

Lecture 9

Mapping an Entity Relationship Schema to a Relational Schema (Enhanced Entity Relationship)

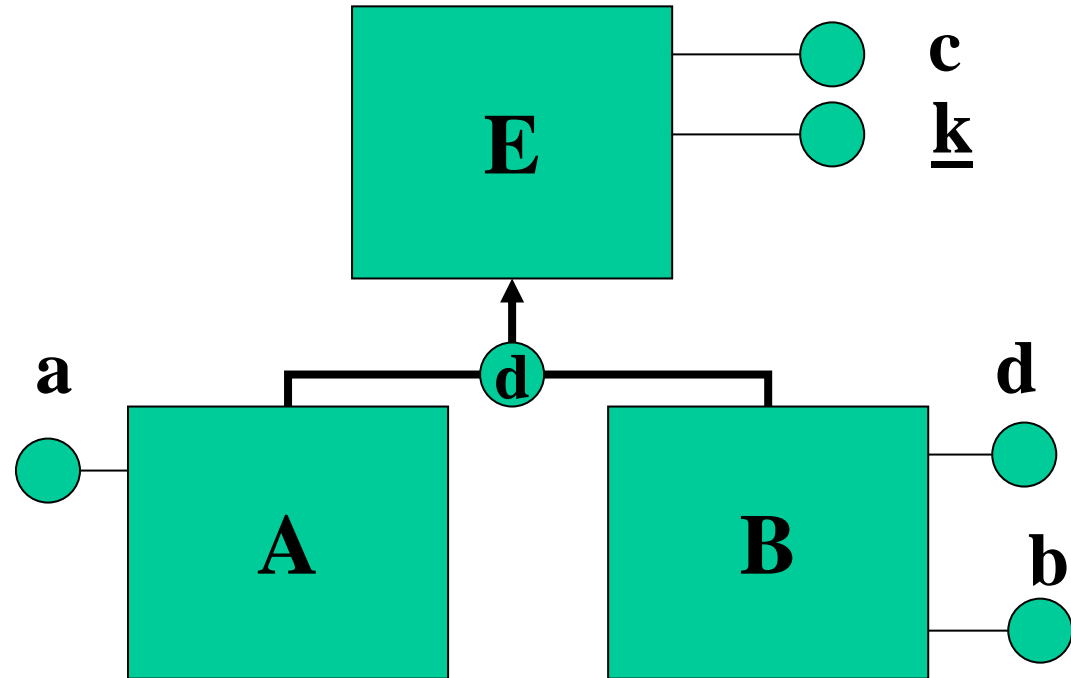
Week 5

Overview

- Mapping generalisation hierarchies: there are several strategies; we shall study four
- The choice depends on the database population and usage patterns

Choice A)

- Map each entity to a separate schema
- Include primary key for each
- Include foreign key constraints



$E(\underline{k}, c)$

$B(\underline{k}, d, b)$ **fk: k is k in E**

$A(\underline{k}, a)$ **fk: k is k in E**

$E(\underline{k},c)$

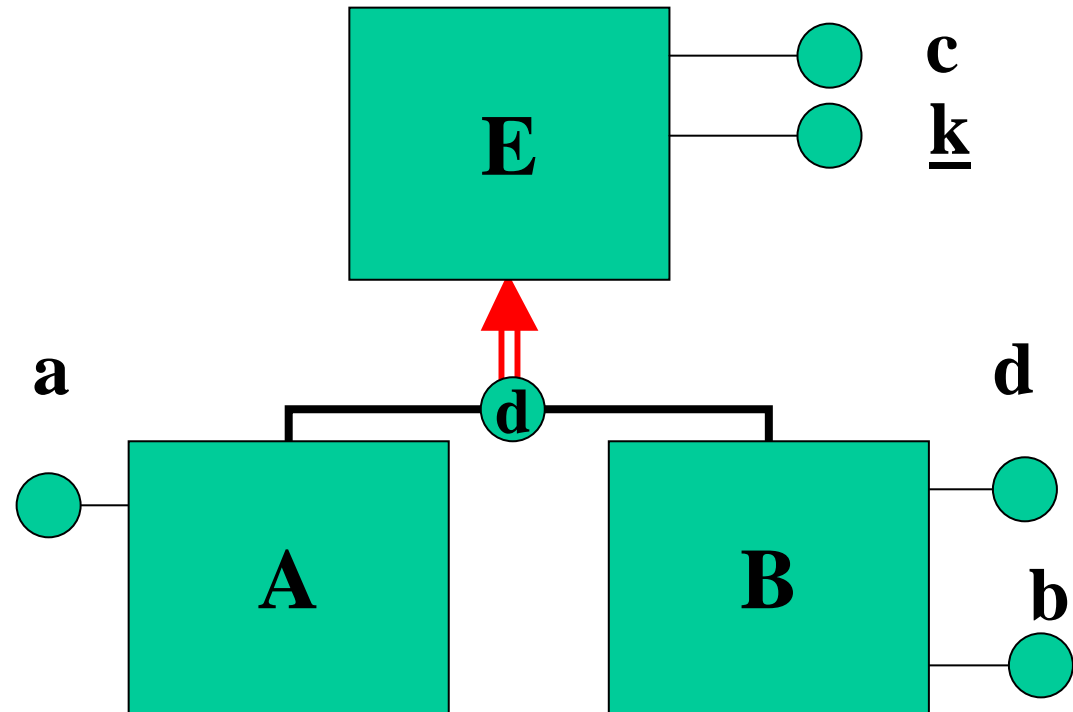
$B(\underline{k},d,b)$ $fk: k \text{ is } k \text{ in } E$

