

ME565 HW1

5-1 Show the following:

(a) $\nabla \times (\nabla \phi) = 0$ for any potential field.

$$\Rightarrow \left[\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right]^T \times \left[\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right]^T$$
$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix} = \hat{i} \left(\frac{\partial^2 \phi}{\partial y \partial z} - \frac{\partial^2 \phi}{\partial z \partial y} \right) - \hat{j} \left(\frac{\partial^2 \phi}{\partial x \partial z} - \frac{\partial^2 \phi}{\partial z \partial x} \right) + \hat{k} \left(\frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial^2 \phi}{\partial y \partial x} \right) = \boxed{0}$$

(b) $\nabla^2 \phi = \nabla \cdot (\nabla \phi)$ for any potential field.

$$\text{LHS} = \nabla^2 = \nabla \cdot \nabla = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

$$\Rightarrow \nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} \quad \textcircled{1}$$

$$\text{RHS} = \nabla \cdot (\nabla \phi) = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial \phi}{\partial x} \\ \frac{\partial \phi}{\partial y} \\ \frac{\partial \phi}{\partial z} \end{bmatrix} = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} \quad \textcircled{2}$$

$$\boxed{\textcircled{1} = \textcircled{2}, \nabla^2 \phi = \nabla \cdot (\nabla \phi)}$$

$$(c) \quad \nabla \cdot (\nabla \phi \times \nabla \psi) = 0 \quad \text{for all potential flow } \phi \text{ \& } \psi$$

$$\Rightarrow \begin{bmatrix} \cancel{\frac{\partial}{\partial x}} \\ \cancel{\frac{\partial}{\partial y}} \\ \cancel{\frac{\partial}{\partial z}} \end{bmatrix} \cdot \left(\begin{bmatrix} \cancel{\frac{\partial \phi}{\partial x}} \\ \cancel{\frac{\partial \phi}{\partial y}} \\ \cancel{\frac{\partial \phi}{\partial z}} \end{bmatrix} \times \begin{bmatrix} \cancel{\frac{\partial \psi}{\partial x}} \\ \cancel{\frac{\partial \psi}{\partial y}} \\ \cancel{\frac{\partial \psi}{\partial z}} \end{bmatrix} \right)$$

$$\Rightarrow \sim \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cancel{\frac{\partial \phi}{\partial x}} & \cancel{\frac{\partial \phi}{\partial y}} & \cancel{\frac{\partial \phi}{\partial z}} \\ \cancel{\frac{\partial \psi}{\partial x}} & \cancel{\frac{\partial \psi}{\partial y}} & \cancel{\frac{\partial \psi}{\partial z}} \end{vmatrix}$$

$$\Rightarrow \sim \cdot \begin{bmatrix} \frac{\partial \phi \partial \psi}{\partial x \partial y} - \frac{\partial \phi \partial \psi}{\partial x \partial y} \\ -\frac{\partial \phi \partial \psi}{\partial x \partial z} + \frac{\partial \phi \partial \psi}{\partial x \partial z} \\ \frac{\partial \phi \partial \psi}{\partial x \partial y} - \frac{\partial \phi \partial \psi}{\partial x \partial y} \end{bmatrix} \Rightarrow \begin{bmatrix} \cancel{\frac{\partial}{\partial x}} \\ \cancel{\frac{\partial}{\partial y}} \\ \cancel{\frac{\partial}{\partial z}} \end{bmatrix} \cdot 0$$

$$\Rightarrow \boxed{0}_{\#}$$

5-2

$$(a) \quad (\vec{a} \times \vec{b}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \begin{bmatrix} a_2 b_3 - a_3 b_2 \\ -a_1 b_3 + a_3 b_1 \\ a_1 b_2 - a_2 b_1 \end{bmatrix}$$

