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“Acceptance Study of the CLAS12 Detector Using
the Forwards Micromegas Tracker for Run Group E”

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Dedication

Dedicated to Opa, for instilling in me the passion for learning.

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Abstract

Abstract— Particle accelerators and detectors are the main source of data for High Energy Physics. In this context, they are usually massive machines with a great number of moving parts, most of which require work in calibration and maintenance to run in optimal conditions. Special care must be put into the software dedicated to this calibration, in addition to event reconstruction.

This thesis presents a calibration effort of this kind, done to the newest detector in the CLAS12 reconstruction chain — the Micromegas Vertex Tracker. The results obtained in this regard are favourable. The calibration proved successful, doubling vertex resolution, and providing harsher criteria for selecting useful particle tracks.

In addition, the thesis goes into detail about the improvements in reconstruction that come from this new detector, focusing on its acceptance, vertex resolution, and SIDIS variables. A full study is presented for the total acceptance in CLAS12, and the multiplicities of various types of particles are measured.

Keywords— Particle detectors; Jefferson Laboratories; CLAS12; Micromegas Detectors.

Resumen— Los aceleradores y detectores de partículas son la principal fuente de datos para la Física de Altas Energías. En este contexto, estos suelen ser máquinas masivas con un gran número de partes móviles, la mayoría de las cuales requieren un trabajo de calibración y mantenimiento para funcionar en condiciones óptimas. Hay que tener especial cuidado en el *software* dedicado a esta calibración, además del dedicado a la reconstrucción de eventos.

Esta tesis presenta un trabajo en calibración de este tipo, realizado al detector más nuevo de la cadena de reconstrucción de CLAS12 — el *Micromegas Vertex Tracker*. Los resultados obtenidos son favorables. La calibración resultó exitosa, duplicando la resolución de vértice y proporcionando criterios más duros para la selección de *tracks* de partículas útiles.

Además, la tesis profundiza en las mejoras en reconstrucción que aporta este nuevo detector, centrándose en su *acceptance*, la resolución de vértices y las variables de SIDIS. Se presenta un estudio completo de *acceptance* total de CLAS12, y se miden las multiplicidades de varios tipos de partículas.

Palabras Clave— Detectores de partículas; Jefferson Laboratories; CLAS12; Detectores Micromegas.

Glossary

BAND: Back Angle Neutron Detector
BMT: Barrel Micromegas Tracker
CCDB: Calibration and Conditions Database
CD: Central Detector
CEBAF: Continuous Electron Beam Accelerator Facility
CLAS12: CEBAF Large Acceptance Spectrometer for Operation at 12 GeV
CND: Central Neutron Detector
CS-Studio: Control System Studio
CTOF: Central Time-of-Flight
CVT: Central Vertex Tracker
DC: Drift Chambers
DIS: Deep Inelastic Scattering
DOCA: Distance Of Closest Approach
EB: Event Builder
EC: Electromagnetic Calorimeter
ECAL: Electromagnetic Calorimeters
ECIN: EC-Inner
ECOU: EC-Outer
EPICS: Experimental Physics and Industrial Control System
FD: Forward Detector
FMT: Forward Micromegas Tracker
FT: Forward Tagger
FTCal: Forward Tagger Calorimeter
FTOF: Forward Time-of-Flight
FTTrk: Forward Tagger Gas Tracker
FTHodo: Forward Tagger Hodoscope
GeV: Giga electronVolt
GUI: Graphical User Interface
HEP: High Energy Physics
HIPO: High-Performance Input Output File Format
HTCC: High Threshold Cherenkov Counter
IOC: Input / Output Controller
JLab: Jefferson Laboratories
linac: Linear Particle Accelerator
LTCC: Low Threshold Cherenkov Counter
MeV: Mega electronVolt
MM: Micro-Mesh Gaseous Structure (Micromegas)
mrad: milliradian
MVT: Micromegas Vertex Tracker
PID: Particle Identification
PCAL: Pre-shower Calorimeter
PDF: Parton Distribution Function
PMT: PhotoMultiplier Tube
pQCD: perturbative Quantum Chromodynamics
PV: Process Variable

QCD: Quantum Chromodynamics

RF: Radio-Frequency

RG-E: Run Group E

RG-F: Run Group F

RICH: Ring Imaging Cherenkov Detector

SVT: Silicon Vertex Tracker

SIDIS: Semi-Inclusive Deep Inelastic Scattering

T: Tesla

Contents

List of Figures	viii
1 Physics Motivation	1
1.1 Deep Inelastic Scattering	3
1.2 Semi-Inclusive Deep Inelastic Scattering	5
1.3 Hadronisation in the Nuclear Medium	6
2 Experiment	9
2.1 CEBAF	9
2.2 CLAS12	10
2.3 RG-E Experiment	26
3 FMT Alignment and Reconstruction	33
3.1 Forwards Micromegas Tracker	33
3.2 FMT Alignment	36
3.3 FMT Reconstruction Work	39
3.4 Validation and Results	40
4 Data Analysis	44
4.1 <code>clas12-rge-analysis</code>	44
4.2 Cuts	49
4.3 Sampling Fraction	51
4.4 Acceptance Correction	53
5 Results and Conclusions	55
5.1 FMT Efficiency	55
5.2 Acceptance Correction Results	59
5.3 Study Results	60
Addenda	61
RG-F Target Layout	61
Replicability	62

List of Figures

1	The standard model.	2
2	DIS in QCD.	3
3	Q^2 dependence of x PDF for the u quark.	5
4	α_s dependence on Q^2 .	6
5	CEBAF.	9
6	CLAS12.	10
7	HTCC	11
8	DC	13
9	LTCC Mirror System	13
10	FTOF	14
11	FT	16
12	CVT	17
13	Central Time-of-Flight	18
14	CLAS12 Reconstruction Chain.	19
15	CVT momentum resolution vs. momentum.	20
17	Particle going through DC.	21
16	DC momentum resolution vs momentum.	21
18	Particle β vs. momentum for positively charged tracks.	24
19	β distribution of neutrals.	25
20	Double-target system.	27
21	RG-E CS-Studio main screen	32
22	MM working principle.	33
23	MVT detector.	34
25	FMT detector geometry.	35
24	FMT reconstruction summary	35
26	Example FMT residuals plot	37
27	Examples of residuals goodness of fit plots	38
28	Residuals distribution improvement.	39
29	DC vs FMT z without geometric correction	40
30	z vs θ for DC and FMT.	41
31	DC vs FMT z with geometry correction	42
32	FMT layers efficiency	43
33	Q^2 vs ν comparison	50
34	Calorimeters E/p plots	51
35	Calorimeters $p_{\text{vis}}E/p$ plots	52
36	v_z for DC and FMT, run 12933	55
37	v_z for DC and FMT, run 12016	56
38	v_z for DC and FMT, w/ and w/out the geometry cut, run 12016	57
39	v_z FMT efficiency for e^- , π^+ , and π^- . Run 12016	58
40	θ FMT efficiency for e^- , π^+ , and π^- . Run 12016	58
41	ϕ FMT efficiency for e^- , π^+ , and π^- . Run 12016	59
42	Number of electrons detected in terms of ϕ for DC and FMT efficiencies for e^- . Run 12016	59
43	p FMT efficiency for e^- , π^+ , and π^- . Run 12016	60

1 Physics Motivation

Since ancient times, humanity has pondered the composition of matter. Philosophers from both East and West have often contemplated this question, and the modern view of this composition is based on the concept of the atom. The notion of the atom, or indivisible particle, was proposed by Democritus in the 6th century B.C. Despite its uncanny similarity to the modern concept of the atom, the model remained an abstract idea for more than two millennia.

In the grand scheme of things, it is only recently that we have been able to probe into the structure of matter and observe the atom. In 1897, J.J. Thomson discovered "corpuscles," or electrons, using a cathode ray tube. Based on this discovery, he proposed an atomic model consisting of a positively charged paste with lighter electrons floating inside. Then, in 1909, Ernest Rutherford put this model to the test in what became the first scattering experiment in history. By bombarding α -particles onto a thin gold foil, he proved that most of the atom's mass was concentrated in a small, positively charged nucleus at its center. He named the constituents of this nucleus protons.

Following that, Niels Bohr proposed the atomic planetary model in 1914. His theory precisely fit the experimental data for Hydrogen but did not apply to heavier atoms. This issue was resolved with the discovery of the neutron in 1932 by James Chadwick. This discovery made the masses of atoms consistent with available experimental data, marking the end of the era of classical particle physics. Then, in the 1950s and 1960s, a bewildering variety of particles were found in scattering experiments. The theory born from this "particle zoo" gave rise to the Standard Model, which explains these particles as combinations of a small number of fundamental particles. The model describes three of the four fundamental forces using force-mediating gauge bosons. Additionally, it describes 24 particles, which are the constituents of matter. Finally, it also includes one scalar boson, the Higgs boson, whose existence was proven in 2012 [Aad et al., 2012].

Half of these 24 particles are elementary constituents of hadrons. They were initially referred to as quarks by Murray Gell-Mann and George Zweig, and later as partons by Richard Feynman. Quarks are point-like spin-1/2 particles with a fraction of an electron's electric charge, and they are distinguished by "flavors". Both Gell-Mann and Zweig's constituent quark model and Feynman's parton model were later merged into the Quark-Parton model [Perkins, 2000].

Deep Inelastic Scattering (DIS) is the process used to investigate the interior of hadrons using leptons. The process is similar to Rutherford scattering and provided the first experimental evidence of quarks. DIS can be employed to delve even deeper into the structure of matter by utilising increasingly higher energies, thanks to Werner Heisenberg's uncertainty principle.

High-energy probes lead to asymptotic freedom, which is the property where the interactions between particles, such as quarks, become increasingly weak at shorter distances. This implies that inside hadrons, quarks mostly move as free, non-interacting particles. This allows for reliable calculation of event cross-sections in particle physics. Another important feature is colour confinement, which is the property of colour-charged particles that prevents their isolation. Colour charge is the Quantum Chromodynamics (QCD) equivalent of electric charge. There are

Standard Model of Elementary Particles

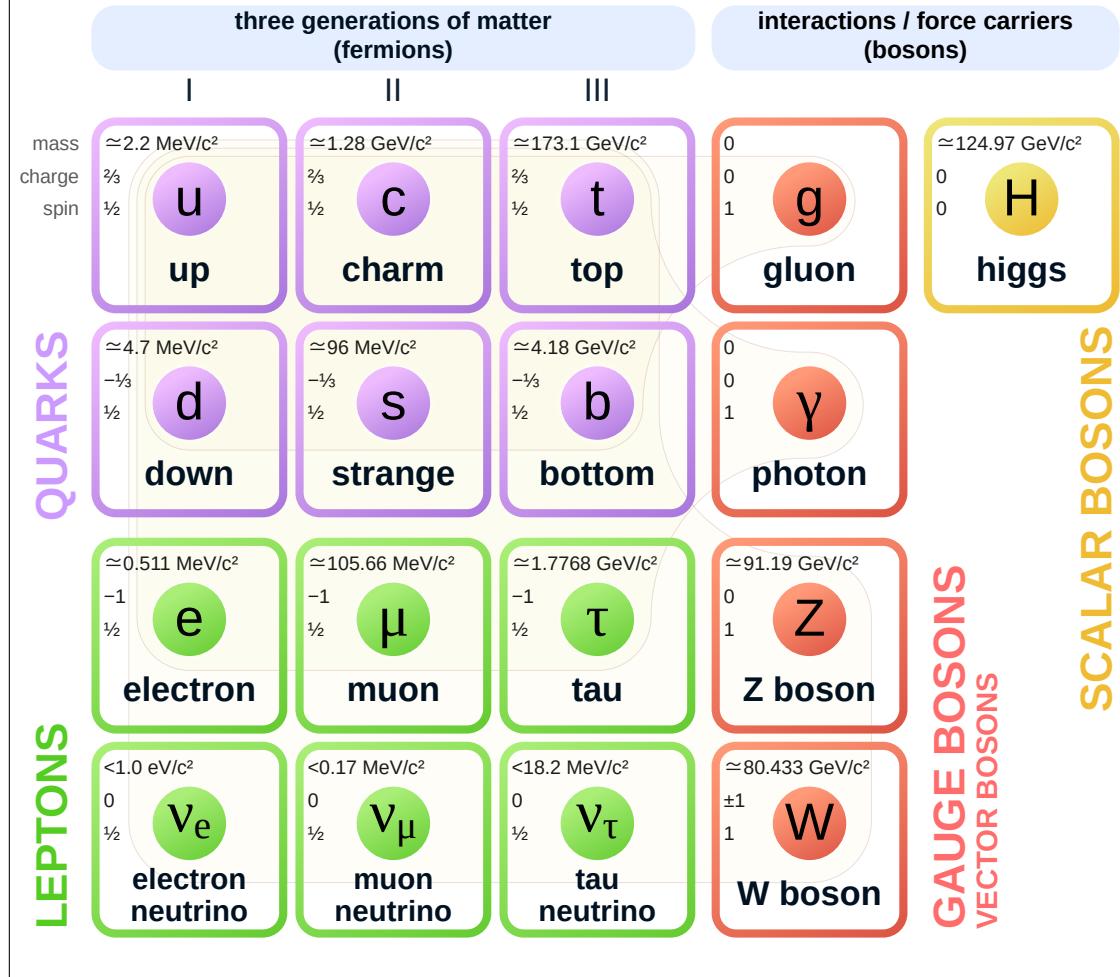


Figure 1: Fundamental particles in the Standard Model. Source: Wikimedia Commons.

three colour charges and their corresponding anticharges. Quarks possess a single colour charge, while gluons, the force-mediators of the strong force, have a bi-colour charge. In a state of equilibrium, the strong force confines quarks to be in close proximity, forming quark-antiquark pairs or 3-quark triplets in such a way that the net colour charge is neutral.

QCD describes these properties and models the quark strong interaction. Similar to the electromagnetic force, the strength of the interaction is determined by the strong coupling constant α . However, unlike the electromagnetic force, this constant weakens as distances decrease. At a larger distance scale, or smaller resolution, confinement is expected to become visible. The α value increases to values close to 1, and the perturbative treatment of QCD is not viable. There is limited knowledge about the non-perturbative behaviour of QCD, and therefore, it mostly relies on phenomenological models at present. The aim of the Run Group E (RG-E) experiment is to gather new data on the hadronic structure in Semi-Inclusive Deep Inelastic Scattering (SIDIS). Through this experiment, we hope to gain further insight into quark propagation and hadron formation.

