

Weak formulation

Weak formulations are important tools for the analysis of mathematical <u>equations</u> that permit the transfer of <u>concepts</u> of <u>linear algebra</u> to solve problems in other fields such as <u>partial differential equations</u>. In a weak formulation, equations or conditions are no longer required to hold absolutely (and this is not even well defined) and has instead <u>weak solutions</u> only with respect to certain "test vectors" or "<u>test functions</u>". In a **strong formulation**, the solution space is constructed such that these equations or conditions are already fulfilled.

The **Lax-Milgram theorem**, named after <u>Peter Lax</u> and <u>Arthur Milgram</u> who proved it in 1954, provides weak formulations for certain systems on Hilbert spaces.

General concept

Let V be a <u>Banach space</u>, let V' be the <u>dual space</u> of V, let $A: V \to V'$, and let $f \in V'$. A vector $u \in V$ is a solution of the equation

$$Au = f$$

if and only if for all $v \in V$,

$$[Au](v) = f(v).$$

Here, v is called a *test vector* (in general) or a *test function* (if V is a function space).

To bring this into the generic form of a weak formulation, find $u \in V$ such that

$$a(u,v) = f(v) \quad \forall v \in V,$$

by defining the bilinear form

$$a(u,v) := [Au](v).$$

Example 1: linear system of equations

Now, let $V=\mathbb{R}^n$ and $A:V\to V$ be a <u>linear mapping</u>. Then, the weak formulation of the equation

$$Au = f$$

involves finding $u \in V$ such that for all $v \in V$ the following equation holds:

$$\langle Au,v
angle = \langle f,v
angle,$$

where $\langle \cdot, \cdot \rangle$ denotes an inner product.

Since A is a linear mapping, it is sufficient to test with basis vectors, and we get

$$\langle Au, e_i
angle = \langle f, e_i
angle, \quad i = 1, \dots, n.$$

Actually, expanding $u=\sum_{j=1}^n u_j e_j$, we obtain the <u>matrix</u> form of the equation

$$Au = f$$

where
$$a_{ij} = \langle Ae_j, e_i \rangle$$
 and $f_i = \langle f, e_i \rangle$.

The bilinear form associated to this weak formulation is

$$a(u, v) = \mathbf{v}^T \mathbf{A} \mathbf{u}.$$

Example 2: Poisson's equation

To solve Poisson's equation

$$-\nabla^2 u = f$$
,

on a domain $\Omega\subset\mathbb{R}^d$ with u=0 on its <u>boundary</u>, and to specify the solution space V later, one can use the L^2 -scalar product

$$\langle u,v
angle = \int_\Omega uv\,dx$$

to derive the weak formulation. Then, testing with differentiable functions \boldsymbol{v} yields

$$-\int_\Omega (
abla^2 u) v \, dx = \int_\Omega f v \, dx.$$

The left side of this equation can be made more symmetric by integration by parts using Green's identity and assuming that v = 0 on $\partial\Omega$:

$$\int_{\Omega}
abla u \cdot
abla v \, dx = \int_{\Omega} f v \, dx.$$

This is what is usually called the weak formulation of <u>Poisson's equation</u>. Functions in the solution space V must be zero on the boundary, and have square-integrable <u>derivatives</u>. The appropriate space to satisfy these requirements is the <u>Sobolev space</u> $H_0^1(\Omega)$ of functions with <u>weak derivatives</u> in $L^2(\Omega)$ and with zero boundary conditions, so $V = H_0^1(\Omega)$.

The generic form is obtained by assigning

$$a(u,v) = \int_{\Omega}
abla u \cdot
abla v \, dx$$

and

$$f(v) = \int_{\Omega} fv \, dx.$$

The Lax-Milgram theorem

This is a formulation of the **Lax–Milgram theorem** which relies on properties of the symmetric part of the bilinear form. It is not the most general form.

Let V be a <u>Hilbert space</u> and $a(\cdot, \cdot)$ a <u>bilinear form</u> on V, which is

- 1. bounded: $|a(u,v)| \leq C||u||||v||$; and
- 2. coercive: $a(u, u) \ge c||u||^2$.

Then, for any $f \in V'$, there is a unique solution $u \in V$ to the equation

$$a(u,v) = f(v) \quad \forall v \in V$$

and it holds

$$||u|| \leq \frac{1}{c} ||f||_{V'}$$
.

Application to example 1

Here, application of the Lax–Milgram theorem is a stronger result than is needed.

- Boundedness: all bilinear forms on \mathbb{R}^n are bounded. In particular, we have $|a(u,v)| \leq \|A\| \, \|u\| \, \|v\|$
- Coercivity: this actually means that the <u>real parts</u> of the <u>eigenvalues</u> of A are not smaller than c. Since this implies in particular that no eigenvalue is zero, the system is solvable.

Additionally, this yields the estimate

$$||u|| \leq \frac{1}{c}||f||,$$

where c is the minimal real part of an eigenvalue of A.

Application to example 2

Here, choose $V=H^1_0(\Omega)$ with the norm

$$\|v\|_V:=\|\nabla v\|,$$

where the norm on the right is the L^2 -norm on Ω (this provides a true norm on V by the <u>Poincaré</u> inequality). But, we see that $|a(u,u)| = \|\nabla u\|^2$ and by the <u>Cauchy-Schwarz inequality</u>, $|a(u,v)| \leq \|\nabla u\| \|\nabla v\|$.

Therefore, for any $f \in [H_0^1(\Omega)]'$, there is a unique solution $u \in V$ of <u>Poisson's equation</u> and we have the estimate

$$\|\nabla u\| \leq \|f\|_{[H^1_0(\Omega)]'}.$$

See also

■ Babuška–Lax–Milgram theorem

■ Lions-Lax-Milgram theorem

References

Lax, Peter D.; Milgram, Arthur N. (1954), "Parabolic equations", Contributions to the theory of partial differential equations, Annals of Mathematics Studies, vol. 33, Princeton, N. J.: Princeton University Press, pp. 167–190, doi:10.1515/9781400882182-010 (https://doi.org/10.1515%2F9781400882182-010), ISBN 9781400882182, MR 0067317 (https://mathscinet.ams.org/mathscinet-getitem?mr=0067317), Zbl 0058.08703 (https://zbmath.org/?format=complete&q=an:0058.08703)

External links

MathWorld page on Lax–Milgram theorem (http://mathworld.wolfram.com/Lax-MilgramTheorem.html)

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