

Experiment No- 1.4

Student Name: Yash Kumar

Branch: CSE

Semester: 5

Subject Name: Machine Learning

UID: 20BCS9256

Section/Group: 616- B

Date of Performance: 27-09-22

Subject Code: 20CSP -317

- 1. Aim/Overview of the practical:** Implementing SVM on any dataset and analyse the accuracy.
- 2. Task to be done/ Which logistics used:** Analysing accuracy by implementing the SVM on any dataset.
- 3. Steps of experiment/Code:**

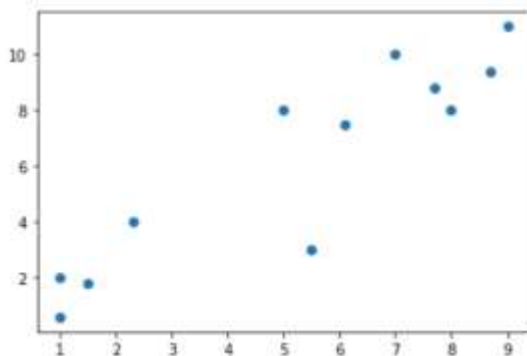
1. Importing libraries such as matplotlib and SVM.

```
import matplotlib.pyplot as plt
import numpy as np
from sklearn import svm

#linear data
x= np.array([1,5,1.5,8,1,9,7,8.7,2.3,5.5,7.7,6.1])
y= np.array([2,8,1.8,8,0.6,11,10,9.4,4,3,8.8,7.5])

plt.scatter(x,y)

<matplotlib.collections.PathCollection at 0x1bf924c6b80>
```



2. Shaping the data for training the model and defining the model:

```
#shaping data for training the model  
training_x= np.vstack((x,y)).T  
training_y= [0,1,0,1,0,1,1,1,0,0,1,1,]
```

```
#define the model  
clf= svm.SVC(kernel='linear', C=1.0)
```

```
#train the model  
clf.fit(training_x,training_y)
```

```
SVC(kernel='linear')
```

3. Get the weight values for the linear equation from the trained SVM model.

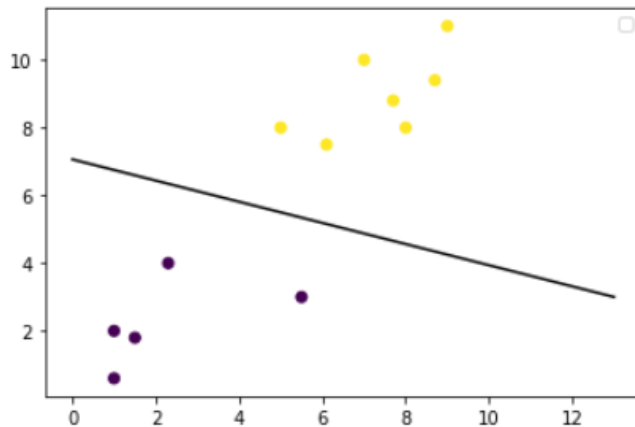
```
# get the weight values for the linear equation from the trained svm model  
w= clf.coef_[0]  
  
# get the y-offset for the linear equation  
a= -w[0] / w[1]  
  
# make the x-axis space for the data points  
xx= np.linspace (0,13)  
  
# get the y-values to plot the decision boundary  
yy= a * xx - clf.intercept_[0] /w[1]  
  
# plot the decision boundary  
plt.plot(xx, yy, 'k-')
```

4. Showing the plot visually.

```
# show the plot visually
```

```
plt.scatter(training_x[:,0], training_x[:,1], c= training_y)  
plt.legend()  
plt.show()
```

No handles with labels found to put in legend.