1.1 Deep Inelastic Scattering

In its simplest description, DIS refers to the scattering of an electron off a quark inside a nucleon. Figure 2 displays the Feynman diagram illustrating DIS. The four-momentum of the nucleon is denoted by P , while that of the quark is represented by p . The initial and final four-momenta of the electron are given by k and k' , respectively. When k' is measured, the momentum transferred to the hadron system by the virtual photon is defined as $q = k - k'$. q is a spacelike vector conventionally denoted as $q^2 = -Q^2$.

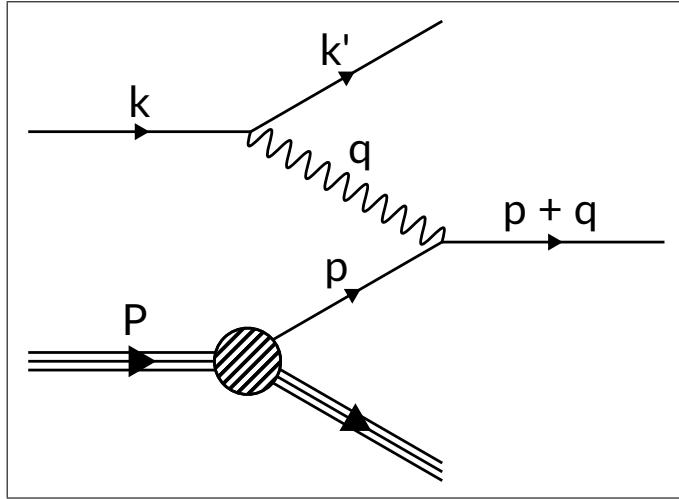


Figure 2: DIS in QCD. The diagram describes the stream of momentum in the scattering of a high energy electron off a quark. The quark's wave function is incorporated in the nucleon's wave function. Source: Own elaboration, using Inkscape.

If Q^2 is sufficiently high, the quark is ejected from the nucleon. Soft processes, such as gluon emission and quark-antiquark pair production, then take place to neutralise the colour charge. This results in the transformation of the ejected quark into a jet of hadrons. The jet propagates in the direction of the transferred momentum from the electron.

1.1.1 DIS Cross Section

To approximate the cross section of electron-nucleon scattering, we will work in the center of mass reference frame. In this frame, the electron and nucleon are moving towards each other with sufficient energy, allowing us to neglect the nucleon's mass. As a result, the nucleon possesses nearly lightlike momentum along the collision axis. Consequently, the constituent quarks of the nucleon also have nearly lightlike momenta that are nearly collinear to the nucleon's momentum. Hence, as a first-order approximation, we can express the quark's momentum as

$$p = \xi P,$$

where ξ represents the longitudinal fraction of the quark's momentum, and thus $0 < \xi < 1$.

In the leading-order approximation, we can also disregard gluon emission and exchange during the collision. Therefore, the cross section of electron-nucleon scattering is equal to that of electron-quark scattering for a given ξ , multiplied by the probability that the nucleon contains a quark with a longitudinal momentum fraction of ξ , integrated over ξ .

This calculation encounters the issue that the probability of a nucleon containing a quark with a specific momentum cannot be computed within perturbative QCD. It relies on the soft processes that determine the nucleon's structure as a composite system of quarks and gluons. Consequently, we must consider this probability as an unknown function that needs to be measured in experiments.

Such probability functions are known as Parton Distribution Functions (PDFs). A PDF can be assigned to various types of quarks, antiquarks, and gluons, and is incorporated into the nucleon's wave function. For each parton f , its PDF is defined as

$$P_f = f_f(\xi) d\xi.$$

Therefore, the cross section for the inelastic scattering of an electron off a nucleon, within the leading-order approximation, can be expressed as

$$\sigma(e^-(k)p(P) \rightarrow e^-(k')X) = \int_0^1 d\xi \sum_f f_f(\xi) \cdot \sigma(e^-(k)q_f(\xi P) \rightarrow e^-(k') + q_f(p')),$$

where X denotes the final hadronic state. It is important to remember that this equation does not provide an exact QCD prediction but represents the first-term expansion of α_s [Halzen and Martin, 1991]. This approximation is known as the parton model.

1.1.2 The Parton Model

In the parton model, the cross section is given by

$$\frac{d^2\sigma}{dxdy} (e^- p \rightarrow e^- X) = \left(\sum_f x f_f(x, Q^2) Q_f^2 \right) \frac{2\pi\alpha s}{Q^4} (1 + (1 - y)^2), \quad (1)$$

where $s \equiv 2P \cdot k$, Q_f represents the charge of parton f , and x and y are the Bjorken variables defined as

$$x \equiv \frac{Q^2}{2P \cdot q}, \quad y \equiv \frac{2P \cdot q}{s}.$$

In the nucleon's rest frame, $y = q^0/k^0$, and it represents the energy transferred to the hadron by the incoming electron.

The PDFs in Equation (1) have a weak dependence on Q^2 due to gluon radiation. This leads to Bjorken scaling violation [Halzen and Martin, 1991]. When the structure functions are known for certain values of Q^2 , they can be evolved to other values using the Dokshitzer-Gribov-Lipatov-Altarelli-Parisi (DGLAP) equations [Dokshitzer et al., 1991].

Figure 3 shows the predictions of the Altarelli-Parisi equations for the evolution of the PDFs with respect to Q^2 . Partons with large x tend to radiate and move towards states with lower x values. Simultaneously, radiation generates new partons with low x values. As Q^2 increases, the parton distributions decrease for large x

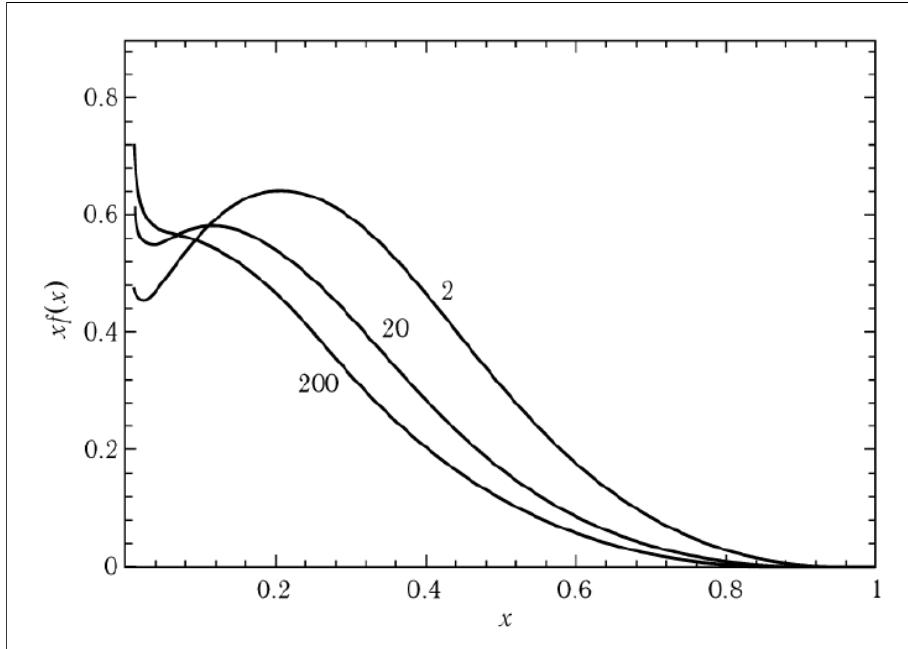


Figure 3: Parton distribution functions $xf_f(x)$ for the u quark at $Q = 2$, $Q = 20$, and $Q = 200$ GeV, showing the parton evolution effect according to the Altarelli-Parisi equations.

values while rapidly increasing for low x . At low Q^2 , the wavelength of the virtual photon is too large to probe the partons directly, resulting in probing the proton as a whole. The precise range of validity for the QCD-extended parton model is not known, but it is assumed to be applicable for $Q^2 > 1 \text{ GeV}^2$, corresponding to a spatial resolution of approximately 0.2 fm.

1.1.3 Strong Coupling Constant α_s

Measuring the experimental value of α_s is crucial for perturbative QCD calculations. To achieve this, the overall scale of renormalisation needs to be determined. Typically, the mass of the neutral Bose particle Z^0 , which is 91.19 GeV, is chosen as the scale. Furthermore, the renormalisation scheme should be fixed, which defines the coupling constant at a specific scale. The experimental results for α_s can be seen in Figure 4.

1.2 Semi-Inclusive Deep Inelastic Scattering

The previous section focused solely on the detection of the scattered electron in the inclusive reaction. However, in the case where one of the produced hadrons is identified, the event is referred to as semi-inclusive. The identification of this hadron provides information about the flavor of the quark that was struck. In SIDIS, it is possible to measure this flavor dependence. The identified hadrons in SIDIS are known as current fragments, and it is important to separate them in the analysis from the fragments originating from the target.

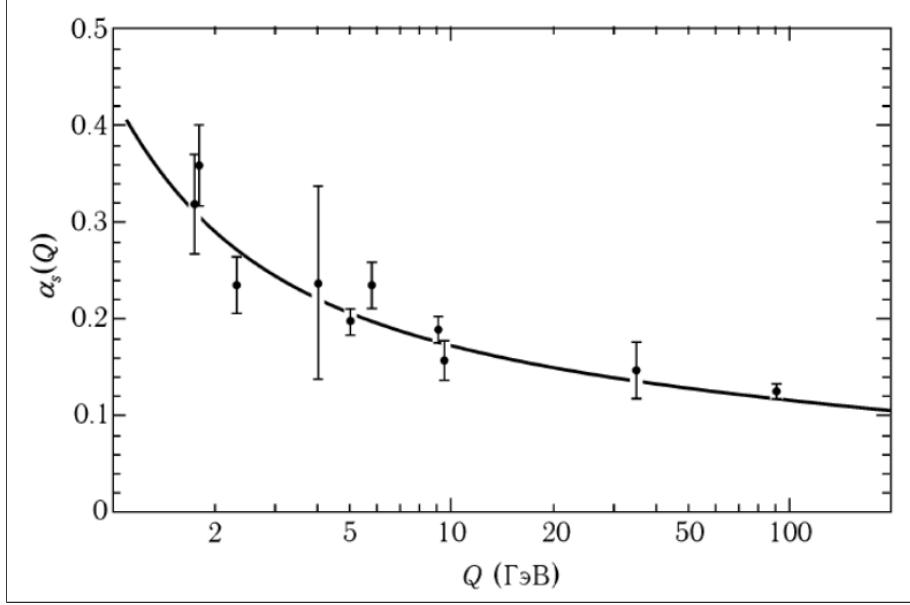


Figure 4: Experimentally measured dependence of α_s on Q . The measured values are compared with the theoretical predictions of renormalised evolution with an initial value of $\alpha_s(m_z) = 0.117$ GeV.

1.2.1 SIDIS Cross Section

In SIDIS, the fragmentation process corresponds to very low Q^2 and is not calculable in perturbative QCD (pQCD). It is parameterised by fragmentation functions $D_f^h(Q^2, z)$, which measure the probability that an f -flavoured quark fragments into an h -type hadron with a fraction z of the virtual photon energy ($E_h = z\nu$).

In the quark-parton model, the cross section for $eN \rightarrow ehX$ is assumed to be the differential cross section from Equation (1) multiplied by the fragmentation probability

$$\frac{d^3\sigma(eN \rightarrow ehX)}{dx dQ^2 dz} = \frac{d^2\sigma(eN \rightarrow eX)}{dx dQ^2} \cdot \frac{\sum_f e_f^2 q_f(x, Q^2) D_f^h(Q^2, z)}{\sum_f e_f^2 q_f(x, Q^2)}. \quad (2)$$

It is assumed that the quasi-free scattering process and the fragmentary process are independent in the cross section.

The hadron multiplicity per DIS event, denoted as $M_h(Q^2, z)$, is given by:

$$M_h(Q^2, z) \equiv \frac{1}{\sigma} \frac{d^3\sigma(eN \rightarrow ehX)}{dQ^2 dz} = \frac{\int dx \sum_f e_f^2 q_f(x, Q^2) D_f^h(Q^2, z)}{\int dx \sum_f e_f^2 q_f(x, Q^2)},$$

where σ is the differential inclusive DIS cross section $\frac{d^2\sigma(eN \rightarrow eX)}{dx dQ^2}$.

1.3 Hadronisation in the Nuclear Medium

Hadronisation is the process in which quarks and gluons form hadrons. In the nuclear medium, this process is influenced by quark energy loss through two mediums: gluon radiation and multiple quark-nucleon scattering. Additionally, hadron-nucleon interactions also affect the process if hadronisation occurs inside the nucleus.

The primary experimental observable in hadronisation is the multiplicity of hadrons produced in a dense nucleus compared to a light one, such as deuterium. In the absence of attenuation from interactions with the medium, these multiplicities should be identical, resulting in a ratio of unity. This ratio is known as the attenuation ratio and is defined as

$$R_{\text{att}}^h(z, \nu) = \frac{\left(\frac{1}{\sigma} \frac{d^2\sigma(eN \rightarrow ehX)}{dz d\nu}\right) A}{\left(\frac{1}{\sigma} \frac{d^2\sigma(eN \rightarrow ehX)}{dz d\nu}\right)^2 H},$$

where the derivative with respect to Q^2 is substituted with one with respect to ν . The ν and z dependence of this ratio can be used to study the nature of the hadron formation mechanism.

One type of observable that can be isolated is the characteristic times for the distinct stages of the hadronisation process. The existence of these stages is dictated by two fundamental properties in QCD: confinement and causality. Confinement implies that a coloured quark can only propagate for a limited distance. Causality dictates that the equilibrium colour field of a hadron cannot be formed instantaneously.

1.3.1 Virtual Photon Absorption

The first stage in the hadronisation process is the absorption of a virtual photon by a quark. This process occurs on a relatively short timescale, much less than 1 fm/c, and is governed by the wavelength of the virtual photon.

