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Other types of learning

- Agnostic learning (model-free)
- Adversarial learning

In this scenario the target $C^*(or\ f^*)$ may not be in $C(or\mathfrak{F})$

The setup for learning involves the following components

- Sets x,y,u
- The distribution \mathcal{P} on $x \times y$
- The function class $\mathfrak{F}(or\ C) = \{f : x \to u\}$
- loss $l: y \times u \to [0,1]$

The process for learning generally involves the following steps

- 1. Get sample iid $Z^n = (z_1, \dots, z_n); \quad z_i \stackrel{iid}{\sim} p \in \mathcal{P}$
- 2. Let Algorithm $\mathcal{A} = \{A_n\}_{n=1}^{\infty}, \quad A_n : \mathbb{Z}^n \to \mathfrak{F}$
- 3. Form a hypothesis $\hat{f}_n = A_n(Z^n) = A_n((x_1, y_1), \dots, (x_n, y_n))$
- 4. Find expected loss of the hypothesis $L_p(\widehat{f}_n) = \mathbb{E}\left[l(y^{n+1}, \widehat{f}(x^{n+1}) \mid Z^n)\right]$
- 5. Then the "best prediction" is given by $L_p^*(\mathfrak{F}) = \inf_{f \in \mathfrak{F}} L_p(f); \quad 0 \le L_p^*(\mathfrak{F} \le L_p(\widehat{f}_n \le 1))$

We can then define risk as follow

$$r_A(n,\epsilon) = \sup_{p \in \mathcal{P}} p^n(Z^n : L_p(\widehat{f}_n \ge L_p^*(\mathfrak{F} + \epsilon))$$

This is the worst loss over data set.

Example: Noisy Classification

We have $\mathcal{X}, p_x \in \mathcal{P}_{\mathcal{X}}, C^*, C$

- $X^n = (x_1, x_n) \stackrel{iid}{\sim} p_x$
- The classification happens with a probability, $y_i = \begin{cases} I(x_i \in C^*), & w.p. & 1-\eta \\ 1 I(x_i \in C^*), & w.p. & \eta \end{cases}$
- $\eta < \frac{1}{2}$ is the noise rate
- $y = u = \{0, 1\}, \quad \mathfrak{F} = \{I_c : c \in \mathcal{C}\}$
- A loss function $l(y, u) = |y u|^2$
- Set of probabilites $\{p_{x,c}: p_x \in \mathcal{P}_x, c \in \mathcal{C}\}$

$$p_{y \mid x,c}(1 \mid X = x,c) = (1 - \eta)I(x \in c) + \eta I(x \in c^{\complement})$$

= $(1 - \eta)I(x \in c) + \eta (1 - I(x \in c))$

$$p_{y \mid x,c}(0 \mid X = x, c) = 1 - P_{y \mid x,c}(1 \mid X = x, c)$$

= $\eta I(x \in c) + (1 - \eta)(1 - I(x \in c))$

So, for any $A \subseteq x$

$$p_{x,c}(A \times 1) = \int_{A} p_{y \mid x,c}(1 \mid X = x) \quad p_{x}(dx)$$

$$= \int_{A} (1 - \eta)I(x \in C) + \eta(1 - I(x \in C)) \quad p_{x}(dx)$$

$$\dots = \eta p_{x}(A) + (1 - 2\eta)p_{x}(A \cap C)$$

Similarly,

$$p_{x,c}(A \times 0) = (1 - \eta)p_x(A) - (1 - 2\eta)p_x(A \cap c)$$

The loss of some hypothesis c' for any c can be written as

$$L_{p_{x,c}}(I_{c'}) = \int_{x \times \{0,1\}} |y - I(x \in c')|^2 \quad p_{x,c}(dx \ dy)$$

$$= \int_X |0 - I(x \in c')|^2 \quad p_x(dx \times \{0\}) + \int_X |1 - I(x \in c')|^2 \quad p_x(dx \times \{1\})$$

$$= \int_X I(x \in c') \quad p_x(dx \times \{0\}) + \int_X I(x \in (c')^{\complement}) \quad p_x(dx \times \{1\})$$

$$= p_{x,c}(c' \times \{0\}) + p_{x,c}((c')^{\complement} \times \{1\})$$

$$= (1 - eta)p_x(c') + (1 - 2\eta)p_x(c' \cap c) + \eta p_x((c')^{\complement}) + (1 - 2\eta)p_x((c')^{\complement} \cap c)$$

$$= \dots = \dots$$

$$= \eta + (1 - 2\eta)L_{p_x}(c', c)$$
The loss can be approximated using $p_{x,c}(c\Delta c')$

The best hypothesis can then be given by

$$L_{p \times c}^*(c) = \inf_{c' \in c} L_{p \times c}(c')$$

$$= \eta + (1 - 2\eta) \inf_{c' \in c} p_{x,c}(c\Delta c')$$

$$= \eta \quad \text{if (c'=c)}$$

Thus, an infimum is achieved at c' = C.

$$L_{p \times c}(c') \ge L_{p \times c}^* + \epsilon$$

 $p_{x,c}(c\Delta c') \ge \frac{\epsilon}{1 - 2\eta}$

A noisy classification to some accuracy ϵ is like noise free classification to accuracy $\frac{\epsilon}{1-2\eta}$. Since $(1-2\eta)$ is very small so the bound is larger.

Noisy classification is more difficult than noiseless classification.