# Notes and exercises from Finite Dimensional Multilinear Algebra

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# Introduction

This document contains notes and exercises from [1] and [2].

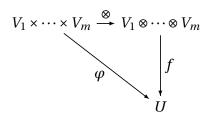
Unless otherwise stated, R denotes a field of characteristic 0 over which all vector spaces are defined.

# Part I

### **Chapter 1**

#### **§3**

**Exercise** (9,10). Let  $\varphi \in M(V_1, ..., V_m : U)$  in this commutative diagram:



Let  $K = \ker f$ . Then  $\operatorname{Im} \varphi = U$  if and only if f is surjective and every element in  $(V_1 \otimes \cdots \otimes V_m)/K$  has a decomposable representative.

*Proof.* If  $\operatorname{Im} \varphi = U$ , then f is surjective and there is an induced isomorphism  $\overline{f}: (V_1 \otimes \cdots \otimes V_m)/K \to U$ . Also for any  $\overline{z} \in (V_1 \otimes \cdots \otimes V_m)/K$  there are  $v_i \in V_i$  with

$$\overline{f}(\overline{v_1 \otimes \cdots \otimes v_m}) = f(v_1 \otimes \cdots \otimes v_m) = \varphi(v_1, \dots, v_m) = f(z) = \overline{f}(\overline{z})$$

Since  $\overline{f}$  is injective, it follows that  $\overline{v_1 \otimes \cdots \otimes v_m} = \overline{z}$ .

For the converse, if  $u \in U$  there are  $v_i \in V_i$  with  $\overline{v_1 \otimes \cdots \otimes v_m} = \overline{f}^{-1}(u)$ , so

$$u = \overline{f}(\overline{v_1 \otimes \cdots \otimes v_m}) = f(v_1 \otimes \cdots \otimes v_m) = \varphi(v_1, \dots, v_m)$$

Therefore  $\operatorname{Im} \varphi = U$ .

*Remark.* In Exercise 11, it is simpler to prove that  $(V_1 \otimes \cdots \otimes V_m)^*$  is a tensor product of  $V_1^*, \ldots, V_m^*$ , then use Theorem 2.4.

*Remark.* In Exercise 12, it is simpler to observe that the linear map induced by v through a tensor product is surjective between spaces of the same finite dimension and hence an isomorphism, then use Exercise 3.

#### **§ 4**

*Remark.* In the extension of the scalar field of V from R to F, it is simpler to observe that the scalar product of F on  $F \otimes V$  is the bilinear map corresponding

to the composite linear map

$$F \otimes (F \otimes V) \rightarrow (F \otimes F) \otimes V \rightarrow F \otimes V$$

using Exercise 4 in Section 1.3, where  $F \otimes F \to F$  is from multiplication in F.

*Remark.* If  $\sigma: R \to R$  is an involutory automorphism and V is a vector space over R, then the  $\sigma$ -conjugate vector space  $V^{\sigma}$  has the same underlying additive group as V, but has scalar multiplication defined by

$$\alpha v = \sigma(\alpha) v \qquad (\alpha \in R, v \in V)$$

where the product on the left is in  $V^{\sigma}$  and the product on the right is in V. Clearly  $(V^{\sigma})^{\sigma} = V$ .

If  $\varphi: U \times V \to R$  is a sesquilinear function, then the corresponding function  $\varphi^{\sigma}: U \times V^{\sigma} \to R$  defined by  $\varphi^{\sigma}(u, v) = \varphi(u, v)$  satisfies

$$\varphi^{\sigma}(u, \alpha v_1 + \beta v_2) = \varphi(u, \sigma(\alpha) v_1 + \sigma(\beta) v_2)$$

$$= \alpha \varphi(u, v_1) + \beta \varphi(u, v_2)$$

$$= \alpha \varphi^{\sigma}(u, v_1) + \beta \varphi^{\sigma}(u, v_2)$$

so  $\varphi^{\sigma}$  is *bilinear*, and the converse also holds.

If  $\otimes: V_1 \times V_2 \to V_1 \otimes V_2$  is a tensor product, then  $\otimes^{\sigma}: V_1^{\sigma} \times V_2^{\sigma} \to (V_1 \otimes V_2)^{\sigma}$  defined by  $v_1 \otimes^{\sigma} v_2 = v_1 \otimes v_2$  is also a tensor product, which means

$$(V_1 \otimes V_2)^{\sigma} = V_1^{\sigma} \otimes V_2^{\sigma}$$

Now if  $\varphi_i: U_i \times V_i \to R$  are sesquilinear for i = 1, ..., m, then we can define

$$\psi^{\sigma}(u_1,\ldots,u_m;v_1,\ldots,v_m)=\prod_{i=1}^m\varphi_i^{\sigma}(u_i,v_i)$$