During this stage, the virtual photon interacts with a quark, transferring energy and momentum to the quark. The quark undergoes a transition to a higher energy state, which initiates the subsequent stages of hadronisation.

1.3.2 Production Time

Then, there must be a stage in which the coloured quark propagates as a quasi-free particle. During this second stage, there is gluon radiation with a differential spectrum given by pQCD as

$$d\omega^{q \rightarrow qg} = \frac{\alpha_s(k_\perp^2)}{4\pi} \frac{8}{3} \left[1 + \left(1 - \frac{k}{E}\right)^2 \right] \frac{dk}{k} \frac{dk_\perp^2}{k_\perp^2},$$

where E is the quark energy, k is the 4-momentum of the gluon, and k_\perp is its transverse momentum. The time associated with this stage is commonly referred to as the “production time” [Kopeliovich et al., 2004], and it represents the duration in which the quark is deconfined. The production time is a characteristic of the propagating quark and should be independent of the final hadron formed.

To a very good approximation, in deep inelastic kinematics and at $x > 0.1$, the struck quark absorbs all the energy of the virtual photon. Thus, the initial energy of the struck quark should be ν . This quantity is much larger than the quark’s mass (assuming an up or down quark), and thus we’ll ignore it in the treatment of this theory.

Conservation of energy then tells us that the final energy of the produced hadron should be no greater than ν . Additionally, the gluon radiation leads to a loss of

energy, resulting in the hadron's energy being below ν . We can estimate this energy loss from the string model [Artru and Mennessier, 1974]. The main parameter in the string model is the string tension $\kappa \approx 1 \text{ GeV/fm}$. The growth of the string creates an energy loss governed by this κ . Therefore, we can estimate the rate of vacuum energy loss as

$$\left. \frac{dE}{dx} \right|_{\text{vacuum}} \approx 1 \text{ GeV/fm}.$$

If $z_h = E_h/\nu$ is the fraction of the struck quark's energy retained by the hadron, then $\nu(1 - z_h)$ is the energy loss through gluon radiation. Thus, an estimate of the distance of gluon emission is

$$l_p = \frac{\nu(1 - z_h)}{\kappa},$$

and therefore the production time τ_p is l_p/c [Kopeliovich et al., 2004].

As an example, for a 10 GeV pion with $z_h = 0.6$, $l_p = 4 \text{ fm}$ – the production time is of the order of only a few fm for Jefferson Lab (JLab) energies.

1.3.3 Formation Time

In the final stage of the hadronisation process, the struck quark finds partner quarks to neutralise its colour, thus ending the gluon radiation. This stage is characterised by the evolution of the pre-hadron to an ordinary hadron and is commonly named the “formation time”. This is the time required to form the colour field of a hadron, and it should depend on the specific hadron being formed.

The formation time is not directly related to confinement, but rather it is a measure of the time required to form the non-perturbative colour field of the hadron, starting from a small colour-singlet object. This field generation time has a well-known analogue in Quantum Electrodynamics.

We can build a simple estimate for the formation time. To form a hadron of radius R from a point-like, single-colour singlet, the speed at which the field can arise (in its rest frame) is bound by the speed of light

$$\tau_{\text{formation}}^{\text{rest}} > \frac{R}{c},$$

which, when Lorentz-boosted into the lab frame, becomes

$$\tau_{\text{formation}}^{\text{lab}} > \frac{E}{m^*} \frac{R}{c},$$

where m^* is the mass of the propagating colour-singlet object. In principle, m^* ranges from the mass of two bare quarks to the fully formed hadron mass m_h . A lower limit for the formation time is given by setting $m^* = m_h$.

While this estimate is a classical calculation, a quantum mechanical analysis taking into account the gluon wavelength arrives at the same result, as is explained in [Dokshitzer et al., 1991].

2 Experiment

The Thomas Jefferson National Accelerator Facility is a High Energy Physics (HEP) laboratory located in Newport News, Virginia, USA. For simplicity and to follow convention, the laboratory will be called JLab hereafter. At the site, there is a recirculating linear electron accelerator named the Continuous Electron Beam Accelerator Facility (CEBAF). This accelerator is capable of delivering a 12 GeV electron beam to four experimental Halls simultaneously: Halls A, B, C, and D.

Different physics topics are studied in each of these halls. This thesis aims to provide a preparatory study for the RG-E experiment, which will take place in Hall B, where the CEBAF Large Acceptance Spectrometer for operation at 12 GeV (CLAS12) is located.

The first section provides a brief description of CEBAF at JLab. The second section then provides detailed information about CLAS12, including its central detector, forward detector, and offline event reconstruction. The third and final section discusses the RG-E experiment to be performed.

2.1 CEBAF

The CEBAF facility consists of a pair of 1.4-km-long antiparallel superconducting radio-frequency (RF) linear accelerators (linacs) constructed 8 meters below the surface. The two accelerators are connected by two 180-degree arcs, each with a

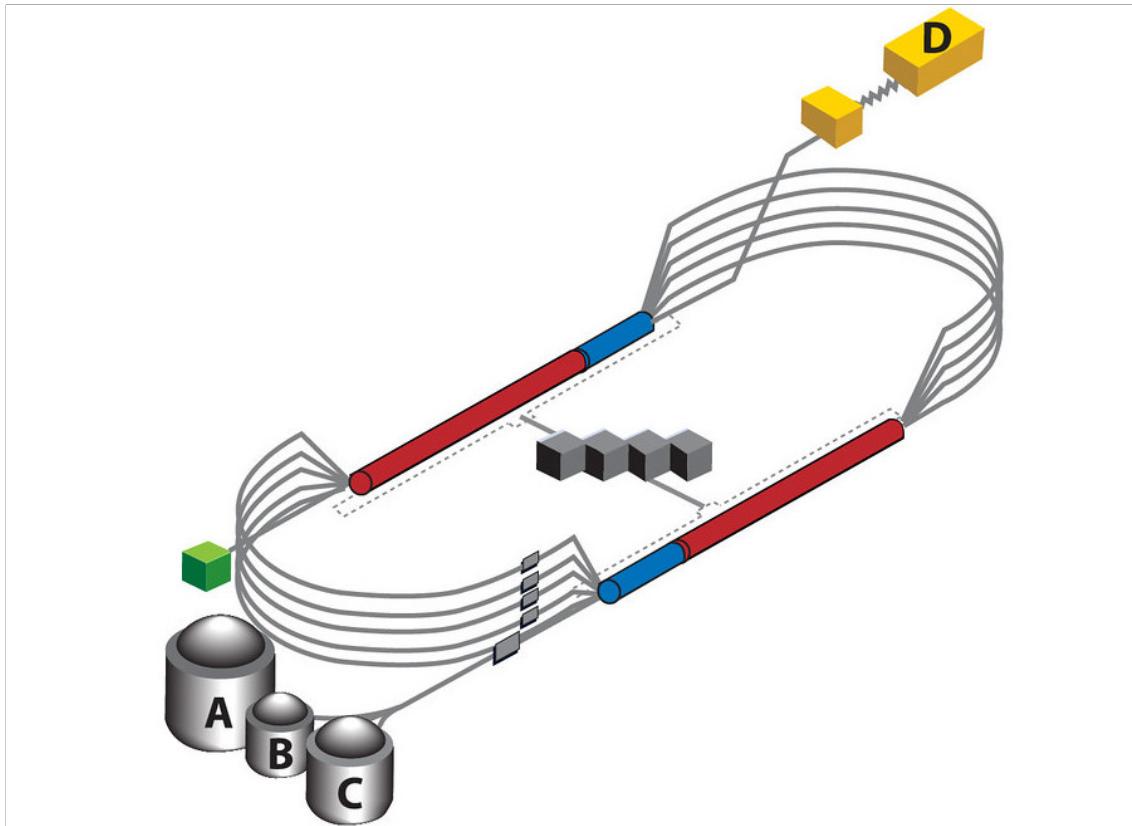


Figure 5: Simplified representation of CEBAF. Source: jlab.org.

radius of 80 meters [Leemann et al., 2001]. A schematic diagram illustrating the design of CEBAF is provided in Figure 5.

The recirculating arcs are composed of five separate beamline sections, allowing the beam to traverse each linear particle accelerator (linac) up to five times. Within each linac, the energy gain of the beam ranges from 0.8 GeV to 1.2 GeV, resulting in a final beam energy of approximately 12 GeV. CEBAF is specifically designed for high-energy electron beam experiments aimed at studying the structure of mesons, nucleons, and nuclei [Rode and Team, 2010].

2.2 CLAS12

The main detector in Hall B is CLAS12, used to study electro-induced nuclear and hadronic reactions [Burkert et al., 2020]. The spectrometer provides efficient detection of charged and neutral particles over a large fraction of the full solid angle.

CLAS12 is based on two superconducting magnets: a solenoid magnet and a 5 T torus magnet. The detector is divided into two parts: the Forward Detector (FD)

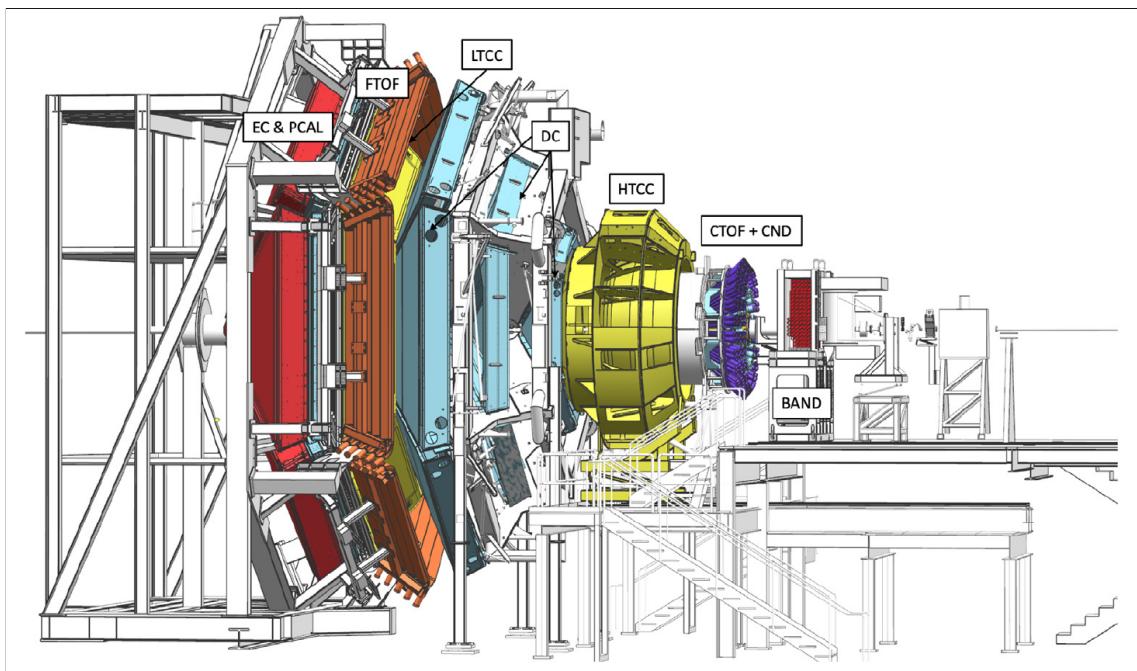


Figure 6: The CLAS12 detector in the Hall B beamline. The electron beam enters from the right and impinges on the target located in the center of the solenoid magnet shown at the right (upstream) end of CLAS12. The FD consists of the High Threshold Cherenkov Counter (HTCC) (yellow), the torus magnet (grey), the Drift Chambers (DC) tracking system (light blue), and another set of Cherenkov counters (hidden), time-of-flight scintillation counters (brown), and Electromagnetic Calorimeters (ECs) (red). Between the HTCC and the torus, the Forward Tagger (FT) is installed. The Central Detector (CD) consists of the Silicon Vertex Tracker (SVT) (hidden), which is surrounded by a Barrel Micromesh Tracker (BMT) (hidden), the Central Time-of-Flight (FTOF) system, and the Central Neutron Detector (CND) (blue). At the upstream end, a Back Angle Neutron Detector (BAND) (red) is installed. Source: CLAS12 wiki.

and the Central Detector (CD). The FD, aided by the torus magnet, covers the forward polar range from 5° up to 35° , while the CD, aided by the solenoid magnet, covers the polar angles from 35° to 125° . Both detectors have full azimuthal coverage.

Trajectory reconstruction is performed using Drift Chambers (DC) in the forward direction, achieving a momentum resolution of less than 1%. In the central detector, trajectory reconstruction is done using a vertex tracker, resulting in a momentum resolution of less than 3%. Particle identification relies on Cherenkov counters, time-of-flight scintillators, and electromagnetic calorimeters [Burkert et al., 2020]. Fast triggering and high data-acquisition rates enable operation at a luminosity of $10^{35} \text{ cm}^{-2} \text{ s}^{-1}$ [Burkert et al., 2020].

A diagram of CLAS12 showing the position of each detector component is provided in Figure 6.

2.2.1 Forward Detector (FD)

High Threshold Cherenkov Counter (HTCC)

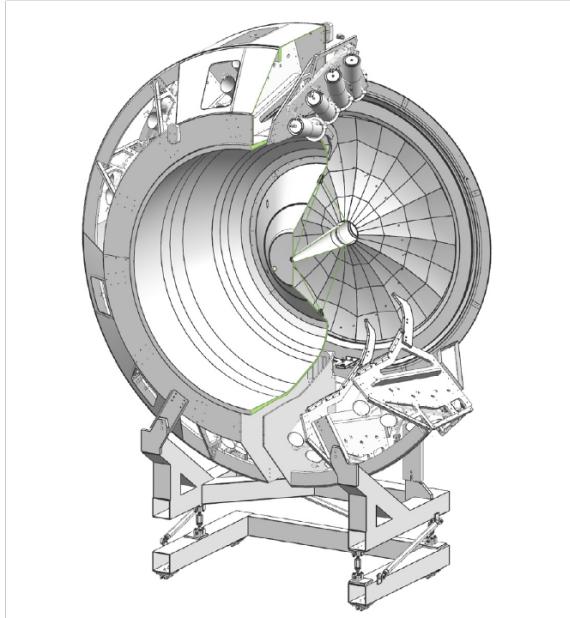


Figure 7: Render of the High Threshold Cherenkov Counter. The container spans a diameter of about 4.5 m. The mirror is seen at the downstream end to the right. The Photomultiplier Tubes (PMTs) are mounted in 12 sectors and in groups of 4 at the outer perimeter of the container. Light collection uses additional Winston cones and 5-in PMTs with quartz windows. Source: CLAS12 wiki.

ables the focusing of Cherenkov light produced by charged particles passing through the detector. The focused light is then detected by 48 PMTs, with each PMT featuring a quartz window of 125 mm in diameter.

