

Requirements

- Identifies the what of the system, not the actual implementation
- Functional requirements:
 - What is the software supposed to do
 - ↳ I/O relationship, sequence of execution, validity check
 - Interaction with people / APIs / Hardware
 - ↳ Screen size, destination of outputs, sources
- Non-functional requirements:
 - Performance (speed, response time)
 - Quality (correctness, security, availability)
 - Constraints (Environment, standards)
- System design: Split into different components
 - Software architecture as a composition of sub systems
 - Components and connectors
- Detailed Design: specify that components
 - Implementation strategy
 - Data structures, Algorithms & subclasses
 - ↳ Is null accepted
 - What can that method return?
 - Will the implementation be thread safe
- Initialization
 - Lazy: delay creation of an object, calculation of a value or something other expensive until the first time it's needed

- If object is accessed, it is checked if member is null or not
- A lot of comparisons
- Faster startup speed

Immediate: Do the things when object is created

- copy on write: Example shared lists

- Multiple callers ask for same resource
- Give all callers same pointer
- When a caller tries to modify its "copy" of resource, at which point a true private copy is created (copied) to prevent the changes becoming visible to everyone else.
- Example shared lists:

• Reference counting: global object
 • shared boolean: if one copies the list shared = true, if an element is changed, copy list and shared = false on copied object

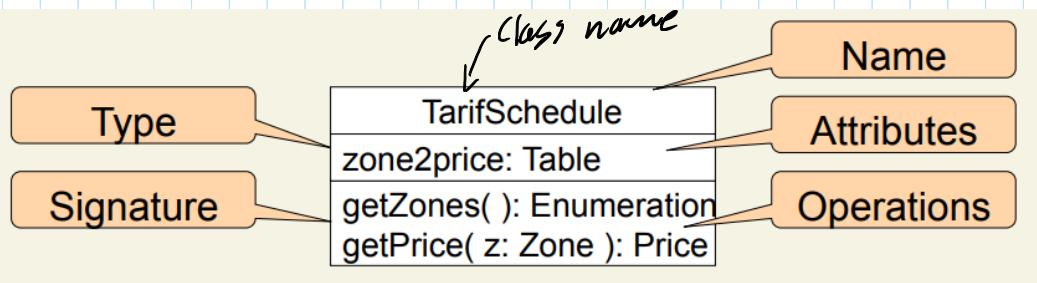
- Documentation

- For implementers:
 - How does the code work
 - Includes hidden methods
- For clients:
 - How to use the code/interface
 - Constructors / Methods / Supertypes
 - Clients need to know how to call a method correctly and how it affects the state
 - No internal information

Informal Modelling

UML (=Unified modeling language)

- Static model: describes structure of a system
- Dynamic model: describes behavior of a system



- A link between two classes represent (=Associations)

- Ability to send messages
- Object A has an attribute whose value is B
- Object A creates object B
- Object A receives a message with object B as value

- Multiplicity of associations

- Exact numbers
- Arbitrary numbers: * (=zero or more)
- Range: 1..3, 1..*

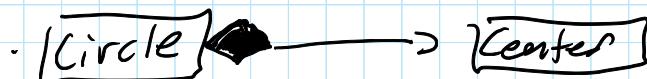
1-to-many association



- Visibility :

The diagram shows a directed association from "Person" to "Company". The arrow is labeled "Person knows about company".

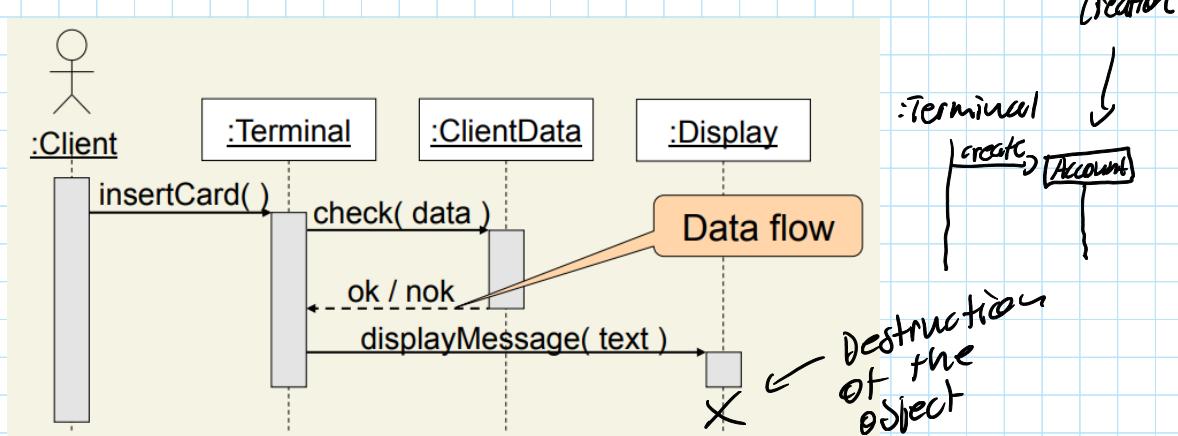
- Composition: - "Has-a" relationship



- Generalization:
 - "is-a" relationship
 - The child inherits the attributes and methods of the parent
 - **[Rectangle] ← child → [Polygon]** ← Parent

