ValleyScript: It's Like Static Typing

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Abstract

We formalize the ES4 notions of like types and wrap operators for a lambda-calculus with ES4-style objects, to better understand these concepts and to clarify what guarantees can be provided by the verifier in strict mode.

1 Change Log

- 6 Oct: extended with generic function, as a warm-up for implementing all this in the verifier.
- 8 Nov: extended with conversion from Int to Bool.
- 14 Nov: extended with generic functions.
- 14 Nov: added wrap as a type constructor.
- 20 Nov: rework based on allocated and current types
- todo: add typedefs, rework verifier and optimizer

2 Language Overview

We consider the implementation of a gradual typed language that supports both typed and untyped terms, which interoperate in a flexible manner. We begin by defining the syntax of terms and types in the language: see Figure 1. In addition to the usual terms of the lambda calculus (variables, abstractions, and application), the language also includes constants and expressions to create, dereference, and update objects. It also includes is expressions, which check that a value has a particular type, and wrap expressions, which, if necessary, wrap the given value to ensure that it behaves like it has that type.

The type language is fairly rich. In addition to base types (Int and Bool), function types, and object types, the language includes additional types related to gradual typing. The type * is (roughly) a top type, and indicates that no static type information is known. The type 1 ike T describes values whose value components match T, but whose type components may be more vague than T, due to the presence of the type *. (Due to imperative constructs, that matching-value guarantee does not persist, and so 1 ike types are helpful for debugging but do not provide strong guarantees.)

We include generic function definition, generic function application, and the associated polymorphic types and type variables.

Figure 1: Syntax

```
e ::=
                                                         Terms:
                                                      constant
         c
                                                       variable
         \boldsymbol{x}
         \lambda x:S. e:T
                                                   {\bf abstraction}
         e e
                                                   application
         \Lambda X.\,e:T
                                             generic function
         \begin{aligned} e[T] \\ \{\bar{l} = \bar{e}\} : T \end{aligned}
                                         generic application
                                           object expression
         e.l
                                           member selection
        e.l()
                                         member invocation
         e.l := e
                                             member update
         e \, \, \mathtt{is} \, \, T
                                        dynamic type check
         e \; \mathtt{wrap} \; T
                                           wrapping a value
                                                    Constants:
c ::=
         n
                                            integer constant
         b
                                            boolean constant
S,T ::=
                                                          Types:
         Int
                                                       integers
                                                      booleans
         Bool
         S \to T
                                                function type
         X
                                                 type variable
         \forall X. T
                                      generic function type
         \{\bar{l}:\bar{T}\}
                                                 object types
                                                dynamic type
         \mathtt{like}\ T
                                                     like types
         \mathtt{wrap}\ T
                                                   wrap types
```

3 Compatible Types

Figure 2: Compatible Types

The judgement $S \sim: T$ (S is compatible with T) checks if values of type S can be assigned to a variable of type T. It is analogous to the usual subtype relation, but somewhat more complex because of like and *. The type * is a top type, and we have width-subtyping on opjects.

The compatibility relation is intransitive since Int \sim : * and * \sim : like Bool, but Int \sim : like Bool does not hold.

It is similar to the consistency relation of Siek and Taha, but differs in that whenever a down-conversion is performed via [CL-Dyn], the type constructor like is inserted to record this fact. Thus, in general, a type T denotes only values of type T, but like T denotes a somewhat larger set of values.

Although the subtyping judgement does not include an explicit environment, the rule [S-GENERIC] means that the types may include free type variables. This rule applies implicit alpha-renaming so that the same type variable can be interpreted as the same on both sides.

The like type constructor is convariant via [CL-Like].

We have (like T) \sim : (like like T), but not the converse, so like like T is somewhat useless. We could add extra rules to covert like like T to like T, but it seems unnecessary.

 $\frac{\text{like } T \sim: \text{like } T}{\text{like } T \sim: \text{like like } T}$

4 Evaluation

We next describe the evaluation semantics of the language. The set of values in the language is given by:

A object store σ maps object addresses a to object values of the form $\{\bar{l} = \bar{v}\} : T$. Values and object values in the store are *closed* in that they do not contain free program variables x or type variables X; though they may contain object addresses.

