#### Error:

Avg: 0.905 mm / 0.202 deg Min: 0.187 mm / 0.079 deg Max: 1.786 mm / 0.353 deg

## Translation (meters):

x: 0.05193987652344801 y: -0.03235963828608199 z: 0.02119829324133516

# Totation (Quaternion):

X: 0.005495619037264013 Y: -0.001944485813654647 Z: 0.7084353613467589 W: 0.7057516248226461

# Rotation (Axis-Angle):

theta(x): 0.01221459299495472 theta(y): -0.004321824827595642 theta(z): 1.574572317223857

### Rotation (RPY):

R: 90.21595366019204 P: -0.6034061724277683 Y: 0.2866105273320089

### Rotation (Rotation Matrix):

 $-0.003768884463184431 -0.99998018701109737 \ 0.0050419336721138118 \\ 0.99993744239807658 -0.0038217260702308998 -0.01051216914997084 \\ 0.01053122976183922 \ 0.0050019991098505349 \ 0.99993203429263555$