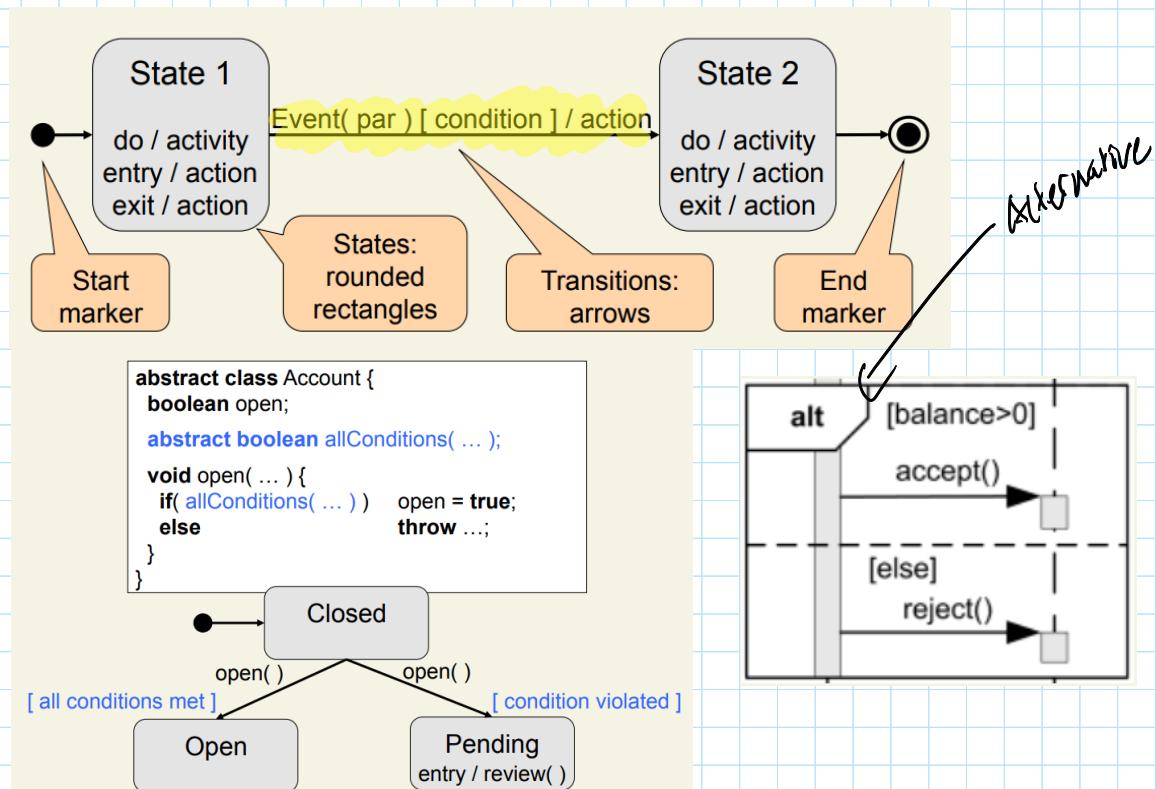
- Sequence Diagram

- Describes collaboration between objects



- State Diagram

- Describes a lifetime of a single object



- Object Constraint Language (=OCL)

```
context SavingsAccount inv:  
self.balance >= 0
```

```
context CheckingAccount inv:  
self.owner.age >= 18
```

Method of class account

```
context Account::Withdraw( a: int )  
pre: a >= 0  
post: GetBalance( ) = GetBalance@pre( ) - a
```

old value

Context specifies method signature

Suffix @pre is used to refer to prestate values

} · Invariants

· SavingsAccount is a class

} · Pre- and Postconditions of a method

Formal Modeling

- Class: sig FSObject { ... }
- Abstract class: abstract sig FSObject { ... }
- Subclass: sig file extends FSObject { ... }
- Class cardinalities:
 - none (zero)
 - one (one) e.g. one sig Root
 - lone (zero/one)
 - some (one/two/three)
 - set (zero/one/two/...)
- Set operations:
 - + (union)
 - & (intersection)
 - - (difference)
 - in (subset)
 - = (Equality)
 - # (Cardinality)
 - none (Empty set)
- Fields:
 - Declares attributes and relations
 - sig Customer {
 isPremium: Bool,
 address: one Address
 ↳ Refers to sig Address
 - sig University {
 enrollment: Student set -> one Program
 }