$A(\underline{k},a)$ $fk: k \text{ is } k \text{ in } E$

- Advantage: there are fewer null valued attributes (relative to the other mapping choices) and all instances of E (including As and Bs) are identifiable in one schema
- Disadvantage: information about one entity is fragmented, an instance of B is partly stored in E and partly in B - frequently querying all needs many joins

Choice B)

- If E is a total generalisation then map A and B separately
- Include disjointness constraint



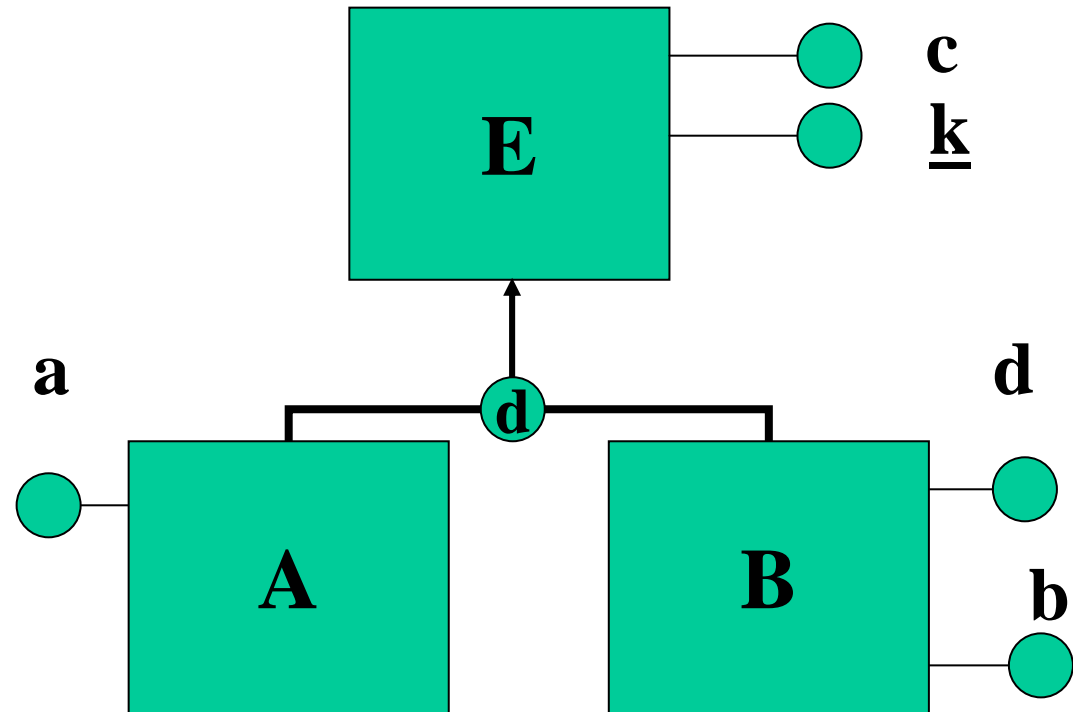
$B(\underline{k}, d, b, c)$ fk: k in B is not a k in A
 $A(\underline{k}, a, c)$ fk: k in A is not a k in B

B(k,d,b,c) k in B is not a k in A ← Disjointness constraints
A(k,a,c) k in A is not a k in B