$$- (\vec{a} \times \vec{b}) \cdot \vec{a} = a_1 (a_2 b_3 - a_3 b_2) + a_2 (-a_1 b_3 + a_3 b_1) + a_3 (a_1 b_2 - a_2 b_1)$$

$$= \underbrace{a_1 a_2 b_3} - \underbrace{a_1 a_3 b_2} - \underbrace{a_1 a_2 b_3} + \underbrace{a_2 a_3 b_1} + \underbrace{a_1 a_3 b_2} - \underbrace{a_2 a_3 b_1} = 0$$

$$- (\vec{a} \times \vec{b}) \cdot \vec{b} = b_1 (a_2 b_3 - a_3 b_2) + b_2 (-a_1 b_3 + a_3 b_1)$$

$$+ b_3 (a_1 b_2 - a_2 b_1)$$

$$= \underbrace{a_2 b_1 b_3} - \underbrace{a_3 b_1 b_2} - \underbrace{a_1 b_2 b_3} + \underbrace{a_3 b_1 b_2} \\ + \underbrace{a_1 b_2 b_3} - \underbrace{a_2 b_1 b_3} = 0$$

$$\therefore \vec{a} \cdot (\vec{a} \times \vec{b}) = 0, \quad \vec{b} \cdot (\vec{a} \times \vec{b}) = 0, \\ \therefore \vec{a} \times \vec{b} \text{ is orthogonal to } \vec{a} \text{ \& } \vec{b}$$

(b) $\nabla \cdot (\nabla \times \vec{f}) = 0$ for any vector field \vec{f}

$$\Rightarrow \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} \cdot \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f_1 & f_2 & f_3 \end{vmatrix} \Rightarrow \dots = \begin{bmatrix} \frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z} \\ -\frac{\partial f_3}{\partial x} + \frac{\partial f_1}{\partial z} \\ \frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \end{bmatrix}$$

$$\Rightarrow \underbrace{\frac{\partial^2 f_3}{\partial x \partial y}} - \underbrace{\frac{\partial^2 f_2}{\partial x \partial z}} - \underbrace{\frac{\partial^2 f_3}{\partial x \partial y}} + \underbrace{\frac{\partial^2 f_1}{\partial y \partial z}} + \underbrace{\frac{\partial^2 f_2}{\partial x \partial z}} - \underbrace{\frac{\partial^2 f_1}{\partial y \partial z}} = \boxed{0}$$

5-3

$$(a) \quad D_v f = \nabla f \cdot \vec{v} = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} \cos x \cdot y^2 \\ 2 \sin x y \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= \boxed{\cos x \cdot y^2 + 4 \sin x y}$$

(b) take gradient to find the slope of f

$$\nabla f = \begin{bmatrix} -4x^3 \\ -2y \\ 0 \end{bmatrix}, \quad \nabla f(1, 2, 15) = \begin{bmatrix} -4 \\ -4 \\ 0 \end{bmatrix}$$

$$\therefore \text{Direction} = \begin{bmatrix} -\frac{4}{4\sqrt{2}} & -\frac{4}{4\sqrt{2}} & 0 \end{bmatrix}^T \\ = \begin{bmatrix} -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \end{bmatrix}^T \quad \#$$

(c) take gradient to find the slope of T

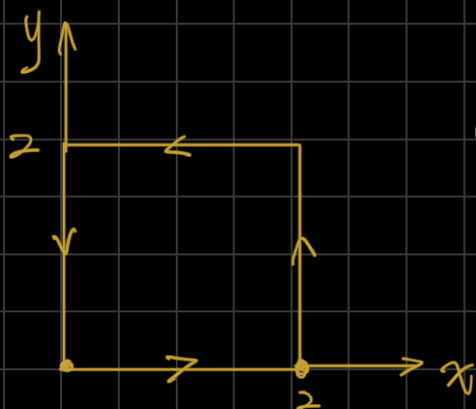
$$\nabla T = \begin{bmatrix} -\sin x \cos y \sin z \\ -\cos x \sin y \sin z \\ \cos x \cos y \cos z \end{bmatrix} \quad (x, y, z \text{ in rad})$$

$$\nabla T(2, 1, 1) = \begin{bmatrix} -\sin(2) \cos(1) \sin(1) \\ -\cos(2) \sin(1) \sin(1) \\ \cos(2) \cos(1) \cos(1) \end{bmatrix}$$

$$\therefore \text{Direction} = \begin{bmatrix} -0.413 \\ 0.294 \\ -0.121 \end{bmatrix} \quad \#$$