- Relation operations:
 - \rightarrow (cross product)
 - $\cdot \cdot$ (relational join)
 - \curvearrowleft (Transposition / Inverse)
 - \curvearrowright (Transitive closure)
 - $\#$ (reflexive transitive closure)
 - \subset : (Domain restriction)
 - \supset : (Range restriction)
 - \leftrightarrow (override)
 - Quantification:
 - all $x : e | F$
 - some $x : e | F$
 - no $x : e | F$
 - lone $x : e | F$
 - one $x : e | F$
 - Predicates:
 - Return true/false
 - pred is Premium [c:customer] {
c.isPremium = true}
 - Functions:
 - Return instances of a predicate
 - fun getAllOrders [c:Chef] : set Order {
c.Order
 >Returns orders}
 - Facts:
 - constraints to model
 - fact pizza {
all p: Pizza | one o: Order | p in o.pizza
3 // A pizza can only be assigned to one order}

- Scopes: · run is primed for S
structure of given size
- Dynamic Behavior: · choose a sig counter as global state
 - Add ordering util/ordering [Counter]
 - Add initialisation of the first global state pred init [c: counter]
 - Add all transition predicates:
 $\text{pred increase } [c, c' : \text{counter}, i : \text{int}] \{$
 $c'.\text{max} = c.\text{max}$ *bc*
 $c'.\text{count} = c.\text{count} + i$
 $\}$
 - Add execution fact:
~~fact execution {~~
~~init[first] & & last element~~
~~all c: counter - last |~~
~~(some i: int | increase [c, c.next, i]) ||~~
~~(other predicates)~~
 $\}$

- To add a file: c.objects + obj1
- To say that there are no files: no c.objects
 ↳ for initialisation
- If $[s, s']$ s is lower than s'

Modularity

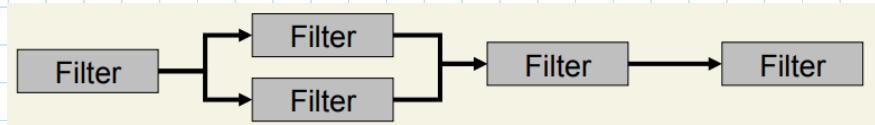
- Coupling: measures independence between different modules
 - Tightly coupled:
 - cannot developed, tested, changed, understood or reused in isolation
 - Exposing internal data is indicator for tightly coupled
 - Data representation is difficult to change during maintenance
 - ↳ Use getter/setter methods instead to hide implementation
- 
- 

Avoid exposure of sub-objects

- Do not return references to sub-objects
- Do not store arguments as sub-objects
- Facade Pattern
 - Use an API to access system
 - Encapsulates subsystem from Client
 - Offers easy methods to client
- Flyweight pattern:
 - Creating an object for each character in the document is costly
 - Define flyweight object that can be shared and is immutable

- Pipes and Filter Pattern

- Used for data-streams



- Filter: - Read data from input port, calculate something and output it into the pipe

- ## Pipe: - Streams

- First-in-first-out buffer

- Data is processed incrementally as it arrives
 - No shared data => filters are independent
 - Not appropriate for interactive data
 - Filters can be easily added or replaced
 - Potential for parallelism

Tightly coupled methods

- If one module (caller) calls another module (callee)
 - Callers cannot be reused without callee modules
 - Change in callee \Rightarrow potential change in caller

→ Solutions: Move code

- Duplicate functionalities to avoid dependencies
 - Event-based architecture
 - Components generate events
 - e.g. User interfaces
 - Implemented by Observer pattern

- Observer pattern: Subject maintains a list of its dependents, called observers and notifies them of any state change by calling one of their methods => generation of an event

- Model-view-controller: · Model: - contains core functionality and data

· View(s): - display information to user
- Bar, charts, tables, etc.

· Controller(s): - handle user input
· Updates via events

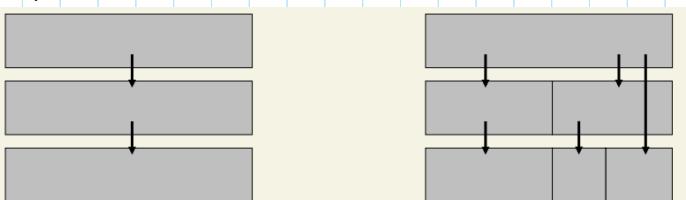
- Event based style: · Strong support for reuse, plug in new components by registering for events

· Add/remove components with no effect on other components
· What component will respond to what event?

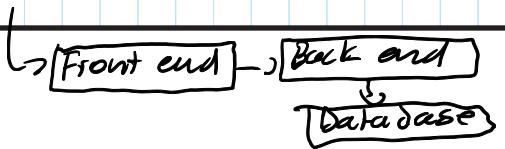
↳ Loss of control

- Restricting calls: · Enforce a policy that restricts which other modules a module may call

· Example: layered architecture



· Example: - three-tier architecture



Inheritance

- Extend functionality of a class by creating a subclass

↳ Introduces dependencies

- Aggregation:
 - If we need to override a lot of functionality use aggregation
 - class Cat {

Eat = dog.eat } Aggregation
Walk = dog.walk }
 }

- Using Interfaces:
 - Replace class name by most general supertype that offers all required operations
 - ↳ TreeMap<Ident, Type> ⇒ Map<Ident, Type>
 - ↳ SymbolTable() {
 - types = new TreeMap<Ident, Type>
 - } convert to