The HTCC is specifically designed to separate electrons and positrons with momenta below 4.9 GeV from other ionizing particles. It achieves this through its capability for electron/positron identification, which provides high rejection of charged pions and low background noise. This is crucial for reliably identifying scattered electrons in an environment with a dense electromagnetic background.

The HTCC, positioned downstream of the target, is fitted in between magnets, upstream of the forward tracking detectors. It ensures full azimuthal coverage, meaning it can detect particles emitted from any direction around its circumference. In terms of the polar angle, it spans from 5° to 35° , covering a specific range of particle emission angles. Importantly, it has no blind areas in its complete solid angle coverage, meaning there are no regions where particles cannot be detected.

Operating in dry CO₂ gas at 1 atm pressure, the HTCC consists of a multi-focal mirror composed of 48 elliptical mirror facets. This mirror design en-

The PMTs are positioned within a magnetic field of up to $3.5 \cdot 10^{-3}$ T, which is oriented along the axes of the phototubes. To minimize the impact of the magnetic field on the PMTs, they are surrounded along their lengths by a multi-layer magnetic shield. This shield includes active compensation coils, which further help in shielding the PMTs from the effects of the magnetic field.

To minimize the effects of multiple scattering and its impact on the momentum analysis of charged tracks in the torus field, the HTCC mirror system is constructed using a backing structure made of low-density composite material. This choice of material helps to reduce the scattering of particles passing through the HTCC, thereby improving the accuracy of momentum measurements.

Since the HTCC is located in front of the momentum analyzing torus magnet, it is important to minimize the presence of materials in the path of charged particles, except for the radiator gas. This is done to prevent interactions and disturbances that could affect the accuracy of momentum analysis. The HTCC is designed with this consideration in mind.

In the HTCC, the density of solid material encountered by charged particles passing through its volume is approximately 135 mg/cm². This low-density configuration ensures that the material contribution to multiple scattering is minimised, allowing for more precise momentum measurements of charged tracks.

The HTCC also serves the purpose of generating a fast signal that can be used as a trigger for scattered electrons. This signal is utilised to identify and select scattered electrons for further analysis.

In conjunction with the energy deposited in the electromagnetic calorimeters, the HTCC plays a role in the identification of electrons with specific energies. By combining the information from the HTCC and the electromagnetic calorimeters, the experiment can accurately identify electrons of interest based on their energy deposition patterns.

A visual representation of the HTCC can be seen in Figure 7, which provides a cut view of the detector and its components.

Overall, the HTCC plays a crucial role in electron/positron identification by using a multi-focal mirror, PMTs, and a magnetic field setup. These components work together to ensure efficient detection and separation of electrons and positrons from other charged particles in a high-energy physics experiment environment.

Drift Chambers (DC)

The forward tracking system in the experiment consists of three independent drift chambers in each of the six sectors of the torus magnet. These drift chambers serve as the primary tracking detectors and are supported by the six coils of the torus magnet.

Each sector of the torus magnet contains a total of 36 layers in the drift chambers, with each layer having 112 sense wires. The sense wires are arranged in three regions, with each region comprising twelve layers. This configuration results in a total of 112 x 36 sense wires per sector.

The arrangement of the drift chambers around the torus coil can be visualised in Figure 8. The figure shows the positioning of the three regions of the drift chambers in each sector of the torus magnet.

In terms of location, the first region of the drift chambers is situated at the entrance to the torus magnetic field region. The second region is positioned inside the magnet, where the magnetic field is close to its maximum strength. Finally, the third region is located downstream of the torus magnet, in a low magnetic field space.

This arrangement of the drift chambers around the torus magnet provides independent and redundant tracking capabilities in each of the six torus sectors. It allows for precise reconstruction of charged particle trajectories and momentum measurements in the experiment.

Each of the three regions in the drift chambers consists of six "superlayers," where each superlayer comprises two layers. The wires in one layer are strung at a stereo angle of $+6^\circ$ relative to the sector midplane, while the wires in the other layer are strung at a stereo angle of -6° . This stereo configuration provides excellent resolution in the polar angle ($\Delta\theta < 2$ mrad) and good resolution in the azimuthal scattering angle ($\Delta\phi < 2$ mrad).

The drift chambers are capable of detecting ionising particles with momenta above 200 MeV/c, with a momentum resolution of $\Delta p/p$ less than 0.5%. This level of resolution corresponds to a track momentum resolution of 3% to 5%. The high precision in momentum measurements allows for accurate reconstruction of particle trajectories and precise determination of their momenta, which is crucial for the physics analysis in the experiment [Mestayer et al., 2020].

Low Threshold Cherenkov Counter (LTCC)

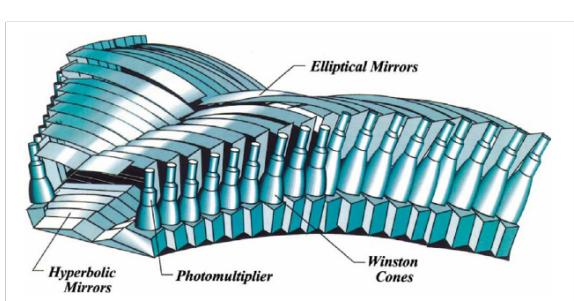


Figure 9: Layout and components of the optical mirror system within each LTCC box from the design model. Source: CLAS12 wiki.

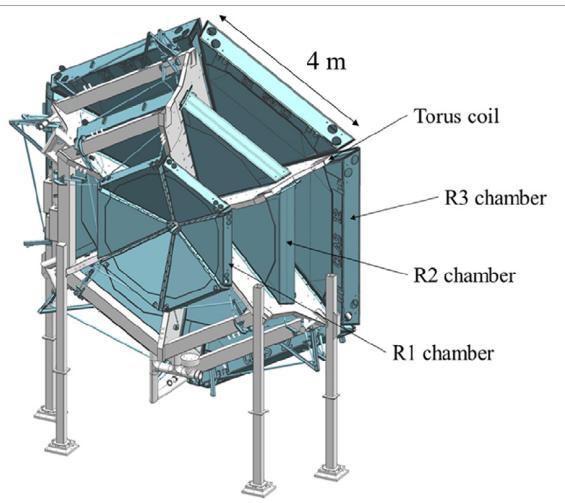


Figure 8: Drift Chambers render. Each of the DC regions are denoted as R1, R2, and R3 in the figure. Source: CLAS12 wiki.

The LTCC system in CLAS12 is designed for the detection of charged pions and kaons in the momentum range of 3.5 to 9 GeV. It consists of boxes shaped like truncated pyramids, with four out of the six sectors of CLAS12 equipped with one LTCC box. Each LTCC box contains 108 lightweight mirrors with composite backing structures, 36 Winston light-collecting cones, 36 125-mm diameter PMTs, and 36 magnetic shields. The LTCC boxes are filled with heavy C4 F10 radiator gas.

As part of the 12 GeV upgrade, the LTCC detector from the previous CLAS experiment was refurbished to enhance its

efficiency for charged pion and kaon detection. The enhancements included increasing the volume of the radiator gas, refurbishing the elliptical and hyperbolic mirrors with new coatings, and improving the sensitivity of the PMTs to Cherenkov light. The sensitivity improvement was achieved by coating the entrance windows of the PMTs with a wavelength-shifting material. This material absorbs ultraviolet (UV) light with wavelengths below 300 nm and re-emits two photons at a larger wavelength. These enhancements aim to improve the overall performance and detection efficiency of the LTCC system [Ungaro et al., 2020a]. A drawing from the design model of the LTCC can be seen in Figure 9.

Forward Time-of-Flight (FTOF)

The FTOF system is designed to measure the time-of-flight of charged particles emerging from the target during beam operation. It consists of six sectors of plastic scintillators with double-sided PMT readout. Each sector is divided into three arrays of counters separated into panels. Panel-1a has 23 counters, panel-1b has 62 counters, and panel-2 has 5 counters. The FTOF system is designed to provide excellent timing resolution for particle identification and good segmentation for flexible triggering options. The detectors cover a polar angle range from 5° to 45° , spanning 50% in azimuth at 5° and 90% at 45° . The lengths of the counters vary across the panels, ranging from 32.3 cm to 376.1 cm in panel-1a, from 17.3 cm to 407.9 cm in panel-1b, and from 371.3 cm to 426.2 cm in panel-2.

The timing resolution achieved in the FTOF system is 125 ps in panel-1a, 85 ps in panel-1b, and 155 ps in panel-2. This timing resolution allows for precise measurements of the particle's time-of-flight, which is crucial for particle identification purposes [Carman et al., 2020b]. A render of the FTOF detector can be seen in Figure 10.

Ring Imaging Cherenkov Detector (RICH)

To improve particle identification in the momentum range of $3 - 8$ GeV, a RICH detector was incorporated into one of the CLAS12 sectors, replacing the corresponding LTCC sector. The RICH detector enhances CLAS12's capabilities in separating kaons from pions.

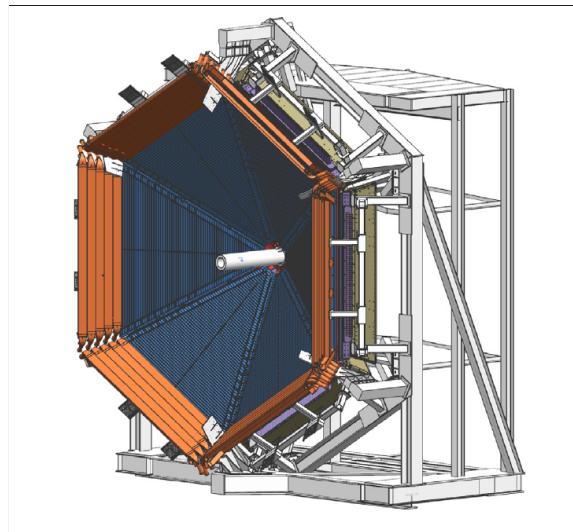


Figure 10: Render of the Forward Carriage with the FTOF system showing the panel-1b counters on the inside (dark blue), and the panel-2 counters on the outside (bronze). The panel-1a counters are located immediately downstream of the panel-1b counters and are not visible in the render. Part of the Pre-shower Calorimeter (PCAL) is visible downstream of the FTOF panels. Source: CLAS12 wiki.

The RICH detector consists of aerogel radiators, visible light photon detectors, and a focusing mirror system. The focusing mirror system is designed to reduce the instrumented detection area to 1 m². Multi-anode PMTs are used as the photon detectors, providing the necessary spatial resolution and matching the aerogel Cherenkov light spectrum in the visible and near-UV region.

For forward scattered particles with momenta between 3 and 8 GeV and angles up to 13°, a proximity imaging method is employed. This method utilises a thin (2 cm) aerogel radiator for direct Cherenkov light detection.

For particles with larger incident angles between 13° and 25° and momenta ranging from 3 to 6 GeV, a different configuration is used. The Cherenkov light is produced by a thicker aerogel layer of 6 cm and focused by a spherical mirror. The light then undergoes two additional passes through thin radiator material and is reflected by planar mirrors before detection [Contalbrigo et al., 2020]. This setup enables efficient particle identification in this momentum and angular range.

Electromagnetic Calorimeters (ECAL)

The CLAS12 package incorporates the existing Electromagnetic Calorimeter (EC) from the CLAS detector and adds a new PCAL upstream of it. Together, they form the ECAL, which is primarily used for the identification and kinematical reconstruction of electrons, photons, and neutrons.

The ECAL consists of six modules, with the PCAL and EC divided into two parts each along the direction from the target. These parts are known as EC-inner (ECIN) and EC-outer (ECOU) and are read out separately. They provide longitudinal sampling of electromagnetic showers and also help improve particle identification through hadronic interactions.

Each module has a triangular shape and is composed of 54 layers of scintillators. The scintillators are 1 cm thick and segmented into strips that are 4.5 cm wide for PCAL and 10 cm wide for EC, fitted between 2.2-mm-thick lead sheets. The total thickness of the calorimeters corresponds to approximately 20.5 radiation lengths. The scintillator layers are grouped into three readout views, with 5/5/8 layers per view for PCAL/ECIN/ECOU, respectively. This arrangement allows for spatial resolutions of less than 2 cm for energy clusters.

To transmit the light signals from the scintillators, flexible optical fibres are used to route the light to the corresponding PMTs [Asryan et al., 2020].

Forward Tagger (FT)

The FT is an extension of the CLAS12 detector that allows for the detection of electrons and photons at very forward polar angles, specifically ranging from 2.5° to 4.5°. By detecting forward-scattered electrons, the FT enables electroproduction experiments at low photon virtuality Q^2 , providing a high-intensity, linearly polarized, quasi-real photon beam with energy tagging. This setup is particularly suitable for hadron spectroscopy studies.

The FT consists of three main components: the FTCal (calorimeter), the FT-Trk (micro-strip gas tracker), and the FTHodo (hodoscope). The FTCal utilises 332 lead-tungstate (PbWO₄) crystals to identify electrons, measure the energy of

electromagnetic showers, and provide fast trigger signals. The FTTrk, located in front of the FTCal, is responsible for measuring the scattering angles of charged particles. The FTHodo, a scintillator detector, assists in the separation of electrons and high-energy photons.

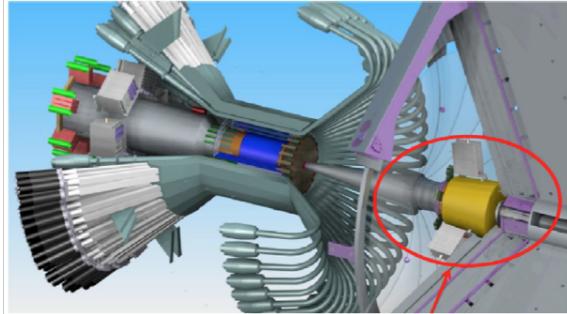


Figure 11: The Forward Tagger system circled downstream of the CD in front of the torus magnet warm bore entrance. Source: CLAS12 wiki.