5-4

(a)



$$\text{Area} = \frac{1}{2} \int_{\partial S} x dy - y dx$$

$$\begin{aligned}
 \Rightarrow A &= \frac{1}{2} \left[\int_{y=0}^2 2 dy - \int_{x=2}^0 2 dx + \int_{y=2}^0 0 dy - \int_{x=0}^2 0 dx \right] \\
 &= \frac{1}{2} \left[2y \Big|_0^2 - 2x \Big|_2^0 \right] = \frac{1}{2} [4 - (-4)] \\
 &= \boxed{4}
 \end{aligned}$$

(b)

$$\begin{aligned}
 f(x, y) &= x^2 + y^2 = 1, \quad x = \cos \theta, \quad y = \sin \theta \\
 \frac{dx}{d\theta} &= -\sin \theta, \quad \frac{dy}{d\theta} = \cos \theta
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow A &= \frac{1}{2} \left[\int_{\theta=0}^{2\pi} \cos \theta (\cos \theta d\theta) - \int_{\theta=0}^{2\pi} \sin \theta (-\sin \theta d\theta) \right] \\
 &= \frac{1}{2} \left(\int_0^{2\pi} \cos^2 \theta d\theta + \int_0^{2\pi} \sin^2 \theta d\theta \right) \\
 &= \frac{1}{2} \left(\int_0^{2\pi} 1 d\theta \right) = \boxed{\pi}
 \end{aligned}$$

(c)

$$f(x, y) = x^{2/3} + y^{2/3} = 1, \quad x = \cos^3 \theta, \quad y = \sin^3 \theta$$

$$\frac{dx}{d\theta} = 3\cos^2(\theta) (-\sin \theta)$$

$$\frac{dy}{d\theta} = 3\sin^2(\theta) (\cos \theta)$$

$$\begin{aligned}
 \Rightarrow A &= \frac{1}{2} \int_{\partial S} x dy - y dx \\
 &= \frac{1}{2} \left[\int_0^{2\pi} \cos^4 \theta \cdot 3\sin^2 \theta + \sin^4 \theta \cdot 3\cos^2 \theta d\theta \right]
 \end{aligned}$$

$$= \frac{3}{2} \int_0^{2\pi} (\sin^2 \theta \cos^2 \theta) (\cos^2 \theta + \sin^2 \theta) d\theta$$

$$= \frac{3}{2} \int_0^{2\pi} \sin^2 \theta \cos^2 \theta d\theta$$

trig identity: $\sin 2\theta = 2 \sin \theta \cos \theta$

$$\Rightarrow \frac{1}{4} \sin^2 2\theta = \sin^2 \theta \cos^2 \theta$$

$$= \frac{3}{8} \int_0^{2\pi} \sin^2(2\theta) d\theta$$

trig identity: $\sin^2 \theta = \frac{1 - \cos 2\theta}{2}$

$$\Rightarrow \sin^2(2\theta) = \frac{1 - \cos 4\theta}{2}$$

$$= \frac{3}{8} \int_0^{2\pi} \frac{1}{2} d\theta - \frac{3}{8} \int_0^{2\pi} \frac{1}{2} \cos 4\theta d\theta$$

$$= \frac{3}{8} \left(\frac{\theta}{2} \Big|_0^{2\pi} \right) = \boxed{\frac{3}{8} \pi}$$