5. Again importing libraries to work for non- linear data:

```
import matplotlib.pyplot as plt  
import numpy as np  
from sklearn import datasets  
from sklearn import svm
```

6. Showing raw non-linear data and making non-linear algorithm for model:

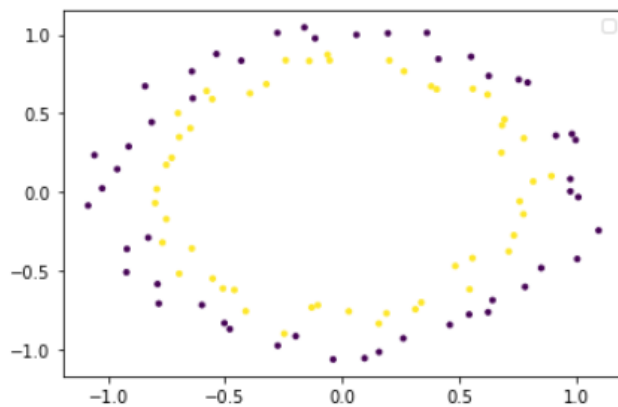
```
# non- linear data

circle_x, circle_y= datasets.make_circles(n_samples=100, noise= 0.05)
```

```
# show raw non-linear data

plt.scatter(circle_x[:,0], circle_x[:,1], c= circle_y, marker= '.')
plt.legend()
plt.show()
```

No handles with labels found to put in legend.



```
# make non-linear algortihm for model

nonLinear_clf= svm.SVC(kernel='rbf', C=1.0)
```

```
# training non-linear model

nonLinear_clf.fit(circle_x, circle_y)

SVC()
```

7. Plot the decision boundary for non-linear SVM problem:

```
# Plot the decision boundary for non_linear svm problem

def plot_decision_boundary(model, ax=None):
    if ax is None:
        ax = plt.gca()

    x_lim = ax.get_xlim()
    y_lim = ax.get_ylim()

    # create grid to evaluate model
    x = np.linspace(x_lim[0], x_lim[1], 30)
    y = np.linspace(y_lim[0], y_lim[1], 30)

    Y, X = np.meshgrid(y, x)

    # show data
    xy = np.vstack([X.ravel(), Y.ravel()]).T

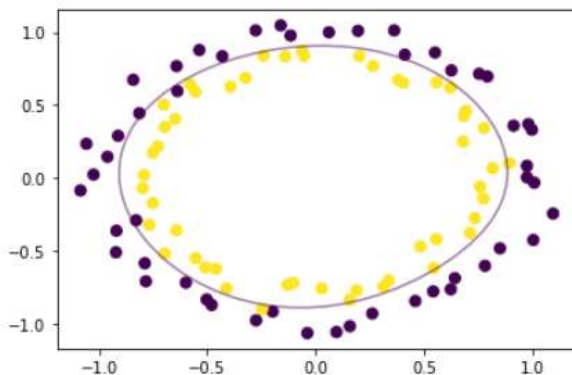
    # get the decision boundary based on the decision model
    P = model.decision_function(xy).reshape(X.shape)

    # Plot decision boundary
    ax.contour(X, Y, P,
               levels=[0], alpha=0.5,
               linestyle=['-'])
```

8. Plotting data and decision boundary:

```
# plot data and decision boundary

plt.scatter(circle_x[:,0], circle_x[:,1], c=circle_y, s=50)
plot_decision_boundary(nonLinear_clf)
plt.scatter(nonLinear_clf.support_vectors_[0], nonLinear_clf.support_vectors_[1], s=50, lw=1, facecolors='none')
plt.show()
```



9. Checking accuracy:

```
: from sklearn.model_selection import cross_val_score
clf = svm.SVC(kernel='linear', C=1, random_state=42)
score=cross_val_score(clf, training_x,training_y, cv=10)
print("avg accuracy:\t{0:,.4f}".format(np.mean(score)))
print("avg std:\t{0:,.4f}".format(np.std(score)))
```

Learning Outcomes (What I have learnt):

1. I have learnt about implementing SVM for both linear as well as non- linear data.
2. I have learnt about plotting data and decision boundary.
3. I have learnt about various libraries which are supported by python such as sklearn, numpy, matplotlib.
4. I have learnt about the various functions provided by various libraries.
5. I have understood the experiment very well.



DEPARTMENT OF COMPUTER SCIENCE & ENGINEERING

Discover. Learn. Empower.

Evaluation Grid:

	Parameters	Marks Obtained	Maximum Marks
1.	Student Performance (Conduct of experiment) objectives/Outcomes.		12
2.	Viva Voce		10
3.	Submission of Work Sheet (Record)		8
	Total		30