

Implementation of Concurrent Hash Tables in Java

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Abstract—Abstract goes here.

Index Terms—Concurrent Programming, Hash-table representations

I. INTRODUCTION

The problem that our group chose to tackle, is how one would parallelize a hash table, and see how much of a performance increase, if any would arise from such an implementation. This paper seeks to explain the how hash tables function as a data structure, previous attempts at parallelizing them, our group's attempt at creating a concurrent hash table, and experimental data collected showing the effects of parallelizing on runtime for the program.

II. RESEARCH

A. What are Hash Tables?

Hash tables are a data structure that utilizes an associative array, which is a structure that associates keys to specific values, in order to store data. The way in which a hash table uses these keys, is by entering them into a hash function. The hash function will then compute the array index in which the value associated with the key will be stored. The hash function is naturally the most important portion of the hash table's construction. The most commonly used hashing methods use some variation of modular hashing. Modular hashing works as follows: assuming there is an array of size M , where M is prime, then for any positive integer key k , compute $k \bmod M$.

Modular hashing is expandable to accepting more than just integer as keys. A common data type used as a key for hash tables would be strings. In order to accomplish this, one would simply have to treat the string as though it were a large integer. This concept of converting data types into integers is commonly used as it is much simpler than creating a custom hashing function. A well made hash function will have three main requirements: deterministic - equivalent keys will always produce the same hash value, computationally efficient, and allows for keys to be uniformly distributed. Deterministic is only one of those requirements that is absolutely necessary for any hash function, as it what allows users to search hash tables for a specific key-value pairing [1].

There is of course, one issue with the hash function: since the hash table is not an array of infinite size, there is guaranteed to be instances where two distinct keys map to the same index when using the hash function. In order to resolve this, several techniques have been developed: linear probing, quadratic probing, double hashing, separate chaining or buckets. The basic concept for linear probing is that if the

current key-value attempting to be entered into the hash table collides at position i , then attempt to place it at $i + 1$. If it collides again, keep increasing the index by 1 until it comes across an index in the hash table array that has not been used yet, ending at $i + n$ where n is the number of collisions. Quadratic probing is similar to linear probing, except instead of ending up at $i + n$, the value will be stored at index $i + n^2$, where n is the number of collisions. Double hashing, also known as rehashing, involves hashing the key a second time, with a different hash function. That result is taken, and then used as the step size for a process similar to the previous two methods, resulting in the value being placed at index $i + jn$, where n is the number of collisions, and j is the result of the second hash function. These methods, known as open addressing, work, but as the hash table begins to fill up, they result in the `add()` operation taking more time to complete due to collisions. Separate chaining, on the other hand, works by having each index of the array be a linked list. Whenever a value maps to that index, it will be added into list, which avoids the issue that open addressing presents. Buckets is a similar method to separate chaining, using an array instead of a linked list. While separate chaining and buckets fix the issues with open addressing, they present more of their own, namely that there exist the possibility that a large majority of keys will map to the same index, which leads to a large amount of time being used searching the array or list at that index for the specified key's value [2].

B. What is Concurrency?

Now given what a hash table is, this paper will look at what exactly it means for a computer program to be concurrent. Concurrency means that multiple computations will be occurring at the same time. This has become increasingly more important, with the clock speed of processors no longer increasing, it results in manufacturers adding more cores to chips, meaning splitting up computation among those chips is the only way to make it faster. Concurrent programming has two common models: shared memory models and message passing models. This paper will only look at shared memory models as the implementation for a concurrent hash table will utilize a shared memory model. A shared memory model works by having concurrent processors read and write objects into the memory that they share [3].

III. RELATED WORK

I've seen a similar problem before

IV. CONTRIBUTIONS

I've fixed this problem once

V. ALGORITHMS

And this is how I did it!

Listing 1. Testing source code in \LaTeX .

```
class HashTable<T> {  
    bool isConcurrent;  
    public static void main(String [] args  
    ) {  
        isConcurrent = true;  
    }  
  
    public HashTable<T>(bool isConcurrent  
    ) {  
        this.isConcurrent = isConcurrent;  
    }  
}
```

VI. EXPERIMENTAL RESULTS

Well, it worked on my machine.

VII. APPENDIX

REFERENCES

- [1] R. Sedgewick and K. Wayne. "Hash Tables." princeton.edu. <https://algs4.cs.princeton.edu/34hash/> (accessed Mar. 13, 2022).
- [2] S. Mitra. "Hashing." utexas.edu. <https://www.cs.utexas.edu/~mitra/csSpring2017/cs313/lectures/hash.html> (accessed Mar. 13, 2022).
- [3] S. Amarasinghe, A. Chlipala, S. Devadas, M. Ernst, M. Goldman, J. Guttag, D. Jackson, R. Miller, M. Rinard, and A. Solar-Lezama. "Reading 17: Concurrency" mit.edu. <https://web.mit.edu/6.005/www/fall4/classes/17-concurrency/> (accessed Mar. 14, 2022).