

```
>> p= 1 -12.1 40.59 -17.015 -71.95 35.88];
>> r=roots(p)
r =
    6.5000
    4.0000
    2.3000
   -1.2000
    0.5000
```

When the roots are known, the polynomial can actually be written as:

$$f(x) = (x + 1.2)(x - 0.5)(x - 2.3)(x - 4)(x - 6.5)$$

The `roots` command is very useful for finding the roots of a quadratic equation. For example, to find the roots of  $f(x) = 4x^2 + 10x - 8$ , type:

```
>> roots([4 10 -8])
ans =
   -3.1375
    0.6375
```

When the roots of a polynomial are known, the `poly` command can be used for determining the coefficients of the polynomial. The form of the `poly` command is:

$p = \text{poly}(r)$

↙

$p$  is a row vector with the coefficients of the polynomial.

↘

$r$  is a vector (row or column) with the roots of the polynomial.

For example, the coefficients of the polynomial in Sample Problem 8-1 can be obtained from the roots of the polynomial (see above) by:

```
>> r=[6.5 4 2.3 -1.2 0.5];
>> p=poly(r)
p =
    1.0000   -12.1000   40.5900  -17.0150  -71.9500   35.8800
```

### 8.1.3 Addition, Multiplication, and Division of Polynomials

#### Addition:

Two polynomials can be added (or subtracted) by adding (subtracting) the vectors of the coefficients. If the polynomials are not of the same order (which means that the vectors of the coefficients are not of the same length), the shorter vector has to be modified to be of the same length as the longer vector by adding zeros (called padding) in front. For example, the polynomials

$f_1(x) = 3x^6 + 15x^5 - 10x^3 - 3x^2 + 15x - 40$  and  $f_2(x) = 3x^3 - 2x - 6$  can be added by:

```
>> p1=[3 15 0 -10 -3 15 -40];
```

```
>> p2=[3 0 -2 -6];
```

```
>> p=p1+[0 0 0 p2]
```

```
p =
     3     15     0     -7     -3     13    -46
```

Three 0s are added in front of p2, since the order of p1 is 6 and the order of p2 is 3.

### Multiplication:

Two polynomials can be multiplied using the MATLAB built-in function `conv`, which has the form:

```
c = conv(a,b)
```

c is a vector of the coefficients of the polynomial that is the product of the multiplication.

a and b are the vectors of the coefficients of the polynomials that are being multiplied.

- The two polynomials do not have to be of the same order.
- Multiplication of three or more polynomials is done by using the `conv` function repeatedly.

For example, multiplication of the polynomials  $f_1(x)$  and  $f_2(x)$  above gives:

```
>> pm=conv(p1,p2)
```

```
pm =
     9     45     -6    -78    -99     65    -54    -12    -10    240
```

which means that the answer is:

$$9x^9 + 45x^8 - 6x^7 - 78x^6 - 99x^5 + 65x^4 - 54x^3 - 12x^2 - 10x + 240$$

### Division:

A polynomial can be divided by another polynomial with the MATLAB built-in function `deconv`, which has the form:

```
[q,r] = deconv(u,v)
```

q is a vector with the coefficients of the quotient polynomial.

r is a vector with the coefficients of the remainder polynomial.

u is a vector with the coefficients of the numerator polynomial.

v is a vector with the coefficients of the denominator polynomial.

For example, dividing  $2x^3 + 9x^2 + 7x - 6$  by  $x + 3$  is done by:

```
>> u=[2 9 7 -6];
```

```
>> v=[1 3];
```