

# 2-way Deterministic Finite Automata

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# Outline

- 1 Introduction
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- 3 Languages accepted by 2DFA
- 4 Established Results

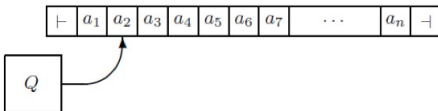
# What is 2DFA?

## 2DFA

A Two-Way Deterministic Finite Automaton (2DFA) is a type of finite state machine that extends the capabilities of a regular Deterministic Finite Automaton (DFA) by allowing its read head to move **bidirectionally** along the input tape.

- 2DFAs were introduced in 1959 by Rabin and Scott.

# How 2DFA works?



- Two-way Finite Automata has a read head, which can move left or right over the input string .
- Read head can revisit the input symbols any number of times.
- The input string is enclosed between left and right endmarkers  $\vdash$  and  $\dashv$ , which are not elements of the input alphabet  $\Sigma$ .
- The read head will not move outside of the endmarkers.
- A 2DFA needs only a single accept state and a single reject state.

# Turing Machine vs 2DFA

## Turing Machine:

- Contains a **read/write** head that moves left or right along the tape
- Has **unbounded** memory.

## 2DFA:

- Has **read** only head that moves left or right along the tape.
- Has **finite** memeory like DFA.

# Formal representation of 2DFA

A 2DFA is of the form

$$(Q, \Sigma, \vdash, \dashv, \delta, s, t, r)$$

where,

- $Q$  is a finite set of states.
- $\Sigma$  is a finite set of input symbols.
- $\vdash$  is the left endmarker. ( $\vdash \notin \Sigma$ )
- $\dashv$  is the right endmarker. ( $\dashv \notin \Sigma$ )
- $\delta : Q \times (\Sigma \cup \{\vdash, \dashv\}) \rightarrow Q \times \{L, R\}$  is a transition function.  
(L = left, R = right)
- $s \in Q$  is the start state.
- $t \in Q$  is the accept state.
- $r \in Q$  is the reject state ( $r \neq t$ ).

# Properties of transition function

For all states  $p$ ,

- $\delta(p, \vdash) = (q, R)$ , for some  $q \in Q$
- $\delta(p, \dashv) = (q, L)$ , for some  $q \in Q$

Current input symbol is  $a \in \Sigma \cup \{\vdash\}$ ,  $t$  = accept state,  $r$  = reject state.

- $\delta(t, a) = (t, R)$  and  $\delta(t, \dashv) = (t, L)$
- $\delta(r, a) = (r, R)$  and  $\delta(r, \dashv) = (r, L)$

In general,  $\delta(p, a) = (q, d)$  where  $p, q \in Q$  and  $d \in \{L, R\}$

# Example 2DFA

## 2DFA for $a^*$

$(Q, \Sigma, \vdash, \dashv, \delta, s, t, r)$  where,

- $Q = \{q_0, q_1, q_2\}$
- $\Sigma = \{a, b\}$
- $s = \text{start state} = q_0$
- $t = \text{accept state} = q_1$
- $r = \text{reject state} = q_2$

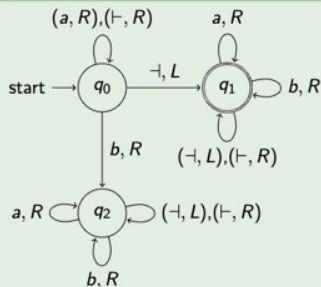


Table: Transition function  $\delta$

$\delta(, )$	$\vdash$	a	b	$\dashv$
$q_0$	$(q_0, R)$	$(q_0, R)$	$(q_2, R)$	$(q_1, L)$
$q_1$	$(q_1, R)$	$(q_1, R)$	$(q_1, R)$	$(q_1, L)$
$q_2$	$(q_2, R)$	$(q_2, R)$	$(q_2, R)$	$(q_2, L)$



# Configurations

Fix an input  $x \in \Sigma^*$ .  $x = a_1 a_2 a_3 \dots a_n$ . Let  $a_0 = \vdash$  and  $a_{n+1} = \dashv$ .  
 $a_0 a_1 a_2 a_3 \dots a_n a_{n+1} = \vdash x \dashv$ .