During beam operations, a conical tungsten shielding pipe is placed in front of the FT to absorb Møller electrons and low-energy photons generated by beam interactions with the target and downstream materials. This shielding not only protects the FT and Forward Detectors from electromagnetic background but also ensures compatibility with the FT acceptance. This configuration, referred to as "FT-ON", allows the FT to detect both electrons and photons, expanding the detection capabilities of CLAS12.

Alternatively, when the FT is not required for the specific physics program, the FT detectors can be turned off, and additional shielding elements are installed in front of the FT, covering up to 4.5° of polar angle. This modified configuration, known as "FT-Off," reduces accidental background by one-third under the same beam conditions, enabling higher luminosity data acquisition with CLAS12 by mitigating background interference from the DC R1 chambers [Acker et al., 2020a].

A render of the FT can be seen in Figure 11.

2.2.2 Central Detector (CD)

In the CD, particles scattered from the target within the polar angle range of 35° to 125° are detected. The CD consists of various detectors that provide particle identification and tracking capabilities. Charged particles are detected in the Central Vertex Tracker (CVT) and the Central Time-of-Flight (CTOF) detector. Neutron detection is provided by the Central Neutron Detector (CND), which is located radially outside of the CVT and the CTOF. All detectors have full coverage in the azimuthal angle.

Central Vertex Tracker (CVT)

The CVT system is an integral part of the CD. It is primarily used for measuring the momentum and determining the vertex position of charged particles scattered from the target.

The CVT system is located inside the solenoid magnet, as depicted in Figure 12. It consists of two distinct detectors: the SVT and the Barrel Micromegas Tracker (BMT).

The SVT system is composed of three regions, each equipped with double-sided modules of silicon sensors. The regions have different numbers of modules: 10, 14, and 18, respectively. These silicon sensors are instrumented with a digital

Application-Specific Integrated Circuit (ASIC) readout. The readout pitch, which refers to the distance between adjacent readout channels, is approximately 156 micrometers. The SVT system comprises 21,504 channels [Antonioli et al., 2020].

The BMT is composed of three layers of strips aligned along the beamline and three layers of circular readout strips around the beamline, totalling 15,000 readout elements. It significantly enhances momentum resolution and tracking efficiency. Each layer is divided azimuthally into three segments, providing 120° azimuthal coverage for each segment. The system is designed to operate at the full luminosity of $10^{35}\text{cm}^{-2}\text{s}^{-1}$ [Acker et al., 2020b].

Central Time-of-Flight (CTOF)

The CTOF system is utilised for the purpose of charged particle identification by measuring their time-of-flight (TOF) in the momentum range of approximately 0.3 to 1.25 GeV. It consists of 48 plastic scintillators with double-sided PMT readout. The PMTs are connected to the scintillators via 1.0-meter-long upstream and 1.6-meter-long downstream focusing light guides. These counters are arranged in a hermetic barrel configuration surrounding the target and the CVT, and they are aligned with the beam axis inside the 5 T solenoid magnet.

To ensure accurate measurements, the PMTs are positioned within a region of 0.1 T fringe field of the solenoid magnet and are enclosed within a triple-layer dynamic magnetic shield. This shield minimises the internal magnetic field near the PMT photocathode, achieving a field strength of less than 0.2 G. The CTOF system is designed to provide a time resolution of 80 ps, enabling precise charged particle identification in the CD [Carman et al., 2020a].

For a visual representation of the CTOF system, you can refer to Figure 13.

Central Neutron Detector (CND)

The CND is a component of the CD positioned radially outward of the CTOF system. Its primary function is to detect neutrons in the momentum range of 0.2 to 1.0GeV by measuring their TOF from the target and the energy deposition in scintillator layers.

The CND is composed of three layers of scintillator paddles, with each layer containing 48 paddles. The paddles are coupled in pairs at the downstream end using semi-circular light guides. The signal generated in the scintillator paddles is

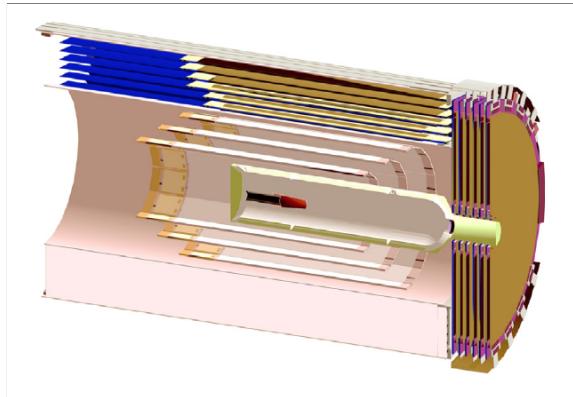


Figure 12: Render of the Central Vertex Tracker. From the inside, the figure shows the target cell and vacuum chamber, the three double layers of the SVT, followed by the six layers of the BMT. The beam enters from the left. The six Forwards Micromegas Tracker (FMT) layers are shown at the downstream end at the right. Source: CLAS12 wiki.

read out at the upstream end by PMTs that are positioned outside the high magnetic field region of the solenoid magnet.

To transmit the scintillation light, the scintillators are connected to 1-meter-long bent light guides, which ensure efficient light propagation to the PMTs for signal detection and readout.

The combination of TOF measurements and energy deposition in the scintillator layers enables the CND to identify and detect neutrons within the specified momentum range in the CD [Chatagnon et al., 2020].

Back Angle Neutron Detector (BAND)

The CLAS12 spectrometer includes the BAND as a dedicated detector for neutron detection at backward angles. Positioned 3 metres upstream of the target, the BAND is designed to detect backward-scattered neutrons with momenta ranging from 0.25 to 0.7 GeV.

The BAND detector consists of 18 horizontal rows and five layers of scintillator bars. Each scintillator bar is equipped with PMT readout on both ends to measure the TOF of neutrons originating from the target. Additionally, there is an extra 1 cm scintillation layer specifically designed to veto charged particles, ensuring that only neutrons are detected.

Covering a polar angle range from 155° to 175° , the BAND detector achieves a design neutron detection efficiency of 35%. It also provides a momentum resolution of approximately 1.5%, allowing for precise measurements of the momentum of the detected neutrons [Segarra et al., 2020].

By utilising the BAND detector, the CLAS12 spectrometer is capable of detecting and characterising backward-scattered neutrons, providing valuable information for various physics studies and experiments conducted at CLAS12.

2.2.3 Offline Reconstruction

The CLAS12 reconstruction and analysis process is facilitated by a data-stream processing framework called CLARA. CLARA adopts a service-oriented architecture, allowing the construction of software applications using micro-services that are connected via data-stream pipes [Gyurgyan et al., 2016].

In this framework, each service plays a specific role. It receives input data, processes it according to its functionality, and produces output data. The input and output data are organised in tabular structures known as “banks”, which are configured by the service developer to match the specific requirements of the service.

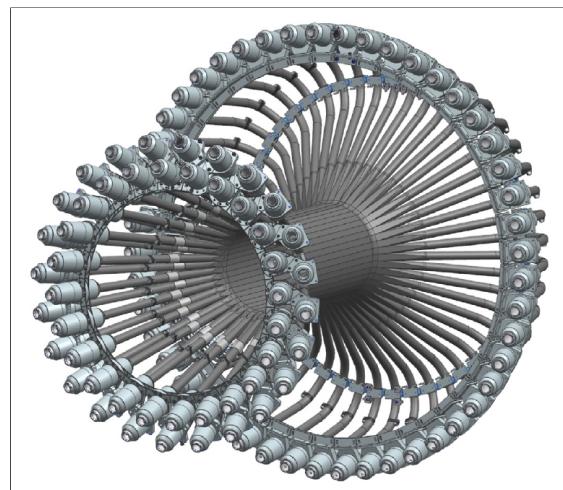


Figure 13: Render of the Central Time-of-Flight. The render shows CTOF’s 48 scintillator bars outfitted with light guides, PMTs, and magnetic shields at both ends of each counter. Source: CLAS12 wiki.

The services within CLARA form a data-flow path, where the output of one service becomes the input for the next service in the sequence. This design enables a flexible and versatile data processing application, as each service can be individually improved or replaced without necessitating structural changes to the framework.

To ensure consistency and modularity, the CLAS12 services are extensions of an abstract reconstruction engine. This engine provides common components such as initialisation and event processing methods, reducing the development complexity of individual micro-services and enforcing a uniform structure throughout the framework.

By leveraging the CLARA framework, the CLAS12 experiment benefits from a modular and adaptable data processing pipeline, allowing for efficient reconstruction and analysis of the collected data. The service-oriented architecture and data-stream processing approach contribute to the flexibility, scalability, and maintainability of the CLAS12 software framework.

The CLAS12 data reconstruction process involves data reader services that access decoded detector data stored in banks. Each entry in the bank represents a decoded detector hit and contains information such as sector, layer, component, order, and digitised data like signal charge, amplitude, time, or pedestal.

During the decoding stage, similar bank structures are created for various quantities required for event reconstruction, including hits, clusters, and tracks. Reconstruction algorithms specific to each CLAS12 subsystem fill these banks. The data persistence service appends and writes these banks to a file for later analysis.

The reconstruction algorithms are implemented as services that operate on input

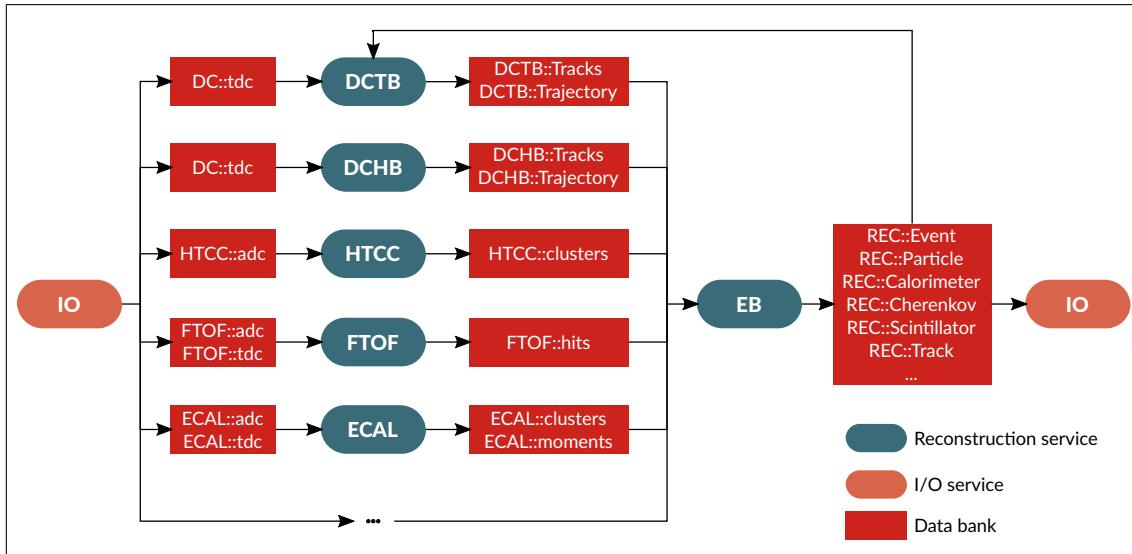


Figure 14: Graphical representation of the CLAS12 interdependencies between services and banks. The I/O service reads events from the input file and distributes them to the reconstruction services chain for processing. Each service reads the relevant banks, applies the reconstruction algorithm, and provides output banks that are passed to the next service in the chain. The Event Builder (EB) service is executed as last in the chain; it collects the relevant banks from all CLAS12 subsystems services and produces event, particle, and detector response banks that are written to the output file. Source: Own elaboration, using Inkscape.

banks and produce output banks, which are then passed to subsequent algorithms in the reconstruction chain. The order in which the services are chained reflects the overall sequence of CLAS12 event reconstruction and the dependencies between subsystems.

The first step is the reconstruction of charged particle tracks in the Central and Forward Detector tracking systems, based on the recorded hit positions in the respective detectors. This process is known as “hit-based” tracking.

Simultaneously, hits recorded in other detectors are processed to reconstruct the energy and time of the associated particle interactions. The Event Builder (EB) service matches these reconstructed quantities with the tracks based on position and time information. Hits that are not matched to any track are retained as neutral particle candidates. The EB also determines the event “start time” and identifies the reconstructed particles.

Once the event start time is determined, a second iteration of forward tracking, known as “time-based” tracking, can be performed. This iteration incorporates the drift times in the Drift Chambers, providing improved tracking precision [Ziegler et al., 2020].

An overview of the composition of reconstruction application services, depicting the dependencies between the services, can be found in Figure 14.

Tracking

In the CLAS12 event reconstruction, charged particle tracking plays a crucial role and is divided into two main regions: the forward region and the central region.

In the forward region, charged particles are bent either inward or outward from the beamline by the torus magnet, depending on their charge. The magnetic field strength varies along the bending path, with an integral magnetic field ($\int B dl$) ranging from 2Tm at 5° to 0.5Tm at 40° . The forward tracking system responsible for tracking in this region consists of two components: the FMT and the DC.

In the central region, charged tracks are curved into helices by the strong 5T solenoidal magnetic field. The central tracking system comprises the SVT and the BMT, which together form the CVT.

These tracking systems in both the forward and central regions use sophisticated detectors to measure the position of charged particle hits, allowing for the reconstruction of particle trajectories. By combining information from these detectors and utilising the magnetic field information, the tracking algorithms reconstruct the paths of charged particles, enabling precise determination of their momenta and vertices.

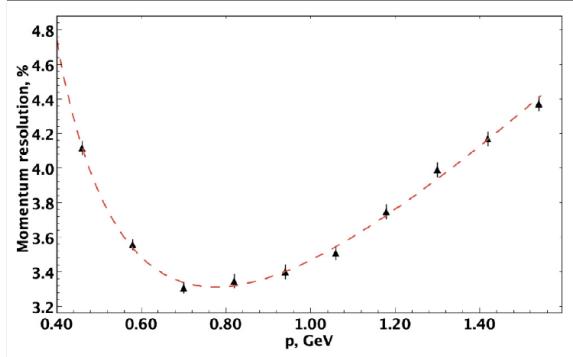


Figure 15: Momentum resolution vs. momentum of simulated protons in the CVT without background. Source: [Ziegler et al., 2020].

