# Non-Linear Optimization

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#### CHAPTER 1

## Background

Our starting point is, for any positive integer  $d \in \mathbb{N}$ , the Cartesian products:

$$\mathbb{R}^d = \mathbb{R} \times \stackrel{(d)}{\dots} \times \mathbb{R} = \{ \boldsymbol{x} = (x_1, \dots, x_d) : x_k \in \mathbb{R} \text{ for } 1 \leq k \leq d \}.$$

We consider in this set the following two (closed) operations:

- (a) Addition: For  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d, \mathbf{x} + \mathbf{y} = (x_1 + y_1, \dots, x_d + y_d) \in \mathbb{R}^d$ .
- (b) Scalar multiplication: For  $\boldsymbol{x} \in \mathbb{R}^d$  and  $\lambda \in \mathbb{R}$ ,  $\lambda \cdot \boldsymbol{x} = \lambda \boldsymbol{x} = (\lambda x_1, \dots, \lambda x_d) \in \mathbb{R}^d$ .

With these two operations,  $(\mathbb{R}^d, +, \cdot)$  turns into a vector space: Given  $x, y, z \in \mathbb{R}^d$ ,  $\lambda, \mu \in \mathbb{R}$ ,

- (a) The addition is commutative: x + y = y + x.
- (b) Existence of identity elements for addition: Let  $\mathbf{0} = (0, \dots, 0)$ .  $\mathbf{x} + \mathbf{0} = \mathbf{x}$ .
- (c) The addition is associative: x + (y + z) = (x + y) + z.
- (d) Existence of inverse elements for addition: If  $\mathbf{x} = (x_1, \dots, x_d)$ , the element  $-\mathbf{x} = (-x_1, \dots, -x_d)$  satisfies  $\mathbf{x} + (-\mathbf{x}) = \mathbf{0}$ . We write  $\mathbf{x} \mathbf{y}$  instead of  $\mathbf{x} + (-\mathbf{y})$ .
- (e) Scalar multiplication is compatible with field multiplication:  $\lambda(\mu x) = (\lambda \mu)x$ .
- (f) Existence of identity for scalar multiplication:  $1 \cdot x = x$ .
- (g) Scalar multiplication is distributive with respect to addition:  $\lambda(x + y) = \lambda x + \lambda y$ .
- (h) Scalar multiplication is distributive with respect to field addition:  $(\lambda + \mu)x = \lambda x + \mu x$ .

A basis of  $\mathbb{R}^d$  is a finite set  $\mathcal{B} = \{ \boldsymbol{b}_k : 1 \leq k \leq d \}$  satisfying two properties:

- (a) Spanning property: For all  $\boldsymbol{x} \in \mathbb{R}^d$  there exist d scalars  $\{\lambda_1, \ldots, \lambda_d\}$  so that  $\boldsymbol{x} = \sum_{k=1}^d \lambda_k \boldsymbol{b}_k$ .
- (b) Linear independence: If  $\{\lambda_1, \ldots, \lambda_d\}$  satisfy  $\sum_{k=1}^d \lambda_k \boldsymbol{b}_k = \boldsymbol{0}$ , then it must be  $\lambda_k = 0$  for all  $1 \leq k \leq d$ .

PROBLEM 1.1. Define in  $\mathbb{R}^d$ , for each  $1 \leq k \leq d$  the element  $e_k$  to be the ordered d-tuple with k-th entry equal to one, and zeros on all other entries.

(a) Prove that  $\{e_k : 1 \le k \le d\}$  is a basis for  $\mathbb{R}^d$ .

(b) Set  $\boldsymbol{b}_k = \boldsymbol{e}_k - \boldsymbol{e}_{k+1}$  for  $1 \le k < d$ ,  $\boldsymbol{b}_d = \boldsymbol{e}_d$ . Is  $\{\boldsymbol{b}_k : 1 \le k \le d\}$  a basis for  $\mathbb{R}^d$ ?

#### 1. Functions

Given sets X, Y, we define a function  $f: X \to Y$  to be a subset of  $X \times Y$  subject to the following condition: for every  $x \in X$  there is exactly one element  $y \in Y$  such that the ordered pair (x, y) is contained in the subset defining f. The sets X and Y are called respectively the domain and codomain of f.