## Configuration

A configuration of the machine on input  $x$  is a pair  $(q, i)$  such that  $q \in Q$  and  $0 \leq i \leq n + 1$ . Informally, the pair  $(q, i)$  gives a **current state** and **current position** of the read head.

The **start configuration is  $(s, 0)$** , meaning that the machine is in its start state  $s$  and scanning the left endmarker.

A binary relation  $\xrightarrow[x]{1}$ , the next configuration relation, is defined on configurations as follows:

$$\delta(p, a_i) = (q, L) \Rightarrow (p, i) \xrightarrow[x]{1} (q, i - 1),$$

$$\delta(p, a_i) = (q, R) \Rightarrow (p, i) \xrightarrow[x]{1} (q, i + 1).$$

# Configurations

The relation  $\xrightarrow[x]{1}$  describes one step of the machine on input  $x$ . We define the relations  $\xrightarrow[x]{n}$  inductively,  $n \geq 0$ :

- $(p, i) \xrightarrow[x]{0} (p, i)$
- if  $(p, i) \xrightarrow[x]{n} (q, j)$  and  $(q, j) \xrightarrow[x]{1} (u, k)$ , then  $(p, i) \xrightarrow[x]{n+1} (u, k)$ .

For any configuration  $(p, i)$ , there is exactly one configuration  $(q, j)$  such that  $(p, i) \xrightarrow[x]{n} (q, j)$ .

# Acceptance and Rejection

$$(p, i) \xrightarrow{x}^* (q, j) \text{ iff } \exists n \geq 0 \text{ such that } (p, i) \xrightarrow{x}^n (q, j).$$

## Acceptance

The input  $x$  is accepted by the machine iff  $(s, 0) \xrightarrow{x}^* (t, k)$  for some  $k$ .

## Rejection

- The input  $x$  is rejected by the machine if  $(s, 0) \xrightarrow{x}^* (r, k)$  for some  $k$ .

If the machine neither reaches accept state nor reject state then the machine is said to be looping on that input.

Language accepted by the machine =  $\{x \in \Sigma^* \mid x \text{ is accepted by the machine}\}$ .

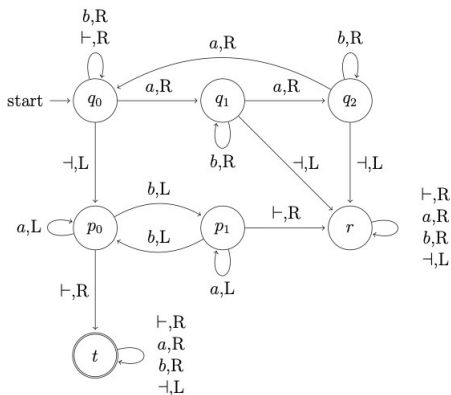
# Constructing 2DFA 'M'

$$L(M) = \{x \in \Sigma^* \mid \#a(x) \text{ is multiple of } 3, \#b(x) \text{ is multiple of } 2\}$$

## Machine Description

- Machine starts scanning from the left endmarker.
- Scan input string from left to right, counting only 'a's. If the count of 'a's is not a multiple of 3, reject and enter state  $r$ .
- Let  $q_0, q_1, q_2$  be the states for counting 'a's.  
 $q_0: 3k; q_1: 3k+1; q_2: 3k+2$ .
- If the count of 'a's is a multiple of 3, start scanning from the right, counting only 'b's. If the count of 'b's is not a multiple of 2, enter state  $t$ ; otherwise, enter state  $r$ .
- Let  $p_0, p_1$  be the states for counting 'b's.  
 $p_0: 2k; p_1: 2k+1$ .