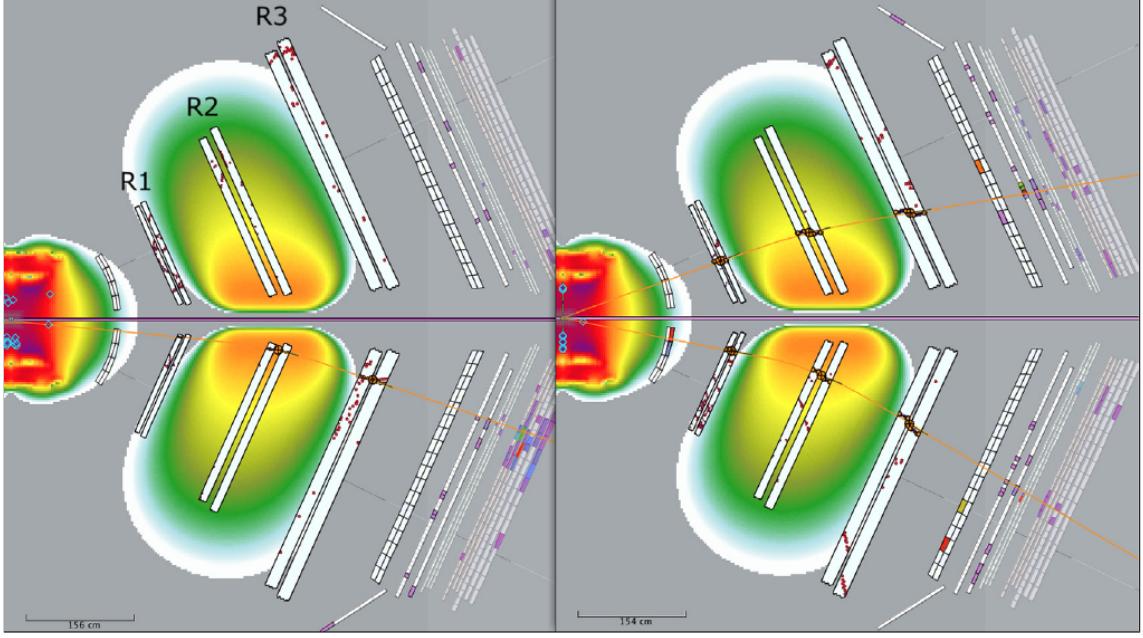


Figure 17: Views from CLAS12 Event Display (ced) of charged particle tracks in the DC showing cut-views to highlight different pairs of sectors of the CLAS12 Forward Detector. The coloured detector elements are the registered hits and the orange lines are the result of track reconstruction using the hits in the DC. The coloured areas about the detectors represent the regions of magnetic field from the torus and the solenoid. In these views the beam is incident from the left and the target is located in the middle of the solenoid (at the left edge of the image). Source: ced render.

In both the forward and central tracking systems, track reconstruction involves two main steps: pattern recognition and track fitting. The first step is to identify hits, which are the recorded signals corresponding to a particle passing through a specific detector component. These hits are transformed from electronic signals into the position of the track within the geometry of the detector subsystem.

A hit is defined as a geometric object that represents a detector element. For example, in the central tracker, a hit can be represented by a line corresponding to a strip in the detector. These hit objects serve as the input for the pattern recognition algorithms.

Pattern recognition involves identifying clusters of hits and determining the spatial coordinates and corresponding uncertainties for the hits and clusters. During the pattern recognition stage, hits that are consistent with belonging to a trajectory, such as a particle track, are identified. This set of hits is then fitted to the expected trajectory, considering their uncertainties and incorporating knowledge of

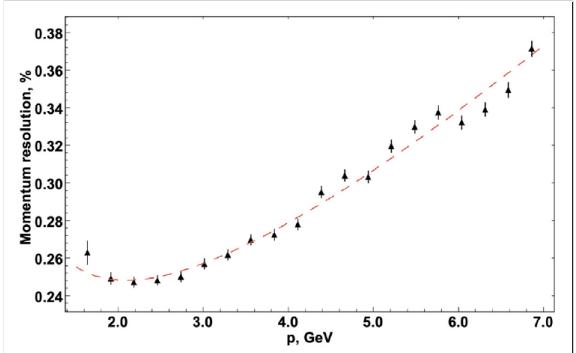


Figure 16: Momentum resolution vs. momentum in the DC evaluated using pions simulated at $\theta = 15^\circ \pm 5^\circ$ and at $\phi = 0 \pm 5^\circ$ without background. Source: [Ziegler et al., 2020].

the detector material and the detailed magnetic field map. Figure 17 illustrates a particle passing through the DC.

The momentum resolutions in the central and forward trackers, as a function of momentum, are shown in Figures 15 and 16, respectively. The distributions are fitted with a function of the form $\sqrt{a + bx^2 + c/(1 + d/x^2)}$. In both distributions, the degradation of resolution at low momentum is attributed to multiple scattering effects. Furthermore, the resolution deteriorates as momentum increases beyond a minimum, primarily because of poorer track curvature resolution.

For central tracking, a simulated proton sample with momenta ranging from 0.5 to 2.5 GeV yields an average CVT reconstruction efficiency of 87.3%. A slight decrease in efficiency is observed for tracks with momenta below 600 MeV. The increased curvature of low transverse momentum (p_{\perp}) tracks leads to a rise in inefficiency due to acceptance effects. The primary source of inefficiency stems from the gaps between the sensitive volumes of the BMT and SVT detectors.

Regarding forward tracking, the momentum resolution in the DC is evaluated using tracks simulated at $\theta = 15^\circ \pm 5^\circ$ and $\phi = 0 \pm 5^\circ$. This range ensures that the majority of tracks fall within the sensitive volume. Moreover, the DC momentum resolution exhibits correlation with the polar angle since track curvature is determined by the magnetic field intensity, which is higher at lower angles in the torus field. These resolutions are obtained from a Monte Carlo sample that excludes out-of-time backgrounds or misalignments of the tracking volumes [Ziegler et al., 2020].

Particle Identification

The Particle Identification (PID) numbering scheme described here was initially introduced by the Particle Data Group (PDG) in 1988 [Yost et al., 1988]. Its purpose is to facilitate communication and data exchange between different generators, simulators, and analysis packages employed in particle physics. The system underwent subsequent revisions and adaptations in 1998 to allow for the systematic inclusion of undiscovered and hypothetical particles [Group et al., 1998]. The PID convention utilised in this thesis is based on the most up-to-date version available at the time of writing, as referenced from the 2020 Review of Particle Physics by the PDG [Group et al., 2020].

The EB is a crucial component within the reconstruction chain, serving multiple functions:

- It gathers information from upstream services.
- It correlates information from sub-detectors to form particles.
- It implements a general particle identification scheme.
- It organises the resulting information into a standardised and persistent data bank structure.

The EB service is executed twice using identical algorithms, first employing hit-based tracks and subsequently using time-based tracks. As mentioned previously, the results obtained from the hit-based EB are utilised to initialise time-based tracking.

In the definition of a reconstructed charged particle within CLAS12, the EB assumes that each reconstructed track in both the FD and the CD will be assigned an identification. The corresponding responses from the calorimeter, scintillator, and Cherenkov detectors are then associated with that particle based on geometric coincidences between the detector responses and the track. Matching criteria are established, which correspond to the resolution of each specific detector. The geometric matching process relies on the Distance of Closest Approach (DOCA) between the track and the detector response.

A similar procedure is employed for the creation of neutral particles, with the distinction that the seeding is presently performed using unassociated responses from the ECAL for the FD and the CND (or the BAND) for the CD, instead of using tracks.

A start time is assigned to the entire event and serves as the precise reference time for all time-based particle identification procedures. The determination of the start time relies on the optimal charged particle candidate in the FD with an associated timing response from the FTOF detector.

The EB assigns the start time based on the highest energy electron detected in the ECAL. If no electron is found in the ECAL, the EB then searches for a positron in the ECAL. In the absence of any lepton candidates, the next track in the priority list is a forward-going positive track, which is assumed to be a positive pion (π^+). Finally, if no forward-going positive track is identified, the EB searches for a forward-going negative track, assumed to be a negative pion (π^-). When searching for π^+ or π^- tracks, only the candidate with the highest momentum within each group is considered.

A parallel event start time is determined from the FT system to facilitate physics analyses and triggers specifically for events where the primary scattered electron is at very forward angles within the FT.

In such cases, all combinations of charged particles in both the FT and the FD are taken into account. The particle in the FT is assumed to be an electron, while all possible hadron mass hypotheses are considered for the FD tracks. The combination that exhibits the best time coincidence is selected, and the timing of the resulting FT electron is used to assign the start time.

A correction to the start time is subsequently applied using the RF signal from the accelerator, in conjunction with the reconstructed event vertex position. This correction effectively aligns the event start time with the most accurate measurement of the beam-bunch arrival time at the target.

The uncorrected measured vertex time of a particle, denoted as t_v , can be expressed as follows

$$t_v = t - \frac{P_L}{\beta c},$$

Here, t represents the measured time response (e.g., in a scintillator), P_L is the path length between the primary interaction vertex and the corresponding response, and βc denotes the speed of the particle.

Next, we calculate the time difference Δt_{RF} between t_v and the nearest beam bunch using the following formula

$$\Delta t_{RF} = t_v + \frac{z_0 - z_v}{c} - t_{RF} - \frac{N}{2f_{RF}},$$

In this equation, z_v represents the z -coordinate of the event vertex position, z_0 is the reference position calibration at the center of the target, and c denotes the speed of light in vacuum. t_{RF} and f_{RF} correspond to the measured and calibrated RF time and frequency of the accelerator. These values can either be 2.004 ns and 249.5 MHz, or 4.008 ns and 499 MHz, respectively. During the reconstruction process, these values are obtained from the Run Conditions Database.

Subsequently, the time can be further corrected to the nearest beam bunch using the equation

$$\Delta t'_{RF} = \text{mod} \left(\Delta t_{RF}, \frac{1}{f_{RF}} \right) - \frac{1}{2f_{RF}},$$

This correction allows for RF-correction to t_v . Thus, we obtain a final RF- and vertex-corrected start time for the event, defined as

$$t' = t_v - \Delta t'_{RF}.$$

The subsequent step involves a basic particle identification scheme designed to be flexible enough to accommodate various physics analyses while retaining essential information for future refinement of the criteria.

For charged particles, the identification process begins by utilising calorimetry and Cherenkov information to positively identify e^-/e^+ candidates in the FD. If the measured energy deposition aligns with the expected sampling fraction of the ECAL and the photoelectron response from the HTCC aligns with $\beta \sim 1$, the particle is assigned as an e^- or e^+ based on the sign of curvature determined from forward tracking with the DC in the presence of the torus magnetic field.

The remaining charged particles are then assumed to be hadrons and are assigned an identity solely based on timing information. The p, K, π candidate with the smallest time residual is selected. This time residual is calculated as the difference between the measured flight time of the particle and the flight time computed for a specific mass hypothesis.

Figure 18 presents the β vs. momentum distributions for forward-going positively charged hadrons reconstructed using data from the FTOF and DC subsystems. The electron is reconstructed either in the FD (top) or in the FT (bottom). The computed curves for different mass hypotheses are superimposed on the distributions.

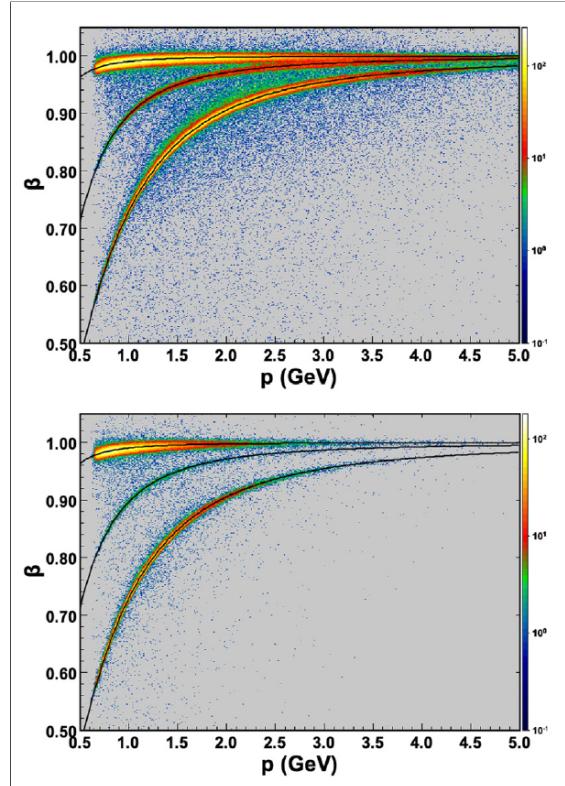


Figure 18: Particle β vs. momentum from simulation data for positively charged tracks with their start time from an electron in the FD (top plot) or in the FT (bottom plot). Source: [Ziegler et al., 2020].

To identify neutral particles, the analysis assumes the presence of only neutrons and photons, distinguished solely by timing and topological information. In the FD, the identification is based on the ECAL, while in the CD, it relies on the CND. The reconstructed cluster positions of these detectors are used to calculate the particle's travel path from the event vertex, assuming a straight-line trajectory.

If the measured β value is close to 1, the particle is identified as a photon; otherwise, it is identified as a neutron. For photons in the FD, the momentum is determined from the deposited energy and the ECAL sampling fraction [Asryan et al., 2020]. For neutrons, the momentum is assigned based on the measured β , assuming the mass of a neutron.

Figure 19 illustrates an example of the reconstructed β values for neutral particles in the FD, demonstrating the separation between photons and neutrons.

A particle identification quality factor, represented as a signed- χ^2 or pull, is assigned based on the contributions from individual detector subsystem responses and their resolutions. For e^-/e^+ identification, the resolution-normalised distance from the expected ECAL sampling fraction is utilised, while for charged hadrons, the resolution-normalised time difference is employed. The resulting information is organised into standardised output bank structures for physics analysis. This includes the particle four-vectors, associated detector responses, and global event information such as beam RF and helicity details.

