

Blaine Costello

COMPUTATIONAL NANOMATERIALS | ALGORITHM DEVELOPMENT

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Education

Georgia Institute of Technology

PH.D. IN ELECTRICAL ENGINEERING (GPA: 3.54)

M.S. IN ELECTRICAL ENGINEERING (GPA: 3.54)

B.S. IN COMPUTER ENGINEERING (GPA: 3.57)

Atlanta, GA

2019 - 2021

2016 - 2019

2013 - 2016

Research

Graduate Research Assistant: Institute for Electronics and Nanotechnology (IEN)

Atlanta, GA

GEORGIA INSTITUTE OF TECHNOLOGY - DEPARTMENT OF ELECTRICAL & COMPUTER ENGINEERING

Aug 2016 - Present

- Designed, fabricated, and tested experimental nanocapacitors to study the impact of highly-polarizable material interfaces on the energy storage properties of nanolaminates ^[4].
- Developed and validated a custom simulator of electric fields in composite materials to study how the stochastic internal microstructure of nanoparticle composite materials impacts the limits and variations of energy density ^[3].
- Implemented a physics-based model to better predict the dielectric breakdown of simulated composites ^[2].
- Updated model for quasistatic electric field approximation to quantify the frequency dependence, energy density, and loss characteristics of simulated metal-insulator nanoparticle composites ^[1].

Undergraduate Research Assistant: Intelligent Robotics & Emergent Automation Lab (IREAL)

Atlanta, GA

GEORGIA INSTITUTE OF TECHNOLOGY - DEPARTMENT OF MECHANICAL ENGINEERING

Jan 2015 - Aug 2016

- Successfully designed, built, programmed, and tested a cooperative system of ground robots for planar payload manipulation ^[4].
- Designed prototype of a wire-traversing robot for a low-cost, low-power autonomous agricultural monitoring platform.

Research Engineer: Autonomous Airdrop & Landing Systems

Atlanta, GA

EARTHLY DYNAMICS CORPORATION - RESEARCH & DEVELOPMENT

May 2011 - Jan 2015

- Maintained prototyping lab equipment and produced user manual that was used in lab training for new employees.
- Fabricated and tested prototype of novel robotic landing gear system.
- Aided in design and experimental measurement of aerodynamic parameters for novel humanitarian aid airdrop system ^[6].

Projects

Decentralized Anonymous Peer-Review Ecosystem: Python, Solidity

2021

- Designed smart contracts for a decentralized service that maintains accountability through credential verification and recursion.
- Devised generalized incentive protocols to motivate adoption, engagement, and content creation.
- Created detailed outline of usage and logical flow for all categories of users.
- **Implementation in Progress...**

Autonomous Cryptocurrency Trading Bot: Python [tkinter, pandas, cbpro]

2019

- Implemented a functional autonomous cryptocurrency trading bot in python that is capable of employing a variety of custom trading strategies.
- Built functional GUI front-end to visualize monitor outputs and to update bot parameters from a remote device.
- Deployed and monitored the bot remotely on a custom-built Linux server.
- Implemented cloud architecture for scalable, account-based distribution.

PROFICIENCIES: Python, Matlab, Solidity, C/C++, Java, Unix terminal, Bash, CUDA, MOAB, Golang, Git, Data structures, Algorithm design.

Publications

- [1] B. Costello and J. A. Davis, "Energy Storage Limits and Variations in Metal-Insulator Nanocomposites Negative Filler Conductivity and Exotic Interphase Properties," <In-Progress>, 2021.
- [2] B. Costello and J. A. Davis, "Breakdown Field Strength Variations and Energy Density Limits of Nanoparticle Composite Materials," *IEEE Transactions on Nanotechnology*, vol. 19, pp. 811-819, 2020.
- [3] B. Costello, J.A. Davis. "Quasi-Electrostatic Simulation of Energy Density Limits and Variability in Nanoparticle (NP) Composite Materials," *TechConnect World Innovation Conference & Expo*, Boston, Massachusetts, 2019.
- [4] Z.M. Karimi, D. Brown, E. Woods, B. Costello, W. Henderson, J. Davis. "Characterization and Simulation of Permittivity Enhancements of Si O₂/Si₃N₄ Nanolaminate Layers," *IEEE Nanotechnology Materials and Devices Conference*, Portland, Oregon, 2018.
- [5] B. Costello, E. Davies, L. Strickland, J. Rogers. "A Novel Distributed Ground Robotic System for Cooperative Manipulation of Payloads of Any Size," CASE 2016, *IEEE International Conference on Automation Science and Engineering*, Fort Worth, Texas, 2016.
- [6] T. Herrmann, M. Costello, C. Montalvo, B. Costello, "Design, Simulation, and Experimental Testing of Humanitarian Aid Airdrop Micro Packages," *AIAA Atmospheric Flight Mechanics Conference*, Minneapolis, Minnesota, 2012.

References

Dr. Jeffrey A. Davis, Associate Professor of Electrical and Computer Engineering
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