# Constructing 2DFA 'M'



- input = bbaabab :

$$\begin{aligned}
 & q_0 \xrightarrow{\vdash} q_0 \xrightarrow{b} q_0 \xrightarrow{b} q_0 \xrightarrow{a} q_1 \xrightarrow{a} q_2 \xrightarrow{b} q_2 \xrightarrow{a} q_0 \xrightarrow{b} q_0 \xrightarrow{\vdash} p_0 \xrightarrow{b} \\
 & p_1 \xrightarrow{a} p_1 \xrightarrow{b} p_0 \dots \xrightarrow{\vdash} t
 \end{aligned}$$

# DFA to 2DFA conversion

## Theorem

- 2DFA only accepts regular languages.
- $L(2DFA) = L(DFA) = \text{Regular languages}$

## Proof: $L(DFA) \subseteq L(2DFA)$

For an arbitrary DFA 'X', let us construct a 2DFA 'Y' that accepts the same language as X.

- $X : (Q, \Sigma, \delta, s, F)$
- Let  $Y : (Q \cup \{t, r\}, \Sigma, \vdash, \dashv, \delta', s, t, r)$
- $\delta' : \delta_R \cup$   
 $\delta'((s, \vdash)) = (s, R)$   
 $\delta'((f, \dashv)) = (t, L) \text{ for } f \in F ; \delta'((n, \dashv)) = (r, L) \text{ for } n \in Q-F.$   
 $\delta'((t, a)) = (t, R) ; \delta'((r, a)) = (r, R) \text{ for } a \in \Sigma - \{-\}$   
 $\delta'((t, \dashv)) = (t, L) ; \delta'((r, \dashv)) = (r, L)$

# DFA to 2DFA conversion

Proof:  $L(X) \subseteq L(Y)$

- Let  $x \in L(X)$ ,  $\text{len}(x)=n$ .
- Then,  $\hat{\delta}(s,x) = f$  where  $f \in F$
- $(s,0) \xrightarrow[\vdash x \vdash]{1} (s,1) \xrightarrow[\vdash x \vdash]{n} (f,n+1) \xrightarrow[\vdash x \vdash]{1} (t,n)$  .
- As  $(s,0) \xrightarrow[\vdash x \vdash]{*} (t,n+1)$ ,  $x \in L(Y)$ .
- Hence,  $L(X) \subseteq L(Y)$ .

Recall:

A configuration of the machine on input  $x$  is the pair  $(q, i)$  , which gives the **current state** and **current position of the read head**.

$(s,0)$  means that the machine is in its start state  $s$  and scanning the left endmarker.

# DFA to 2DFA conversion

Proof:  $L(Y) \subseteq L(X)$

- Let  $x \in L(Y)$ ,  $\text{len}(x)=n$ .
- Then  $(s,0) \xrightarrow[\vdash x \vdash]{*} (t,m)$  in  $Y$
- So  $(s,0) \xrightarrow[\vdash x \vdash]{1} (s,1) \xrightarrow[\vdash x \vdash]{n} (f,n+1) \xrightarrow[\vdash x \vdash]{1} (t,n)$ .
- As  $\hat{\delta}(s,x) = f$  where  $f \in F$ ,  $x \in L(X)$
- Hence,  $L(Y) \subseteq L(X)$ .

**Therefore,  $L(Y) = L(X)$**



# Language accepted by a 2-way DFA is regular

- Claim: The language accepted by a 2-way finite automaton is regular
- We will prove this using Myhill-Nerode theorem
- Recall that the Myhill-Nerode theorem states that a language is regular if and only if the canonical equivalence relation has finitely many equivalence classes

# Language accepted by a 2-way DFA is regular

- Let  $M = (Q, \Sigma, \vdash, \dashv, \delta, s, t, r)$  be a 2-way finite automaton
- Let  $w = xz$  be a string in  $\Sigma^*$
- As the automaton is 2-way, its read head can cross the boundary between  $x$  and  $z$  several times.
- Consider the function  $T_x : (Q \cup \{\bullet\}) \rightarrow (Q \cup \{\perp\})$
- If the automaton goes to state  $q$  when it first crosses the boundary between  $x$  and  $z$ , define  $T_x(\bullet) = q$
- If the read head never crosses the boundary between  $x$  and  $z$ , define  $T_x(\bullet) = \perp$

