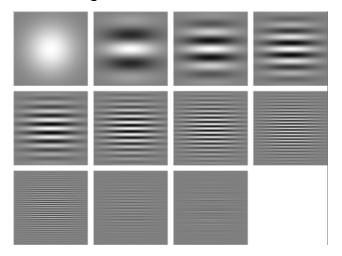
A Perceptual Discrimination Task to Study Decision Making

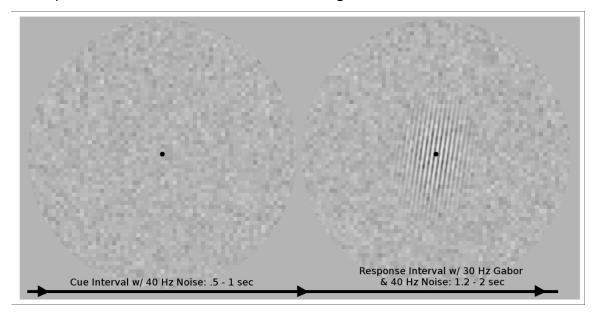
This is actual data from my lab, which was published here:

Nunez, M. D., Vandekerckhove, J., & Srinivasan, R. (2017). How attention influences perceptual decision making: Single-trial EEG correlates of drift-diffusion model parameters. Journal of Mathematical Psychology, 76(Part B), 117–130. https://doi.org/10.1016/j.jmp.2016.03.003

Human subject were asked to discriminate the spatial frequency of Gabor patches (as shown below), embeded in noise. Task difficulty was controlled by the difficulty of the discrimination. Two Gabors with more similar spatial frequencies are harder to discriminate, especially when noise is added. In each of 34 participant, The experiment was performed in Easy, Medium, and Hard blocks each consisting of with decreasing differences between the Gabor spatial frequencies.



An experimental trial would look something like this.



The datafile ReactionTimeData.csv is for use in this homework. You can load it into your notebook using pandas using pandas. There are 3 variables in the file:

- Subject indicates a numeric subject id
- Experimental Condition Easy, Medium, Hard
- Correct 1 if correct 0 if incorrect
- ResponseTime time from stimulus presentation to decision in units of millisecond

In [1]:

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import seaborn as sns
import scipy.stats as stats
from scipy.optimize import minimize
```

memory usage: 452.6+ KB

```
In [2]:
df = pd.read_csv('../data/ResponseTimeData.csv')
#I always like to dump info as soom as I load a dataframe
df.info()
  <class 'pandas.core.frame.DataFrame'>
  RangeIndex: 11584 entries, 0 to 11583
  Data columns (total 5 columns):
     Column
                    Non-Null Count Dtype
      Unnamed: 0
                    11584 non-null int64
                    11584 non-null int64
      Subject
   2 Condition
                    11584 non-null object
                    11584 non-null int64
   3 Correct
      ResponseTime 11584 non-null int64
  dtypes: int64(4), object(1)
```

Name: count, dtype: int64

```
In [3]:
#Since I don't know anything about this data, I will do some Exploratory Data Analysis (EDA)
#Lets see how many subjects are there
df['Subject'].nunique()
#Lets see how many trials per subject
df['Subject'].value_counts()
#It varies a little bit. Every subject did 360 trials, but I removed trials with no response or too rapid of a response
Out[3]:
  Subject
        355
  9
        355
  32
        355
  22
        355
  16
        355
        354
  10
        353
  27
        352
  23
        352
        352
  17
        352
  28
        352
  15
        352
  6
        351
  31
        350
  13
        350
        348
  11
  18
        346
  24
        345
  19
        345
  20
        344
        344
  25
        343
  26
        342
        340
  30
        340
  34
        338
  29
        338
  12
        336
  2
        332
  33
        329
  14
        317
        308
  21
        204
```

```
In [4]:
```

```
#Lets see how many conditions are there
df['Condition'].value_counts()
#Looks like there are 3 conditions - Easy, Medium, Hard
```

Out[4]:

Condition Hard 3893 Medium 3872 Easy 3819

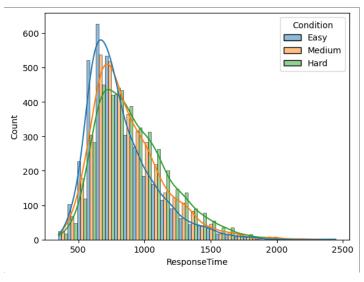
Name: count, dtype: int64

Name: count, dtype: int64

```
In [5]:
#Lets see how many correct and incorrect trials are there
df['Correct'].value_counts()
#1 is correct 0 is incorrect

Out[5]:
    Correct
    1    9105
    0    2479
```

There is a lot of values of response time, and they are continuous. We will make a histogram to take a look at it.



• Lets compute some overall statistics