If A is any subset of the domain X, then f(A) is the subset of the codomain Y consisting of all images of elements of A. We say that f(A) is the *image* of A under f. The image of f is given by f(X). The *inverse image* of a subset B of the codomain Y under a function f is the subset of the domain X defined by  $f^{-1}(B) = \{x \in X : f(x) \in B\}$ .

For sets X, Y, Z, the function composition of  $f: X \to Y$  with  $g: Y \to Z$  is the function  $g \circ f: X \to Z$  defined by  $(g \circ f)(\mathbf{x}) = g(f(\mathbf{x}))$ .

If  $Y \subset \mathbb{R}$ , we say that the function f is real-valued. For a real-valued function  $f: \mathbb{R}^d \to \mathbb{R}$ , we may regard the corresponding ordered pairs  $(x, y) \in \mathbb{R}^d \times \mathbb{R}$  as points in a (d+1)-dimensional space. We call this set the *graph* of f.

Unless specifically stated, all functions in these notes are real-valued functions  $f: \mathbb{R}^d \to \mathbb{R}$ .

EXAMPLE 1.1 (Linear Functions). We say that a real-valued function is *linear* if it preserves the operations in  $\mathbb{R}^d$ :

$$f(\boldsymbol{x} + \lambda \boldsymbol{y}) = f(\boldsymbol{x}) + \lambda f(\boldsymbol{y}) \text{ for } \boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^d, \lambda \in \mathbb{R}.$$

With this definition, the function f(x) = 3x is indeed a linear function, but g(x) = 3x + 5 is not!

EXAMPLE 1.2 (Inner products). We say that a function  $\langle \cdot, \cdot \rangle \colon \mathbb{R}^d \to \mathbb{R}$  is an *inner product* if it satisfies the following five properties for all  $\boldsymbol{x}, \boldsymbol{y}, \boldsymbol{z} \in \mathbb{R}^d$  and  $\lambda \in \mathbb{R}$ .

- (a)  $\langle \boldsymbol{x} + \boldsymbol{y}, \boldsymbol{z} \rangle = \langle \boldsymbol{x}, \boldsymbol{z} \rangle + \langle \boldsymbol{y}, \boldsymbol{z} \rangle$ .
- (b)  $\langle \lambda \boldsymbol{x}, \boldsymbol{y} \rangle = \lambda \langle \boldsymbol{x}, \boldsymbol{y} \rangle$ .
- (c)  $\langle \boldsymbol{x}, \boldsymbol{y} \rangle = \langle \boldsymbol{y}, \boldsymbol{x} \rangle$ .
- (d)  $\langle \boldsymbol{x}, \boldsymbol{x} \rangle \geq 0$ .
- (e)  $\langle \boldsymbol{x}, \boldsymbol{x} \rangle = 0$  if and only if  $\boldsymbol{x} = 0$ .

PROBLEM 1.2. Consider the real-valued function  $\langle \cdot, \cdot \rangle \colon \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}$  as follows: Given  $\boldsymbol{x} = (x_1, \dots, x_d), \boldsymbol{y} = (y_1, \dots, y_d) \in \mathbb{R}^d$ ,

$$\langle x, y \rangle = \sum_{k=1}^{d} x_k y_k.$$

Prove this is a well-defined function:

(a) The domain of  $\langle \cdot, \cdot \rangle$  is  $\mathbb{R}^d \times \mathbb{R}^d$ .

- (b) For all  $\boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^d$ ,  $\langle \boldsymbol{x}, \boldsymbol{y} \rangle \in \mathbb{R}$ .
- (c) If  $\langle \boldsymbol{x}, \boldsymbol{y} \rangle = \lambda_1$  and  $\langle \boldsymbol{x}, \boldsymbol{y} \rangle = \lambda_2$ , then  $\lambda_1 = \lambda_2$ .

Prove that this function is an inner product.

PROBLEM 1.3. Prove that, if f is a linear function in the sense of Example 1.1, then there exist a unique  $\mathbf{a}_0 \in \mathbb{R}^d$  so that  $f(\mathbf{x}) = \langle \mathbf{a}_0, \mathbf{x} \rangle$  for all  $\mathbf{x} \in \mathbb{R}^d$ .