# Language accepted by a 2-way DFA is regular

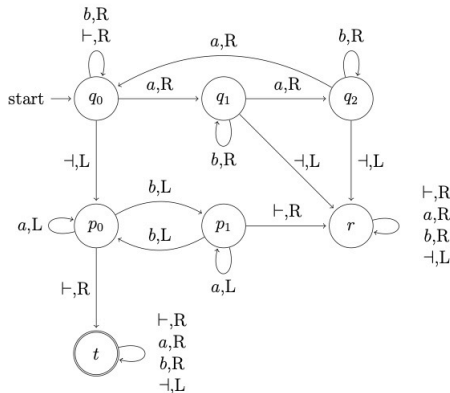
- Suppose the read head comes back from  $z$  to  $x$  and reaches state  $q$
- Then it may either go back to  $z$  reaching state  $p$ , in which case define  $T_x(q) = p$
- Else, it may never go back to  $z$ , in which case define  $T_x(q) = \perp$
- Note that the function  $T_x$  is well-defined as the automaton is deterministic
- Also,  $T_x$  depends only on  $x$  and is independent of  $z$
- And if  $y$  is another string in  $\Sigma^*$  such that  $T_x = T_y$ , then  $yz$  is accepted by the automaton if and only if  $xz$  is accepted by the automaton

# Language accepted by a 2-way DFA is regular

- Hence,  $xRy$  if and only if  $T_x = T_y$  becomes a canonical equivalence relation
- Since the number of unique functions is finite (at most  $(k+1)^{k+1}$ ), the canonical equivalence relation has finitely many equivalence classes
- Hence the language accepted by the 2-way DFA is regular

# Example

- Let us consider an example of a 2-way DFA accepting the language  
$$L = \{x \in \{a, b\}^* \mid \#a(x) \text{ is a multiple of 3 and } \#b(x) \text{ is even}\}$$



# Example

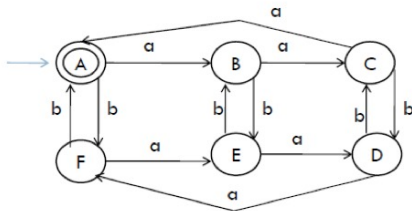
- For any  $x \in \{a, b\}^*$ ,
- If  $\#a(x) = k \pmod 3$ , then  $T_x(\bullet) = p_k$
- If  $\#b(x) = 0 \pmod 2$ , then  $T_x(p_0) = t$  and  $T_x(p_1) = r$
- If  $\#b(x) = 1 \pmod 2$ , then  $T_x(p_0) = r$  and  $T_x(p_1) = t$
- And  $T_x(t) = t$ ,  $T_x(r) = r$
- Hence, the canonical equivalence relation has 6 equivalence classes and the language is regular

# Constructing DFA from 2-way DFA

- Once we have the canonical equivalence relation, we can easily construct a DFA.
- Let  $M = (Q, \Sigma, \vdash, \dashv, \delta, s, t, r)$  be a 2-way finite automaton
- Let  $Q'$  be the set of all equivalence classes of the canonical equivalence relation
- $s' = T_\epsilon$
- $\delta'(T_x, a) = T_x a$
- $F' = \{T_x \mid x \in L(M)\}$
- DFA  $M' = (Q', \delta', s', F')$  will accept the same language as the 2-way DFA  $M$

# Example

- The DFA accepting the same language as the 2-way DFA is as follows:





# Unary finite automata

Below,  $H(n)$  represents the function  $e^{\sqrt{n \log(n)}}$

These are some statements related to unary finite automata

- Each unary  $n$ -state 2dfa can be simulated by a 1dfa with  $O(H(n))$  states.
- For each  $n$  there is a unary  $n$ -state 2dfa  $A$  such that each 1dfa recognizing  $L(A)$  requires  $\Omega(H(n))$  states.