```
In [7]:
# I can do this inside pandas actually.
accuracy = df['Correct'].mean()
print(f'Overall accuracy is {accuracy*100:.2f}%')

Overall accuracy is 78.60%

In [8]:

mean_rt = df['ResponseTime'].mean()
print(f'Overall mean response time is {mean_rt:.1f} ms')

Overall mean response time is 868.7 ms
```

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• This is the pandas way of grouping the data and getting separate means

```
In [9]:

mean_rt_by_condition = df.groupby('Condition')['ResponseTime'].mean()
mean_acc_by_condition = df.groupby('Condition')['Correct'].mean()
print('Mean Response Time by Condition:')
print(mean_rt_by_condition)
print('Mean Accuracy by Condition:')
print(mean_acc_by_condition)
```

```
Mean Response Time by Condition:
Condition
Easy
          812.957842
          920.328282
Hard
Medium
          871.684659
Name: ResponseTime, dtype: float64
Mean Accuracy by Condition:
Condition
Easy
          0.884263
Hard
          0.671462
Medium
          0.804236
Name: Correct, dtype: float64
```

• I want to look at it by condition, and I dont want to hassle dealing with pandas syntax

```
In [10]:

rt = np.array(df['ResponseTime'])
  correct = np.array(df['Correct'])
  condition = np.array(df['Condition'])
```

```
In [11]:

condition_labels = ['Easy', 'Medium', 'Hard']
#mean_rt = [np.mean(rt[condition==cl]) for cl in condition_labels]
#mean_acc = [np.mean(correct[condition==cl]) for cl in condition_labels]
mean_rt = dict()
std_rt = dict()
mean_acc = dict()
for cl in condition_labels:
    mean_rt[cl] = np.mean(rt[condition==cl])
    std_rt[cl] = np.std(rt[condition==cl])
    mean_acc[cl] = np.mean(correct[condition==cl])
```

```
In [12]:
print('Mean Accuracy by condition:')
print(mean_acc)

Mean Accuracy by condition:
    {'Easy': np.float64(0.8842628960460853), 'Medium': np.float64(0.8042355371900827), 'Hard': np.float64(0.6
    714615977395325)}
```

```
In [13]:

print('Mean RT by condition:')
print(mean_rt)
print('Std RT by condition:')
print(std_rt)

Mean RT by condition:
   {'Easy': np.float64(812.9578423671118), 'Medium': np.float64(871.6846590909091), 'Hard': np.float64(920.3 28281530953)}
Std RT by condition:
   {'Easy': np.float64(248.6647264233954), 'Medium': np.float64(267.98087231333045), 'Hard': np.float64(28 1.14363089159184)}
```

MLE Estimate of a Normal Distribution

If we have a set of samples $X = \{x_n\}$, n = 1,...,N that we wish to fit to a normal distribution, we have to develop an expression for the Likelihood.

The Normal distribution $\mathcal{N}(\mu,\sigma^2)$ has probability density

$$p(x|\mu,\sigma^2) = rac{1}{\sigma\sqrt{2\pi}}e^{rac{-(x-\mu)^2}{2\sigma^2}}$$

where μ is the mean and σ^2 is the variance or standard deviation squared.

The Likelihood for the set of observation $\{x_n\}$, n = 1,..N is the product of the normal density for each observation,

$$L(\mu,\sigma)=p(\{x_n\}|\mu,\sigma)=\prod_{n=1}^N p(x_n|\mu,\sigma)$$

$$ln(L(\mu,\sigma)) = ln(p(\{x_n\}|\mu,\sigma)) = \sum_{n=1}^N ln(p(x_n|\mu,\sigma))$$

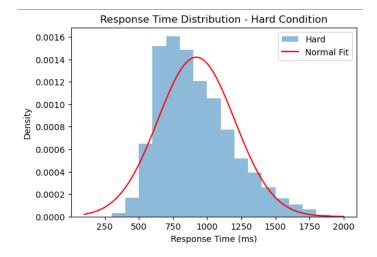
• The maximum likelihood estimate is

$$\mu = rac{1}{N} \sum_{n=1}^N x_n = ar{X}$$

$$\hat{\sigma}^2 = rac{1}{n} \sum_{i=1}^n (x_i - ar{x})^2 = s_X^2$$

```
In [14]:

plt.figure(figsize=(6,4))
plt.hist(rt[condition=='Hard'], np.arange(100,2000,100), alpha=0.5, label='Hard',density =True)
normal = stats.norm(loc=mean_rt['Hard'], scale=std_rt['Hard'])
x = np.linspace(100,2000,100)
plt.plot(x, normal.pdf(x), 'r-',label = "Normal Fit")
plt.xlabel('Response Time (ms)')
plt.ylabel('Density')
plt.title('Response Time Distribution - Hard Condition')
plt.legend()
plt.show()
```



Lets write down the likelihood for a normal distribution using norm.pdf

negloglike = np.sum(-np.log(stats.norm(mu, sigma).pdf(data)))

return negloglike