SymbolTable(Map<Ident, Type> +) {
types = +

} to shift problem to client

- Delegation Allocation:
 - Hand over responsibility for a task to another class (=Fabric)
 - AbstractFactory is called for a particular object
 - AbstractFactory calls a concrete factory to generate concrete object

Adaptation

- Sometimes need to change software architecture
- For example new interfaces/features
- Parameterization:
 - prepare modules for changes
 - use variable values instead of constant ones
 - `stringstream f1 => stringstream [J streams]`
 - use generic types
 - ↳ `Filter<D> [J filters]`
 - Static:
 - Nur ein Mal in ganzer Klasse, also alle Objekte zeigen auf gleiche Speicherstelle
 - static method can be accessed without the creation of the corresponding object
 - can access static variables
 - Static Binding:
 - Can be resolved at compile time
 - static / private / final methods
 - cannot be overridden
 - compiler has no difficulties determining object of class
 - static methods / variables cannot be overridden by subclasses
 - Dynamic Binding:
 - Is resolved at run-time
 - used for case distinction
 - class RegularMovie extends Movie {
 int getCost() { return 10; }
 - Dynamic method binding is a case distinction on the dynamic type of the receiver object.

distinction on the dynamic type of the receiver object.

Testing

- Unit Test (JUnit) for detailed design module

[Test] ✓ ~~OK~~

```
public void withdrawTest( int balance, int amount ) {
    SavingsAccount target = new SavingsAccount();
    target.deposit( balance );
    target.withdraw( amount );
    Assert.IsTrue( target.getBalance() == balance - amount );
}
```

- assertEquals(x,y)

- assertTrue(bool)

- assertArrayEquals([S],[S])

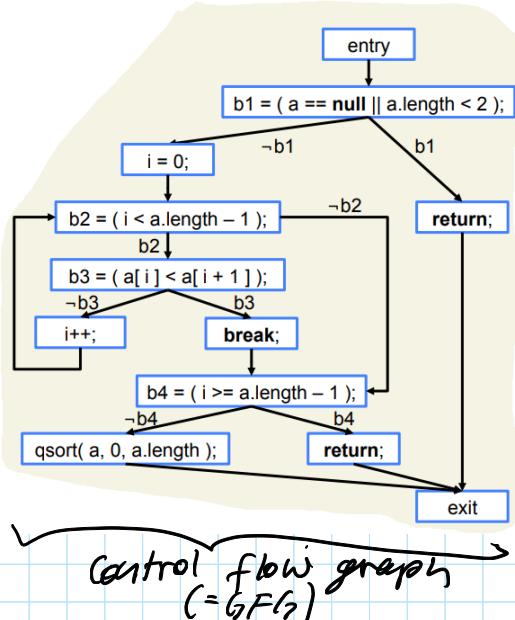
- Functional testing: Black-box for covering all requirements
- Structural testing: White-box for covering all code
- Random testing: Black-box for covering all corner-cases
- For exceptions: @Test(expected = exception.class)
- You can add many assertEquals(1, method()) into one method.

Structural Testing

- Use design knowledge to cover most of the code

```
public void sort( int[ ] a ) {
    if( a == null || a.length < 2 )
        return;
    int i;
    for( i = 0; i < a.length - 1; i++ ) {
        if( a[ i ] < a[ i + 1 ] )
            break;
    }
    if( i >= a.length - 1 )
        return;
    qsort( a, 0, a.length );
}
```

Basic blocks



control flow graph
($= GFG$)

- The more parts of a CFG are executed, the higher the chance is to find a bug
- Statement coverage: $\frac{\# \text{executed blocks}}{\# \text{total blocks}}$

• entry/exit not counted as block

- Branch coverage: $\frac{\# \text{executed branches}}{\# \text{total branches}}$



- Path coverage: $\frac{\# \text{executed paths}}{\# \text{total paths}}$

- A path is a sequence of blocks from $n_1 = \text{entry}$ to $n_k = \text{exit}$
- An arbitrary large number of test cases is needed to complete path coverage for loops

- Loop coverage: $\frac{\# \text{of executed loops with 0, 1, and more than one iteration}}{\# \text{number of loops} + 3}$

- Loop coverage \Rightarrow path coverage \Rightarrow branch coverage \Rightarrow statement coverage