# Unary finite automata

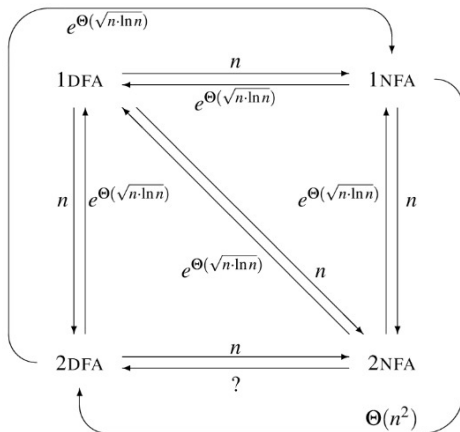
- For each  $n$  there is a unary  $n$ -state 2dfa  $A$  such that each 1nfa recognizing  $L(A)$  requires  $\Omega(H(n))$
- Each unary  $n$ -state 1nfa  $A$  can be simulated by a 2dfa  $B$  with  $O(n^2)$  states.
- For each  $n$  there is a unary  $n$ -state 1nfa  $A$  such that each 2dfa recognizing  $L(A)$  requires  $\Omega(n^2)$  states.

# Unary finite automata

Informally speaking we can see that 2dfa's are hard to simulate by 1dfa's, even if we consider only unary languages.

Also, for unary languages, two-way motion is more powerful, in a sense, because we can simulate unary 1nfa's by 2dfa's increasing the number of states only polynomially, which is not possible the other way round.

# Unary finite automata



# 1nfa to 2dfa

Lemma A: If  $\gcd(a,b)=1$ , then the greatest number such that the equation  $ax + by = c$  has no solutions in natural numbers is  $(a-1)(b-1)-1$ .

Theorem: For each  $n$  there is a unary  $n$ -state 1nfa  $A$  such that each 2dfa recognizing  $L(A)$  requires  $\Omega(n^2)$  states.

Proof: Let  $L = \{x \mid x = nx_1 + (n-1)x_2 \text{ for } x_1, x_2 \in \mathbb{N}\}$ .  $L$  can be recognized by a 1nfa  $A$  with  $n$  states.  $A = (Q, q_0, E, F)$  is defined as follows:  $Q = q_0, \dots, q_{n-1}$ ,  $E = \{(q_i, q_{i+1}) \mid i = 0, \dots, n-1\} \cup (q_1, q_0)$  (the addition is mod  $n$ ) and  $F = q_0$ . Let  $m = \max(\mathbb{N} - L)$ . By Lemma A,  $m = O(n^2)$ . Consider a 2dfa  $B$  recognizing  $L$  and its computation on  $m$ . Suppose that, in all passes on  $m$ ,  $B$  enters a cycle and let  $y_1, \dots, y_k$  be the lengths of these cycles. Then  $B$  would reject also  $m' = m + \text{lcm}(y_1, \dots, y_k)$ , which contradicts the fact that  $m' \in L$ . Therefore, there is a pass. of  $B$  on  $m$  without a cycle and the theorem follows.

# (Unary)2-DFA to 1-NFA/1-DFA - A worst case example

- Let  $F(n)$  be defined as follows:
- Maximum value of  $lcm(x_1, x_2, \dots, x_k)$  such that  $x_1 + x_2 + \dots + x_k = n$  and  $x_1, x_2, \dots, x_k \in \mathbb{N}$

Some properties of  $F(n)$ :

- $x_1, x_2, \dots, x_k$  can be found to be coprime satisfying  $lcm(x_1, x_2, \dots, x_k) = F(n)$
- $F(n) = O(H(n))$

# (Unary)2-DFA to 1-NFA/1-DFA - A worst case example

- Let the language  $L = \{a^{iF(n)} \mid i \in \mathbb{N}, i \geq 1\}$ .
- Take any 1-NFA accepting this language.
- Any simple path from a start state to a final state must have length at least  $F(n)$ .
- Canonical MN Relation has atleast  $F(n)$  classes.
- But 2-DFA can do better. Have  $x_i$  states to check divisibility by  $x_i$ .
- Upon seeing right end marker transition to new set of  $x_{i+1}$  states if divisible by  $x_i$ .
- Reject if not divisible by any  $x_i$ . Go to final state if divisible by all  $x_i$ . Total number of states =  $n + 2$ .

