## CS6700: Tutorial 2

## **MENACE**

```
Gautham Govind A, EE19B022
import numpy as np
import matplotlib.pyplot as plt
from typing import NamedTuple
from google.colab import output
SEED = 0
BOARD COL = 3
BOARD ROW = 3
BOARD_SIZE = BOARD_COL * BOARD_ROW
Game board and actions are: \{q, w, e, a, s, d, z, x, c\}
q \mid w \mid e
-- | - - - | - -
a | s | d
-- | - - - | - -
Z \mid X \mid C
ACTIONS_KEY_MAP = { 'q': 0, 'w': 1, 'e': 2, 'a': 3, 's': 4, 'd': 5,
                    'z': 6, 'x': 7, 'c': 8}
np.random.seed(SEED)
State Defination
def print_state(board, clear_output=False):
  if clear output:
    output.clear()
  for i in range(BOARD_ROW):
    print('----')
    out = '| '
    for j in range(BOARD COL):
      if board[i, j] == \overline{1}:
           token = 'x'
      elif board[i, j] == -1:
          token = 'o'
      else:
           token = ' ' # empty position
      out += token + ' | '
    print(out)
  print('----')
```

```
class State:
  def init (self, symbol):
   # \overline{\text{the}} board is represented by an n * n array,
    # 1 represents the player who moves first,
    # -1 represents another player
    # 0 represents an empty position
    self.board = np.zeros((BOARD ROW, BOARD COL))
    self.symbol = symbol
    self.winner = 0
    self.end = None
  @property
  def hash value(self):
    hash = 0
    for x in np.nditer(self.board):
      hash = 3*hash + x + 1 # unique hash
    return hash
  def next(self, action: str):
    id = ACTIONS KEY MAP[action]
    i, j = id // BOARD COL, id % BOARD COL
    return self.next by pos(i, j)
  def next_by_pos(self, i: int, j: int):
    assert self.board[i, j] == 0
    new state = State(-self.symbol) # another player turn
    new state.board = np.copy(self.board)
    new state.board[i, j] = self.symbol # current player choose to
play at (i, j) pos
    return new state
 @property
  def possible actions(self):
    rev action map = {id: key for key, id in ACTIONS KEY MAP.items()}
    actions = []
    for i in range(BOARD ROW):
      for j in range(BOARD COL):
        if self.board[i, j] == 0:
          actions.append(rev action map[BOARD COL*i+j])
    return actions
  def is end(self):
    if self.end is not None:
      return self.end
    check = [1]
    # check row
```

```
for i in range(BOARD ROW):
      check.append(sum(self.board[i, :]))
    # check col
    for i in range(BOARD COL):
      check.append(sum(self.board[:, i]))
    # check diagonal
    diagonal = 0; reverse diagonal = 0
    for i in range(BOARD ROW):
      diagonal += self.board[i, i]
      reverse diagonal += self.board[BOARD ROW-i-1, i]
    check.append(diagonal)
    check.append(reverse diagonal)
    for x in check:
      if x == 3:
        self.end = True
        self.winner = 1 # player 1 wins
        return self.end
      elif x == -3:
        self.end = True
        self.winner = 2 # player 2 wins
        return self.end
    for x in np.nditer(self.board):
      if x == 0:
                          # play available
        self.end = False
        return self.end
    self.winner = 0 # draw
    self.end = True
    return self.end
Environment
class Env:
  def init (self):
    self.all_states = self.get all states()
    self.curr state = State(symbol=1)
  def get all states(self):
    all states = {} # is a dict with key as state hash value and
value as State object.