- Exceptions

- Treat as block with arrow to exit

• checked exception: - Need to be caught

- At compile time
- e.g. FileNotFoundException

} Regular control flow

{ • unchecked exception: - At run-time

- division by zero

- Not supposed to occur

} Ignore this type of exception

- Definition clear path

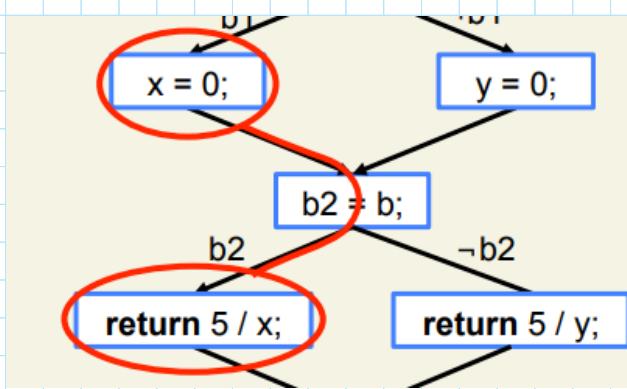
- No altering of a specific variable

- n_1 is the definition of the variable

- n_k alters the variable

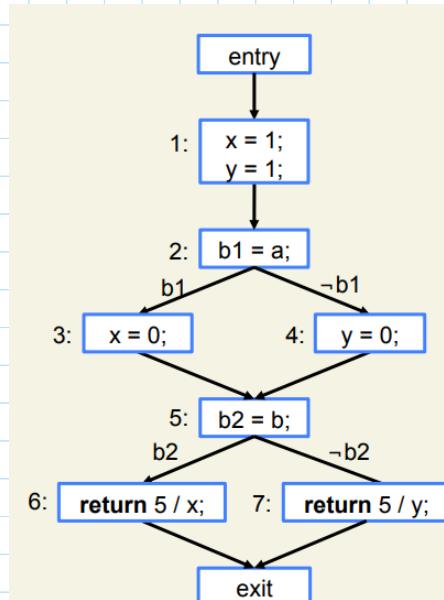
- Definition-use pair (=DUI-pair)

- Variable - v
- Pair of nodes (d, u) such there is a definition-clear path



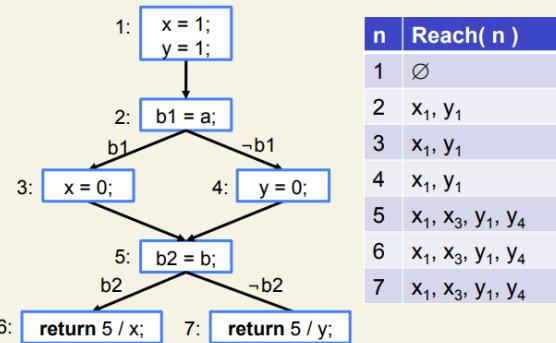
- Static reaching-definition analysis

- The reaching definitions at a node n are:
 - The reaching definitions of n's predecessors in the CFG
 - minus the definitions killed by one of n's predecessors
 - plus the definitions made by one of n's predecessors
- $\text{pred}(n) = \{ m \mid (m, n, c) \text{ is an edge in the CFG} \}$
- $\text{succ}(m) = \{ n \mid (m, n, c) \text{ is an edge in the CFG} \}$
- $\text{gen}(n) = \{ v_n \mid n \text{ is a variable definition for } v \}$
- $\text{kill}(n) = \{ v_m \mid n \text{ is a variable definition for } v \text{ and } m \neq n \}$
- $\text{Reach}(n)$: The reaching definitions at the beginning of n
- $\text{ReachOut}(n)$: The reaching definitions at the end of n



n	Reach(n)	ReachOut(n)
1	\emptyset	x_1, y_1
2	x_1, y_1	x_1, y_1
3	x_1, y_1	x_3, y_1
4	x_1, y_1	x_1, y_4
5	x_1, x_3, y_1, y_4	x_1, x_3, y_1, y_4
6	x_1, x_3, y_1, y_4	x_1, x_3, y_1, y_4
7	x_1, x_3, y_1, y_4	x_1, x_3, y_1, y_4

- The set of DU-pairs is easily determined as
 $\{ (d, u) \mid u \text{ is a variable use for } v \text{ and } v_d \in \text{Reach}(u) \}$

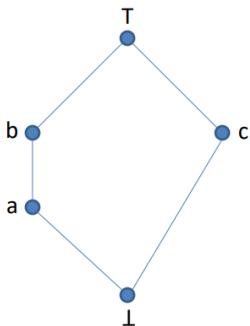


- DU-pairs for x:
 $(1, 6), (3, 6)$
- DU-pairs for y:
 $(1, 7), (4, 7)$

Joins (= A \sqcup B)

- When we have two abstract elements A and B, we can join them
- $A \sqsubseteq A \sqcup B$ & $B \sqsubseteq A \sqcup B$
- Cannot always reach a fixed point \Rightarrow widening

Poset (=Partially ordered set)



- T: ·TOP

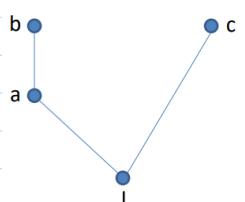
·includes everything else

- \perp : ·Bottom

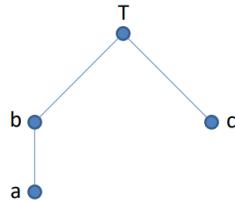
$\{ (\perp, a), (\perp, c), (a, b), (b, T), (c, T),$
 $(a, a), (b, b), (c, c), (T, T), (\perp, \perp),$
 $(\perp, b), (\perp, T), (a, T) \}$