The accuracy of the currently implemented particle identification algorithm can be estimated by comparing the assigned particle identification with the true identification in Monte Carlo simulations. Table 1 presents the particle identification matrix for the FD (left) and CD (right). The values are derived from simulations involving electron-hadron or electron-photon pairs with hadron and photon momenta ranging from 1 to 2.5 GeV and electron momenta ranging from 1 to 9 GeV. The diagonal elements represent cases where the particle is correctly identified, while the off-diagonal elements represent cases of misidentification [Ziegler et al., 2020].

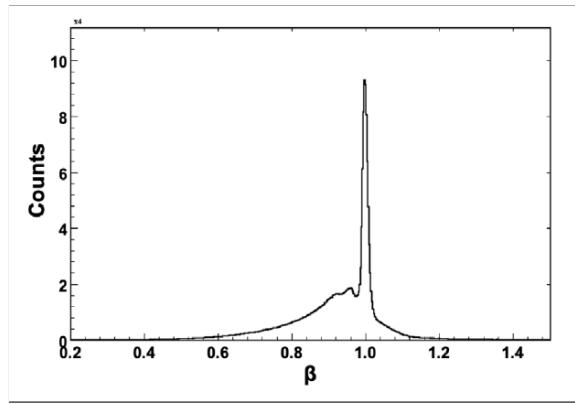


Figure 19: β distribution for neutral particles as measured by the ECAL from simulation data, showing a sharp peak at $\beta = 1$ from photons and a broader, slower distribution from neutrons. Source: [Ziegler et al., 2020].

25

Table 1: Particle identification matrix for the FD (left matrix) and CD (right matrix). The FD matrix is based on simulated hadrons and photons with momentum between 1 and 2.5 GeV, and electrons up to 9 GeV. The CD matrix is based on simulated hadrons with momentum between 0.3 and 1.1 GeV. The diagonal elements are correctly identified, while the off-diagonal elements are misidentified. Detector inefficiencies are included.

Forward Detector Truth							Central Detector Truth				
	e	π	K	p	n	γ		π	K	p	n
e	0.98							0.84	0.14	0.00	
π		0.93	0.10	0.00				0.11	0.80	0.01	
K		0.03	0.80	0.00				0.03	0.04	0.95	
p		0.03	0.02	0.98							0.11
n					0.66	0.01					
γ					0.14	0.95					

2.3 RG-E Experiment

The RG-E experiment, to be conducted in Hall B, focuses on measuring the hadronic multiplicity ratio between various nuclei and deuterium. To achieve this, a double-target system is being constructed. This system will enable a precise comparison between a deuterium target and heavy solid targets such as carbon, aluminium, copper, tin, lead, and others. The primary objective of the experiment is to enhance our understanding of hadronisation in the nuclear medium, colour transparency, and nuclear short-range correlations.

During the data acquisition process, both the cryo-target (deuterium) and a solid target will be exposed to the electron beam simultaneously. To minimize differences in acceptance corrections between the targets, efforts are made to maintain a minimal distance between them. However, it is crucial to ensure that the targets can still be differentiated during the reconstruction process. The work behind this thesis contributes to the experiment by improving the offline reconstruction methods prior to the actual experiment, with the aim of reducing the distance between the targets. Further details on this topic can be found in Section 3.

Simultaneously positioning both targets in the beam allows for the cancellation of time-dependent systematic effects, thereby increasing the precision of the final results. These effects can include drifting gains and inefficient detector channels when measuring ratio-like observables. Since the target system will be placed in a vacuum, the switching between solid targets needs to be done remotely. It is essential to perform the switching quickly to maximise the beam time available for the experiment.

The double target system is designed to enable switching between up to five different solid targets. Previous experiments, such as EG2 conducted on the former CLAS, have demonstrated that the design of the double target system offers significant advantages in reducing systematic uncertainties [Hakobyan et al., 2008]. The principle of the target system involves installing the solid targets on a carbon fibre band that slides on torlon rails. The movement of the band is accomplished using a piezo-motor, chosen for its insensitivity to magnetic fields. Figure 20 illustrates the

proposed design of the double target system.

To ensure the proper functioning of the target, a series of tests have been conducted. These tests cover various aspects of the target's operation and performance. They include:

- Movement under vacuum and high magnetic field: The target system has been tested to ensure that it can operate smoothly and reliably under vacuum conditions and in the presence of high magnetic fields. This is important to verify that the target's movement and positioning are not affected by these conditions.
- Radiation hardness of selected materials: The materials used in the target system have been tested for their resistance to radiation. This is crucial because the target may be exposed to radiation during the experiment. By assessing the radiation hardness of the materials, it can be ensured that they will maintain their structural integrity and functionality throughout the experiment.
- Heat removal tests: The target system has undergone heat removal tests to ensure that it can effectively dissipate heat generated during operation. It is essential to keep the target temperature well below its melting point to prevent any damage or degradation. By conducting heat removal tests, the target's cooling capabilities have been evaluated to ensure optimal performance and longevity.

These tests collectively aim to validate the target's operational robustness and reliability under the specific conditions of the experiment, thereby ensuring accurate and consistent data collection.

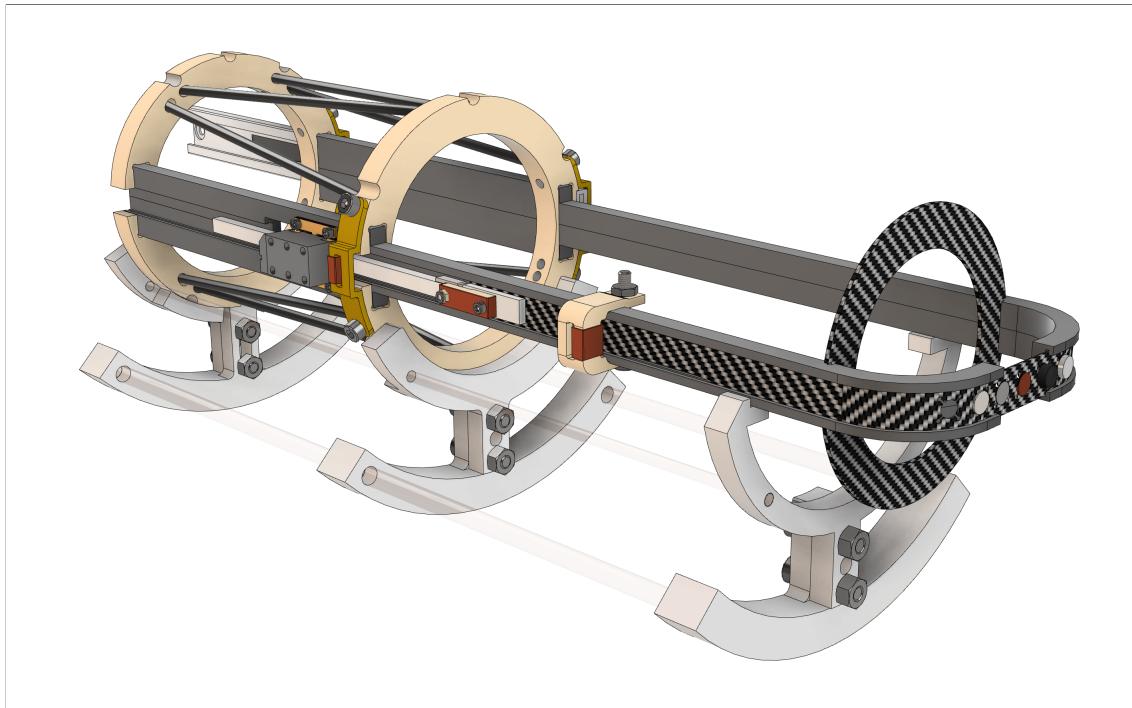


Figure 20: Double-target system CAD render. Render by Alonso Lepe, from the Double Target group.

2.3.1 Slow Control System

A modern experimental physics experiment usually involves many moving parts and complex components that require constant monitoring and calibration. Additionally, continuous data collection is necessary. This task is accomplished through the use of slow control systems. These systems typically integrate the entire detector and experiment into one complex interface, facilitating easy access and maintenance.

The standard framework used in the context of HEP for achieving this is the Experimental Physics and Industrial Control System (EPICS). EPICS was developed at the Los Alamos National Laboratory to facilitate data acquisition and control for such experiments. This framework offers a distributed process control system that includes software communication, functional subsystems for data acquisition, supervisory control, closed-loop control, channel archiving, and alarm management [Dalesio et al., 1991].

Similar to many HEP experiments, the slow control system of CLAS12 is based on EPICS [Boyarinov et al., 2020].

To enable the integration of the RG-E target into the CLAS12 slow control system, the author developed an EPICS support module and Input/Output Controller (IOC). This module was not created from scratch since the motor developers had already developed a generic support module for Galil motors [Farnsworth, 2009]. The existing system proved to be capable of supporting the movement of the RG-E target system, requiring only the removal of unnecessary features and the addition of experiment-specific database variables.

The RG-E IOC, along with the complete set of EPICS support modules necessary to run it, can be found at

```
github.com/bleaktwig/rge-epics-support.
```

The EPICS module includes Process Variables (PVs) that have been added to facilitate the control of the RG-E target system. Below is a list of these PVs along with a brief description of each. The user-defined records database, where these PVs can be viewed and edited, is located at

```
$EPICS_BASE/support/galil/3-6/db/galil_userdef_records.template.
```

Analog Input (ai)

The normal use for this record type is to obtain an analog value from hardware and then convert it to engineering units [Stanley et al., 1998]. The record can also be used to write constants to be read from the database, such that they can be changed in runtime.

DMC01:A_curr_pos. Current position of the band. Displayed at the Graphical User Interface (GUI) and used for internal calculations.

DMC01:A_home. Position of the home. Displayed at the GUI and used for calculations.

DMC01:A_pos#. # is a number from 1 to 7. Positions of each of the seven targets. Displayed at the GUI and used for calculations.

DMC01:A_lowlimit. Position of the low limit. If DMC01:A_curr_pos is lesser than this value, a major alarm is fired.

DMC01:A_highlimit. Position of the high limit. If DMC01:A_curr_pos is greater than this value, a major alarm is fired.

DMC01:A_tolerance. Equivalence tolerance for the position of each target and the position of the band. It defines a valid range around the target position.

DMC01:COMMERR_STATUS. Variable that is true when there's a communication error with the controller and false otherwise. Used for triggering a communication alarm.

IOC01:SR_i_am_alive. Variable that is true when the IOC is up and running, false otherwise. Used for triggering a communication alarm.

Analog Output (ao)

The normal use for this record type is to output values to digital-analog converters. The desired output can be controlled by either an operator or a state program, or it can be fetched from another record [Stanley et al., 1998].

DMC01:A_go_home. Command to move the band to the home position, as defined in DMC01:A_home.

DMC01:A_go_pos#. Command to move the band to the position of target #, as defined in DMC01:A_pos#.

Calculation (calc)

The calculation or “Calc” record is used to perform algebraic, relational, and logical operations on values retrieved from other records. The result of its operations can then be accessed by another record so that it can be used [Stanley et al., 1998]. In the context of the RG-E target, each calculation returns a number from 0 to 11. This number represent the state the target is in, and is later used by a Select PV.

DMC01:A_at_pos#. Calculation that checks if the band position is equal to that of target # in DMC01:A_pos#, within the tolerance margin DMC01:A_tolerance. If it is, it returns #. Otherwise, it returns 0.

DMC01:A_at_home. Calculation that checks if the band position is equal to the home position in DMC01:A_home, within the tolerance margin defined by the tolerance. If it is, it returns 8. Otherwise, it returns 0.

DMC01:A_moving. Calculation that checks if the target is moving by checking the motor PV DMC01:A.MOVN. If it is, it returns 9. Otherwise, it returns 0.

DMC01:A_at_lowlimit. Calculation that checks if the band position is lesser than the low limit DMC01:A_lowlimit. If it is, it returns 10. Otherwise, it returns 0.

DMC01:A_at_highlimit. Calculation that checks if the band position is greater than the high limit DMC01:A_highlimit. If it is, it returns 11. Otherwise, it returns 0.

Select (sel)

The select record computes a value based on input obtained from up to 12 locations [Stanley et al., 1998]. By default, it is equal to the highest value among its input PVs.

DMC01:A_sel_tgtype. This record returns the highest value between the previously defined calculations. Thus, it associates the values returned to a state of the target. By convention, this PV assumes that *no more than one calc is greater than 0*. This assumption holds as long as DMC01:A_tolerance is not set higher than half the distance between targets and between the targets and the lower and higher limits.

Multi-Bit Binary Input (mbbi)

The normal use for the multi-bit binary input record is to read multiple bit inputs from hardware. The binary value represents a state from a range of up to 16 states. The multi-bit input record interfaces with devices that use more than one bit [Stanley et al., 1998].

DMC01:A_tgtype. This mbbi encodes the output of DMC01:A_sel_tgtype to a string and alarm level. The encoding is specified in Table 2.

CS-Studio

The GUI of CLAS12 EPICS is built on the Control System Studio (CS-Studio) toolkit. CS-Studio is specifically designed for monitoring and operating large-scale control systems and is based on the eclipse Rich Client Platform framework [Kasemir et al., 2007]. To integrate the RG-E target system into CLAS12 EPICS, a CS-Studio screen was developed.

Below is a list of the requirements that the screen needed to fulfil. These requirements were derived from the specifications of the physics experiments as well as the needs of the electronics team responsible for the target system.

- Buttons to move the target band to the targets and a home location.

- A Button to stop the target band in case of emergency.
- A status check on the position of the target band.
- Alarm handling for the case when the band moves beyond low and high limits.
- Alarm handling for the IOC and communication problems.

The implemented screen, shown in Figure 21, incorporates these requirements. Along with the buttons, text displays indicate the position of each target within the band. Adjacent LED displays illuminate green when the band position aligns with the target position, within the tolerance specified in the database. Additionally, four LED displays are positioned to the right of the two IOC statuses, as well as the low and high limits. These LEDs indicate alarm conditions and work in conjunction with the CLAS12 Slow Control alarm system to alert the user of any issues.