```
In [15]:

def negloglikenormal(params):
    ''' Please note that this function uses a global variable called data, which is the data you are fitting
        params is a list or array with two elements - mean and standard deviation
    ""
    mu = params[0]
    sigma = params[1]
    N = len(data)
```

Even though we know the correct answer we could in fact use this negative log-likelihood to search for the best fit parameters. We need this function, and the minimize function from scipy.optimize

```
In [16]:

data = rt[condition=='Hard'] #global variable used in the function above
bnds = ((0,2000),(0,500)) #bounds for mean and standrd deviation
paramfit = minimize(negloglikenormal,(1000,250),bounds = bnds); #initial guess is (1000,250)

In [17]:

print('Fitted parameters for Hard condition:')
print(f'Mean: {paramfit.x[0]:.1f}, Std: {paramfit.x[1]:.1f}')
print(f'Function value (Negative Log Likelihood): {paramfit.fun:.1f}')

Fitted parameters for Hard condition:
Mean: 920.3, Std: 281.1
Function value (Negative Log Likelihood): 27476.0
```

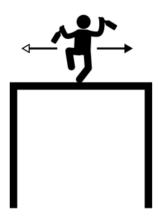
MLE is a powerful method.

- If I choose a useful, meaningful **probability model** $P(X|\theta)$,
- And if I can write down a **likelihood** as the product of the probability of observing each observation of data.
- Then I can find the **parameters** of the probability model that maximize the likelihood.
- In practice, I will work with **log-likelihood** because by taking a log, I replie the product of probabilities with the sum of log(probability). The maximum of log-likelihood is at the same parameter values as the maximum of likelihood.
- In practice, I will often work with **negative log-likelihood** because I will find myself using optimization to tools that are designed to find the minimum of a function.

A hypothesis about the decision making process

- Assume a model that samples evidence in discrete time windows. The evidence obtained in each time window will favor one of the two alternatives (a "nudge").
- Each sample represents a nudge toward one decision or another. The magnitude of that nudge reflects how much information is acquired in that single sample.
- The nudge would then be added to the sum of previous nudges, moving a decision variable towards one or the other alternative. (An alternative view is that there are two decision variables involved in a race)
- A decision is made when the decision variable crosses a boundary (In a race or competing accumulator model, one of the two accumulators crosses the boundary).

Random Walk Models



Random walk models originated in physics and chemistry (e.g., Brownian motion of a gas) They are used in psychology and neuroscience. They are also used in economics and finance. Ramesh Srinivasan Cognitive Sciences Lecture 2

Random Walk Models

- ullet Random walk process starts at Z(0) (This is an important variable that expresses bias, i.e., intrinsic preference for one choice over the other!)
- At each time point t, the walker takes a step X(t).
- ullet X(t) can be any positive or negative number randomly drawn from some distribution, e.g., $\mathcal{N}(\mu,\sigma^2)$
- The evidence, i.e. position of the walker, after 1 step is defined as:

$$Z(1) = Z(0) + X(1)$$

• The evidence, i.e. position of the walker, after 2 steps is defined as:

$$Z(2) = Z(1) + X(1) = Z(0) + X(1) + X(2)$$

• More generally, after T steps

$$Z(T)=Z(0)+\sum_{t=0}^T X(t)$$

Random Walker

- ullet In our example of the drunken walker, let's assume they start at the middle of the table. We will call that position Z=0
- ullet The two edges of the table are then at $Z=\pm B$
- Each step could be equally to the left or right, so we can reasonably assume that steps are equally likely to be to the left or right.

$$X \sim \mathcal{N}(0, \sigma^2)$$

• The steps taken by the drunk **accumulate** and there is some possibility the drunk will fall-off one side of the table.

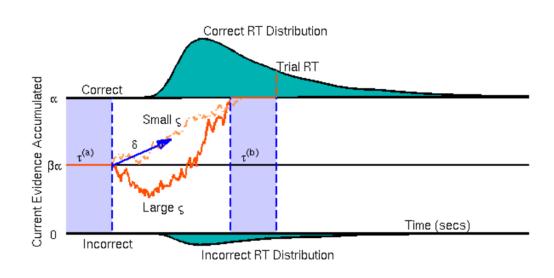
Relationship to Decision Making

- Our narrative of the random walker, provides a useful metaphor for a model of decision making.
- After figure-ground segregation, a neural representation of the stimulus in an experiment is available in the brain.
- In a two-alternative decision making task, the stimulus must be classified as being from one of two classes. For example, high or low spatial frequency.
