		7	40	11	29	72.5
		8	40	10	30	75
		9	40	8	32	80
faces94	151	19	151	1	150	99.337
		10	151	3	148	98.0132
		4	151	2	149	98.6755
Friends	7	4	12	3	9	75

These are the screen shots of the program resulting unknown test images:



CHAPTER 6. CONCLUSION AND FUTURE WORK

6.1 Conclusion:

The purpose of this project is to build a face recognition system based on local binary pattern features using less number of faces per person. From the result of this project/program it is true that more the number of faces per person more the recognition accuracy.

Also more the execution time. But for the less number of faces per person LBP is known to be the best features till now. Also the accuracy is depend on the classifier that is used. Here euclidean distance is working as a classifier, but SVM(support vector machine) will give more accuracy and lot more faster. The library used in the program is OpenCV which gives automatic optimization by using intel IPP library but not for every task. So, to achieve this intel IPP library can be used and manually instructions of IPP can be used, but also intel IPP will work on intel processor most of the time. There are built in functions in OpenCV that could be used, but I have implemented some manually to learn about them.

If an unknown test face is given to the program and the corresponding person is not in the database, then still the program will result some faces, which is incorrect. To resolve this issue a threshold of euclidean distance can be considered and if the distance is minimum than threshold then results possible faces.

Also I have used the simplest original LBP algorithm, but there are more variation of LBP, which may results more accuracy.

6.2 Future work:

Face detection: in this project I have extracted faces from images using third party tools, also resize them. But this could be done automatically by adding another sub system to the project. Face detection can be done using LBP, but we should choose a good classifier and more images of face and non face, and for the classifier SVM will work fine, and will be good is there is less number of training images.

Face recognition from video : in this project recognition is done from images, also it can be done in video by taking frames images and then detect faces and then feed it to the program. But using euclidean distance will result very slow recognition, to solve this a faster classifier can be used, like SVM.

Recognition is other image: I have used human faces for recognition, but LBP can be used in many types images, like texture recognition and also other object recognition.

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