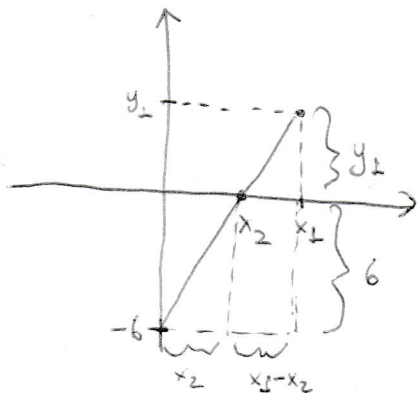


Task 1:



Given is a point  $(x_1, y_1)$ .  
After projection our point will be  $(x_2, 0)$ .  
With the similar triangles, we get the equation:

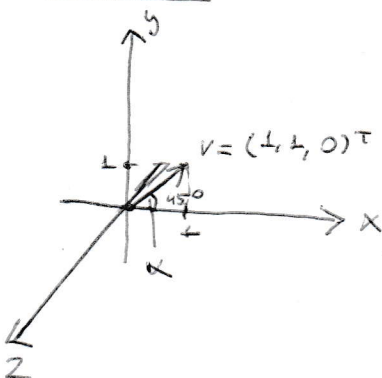
$$\frac{6}{y_1 + 6} = \frac{x_2}{x_1} \Leftrightarrow \frac{6x_1}{y_1 + 6} = x_2$$

With this we get the following transformation matrix  $M$ :

$$M = \begin{pmatrix} 6 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 6 \end{pmatrix}, \text{ because for a point } (x_1, y_1) \text{ we have:}$$

$$M \cdot \begin{pmatrix} x_1 \\ y_1 \\ 1 \end{pmatrix} = \begin{pmatrix} 6 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 6 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ y_1 \\ 1 \end{pmatrix} = \begin{pmatrix} 6x_1 \\ 0 \\ y_1 + 6 \end{pmatrix}, \text{ and after homogenous division we get the point } \left( \frac{6x_1}{y_1 + 6}, 0 \right) \text{ which is } (x_2, 0). \quad \square$$

Task 2:



- We solve this problem with three steps.
1. Rotate  $\alpha$  degrees around z-axis, so the vector is equivalent to x-axis
  2. Rotate point  $90^\circ$  degrees around x-axis
  3. Reverse rotate  $\alpha$  degrees around z-axis, so the vector comes back to its original position.

Because of isosceles Triangle  $\sqrt{2}$  with  $90^\circ$  degrees in the x-y-Plane with Vector  $v = (1, 1, 0)^T$ , we get  $\alpha = 45^\circ$ . Thus we have the transformation matrix: (See next page)

All rotations are counter-clockwise (To get to the step 1 for example, calculate  $R_z(-\alpha)$ )

$$M = R_z(-45^\circ) \cdot R_x(90^\circ) \cdot R_z(45^\circ) = \begin{pmatrix} \cos 45^\circ & -\sin 45^\circ & 0 \\ \sin 45^\circ & \cos 45^\circ & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos 90^\circ & -\sin 90^\circ \\ 0 & \sin 90^\circ & \cos 90^\circ \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos 45^\circ & -\sin 45^\circ \\ 0 & \sin 45^\circ & \cos 45^\circ \end{pmatrix}$$

$$M = R_z(45^\circ) \cdot R_x(90^\circ) \cdot R_z(-45^\circ)$$

$$\begin{aligned}
 &= \begin{pmatrix} \cos(45^\circ) & -\sin(45^\circ) & 0 \\ \sin(45^\circ) & \cos(45^\circ) & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos(90^\circ) & -\sin(90^\circ) \\ 0 & \sin(90^\circ) & \cos(90^\circ) \end{pmatrix} \cdot \begin{pmatrix} \cos(-45^\circ) & -\sin(-45^\circ) & 0 \\ \sin(-45^\circ) & \cos(-45^\circ) & 0 \\ 0 & 0 & 1 \end{pmatrix} \\
 &= \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \\
 &= \begin{pmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & \frac{\sqrt{2}}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & 1 \end{pmatrix} \quad \square
 \end{aligned}$$