

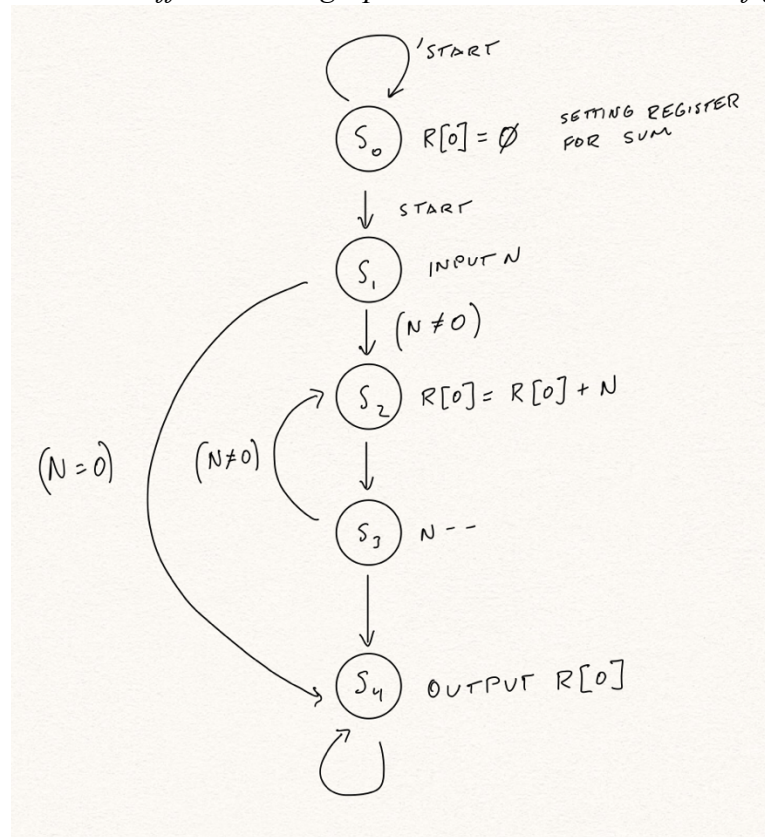
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Instructor's comments:			

Introduction / Theory of operation

- For this lab experiment, we will be designing the control unit for the GDP that was designed in lab experiment #6. We will be creating the CU module to implement the summation algorithm, instantiate it within the top-level GDP module, verify it with a testbench and waveform and display it on the DE2 board.

Prelab main content

1. Implement a state graph for the summation algorithm and verify it with fig 4. Is it possible to have a different state graph than the one mentioned in fig 4?



It is not possible to have a different state graph than the one mentioned in fig 4. This is because the state graph follows specific steps, states and next states in order to implement the algorithm.

2. Implement the control words for the state graph that you created in 1 and verify it with fig 6. Is it possible to have a different control words than the one mentioned in fig 6?

CW 1	$R[0] = 0$	0	1	0	0	1	0	0	1	0	1	0	0	0
CW 2	INPUT N	1	1	0	1	0	x	x	0	x	x	x	x	0
CW 3	$R[0] = R[0] + N$	0	1	0	0	1	0	0	1	0	1	1	0	0
CW 4	N --	0	1	0	1	1	0	1	0	x	x	1	1	1
CW 5	OUTPUT R[0]	x	0	x	x	1	0	0	0	x	x	0	0	0

It is possible to have different control words because someone may use different registers to store the value of sum and input n. Changing the register will cause a change in the control words. Instead of 00, one may use 01, 10, or 11 this will cause the control words to be different than the control words that I created.