

# BLASE LONDOÑO

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EDUCATION	<b>Bachelor of Science</b> University of California, San Diego <ul style="list-style-type: none"><li>Major in Mechanical Engineering, Expected June 2027</li><li>Specialization in Controls and Robotics</li><li>Current GPA: 3.96</li></ul>			9/2024 - 6/2027
TECHNICAL SKILLS	<ul style="list-style-type: none"><li>MATLAB</li><li>Arduino C</li><li>Fusion 360</li></ul>	<ul style="list-style-type: none"><li>AutoCAD</li><li>Altium Designer</li><li>3D Printing</li></ul>	<ul style="list-style-type: none"><li>Laser Cutting</li><li>Soldering</li><li>Python</li></ul>	<ul style="list-style-type: none"><li>Java</li><li>LaTeX</li><li>Canva</li></ul>
EXPERIENCE	<b>IEEE-Eta Kappa Nu</b> <ul style="list-style-type: none"><li><i>Project Lead, Thermoacoustic Refrigerator Project</i>11/2025 - Present<ul style="list-style-type: none"><li>Selected to lead thermoacoustic refrigerator design project, recruiting team of first- and second-year mechanical engineering students for spring 2026 build cycle</li></ul></li><li><i>Sponsorship Chair</i>2/2025 - Present<ul style="list-style-type: none"><li>Secured corporate partnerships for networking events through targeted outreach campaign, consolidating 15+ years of contact data to improve engagement efficiency by 40%</li></ul></li><li><i>Mechanical Team Member, MacroPad Project</i>2/2025 - Present<ul style="list-style-type: none"><li>Designed 2-layer parametric keycap for integrated 0.6" OLED display with flexible housing adaptable to subteam requirements</li><li>Validated design through iterative prototyping and physical testing</li></ul></li></ul> <b>Mentee, Apple Next-Gen Innovators Mentorship Program</b> 10/2025 - Present <ul style="list-style-type: none"><li>Engaging in bi-weekly consultations with Apple Senior Product Designer on professional development strategies and mechanical design methodologies for robotics applications</li><li>Participating in technical workshops covering hardware engineering career pathways and product development processes</li></ul> <b>Undergraduate Student Researcher, Bandaru Group</b> 10/2025 - Present <ul style="list-style-type: none"><li>Conducting electrical characterization of semiconductor dielectrics using Keysight B1500A analyzer, supporting joint project between Professors Prabhakar Bandaru and Kenji Nomura</li><li>Performing I-V curve measurements and capacitance analysis to evaluate material properties for next-generation electronic devices</li></ul> <b>UCSD Yonder Dynamics</b> <ul style="list-style-type: none"><li><i>Mechanical Team Member</i>10/2025 - Present<ul style="list-style-type: none"><li>Redesigning rover wheel assembly in OnShape, reducing weight by 15% through topology optimization while maintaining structural integrity; manufactured using ASA 3D printing with carbon fiber reinforcement</li></ul></li><li><i>Electrical Team Member</i>10/2024 - 10/2025<ul style="list-style-type: none"><li>Engineered custom PCB for 24V/60A power distribution system in Altium Designer, achieving 20% footprint reduction through optimized component placement and high-current trace routing</li><li>Implemented thermal management solutions and executed fabrication tasks including crimping, soldering, and wire harnessing for rover electrical systems</li></ul></li></ul> <b>MATLAB Tutor, UCSD MAE Department</b> 8/2025 - 9/2025 <ul style="list-style-type: none"><li>Tutored ~35 students in MATLAB fundamentals: vectors, loops, functions, plotting</li><li>Developed challenge problems featuring Monte Carlo methods, PDE analysis, Fourier series</li></ul>			
PROJECTS	<b>Robotic Arm Competition Robot</b> 3/2025 - 6/2025 <ul style="list-style-type: none"><li>Designed and fabricated robot achieving 28" extension with yaw and pitch rotational capability using spherical coordinate positioning system; implemented laser-cut and 3D-printed components for structural elements</li><li>Optimized mechanical linkages in Fusion 360 to maximize reach while maintaining structural stability during ring collection and placement tasks</li></ul> <b>MATLAB Pirouette Movement Recognition Project</b> 8/2024 - 9/2024 <ul style="list-style-type: none"><li>Developed LSTM model in MATLAB to classify dancer movements from IMU time-series data, achieving &gt;85% accuracy</li><li>Documented methodology and results for analysis paper</li></ul>			