- Advantage: non-redundant storage, all attributes of an entity are stored in one place
- Disadvantage: there is no single relation to retrieve the identifiers (primary keys) of all Es. (Basically the notion of E is not represented)

Choice C)

- If space is not a problem
- Must be disjoint types



$E(a, b, c, d, \underline{k}, \text{type})$

where type is one of { 'A', 'B', 'E' }

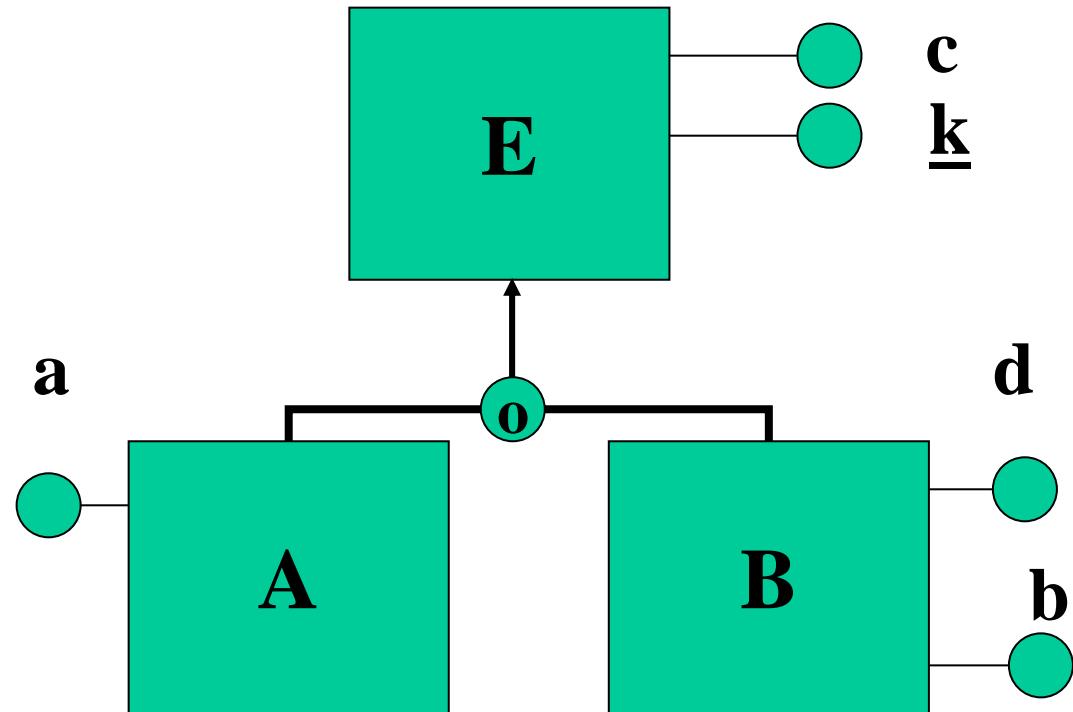
E(a, b, c, d, k, type)

where type is one of { 'A', 'B', 'E' }

- Advantage: one schema for all instances of E, A and B
- Disadvantage: does not work for overlapping generalisations (although they are rare); always has null values (non-applicable attributes)

Choice D)