Every value has an allocated type according to the function $aty_{\sigma}(v)$:

$$\begin{array}{rcl} aty_{\sigma}(n) & = & \text{Int} \\ aty_{\sigma}(b) & = & \text{Bool} \\ aty_{\sigma}(\lambda x \colon S \colon e \colon T) & = & (S \to T) \\ aty_{\sigma}(\Lambda X \colon t \colon T) & = & (\forall X \colon T) \\ aty_{\sigma}(v \text{ wrapped } T) & = & T \\ aty_{\sigma}(a) & = & T & \text{if } \sigma(a) = \{ \ldots \} \colon T \end{array}$$

In addition, every value has a current type $cty_{\sigma}(v)$, whose definition is identical to $aty_{\sigma}(v)$, except for objects:

$$cty_{\sigma}(a) = \{l_i : T_i\}$$
 if $\sigma(a) = \{l_i = v_i\} : S$ and $T_i = cty_{\sigma}(v_i)$

The allocated type of an object is invariant and never changes; the current type of an object changes over time but is more precise in the case of objects.

A type tag is a type that can be returned by $aty_{\sigma}(v)$ or $cty_{\sigma}(v)$; in particular, it excludes *, like, and wrap types, and type variables.

An evaluation context is:

A *state* is a pair of an object store and a current expression. The evaluation relation on states is defined by the rules in Figure 3. The rule [E-Alloc] requires an explicit object type with a type for each field, but those field types could simply be *. (Note, fields can never be deleted in our semantics.)

Several rules refer to the function $convert_{\sigma}(v,T)$, which checks if the value v can be converted to the type T: see Figure 4.

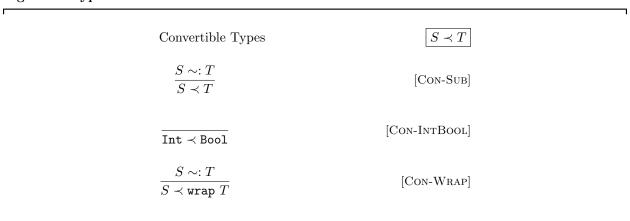
Figure 3: Evaluation Rules

```
\sigma, C[(\lambda x : S. \ t : T) \ v] \longrightarrow \sigma, C[t[x := v'] \ \text{is} \ T] \quad \text{if} \ v' = convert_{\sigma}(v, S)
                                                                                                                                                            [E-Beta1]
         \sigma, C[(w \text{ wrapped } (S \to T)) \ v] \longrightarrow \sigma, C[(w \ (v \text{ wrap } S)) \text{ wrap } T]
                                                                                                                                                            [E-Beta2]
                          \sigma, C[(\Lambda X.\, t:T)[S]] \quad \longrightarrow \quad \sigma, C[t[X:=S] \text{ is } T[X:=S]]
                                                                                                                                                            [E-Generic1]
         \sigma, C[(w \; \mathtt{wrapped} \; (\forall X.\, S))[T]] \quad \longrightarrow \quad \sigma, C[w[T] \; \mathtt{is} \; S[X := T]]
                                                                                                                                                            [E-Generic2]
                                      \sigma, C[v \text{ is } T] \longrightarrow \sigma, C[v] \text{ if } aty_{\sigma}(v) \sim: T
                                                                                                                                                            [E-As]
                                  \sigma, C[v \text{ wrap } T] \longrightarrow \sigma, C[v'] \text{ if } v' = convert_{\sigma}(v, \text{wrap } T)
                                                                                                                                                            [E-Wrap]
                   \sigma, C[\{l_i = v_i^{i \in 1..n}\} : T] \quad \longrightarrow \quad \sigma[a := (\{l_i = v_i'\} : T)], C[a]
                                                                                                                                                            [E-Alloc]
                                                                         where T = \{l_i : T_i^{i \in 1..n}\}, \ v_i' = convert_\sigma(v_i, T_i)
                                                                         and a fresh
                                            \sigma, C[a.l] \longrightarrow \sigma, C[v] if \sigma(a) = \{l = v, ...\} : T
                                                                                                                                                            [E-Get1]
        \sigma, C[(w \; \mathtt{wrapped} \; \{l:T,\ldots\}).l] \quad \longrightarrow \quad \sigma, C[(w.l) \; \mathtt{wrap} \; T]
                                                                                                                                                            [E-Get2]
                                         \sigma, C[a.l()] \quad \longrightarrow \quad \sigma, C[(a.l) \ a]
                                                                                                                                                            [E-Call]
                                    \sigma, C[a.l := v] \longrightarrow \sigma[a, l := v'], C[v]
                                                                                                                                                            [E-Assign1]
                                                                        where if \sigma(a) = \{...\}: \{l:T,...\}
then v' = convert_{\sigma}(v,T)
else v' = v
                                                                                                                                                            [E-Assign2]
\sigma, C[(w \; \mathtt{wrapped} \; \{l:T,\ldots\}).l := v] \quad \longrightarrow \quad \sigma, C[w.l := (v \; \mathtt{wrap} \; T)]
```

Figure 4: Dynamic Type Checks

5 Strict Mode Type System

Figure 5: Type Relations



In a traditional statically typed language, the type system fulfills two goals:

- 1. It detects certain errors at compile time.
- 2. It guarantees what kinds of values are produced by certain expressions, which enables run-time check elimination.