$\left. \begin{array}{l} \perp \sqsubseteq a \\ \perp \sqsubseteq c \end{array} \right\} \begin{array}{l} T \text{ contains} \\ \text{everything} \end{array}$
 $\perp \sqsubseteq \perp$

- Least/greatest element may not exist, but if they do, they are unique



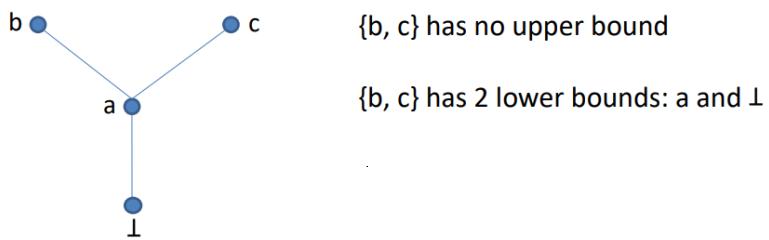
No greatest element



No least element

? a and c are on the same level

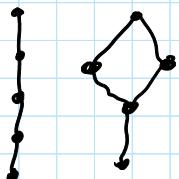
Bounds in Posets



- {c} has as upper bound {a, d}
 - has as lower bound {d, f}
 - has as least upper bound {b} (L)
 - has as greatest lower bound {d, f} (H)
- ⇒ We write $p \sqcap q$ for $\sqcap\{p, q\}$

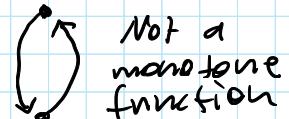
Complete Lattice

- A Poset in which each element has a \sqcap & \sqcup



Monotone Function

- $d \sqsubseteq d' \Rightarrow f(d) \sqsubseteq f(d')$



Fixed Point

- x is a fixed point, iff $f(x) = x$

All fixed points are post-fixed points

- x is a post-fixed point, iff $f(x) \sqsubseteq x$ ($= f(x) \leq x$)

Least fixed point

- smallest fixed point

- fixed point which is less than all other fixed points

Tarki's fixed point theorem

- complete lattice + monotone function \Rightarrow Least-fixed point exists

Approximating a function

- Concrete C
- Abstract A (=approximates the concrete function)
- $\alpha: C \rightarrow A$ (=abstraction function)
- $\gamma: A \rightarrow C$ (=concretization function)

Abstract Interpretation

1. Select abstract domain

e.g. interval domain

- $[a, b] \sqsubseteq_i [c, d]$ if $c \leq a$ and $b \leq d$
- $[a, b] \sqcup_i [c, d] = [\min\{a, c\}, \max\{b, d\}]$
- $[a, b] \sqcap_i [c, d] = \text{meet}(\max\{a, c\}, \min\{b, d\})$
where $\text{meet}(a, b)$ returns $[a, b]$ if $a \leq b$ and \perp_i otherwise

$$\alpha^i: \wp(\Sigma) \rightarrow (\text{Lab} \rightarrow (\text{Var} \rightarrow L^i))$$

$$\gamma^i: (\text{Lab} \rightarrow (\text{Var} \rightarrow L^i)) \rightarrow \wp(\Sigma)$$

↗ current label ↗ variable ↗ value
 ↗ of variable
 in abstract domain ↗ Actual program states

```

 $\alpha^i ($ 
{ ⟨1, {x→1, y→9, q→-2}⟩, ⟨1, {x→5, y→9, q→-2}⟩, ⟨1, {x→8, y→9, q→-2}⟩,
  ⟨1, {x→1, y→9, q→4}⟩,   ⟨1, {x→5, y→9, q→4}⟩,   ⟨1, {x→8, y→9, q→4}⟩}
 $) = 1 \rightarrow (x \mapsto [1, 8], y \mapsto [9, 9], q \mapsto [-2, 4])$ 
  
```

↗ Abstraction to intervals

```

 $\gamma^i (1 \rightarrow (x \mapsto [1, 8], y \mapsto [9, 9], q \mapsto [-2, 4]))$ 
= { ⟨1, {x→1, y→9, q→-2}⟩, ⟨1, {x→5, y→9, q→-2}⟩, ⟨1, {x→8, y→9, q→-2}⟩,
  ⟨1, {x→1, y→9, q→4}⟩,   ⟨1, {x→5, y→9, q→4}⟩,   ⟨1, {x→8, y→9, q→4}⟩,
  ⟨1, {x→7, y→9, q→3}⟩,   ⟨1, {x→3, y→9, q→4}⟩,   ⟨1, {x→1, y→9, q→-1}⟩,
  ..., ..., ... }
  
```

↗ can be many more actual states

2. Select abstract semantics

$$F^\# : (\text{Lab} \rightarrow A) \rightarrow (\text{Lab} \rightarrow A)$$

Next state where
transformer
is applied

$$F^\#(m)\ell = \begin{cases} T & \text{if } \ell \text{ is initial label} \\ \bigsqcup_{(\ell', \text{action}, \ell)} [\text{action}](m(\ell')) & \text{otherwise} \end{cases}$$