PROBLEM 1.4. We say that  $\tau \colon \mathbb{R}^d \to \mathbb{R}^d$  is a translation if there exist a fixed  $\mathbf{x}_0 \in \mathbb{R}^d$  so that  $\tau(\mathbf{x}) = \mathbf{x} + \mathbf{x}_0$  for all  $\mathbf{x} \in \mathbb{R}^d$ .

An affine function  $h: \mathbb{R}^d \to \mathbb{R}$  is a composition of a linear function  $f: \mathbb{R}^d \to \mathbb{R}$  with a translation  $\tau: \mathbb{R} \to \mathbb{R}$ .

Prove that for each affine function h there exist a unique  $\mathbf{a}_0 \in \mathbb{R}^d$  and a unique  $\lambda_0 \in \mathbb{R}$  so that  $h(\mathbf{x}) = \lambda_0 + \langle \mathbf{a}_0, \mathbf{x} \rangle$  for all  $\mathbf{x} \in \mathbb{R}^d$ . Use this result to prove that the graph of an affine function is a hyperplane in  $\mathbb{R}^{d+1}$ .

EXAMPLE 1.3 (Norms). A *norm* in  $\mathbb{R}^d$  is a function  $\|\cdot\|: \mathbb{R}^d \to \mathbb{R}$  that satisfies the following properties: For all  $\boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^d$ , and for all  $\lambda \in \mathbb{R}$ ,

- (a)  $\|x\| \ge 0$ .
- (b)  $\|\boldsymbol{x}\| = 0$  if and only if  $\boldsymbol{x} = \boldsymbol{0}$
- (c)  $\|\lambda \boldsymbol{x}\| = |\lambda| \|\boldsymbol{x}\|$ .
- (d) Triangle inequality:  $||x + y|| \le ||x|| + ||y||$ .

PROBLEM 1.5. Consider the function  $\|\cdot\|: \mathbb{R}^d \to \mathbb{R}$  defined by

$$\|\boldsymbol{x}\| = \langle \boldsymbol{x}, \boldsymbol{x} \rangle^{1/2}.$$

- (a) Prove that  $\|\cdot\|$  is a norm
- (b) Prove the Cauchy-Schwartz inequality: For all  $x, y \in \mathbb{R}^d$ ,

$$|\langle \boldsymbol{x}, \boldsymbol{y} \rangle| \le \|\boldsymbol{x}\| \|\boldsymbol{y}\|.$$

### 2. Topology

The norm introduced in Example 1.3 induces a metric d:  $\mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}^d$  on the space  $\mathbb{R}^d$ :

$$d(\boldsymbol{x}, \boldsymbol{y}) = \|\boldsymbol{x} - \boldsymbol{y}\| \text{ for any } \boldsymbol{x}, \boldsymbol{y} \in \mathbb{R}^d.$$

Given  $\boldsymbol{x}, \boldsymbol{y}, \boldsymbol{z} \in \mathbb{R}^d$ ,

- (a) Separation property:  $d(x, y) \ge 0$ .
- (b) Identity of indiscernibles: d(x, y) = 0 if and only if x = y.
- (c) Symmetry: d(x, y) = d(y, x).
- (d) Triangle inequality:  $d(x, z) \le d(x, y) + d(y, z)$ .

We say then that  $(\mathbb{R}^d, d(\cdot, \cdot))$  is a *metric space*. Metric spaces inherit a *topology* in a natural manner, as explained below.

We define the *open ball* of radius r > 0 about  $\boldsymbol{x}$  as the set  $B_d(\boldsymbol{x}, r) = \{\boldsymbol{y} \in \mathbb{R}^d : \|\boldsymbol{x} - \boldsymbol{y}\| < r\}$ . We say  $\boldsymbol{x}$  is an interior point of  $D \subset \mathbb{R}^d$  if  $\boldsymbol{x} \in D$  and there exists r > 0 so that  $B_d(\boldsymbol{x}, r) \subset D$ . A subset  $G \subset \mathbb{R}^d$  is said to be open if all its points are interior.