The situation in ES4 is somewhat different, because of two reasons. First, in **standard** mode, we would like to eliminate run-time checks where possible, using a type-based analysis, without reporting any compile-time type errors. Second, **like** types weaken the guarantees provided by **strict** mode. For these reasons, we actually present *two* type systems.

For example, if a variable x has type like $\{f : \mathtt{Int}\}$, then x.f could actually return a value of any type. Nevertheless, x.f would be expected to produce values of type \mathtt{Int} , and so the expression x.f.g would yield a compile-time type error. Thus, we say that x.f has type \mathtt{Int} , but this type is only a statement of intent; it does not guarantee what kinds of values are returned by that expression, and so cannot be used for run-time check elimination.

The strict mode type system is based on a judgement $E \vdash e : T$, stating that expression e has type T in environment E. Note that the type T only indicates that e is intended to produce values of type T; there are no guarantees here, due to the use of like types. Thus, the strict mode type system If T is not a like type, then e will only produce values of that type. If T = like T', then the intent is that e will only produce values of type T', but there is no guarantee. However, this intent can be still used to detect type errors at compile time.

Note that the judgement $E \vdash e : T$ means that e is *expected* to only produce values of type T, and the purpose of the strict mode type system is only to heuristically detect errors at verification time. The following section presents a type system with stronger guarantees that are sufficient for removing some run-time type checks.

If $E \vdash e : T$, then T is not a like or wrap type (at least at the top level).

Figure 6: Type Rules for Strict Mode

$$\begin{array}{c} \underline{T} \text{ype rules} & \underline{E} \vdash t : T \\ \\ \underline{K} \vdash x : T & \\ \\ \underline{E} \vdash x : S \vdash e : T' \quad T' \prec T \\ \underline{E} \vdash x : S \vdash e : T : S \vdash x \\ \underline{E} \vdash x : S \vdash x \\$$

6 Check Optimization

We now sketch a type-based analysis that statically identifies dynamic type checks that can be eliminated. We introduce the following additional "safe" expression forms, for which run-time checks are unnecessary.

```
Expressions:
e ::=
                                      expressions mentioned earlier
        \mathtt{safe}\ x
                                                           safe variable
        safe \lambda x : S. e : T
                                                       safe abstraction
                                                       safe application
        \mathtt{safe}\;e\;e
        \mathtt{safe}\ \{ar{l}=ar{e}\}:T
                                               safe object allocation
                                                    safe field selection
        \mathtt{safe}\ e.l
        \mathtt{safe}\ e.l := e
                                                      safe field update
                                                                  Values:
v ::=
                                            values mentioned earlier
        safe \lambda x:S. e:T
                                                       safe abstraction
```

It is straightforward to formulate the operational semantics of the extended language.

Figure 7 presents *optimization rules*, which verify that **safe** ... occurs in correct places; it is straightforward to reformulate the analysis to infer these **safe** annotations.

The following lemmas remain to be proven.

Lemma 1 (No Failure) For any term e, there is some placement of safe annotations into e yielding e' such that $\emptyset \vdash e' : T$ for some T.

Lemma 2 (Soundness) If $\emptyset \vdash e : T$, then safe operation in e can never get stuck.

Figure 7: Type Rules for Optimization

$$E \vdash t : T$$

$$(x : T) \in E$$

$$E \vdash safe x : T$$

$$[O-VAR-SAFE]$$

$$E \vdash x : *$$

$$[O-VAR-UNSAFE]$$

$$E \vdash x : *$$

$$[O-CONST]$$

$$E, x : S \vdash e : T' \qquad T' \sim : T$$

$$E \vdash safe (\lambda x : S. e : T) : (S \rightarrow T)$$

$$E \vdash (\lambda x : S. e : T) : (S \rightarrow T)$$

$$E \vdash (\lambda x : S. e : T) : (S \rightarrow T)$$

$$E \vdash (\lambda x : S. e : T) : (S \rightarrow T)$$

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$$E \vdash (\lambda x$$