which is *multilinear* and hence induces a bilinear  $\varphi^{\sigma}: (\bigotimes_{1}^{m} U_{i}) \times (\bigotimes_{1}^{m} V_{i})^{\sigma} \to R$  and corresponding sesquilinear  $\varphi: (\bigotimes_{1}^{m} U_{i}) \times (\bigotimes_{1}^{m} V_{i}) \to R$  with

$$\varphi(u_1 \otimes \cdots \otimes u_m, v_1 \otimes \cdots \otimes v_m) = \prod_{i=1}^m \varphi_i(u_i, v_i)$$

as in Theorem 4.4. This approach avoids the use of a basis in defining  $\varphi$ .

### Chapter 2

#### **§ 1**

*Remark.* The tensor product of linear maps of finite dimensional vector spaces is really a tensor product. More specifically, the map

$$\otimes: L(V_1, U_1) \times \cdots \times L(V_m, U_m) \to L(V_1 \otimes \cdots \otimes V_m, U_1 \otimes \cdots \otimes U_m)$$

defined by

$$(T_1,\ldots,T_m)\mapsto T_1\otimes\cdots\otimes T_m$$

is a tensor product map, so

$$L(V_1, U_1) \otimes \cdots \otimes L(V_m, U_m) = L(V_1 \otimes \cdots \otimes V_m, U_1 \otimes \cdots \otimes U_m)$$

This is the content of Theorem 2.7, which should be in this section. Similarly the Kronecker product of matrices is a tensor product.

*Remark.* In Example 1.2(b), it is simpler to prove (13) directly from definition (10) of the Kronecker product.

Remark. In Example 1.2(f), it is also possible to observe by (17) that

$$\det(A_1 \otimes A_2) = \det(A_1 \otimes I_{n_2}) \det(I_{n_1} \otimes A_2)$$

By Example 1.2(d),

$$\det(I_{n_1} \otimes A_2) = \det(A_2)^{n_1}$$

and by the same example after permuting rows and columns in the Kronecker product,

$$\det(A_1\otimes I_{n_2})=\det(I_{n_2}\otimes A_1)=\det(A_1)^{n_2}$$

so

$$\det(A_1 \otimes A_2) = \det(A_1)^{n_2} \det(A_2)^{n_1}$$

#### **§ 2**

*Remark.* In Exercise 4, it is also possible to use Example 2.6(c).

#### **§ 4**

*Remark.* In Exercise 11, it is simpler to use Exercise 10, together with Exercise 15 in Section 2.3.

### Chapter 3

#### **§ 1**

*Remark.* It follows from Theorem 1.7, together with Theorem 3.4 in Section 2.3, that if  $\varphi \in M_m(V, R, S_m, 1)$  and  $\varphi(x, ..., x) = 0$  for all  $x \in V$ , then  $\varphi = 0$ . In other words, *a* (completely) symmetric multilinear function is completely determined by its output values on equal input values.

#### **§ 2**

*Remark.* It follows from Theorem 2.7 that a linear transformation of  $\bigotimes_1^m V$  is bisymmetric as a transformation if and only if it is (completely) symmetric as a tensor, when we take

$$L(\bigotimes_{1}^{m} V, \bigotimes_{1}^{m} V) = \bigotimes_{1}^{m} L(V, V)$$

as in the remark from Section 2.1 above. For decomposable transformations, this is immediate from Exercise 6 in Section 2.1.

*Remark.* In Exercise 25, if  $\varphi(x, y) = \langle x, y \rangle$  is an inner product on V over  $\mathbb{R}$ , then the induced derivation  $\delta_x : \bigwedge V \to \bigwedge V$  given by

$$\delta_x(x_1 \wedge \dots \wedge x_m) = \sum_{k=1}^m (-1)^{k-1} \langle x, x_k \rangle x_1 \wedge \dots \wedge \widehat{x_k} \wedge \dots \wedge x_m$$

is adjoint to the multiplication operator  $M_x: \Lambda V \to \Lambda V$  in Exercise 24 given by

$$M_x(x_1 \wedge \cdots \wedge x_m) = x \wedge x_1 \wedge \cdots \wedge x_m$$

under the induced inner product in  $\wedge V$ .

*Remark.* In Exercise 33, if  $H = S_m$  then

$$D(T_1,\ldots,T_m)=m!\Omega(T_1,\ldots,T_m)$$

# References

- $[1] \ \ Marcus, M.\ \textit{Finite Dimensional Multilinear Algebra I.} \ 1973.$
- $[2] \ \ Marcus, M.\ \emph{Finite Dimensional Multilinear Algebra II.}\ 1975.$