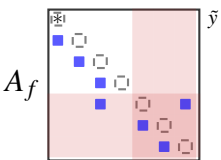
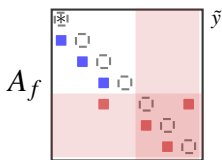


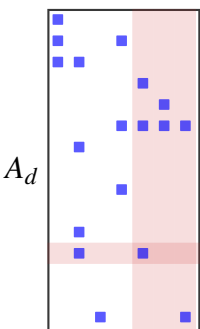
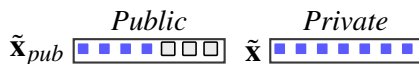
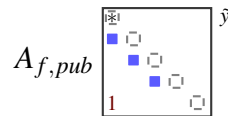
a. Private Foreground



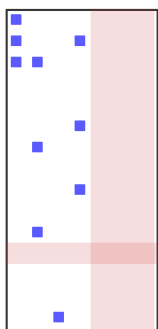
b. Partitioned Foreground



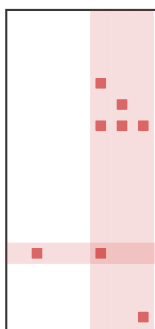
c. Disclosed Model



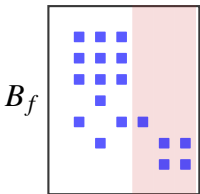
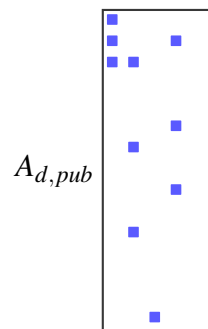
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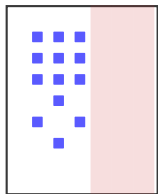
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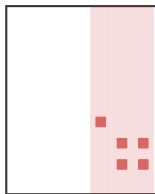
$$B_x \cdot A_{d,priv} \cdot \tilde{x}$$



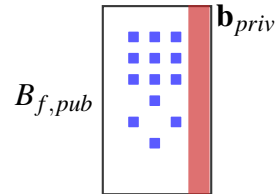
=



+



$$B_{f,priv} \cdot \tilde{x}$$



— Non-zero value



— Reference flow placemarker



— Disclosure constraint



— Private data point



— Aggregated private data vector



— Unit-weighted aggregation node