# (Unary)2-DFA to 1-DFA - Best known Bound

- Any unary 2-DFA with  $n$  states can be converted to 1-DFA with at most  $O(H(n))$  states.
- Any 2-DFA can be converted into an equivalent sweeping 2-DFA without changing the number of states. [Chrobak]
- For accepting words of length  $\leq n$  accepted by the 2-DFA, we have  $n$  states, mark them as final accordingly
- Note that any word of length longer than  $n$  accepted by the 2-DFA must pass through a cycle/pump.
- Any given state can be a part of at most one of these cycles.
- Say on a word  $u$  of length more than  $n$  the machine passes through at most  $k$  cycles.



# (Unary)2-DFA to 1-DFA - Best known Bound

- Let the lengths of the cycles be  $y_1, y_2, \dots, y_k$ . Then  $y_1 + y_2 + \dots + y_k \leq n$ .
- If a machine accepts a word  $u$  of length more than  $n$ , it must also accept a word of length  $|u| + lcm(y_1, y_2, \dots, y_k)$ .
- Construct a 1-DFA with first  $n$  states as mentioned and a loop of length  $lcm(y_1, y_2, \dots, y_k)$  attached to the last state. Mark states as final accordingly.
- Prove: This accepts the same language as the 2-DFA.
- The number of states in the 1-DFA is at most  $n + lcm(y_1, y_2, \dots, y_k) \leq n + F(n) = O(H(n))$ .

# Some other automata

- **2 way Non-deterministic Finite Automata:-** A two-way nondeterministic finite automaton (2NFA) may have multiple transitions defined in the same configuration.
- Its transition function is  $\delta : (Q \times \Sigma \cup \{L, R\}) \rightarrow 2^{Q \times \{left, right\}}$
- A 2NFA accepts a string if at least one of the possible computations is accepting. Like the 2DFAs, the 2NFAs also accept only regular languages.
- **Sweeping Automata:-** A two-way automaton performing head reversal only when the input head is visiting the endmarkers is called sweeping automaton.
- **Rotating Automata:-** A computation of a rotating automaton is a sequence of left-to-right scans of the input. In particular, when the right end of the input is reached, the computation continues on the leftmost input symbol.

## Some other automata

- In other words, we can imagine the input tape as circular, with a special cell containing a marker and connecting the end with the beginning of the tape.
- With a trivial transformation which doubles the number of the states, each rotating automaton can be transformed into an equivalent sweeping automaton.
- **2 way Alternating Finite Automata(AFA):** Structure same as 2 way NFA. Transitions divided into 2: existential and universal.
- Existential and universal transitions simulate all possible moves that can be made. Every state is given a truth value.
- Even if there is one simulation that leads to a final state, existential transitions return 1. Universal transitions return 1 only if all simulations lead to a final state.

## Other established results and open problems

- Christos Kapoutsis determined that transforming an  $n$ -state 2-DFA to an equivalent 1-DFA requires  $n(n^n - (n-1)^n)$  states in the worst case.
- If an  $n$ -state 2DFA or a 2NFA is transformed to a 1-NFA, the worst-case number of states required is  $\binom{2n}{n+1} = O(\frac{4^n}{\sqrt{n}})$ .
- Sipser constructed a sequence of languages, each accepted by an  $n$ -state NFA, yet which is not accepted by any sweeping automata with fewer than  $2^n$  states.
- **Sakoda-Sipser's open problem:-** Is there a 2-DFA with polynomial number of states accepting the same language as a 2-NFA?
- **Another open problem:** What is the relationship between unary 1-afa's (or 2-afa's) and other fa's? It is easy to show some lower and upper bounds for 1-afa's with only universal states.

# References

- Papers referenced are available on [Github](#)
- [Wikipedia link](#)