Transformer
map

Approximation function for concrete program

$$- (v', \text{action}, v) \stackrel{?}{=} (v', a') \rightarrow (v, a)$$

$$\hookrightarrow x := a$$

$$[0, 4] \leq [3, 5] = ([0, 4] \sqcap_i [-\infty, 5], [0, \infty] \sqcap_i [3, 5]) \\ = ([0, 4], [3, 5])$$

\rightarrow Transformer definition

3. Iterate over abstract domain with transformer until we reach fixed point

```

foo (int i) {
    1: int x := 5;
    2: int y := 7;

    3: if (i ≥ 0) {
        4:     y := y + 1;
        5:     i := i - 1;
        6:     goto 3;
    }
    7:
}

```

- 1: $x \rightarrow [-\infty, \infty], y \rightarrow [-\infty, \infty], i \rightarrow [-\infty, \infty]$
- 2: $x \rightarrow [5, 5], y \rightarrow [-\infty, \infty], i \rightarrow [-\infty, \infty]$
- 3: $x \rightarrow [5, 5], y \rightarrow [7, 7], i \rightarrow [-\infty, \infty]$
- 4: $x \rightarrow \perp_i, y \rightarrow \perp_i, i \rightarrow \perp_i$
- 5: $x \rightarrow \perp_i, y \rightarrow \perp_i, i \rightarrow \perp_i$
- 6: $x \rightarrow \perp_i, y \rightarrow \perp_i, i \rightarrow \perp_i$
- 7: $x \rightarrow \perp_i, y \rightarrow \perp_i, i \rightarrow \perp_i$

Not initialized $\stackrel{?}{=} T$

- If we can't reach fixed point \Rightarrow Widening

Widening Operator ($=\nabla$)

- If we see that an endpoint is unstable, we move it to the extreme

- $[1, 2] \triangleright [0, 2] = [-\infty, 2]$
 - $[0, 2] \triangleright [1, 2] = [0, 2]$
 - $[1, 5] \triangleright [1, 5] = [1, 5]$
 - $\overbrace{[2, 3]}^{\text{last state}} \triangleright \overbrace{[2, 4]}^{\text{current state}} = [2, \infty)$

Pointer Analysis

- All objects allocated at the same program point (=loc) get represented by a single abstract object.
 - Flow sensitive:
 - Respect the program order
 - Separate set of points-to pairs for every program point
 - Set represents all possible may-aliases
 - Flow insensitive:
 - All execution orders are possible
 - Good for concurrency
 - We have two mappings:
 - Pointer variable \rightarrow set abstract objects
 - Variable abstract objects \rightarrow set of abstract objects

Flow Sensitive

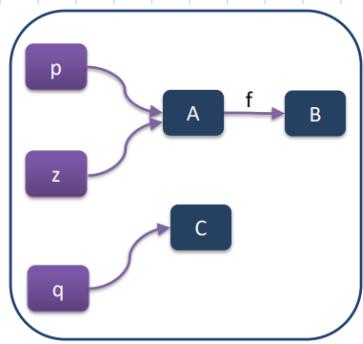
flow Sensitive

Label	Pointer to object	Set symbol
↓		↓ Objects pointer can point to
Labs → ((PtrVar → \wp (AbsObj)) ×	
	(AbsObj × Field → \wp (AbsObj)))	

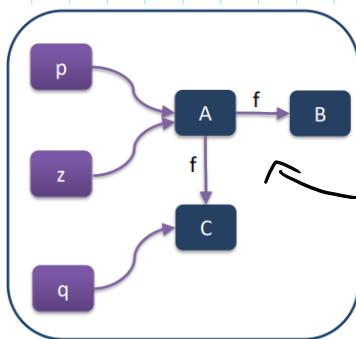
label	object	variable of object
$1 \rightarrow (p \rightarrow \{a_5, a_{10}\}, a_5.f \rightarrow \{a_6, a_9\})$		

$1 \rightarrow (p \rightarrow \{ a_5, a_{10} \}, a_5.f \rightarrow \{ a_6, a_9 \})$

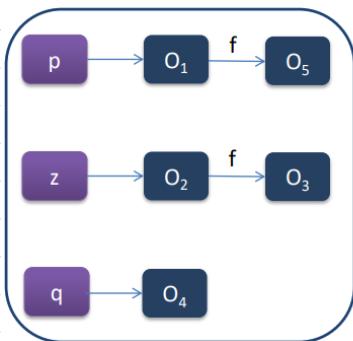
$$1 \rightarrow (p \rightarrow \{a_5, a_{10}, a_{15}\}, a_5.f \rightarrow \{a_6, a_9, a_{52}\})$$