    def explore all substates(state):
      for i in range(BOARD ROW):
        for j in range(BOARD COL):
          if state.board[i, j] == 0:
            next_state = state.next_by_pos(i, j)
            if next state.hash value not in all states:
              all states[next state.hash value] = next state
```

```
if not next state.is end():
                explore all substates(next state)
    curr_state = State(symbol=1)
    all states[curr state.hash value] = curr state
    explore all substates(curr state)
    return all states
  def reset(self):
    self.curr state = State(symbol=1)
    return self.curr state
  def step(self, action):
    assert action in self.curr_state.possible_actions, f"Invalid
{action} for the current state \n{self.curr state.print state()}"
    next state hash = self.curr state.next(action).hash value
    next state = self.all states[next state hash]
    self.curr state = next state
    reward = 0
    return self.curr_state, reward
 def is end(self):
    return self.curr state.is end()
 @property
  def winner(self):
    result id = self.curr state.winner
    result = 'draw'
    if result id == 1:
      result = 'player1'
    elif result_id == 2:
      result = 'player2'
    return result
Policy
class BasePolicy:
  def reset(self):
    pass
  def update values(self, *args):
    pass
  def select action(self, state):
    raise Exception('Not Implemented Error')
class HumanPolicy(BasePolicy):
  def init (self, symbol):
    self.symbol = symbol
 def select action(self, state):
    assert state.symbol == self.symbol, f"Its not {self.symbol}
```

```
symbol's turn"
    print state(state.board, clear output=True)
    key = input("Input your position: ")
    return kev
class RandomPolicy(BasePolicy):
  def __init__(self, symbol):
    self.symbol = symbol
  def select action(self, state):
    assert state.symbol == self.symbol, f"Its not {self.symbol}
symbol's turn"
    return np.random.choice(state.possible actions)
class ActionPlayed(NamedTuple):
  hash value: str
  action: str
class MenacePolicy(BasePolicy):
  def __init__(self, all_states, symbol, tau=5.0):
    self.all states = all states
    self.symbol = symbol
    self.tau = tau
    # It store the number of stones for each action for each state
    self.state action value = self.initialize()
    # variable to store the history for updating the number of stones
    self.history = []
  def initialize(self):
    state action value = {}
    for hash value, state in self.all states.items():
      # initially all actions have 0 stones
      state action value[hash value] = {action: 0 for action in
state.possible actions}
    return state action value
  def reset(self):
    for action value in self.state action value.values():
      for action in action value.keys():
        action value[action] = 0
  def print updates(self, reward):
    print(f'Player with symbol {self.symbol} updates the following
history with {reward} stone')
    for item in self.history:
      board = np.copy(self.all_states[item.hash_value].board)
      id = ACTIONS KEY MAP[item.action]
```

```
i, j = id//BOARD COL, id%BOARD COL
      board[i, j] = self.symbol
      print state(board)
  def update values(self, reward, show update=False):
    # reward: if wins receive reward of 1 stone for the chosen action
             else -1 stone.
    # reward is either 1 or -1 depending upon if the player has won or
lost the game.
    if show update:
      self.print updates(reward)
    for item in self.history:
      # your code here
      self.state_action_value[item.hash_value][item.action] += reward
# update state action with appropriate term.
    self.history = []
 def select action(self, state): # Softmax action probability
    assert state.symbol == self.symbol, f"Its not {self.symbol}
symbol's turn"
    action value = self.state action value[state.hash value]
    max value = action value[max(action value, key=action value.get)]
    exp values = {action: np.exp((v-max value) / self.tau) for action,
v in action value.items()}
    normalizer = np.sum([v for v in exp_values.values()])
    prob = {action: v/normalizer for action, v in exp values.items()}
    action = np.random.choice(list(prob.keys()),
p=list(prob.values()))
    self.history.append(ActionPlayed(state.hash value, action))
    return action
Game Board
class Game:
  def __init__(self, env, player1, player2):
    self.env = env
    self.player1 = player1
    self.player2 = player2
    self.show_updates = False
 def alternate(self):
    while True:
      yield self.player1
     yield self.player2
  def train(self, epochs=1 00 000):
    game results = []
    player1 reward map = {'player1': 1, 'player2': -1, 'draw': 0}
```

```
for in range(epochs):
      result = self.play()
      # if player1 wins add 1 stone for the action chosen
      player1 reward = player1 reward map[result]
      player2 reward = -player1 reward # if player2 wins add 1 stone
      self.player1.update values(player1 reward)
      self.player2.update values(player2 reward)
 def play(self):
    alternate = self.alternate()
    state = self.env.reset()
    while not self.env.is end():
      player = next(alternate)
      action = player.select action(state)
      state, _ = self.env.step(action)
    result = self.env.winner
    return result
Experiment
env = Env()
player1 = MenacePolicy(env.all states, symbol=1)
player2 = MenacePolicy(env.all states, symbol=-1)
# player2 = RandomPolicy(symbol=-1)
game = Game(env, player1, player2)
game.train(epochs=1 00 000)
Game against Player 1
game with human player = Game(env, player1, HumanPolicy(symbol=-1))
game with human player.play()
result = env.winner
print(f"winner: {result}")
player1 reward map = {'player1': 1, 'player2': -1, 'draw': 0}
player1.update values(player1 reward map[result], show update=True)
- - - - - - - - - - - -
| x | 0 | x |
| x | o | o |
| | x | |
Input your position: z
```

```
winner: draw
Player with symbol 1 updates the following history with 0 stone
| | x | |
| | 0 | |
| x | 0 | x |
| | 0 | |
| | x | |
| x | 0 | x |
-----
| x | 0 | 0 |
 | x | |
| x | o | x |
| x | 0 | 0 |
| o | x | x |
Game against Player 2
game with human player = Game(env, HumanPolicy(symbol=1), player2)
game_with_human_player.play()
result = env.winner
print(f"winner: {result}")
player2_reward_map = {'player1': 1, 'player2': -1, 'draw': 0}
player2.update_values(player2_reward_map[result], show_update=True)
```

x   0
<pre>Input your position: z winner: player1 Player with symbol -1 updates the following history with 1 stone</pre>
x   o