

## Broyden's Method

See Also: [Unconstrained Optimization \(/guide/types/#unconstrained\)](/guide/types/#unconstrained) > [Nonlinear Optimization \(/guide/types/nonlin/\)](/guide/types/nonlin/)

Recall that a potential shortcoming of Newton's method for nonlinear equations is that the derivatives required for the Jacobian may not be available or may be difficult to calculate. *Secant methods*, also known as *quasi-Newton* methods, do not require the calculation of the Jacobian; they construct an approximation to the matrix, which is updated at each iteration, so that it behaves similarly to the true Jacobian along the step. *Broyden's method* is the most successful secant-method for solving systems of nonlinear equations.

Let  $B_k$  be the Jacobian approximation at iteration  $k$  and let  $s_k = x_{k+1} - x_k$ . Then, the updated Jacobian approximation  $B_{k+1}$  must satisfy the *secant equation*

$$B_{k+1} s_k = f(x_{k+1}) - f(x_k). \quad (1)$$

Given an initial matrix  $B_0$  (often a finite-difference approximation to the Jacobian matrix), Broyden's method generates subsequent matrices by the update formula

$$B_{k+1} = B_k + \frac{(y_k - B_k s_k) s_k^T}{\|s_k\|_2^2}, \quad (2)$$

实际应用中,  $y_k$  是使用  $y_k - y_{(k-1)}$  替代

where  $y_k = f(x_{k+1}) - f(x_k)$ .

The remarkable feature of Broyden's method is that it is able to generate a reasonable approximation to the Jacobian matrix with no additional evaluations of the function. This feature is partially explained by noting that, because of equation (1), the updated  $B_{k+1}$  mimics the behavior of the true Jacobian along the line joining  $x_k$  to  $x_{k+1}$ .



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