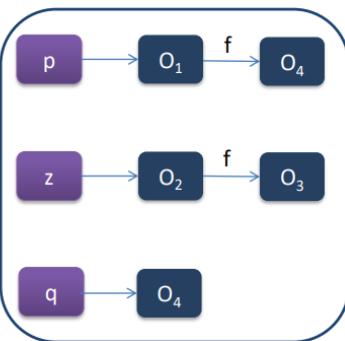
$p.f := q$



Need to take the union



$p.f := q$



- Initial state: $\text{Top} \equiv \{\text{A1}, \text{A2}, \text{null}\}$

- Unreachable object: $\text{Bottom} \equiv \emptyset$

```

p := alloc1; // A1
q := alloc2; // A2
if p=q3 then
    z:=p4
else
    z:=q5

```

$p \mapsto \{\text{A1}, \text{A2}, \text{null}\}$,
$q \mapsto \{\text{A1}, \text{A2}, \text{null}\}$,
$z \mapsto \{\text{A1}, \text{A2}, \text{null}\}$
$p \mapsto \{\text{A1}\}, q \mapsto \{\text{A1}, \text{A2}, \text{null}\}$,
$, z \mapsto \{\text{A1}, \text{A2}, \text{null}\}$
$p \mapsto \{\text{A1}\}, q \mapsto \{\text{A2}\}$,
$z \mapsto \{\text{A1}, \text{A2}, \text{null}\}$
$p \mapsto \emptyset, q \mapsto \emptyset, z \mapsto \{\text{A1}, \text{A2}, \text{null}\}$
$p \mapsto \emptyset, q \mapsto \emptyset, z \mapsto \emptyset$
$p \mapsto \{\text{A1}\}, q \mapsto \{\text{A2}\}$,
$z \mapsto \{\text{A1}, \text{A2}, \text{null}\}$
$p \mapsto \{\text{A1}\}, q \mapsto \{\text{A2}\}, z \mapsto \{\text{A2}\}$

flow sensitive

Flow insensitive

- Does not keep information per label

```

(PtrVar → ⋃ (AbsObj)) ×
(AbsObj × Field → ⋃ (AbsObj))
p := alloc1; // A1      p := alloc1; // A1
q := alloc2; // A2      q := alloc2; // A2
if p=q3 then           if p=q3 then
    z:=p4                z:=p4
else                      else
    z:=q5                z:=q5

```

First, look at all object creation terms

Output of Analysis:

$p \mapsto \{\text{A1}, \text{A2}\}, q \mapsto \{\text{A2}\}, z \mapsto \{\text{A1}, \text{A2}\}$

Then, look at other things and add them

Symbolic execution

- Instance of under-approximation and over-approximation
- We give each variable a symbolic value and get big constraint formula for each one
- During execution we keep two sets:
 - symbolic store:
 - Input: Variable
 - Output: symbolic value
 - ↳ $\sigma_S: x \rightarrow x_0, y \rightarrow y_0, z \rightarrow x_0 + y_0$
 - path constraints:
 - Records the history of all branches taken so far
 - To initialize: $pct: true$
 - ↳ $pct: x_0 > 10 \wedge x_0 > y_0 + 1$
- We explore all paths of the program
 - At each branch we duplicate the current state of the analysis
 - Exponentially in the number of branches
- At the end we can ask the SMT-solver for a satisfying assignment to the pct formula
- Unbounded loops:
 - Underapproximate them
 - Bound iteration by some number
- Caching:
 - Save formula \rightarrow solution mapping
 - If same/weaker formula reappears, don't use SMT, just use cached solution
 - If stronger formula appears, check first, if cached solution that the stronger formula has some subparts in it, works.

Concolic Execution

- SMT-solver can't solve non-linear functions w/o
- combine concrete and symbolic execution
- Run program with concrete values but keep constraints

```
int twice(int v) {
    return 2 * v;
}

void test(int x, int y) {
    z = twice(y);
    if (x == z) {
        if (x > y + 10)
            ERROR;
    }
}

int main() {
    x = read();
    y = read();
    test(x,y);
}
```

Hence, we get:

$$\sigma : \begin{array}{l} x \mapsto 22, \\ y \mapsto 7, \\ z \mapsto 14 \end{array}$$

$$\sigma_s : \begin{array}{l} x \mapsto x_0, \\ y \mapsto y_0 \\ z \mapsto 2 \cdot y_0 \end{array}$$

$$pct : x_0 \neq 2 \cdot y_0$$

Bad decision
for values
because we
don't reach
ERROR

- Wenn die values nicht richtig sind, um die richtigen branch-paths zu nehmen:
 - Negate pct, dann rufen wir den SMT solver um concrete values zu bekommen
 - Wenn wir diese values bei der erwarteten Ausführung wählen, nehmen wir die andere branch prediction
- Wenn es sich um non-linear constraints handelt, setzen wir concrete values in die formula ein um so eine einfache Formel zu bekommen
 1. $x \neq y_0 \cdot y_0$ | negate it
 2. $x = y_0 \cdot y_0$ | insert actual values
 3. $x = 8 \cdot 8$
 4. $x = 64$