A neighborhood of the point x is any subset of  $\mathbb{R}^d$  that contains an open ball about x as subset.

A sequence  $(\boldsymbol{x}_n)_{n\in\mathbb{N}}$  in  $\mathbb{R}^d$  is an enumerated collection of elements of  $\mathbb{R}^d$  in which repetitions are allowed. A sequence is said to converge to the limit  $\boldsymbol{x} \in \mathbb{R}^d$  if and only if for every  $\varepsilon > 0$  there exists  $N = N(\varepsilon) \in \mathbb{N}$  so that  $\|\boldsymbol{x}_n - \boldsymbol{x}\| < \varepsilon$  for all  $n \geq N$ . We write then

$$x = \lim_{n} x_n$$
, or  $\lim_{n} ||x_n - x|| = 0$ .

We say that a sequence  $(\boldsymbol{x}_n)_{n\in\mathbb{N}}$  is a Cauchy sequence if for every  $\varepsilon > 0$  there exists  $N = N(\varepsilon) \in \mathbb{N}$  so that for any  $m, n \geq N$ ,  $\|\boldsymbol{x}_n - \boldsymbol{x}_m\| < \varepsilon$ . In  $\mathbb{R}^d$ , all Cauchy sequences converge (this is direct consequence of the completeness of  $\mathbb{R}$ ).

The complement of an open set is called *closed*. In  $\mathbb{R}^d$ , all subsets F are closed if and only if they are *sequentially closed*: If  $\mathbf{x}_n \in F$  for all  $n \in \mathbb{N}$  and  $\lim_n ||\mathbf{x}_n - \mathbf{x}|| = 0$ , then  $\mathbf{x} \in F$ .

We say D is bounded if there exists M > 0 so that  $D \subset B_d(\mathbf{0}, M)$ . A bounded and closed subset of  $\mathbb{R}^d$  is called *compact*.

THEOREM 2.1 (Bolzano-Weierstrass). Every sequence in a compact subset  $K \subset \mathbb{R}^d$  contains a convergent subsequence.

#### 3. Analysis

A real-valued function  $f: \mathbb{R}^d \to \mathbb{R}$  is continuous at  $\mathbf{x}_0$  if for any  $\varepsilon > 0$  there exists  $\delta = \delta(\varepsilon) > 0$  so that  $|f(\mathbf{x}) - f(\mathbf{x}_0)| < \varepsilon$  for all  $x \in B_d(\mathbf{x}_0, \delta)$ .

Equivalently,  $f: \mathbb{R}^d \to \mathbb{R}$  is continuous at  $\boldsymbol{x}_0$  if  $\lim_n f(\boldsymbol{x}_n) = f(\boldsymbol{x}_0)$  for any sequence  $(\boldsymbol{x}_n)_{n \in \mathbb{N}}$  satisfying  $\lim_n \boldsymbol{x}_n = \boldsymbol{x}_0$ .

We say that f is continuous in  $D \subset \mathbb{R}^d$  if f is continuous at all points  $x \in D$ .

A real-valued function  $f: \mathbb{R}^d \to \mathbb{R}$ 

Given a set  $D \subset \mathbb{R}^d$ , and a real-valued function  $f: D \to \mathbb{R}$ , we say that a point  $x^* \in D$  is:

- (a) A global minimum for f on D if  $f(x^*) \leq f(x)$  for all  $x \in D$ .
- (b) A strict global minimum for f on D if  $f(x^*) < f(x)$  for all  $x \in D \setminus \{x^*\}$ .
- (c) A local minimum for f on D if there exists  $\delta > 0$  so that  $f(x^*) \le f(x)$  for all  $x \in B_{\delta}(x^*) \cap D$ .
- (d) A local minimum for f on D if there exists  $\delta > 0$  so that  $f(\mathbf{x}^*) < f(\mathbf{x})$  for all  $\mathbf{x} \in B_{\delta}(\mathbf{x}^*) \cap D$ ,  $\mathbf{x} \neq \mathbf{x}^*$ .

A real-valued function  $f: \mathbb{R}^d \to \mathbb{R}$  is continuous at a point x

## $CHAPTER \ 2$

## Unconstrained Optimization via Calculus