- Slight variant of choice C)
- Works for overlapping generalisations



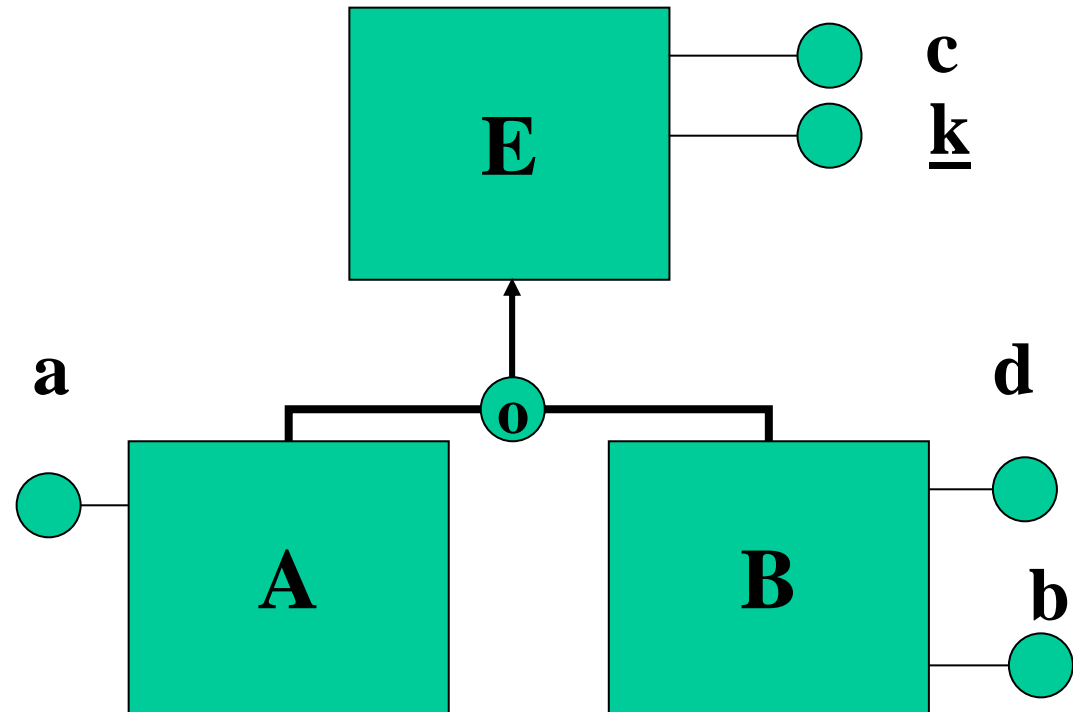
$E(a, b, c, d, \underline{k})$

Not quite correct yet!

Loses information (e.g. how to interpret that the value for **a** is NULL?); therefore...

Choice D)

- Therefore...to rectify this problem we add two boolean attributes: *isA* and *isB*
- Slight variant of choice C)
- Works for overlapping generalisations

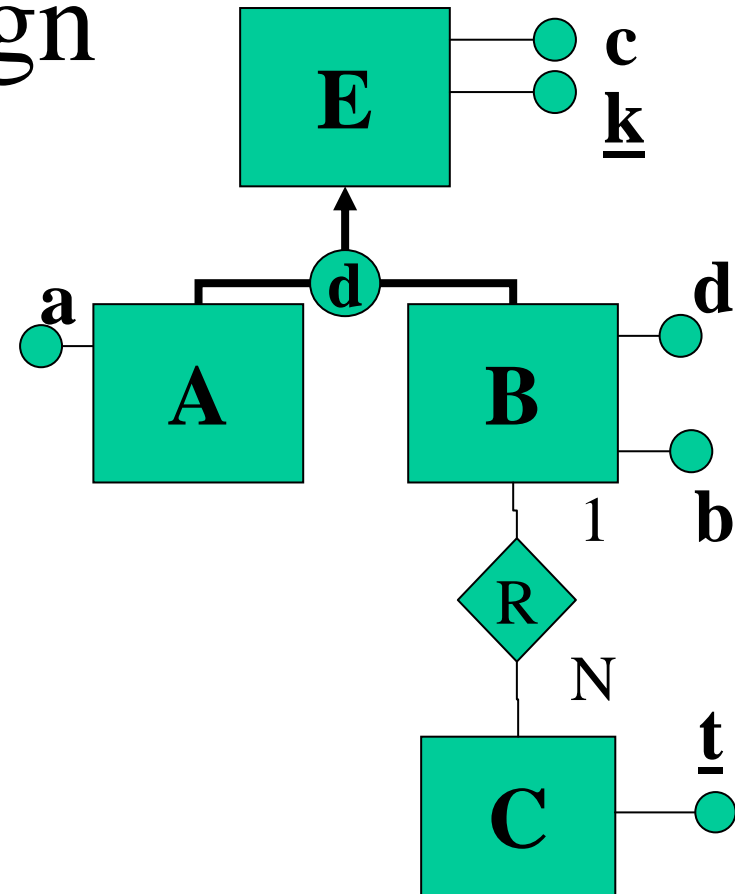


$E(a, b, c, d, \underline{k}, \text{bool: isA}, \text{bool: isB})$

Works also with null values

Important note on foreign key constraints

- Suppose we mapped E, B, and A as follows
- Also we have R between C and B (mapped as an attribute of C).



$E(\underline{k}, c)$

$A(\underline{k}, a)$ fk: k is k in E

$B(\underline{k}, d, b)$ fk: k is k in E

$C(\underline{t}, k)$ fk: k is k in **B**

- Notice the fk constraint on relation C! It says that 'k' must be an actual k-value in relation B. It is *not* enough for this k-value to be a k-value in relation E, because Cs are only related to Bs !

Conclusion

- We propose that the first mapping choice is the cleanest one, because it has no redundancy
- However, if efficiency dictates, then one of the other three options may have to be considered

The end