```
view_frames Result

Recorded at time: 1655356171.700
```

world

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1655356171.700 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1655356171.680 (0.020 sec old)
Buffer length: 4.900 sec

X_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1655356171.680 (0.020 sec old)
Buffer length: 4.900 sec

Y_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1655356171.680 (0.020 sec old)
Buffer length: 4.900 sec

Z_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1655356171.680 (0.020 sec old)
Buffer length: 4.900 sec

tool0

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1655356171.700 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1655356171.700 sec old)
Buffer length: 0.000 sec

lj_v7200_optical_frame

torch

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1655356171.700 sec old)
Buffer length: 0.000 sec

lj_v7200_frame