- ullet At each time step, a sample of evidence can obtained from the neurons that represent the stimulus. Since there is actual information in the stimulus, this evidence will (on average) favor the correct decision. But these samples are noisy, and could providence evidence X for the wrong decision

$$X(t) \sim \mathcal{N}(d, \sigma^2)$$

- ullet Here d represents the information available in the stimulus.
- ullet The boundary B represents a criterion for how much accumulated evidence Z is needed to select one decision. There is a boundary at +B and a boundary at -B. We can have these boundaries represent the two decisions, but its better to follow a convention that d is always positive, and +B is correct decision and -B is the incorrect decision.
- ullet The sample on which Z>B or Z<-B triggers a motor response.
- We can introduce the notion of bias by starting the walks $X(0) \neq 0$. This represents a prior belief by the decision maker that one choice is correct.

Drift-Diffusion Model



$$au = au^{(a)} + au^{(b)} = au_{v} + au_{m}$$
 Non-decision time

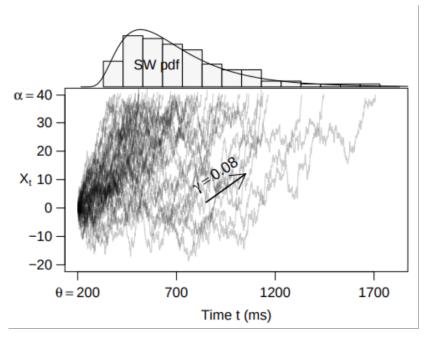
 δ Drift Rate - Mean Evidence Accumulation Rate

 ζ Diffusion Coefficient- Standard Deviation (variability) in Evidence Accumulation

 α Boundary Separation or Criterion. Usually a positive parameter.

 β Bias - Fraction between 0 and 1.

Shifted Wald Distribution



- In this simplified diffusion, we simply focus on the correct (or incorrect) trials separately, and assume there is only one boundary.
- In this process model, there are 3 parameters:
 - ullet heta which is referred to as shift which is nondecision time.
 - ullet lpha which is the boundary separation or caution.
 - ullet γ which is drift rate or the rate of evidence accumulation.

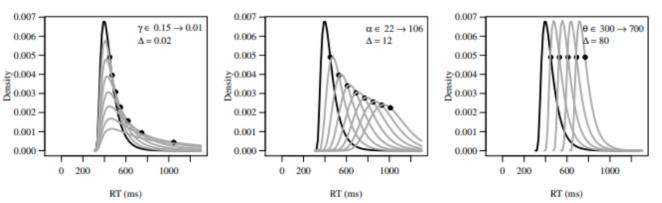


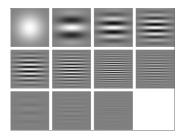
Figure 2. An illustration of how the SW distribution shape changes as one manipulates each parameter. Left to right, changes in γ , α , and θ , each in a direction that produces larger mean values. In the left plot, the black distribution starts with $\gamma = 0.15$ and each successive grey distribution is a reduction of 0.02 units, until γ reaches 0.01.

$$f(X|\gamma,lpha, heta)=rac{lpha}{\sqrt{2\pi(X- heta)^3}}e^{-rac{|lpha-\gamma(X- heta)|^2}{2(X- heta)}}$$

Shifted-wald interpretation

- The shifted Wald model has a clear link to the process that generated the data. Each of the parameters has a meaning.
- The shift parameter θ is related to the time outside of "decision making", i.e., evidence accumulation process. This is the time for sensory processing and motor response.
- The boundary parameter α reflect the caution of the subject how much information do they need to make a decision.
- The drift parameter γ reflect the rate of information accrual, or difficulty of the task.
- The main "weakness" of the shifted Wald model is that it can only make use of correct trials and completely ignores the incorrect trials.
- The full drift-diffusion model maybe a better model as it incorporates the incorrect trials.
- Which model to fit depends on the nature of the task and the data available. For example, in tasks with very high accuracy, the shifted Wald model may be a better model, as there are insufficient incorrect trials to fit the drift-diffusion model.

Framing Your Hypothesis Quantitatively in a Model



- Consider the spatial frequency discrimination task whose data you will look at.
- The data show that as the discrimination becomes more difficult (difference in spatial frequency becomes smaller), accuracy is lower, and response time increases for accurate trials.
- Using the single diffusion model (shifted-Wald) can we express some hypothesis about the data:
 - The experiment was designed to manipulate drift rate by reducing the information available in the stimuli. As the spatial frequencies become closer there is less evidence to accumulate on each sample, so γ should be smaller and response time increases.
 - However, keep in mind, since we used a block design there is always the possibility that boundary is varying with task difficulty as the subjects became more cautious when they find evidence accumulation is slower (task harder).