Furthermore, in addition to the aforementioned screen, users can access other screens through the Motor Screens menu button. These screens are part of the motor EPICS support module and are retained for debugging purposes. They include a manual motor movement screen, a motor setup screen, a direct command line interface with the motor, and an amplifier configuration screen. All of these screens were developed by the Galil EPICS team [Farnsworth, 2009].

To enhance user experience, the GUI was designed using the Gruvbox colour palette. This palette is specifically chosen to ensure that colours are easily distinguishable, with sufficient contrast, while also being visually appealing and comfortable for the eyes. The Gruvbox colour palette can be found on GitHub at

github.com/morhetz/gruvbox.

Table 2: Names and alarm levels for the different values of the PV DMC01:A_tgtype.

Value	Name	Alarm Severity
0	Not Moving	Major
1	Target 1	No alarm
2	Target 2	No alarm
3	Target 3	No alarm
4	Target 4	No alarm
5	Target 5	No alarm
6	Target 6	No alarm
7	Target 7	No alarm
8	Home	No alarm
9	Moving	Minor
10	Low Limit	Major
11	High Limit	Major

Alarm System

To ensure the reliable operation of the CLAS12 detector, all EPICS-controlled subsystems within it are equipped with PVs that define alarm conditions. These alarms, along with their severity, associated subsystems, and pre-defined instructions on how to respond to them, are displayed in a centralised alarm system.

For each experiment conducted in Hall B involving a non-trivial target system, a specific set of alarms is required. In the case of the RG-E target, the list of implemented alarms and their corresponding PVs is provided in Table 3.



Figure 21: RG-E CS-Studio main screen. The HOME and A, B, C, etc buttons move the target strip to the corresponding location, the STOP button is an emergency, instant stop of the target system, and the Motor Screens button allows the user to open additional motor screens. Source: Own Elaboration, using CS-Studio.

Table 3: Alarm names, triggers, and severities for the RG-E target slow control system.

Name	Trigger	Severity
Band is not moving	DMC01:A_tgtype = 0	Major
Band is moving	DMC01:A_tgtype = 9	Minor
Band beyond low limit	DMC01:A_tgtype = 10	Major
Band beyond high limit	DMC01:A_tgtype = 11	Major
Controller comm. error	DMC01:COMMERR_STATUS = 1	Major
IOC comm. error	IOC01:SR_i_am_alive = 0	Major

3 FMT Alignment and Reconstruction

In paper, the FMT offers a 3 to 10-fold increase in resolution when compared to DC [Aune et al., 2009]. Achieving this improvement requires work on the alignment and calibration of the detector, as well as the reconstruction from its data. This chapter focuses on the work carried out in this endeavour, specifically addressing alignment and reconstruction.

The first section provides a detailed description of Micromegas detectors in general and the FMT in particular. Subsequently, the second and third sections discuss the efforts made in alignment and reconstruction, respectively. Finally, the fourth and final section of the chapter elaborates on the resolution improvement resulting from this work.

3.1 Forwards Micromegas Tracker

A Micro-Mesh Gaseous Detector or Micromegas (MM) is a gaseous particle detector that is derived from wire chambers. These types of detectors are commonly used in experimental physics for detecting ionising particles. The MM detector offers very precise temporal and spatial resolution, on the order of 100 nanoseconds and below 100 micrometers [Giomataris et al., 1996].

The detector operates by amplifying the charges created by ionisation in the gas volume. Its volume is divided into two parts by a metallic micro-mesh placed less than 150 micrometers away from the readout electrode or strip.

To illustrate this process, refer to Figure 22.

When a particle passes through the detector, it ionises the gas atoms by stripping

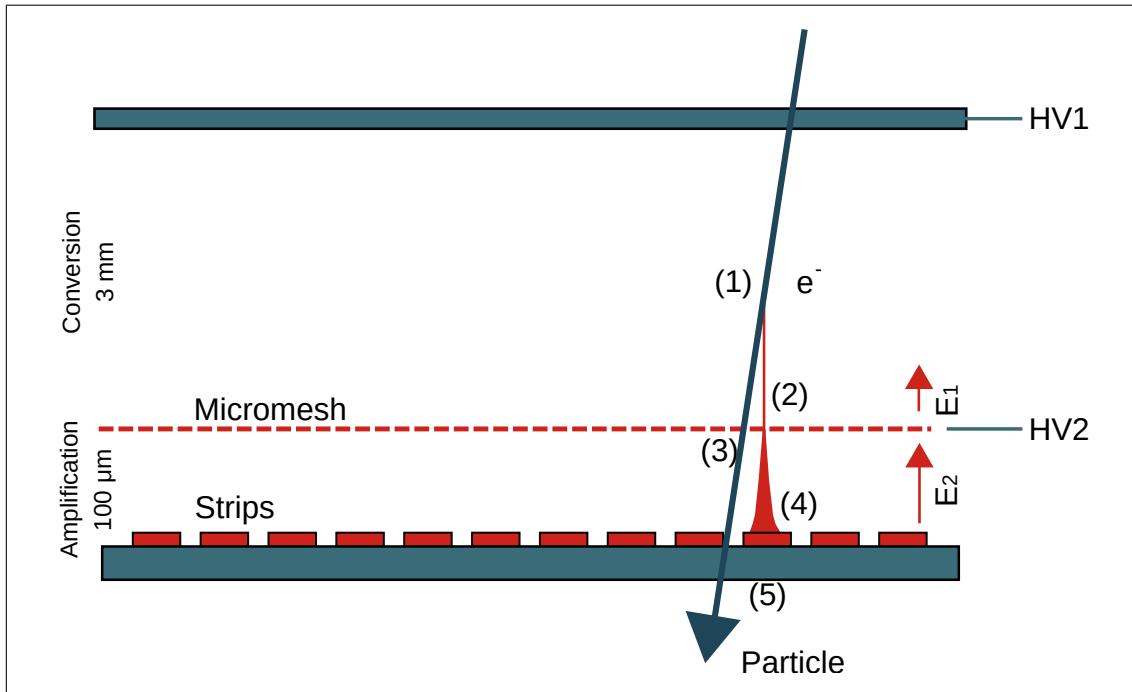


Figure 22: Micromegas working principle. Source: Re-render of original illustration by [Giomataris et al., 1996] using Inkscape.

an electron, resulting in an electron-ion pair (1). An electric field, denoted as E_1 , is applied to the gas, causing the electron to drift towards the amplification electrode (2) while the ion moves towards the cathode. As the electron crosses the mesh (3), it enters a strong electric field, denoted as E_2 , triggering an avalanche effect (4). This produces a significant signal at the readout strip (5), which can then be stored for reconstruction [Giomataris et al., 1996].

Inside the CLAS12 detector, a diverse set of tracking detectors is utilised to determine the positions and momenta of particles at different points along their trajectories. The proximity of these detectors to the particle source directly correlates to the precision achieved in determining the position and momentum at the interaction vertex, which refers to the point where the particle was generated. To optimise this precision, the Micromegas Vertex Tracker (MVT) is positioned as close as feasible to the target, as depicted in Figure 23.

Similar to the division of CLAS12 into the CD and FD, the MVT is also divided into two parts to maximise the angular coverage.

The first component is the BMT, which consists of 18 cylindrical detectors arranged in 6 layers. When combined with the SVT, this detector covers the angular region from 35 to 125 degrees, significantly enhancing the resolution of the polar angle [Acker et al., 2020b].

Then, the FMT, which is made of six circular, flat detectors covering angles from 6 to 29°. In theory, it should improve the vertex resolution by a factor of 3 to 10 when compared to the DC [Aune et al., 2009]. While the original design of the

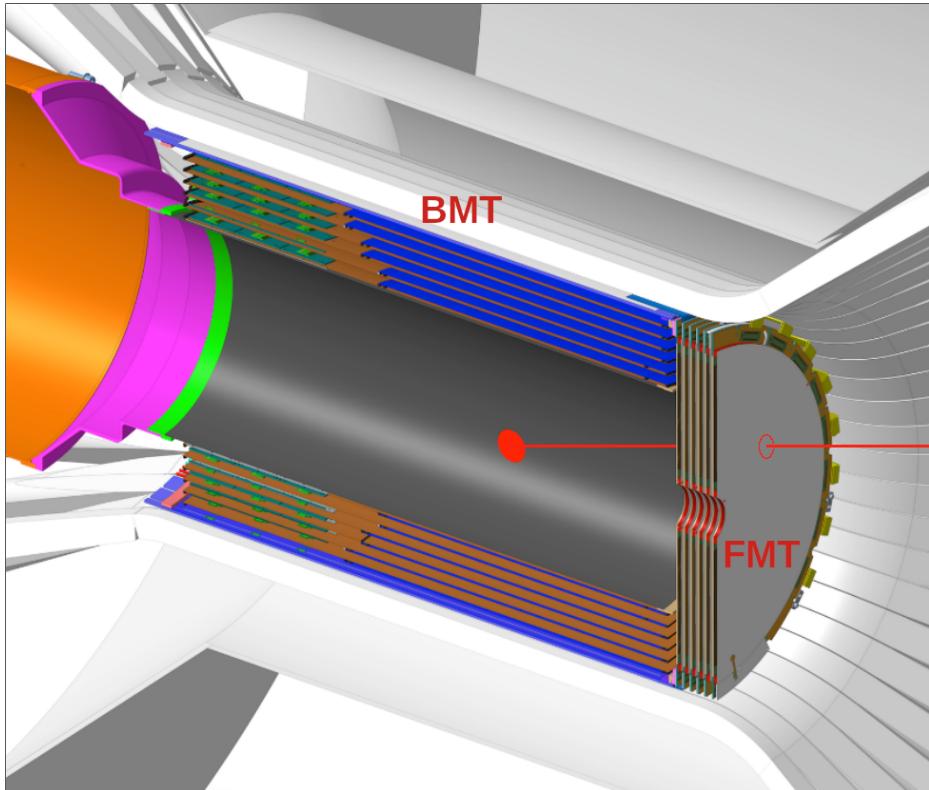


Figure 23: MVT detector. The red dot denotes the $z = 0$ point in the beamline, the red line denotes an arbitrary track coming from that point, and the circumference in the FMT denotes where that track produces a signal in an FMT layer. Source: CLAS12 wiki.

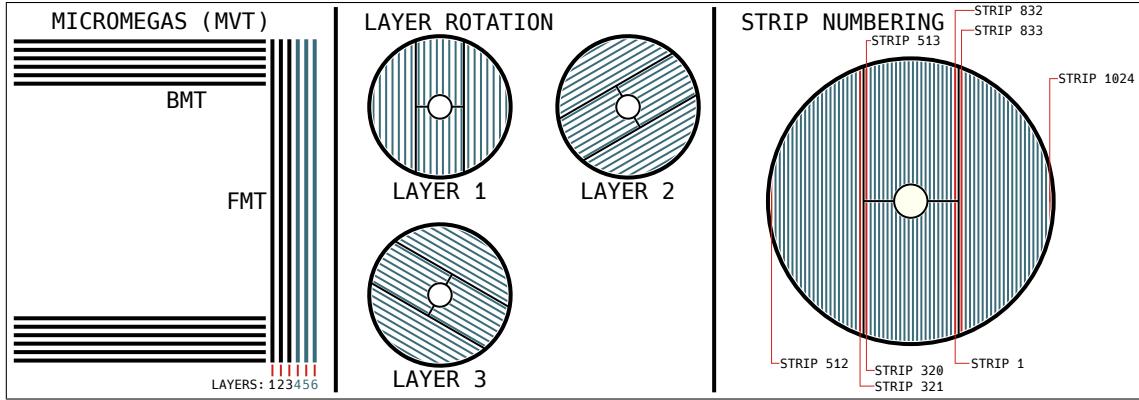


Figure 25: FMT detector geometry. The first picture shows the distribution of the BMT and FMT layers, the second the different angle of each FMT layer, and the third the readout strip distribution of each FMT layer. Source: Own elaboration, using Inkscape.

FMT included six layers, the current implemented detector has only three layers installed. This is due to technical difficulties and concerns regarding its Lorentz angle [Konczykowski et al., 2010].

Each of the three FMT layers has 1024 readout strips, which follow a peculiar distribution, as can be seen in the image to the right of Figure 25. In addition, each layer's orientation differs by 60° to provide an accurate measurement in the xy-plane, as is shown in the image at the centre of the same Figure [Acker et al., 2020b].

The FMT is composed of six circular, flat detectors that cover angles ranging from 6 to 29 degrees. In its conception, it was anticipated that the FMT would improve the vertex resolution by a factor of 3 to 10 compared to the DC [Aune et al., 2009]. However, the currently implemented FMT deviates from the original design, with only three layers installed. This modification was necessitated by technical difficulties and concerns related to its Lorentz angle [Konczykowski et al., 2010].

Each of the three FMT layers is equipped with 1024 readout strips that exhibit a distinctive distribution, as depicted in the image on the right-hand side of Figure 25. Additionally, the orientation of each layer differs by 60° degrees to ensure accurate measurements in the xy-plane, as illustrated in the image at the center of the same Figure [Acker et al., 2020b].

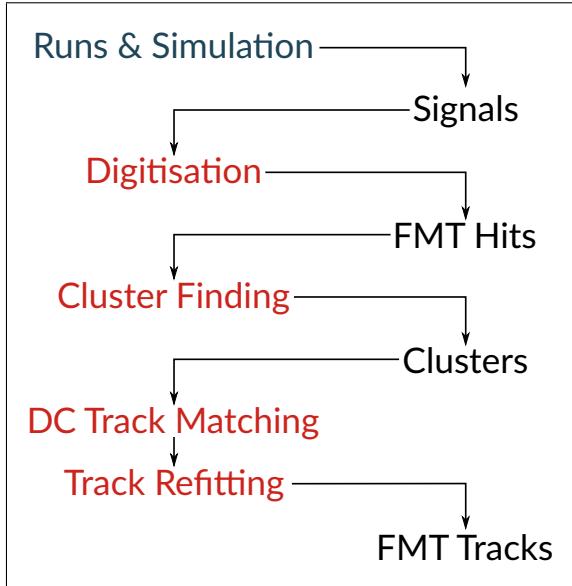


Figure 24: FMT reconstruction summary. Data taking is coloured blue, data in black, and processes in red. Source: Own elaboration, using Inkscape.

3.1.1 FMT Track Reconstruction

Once a signal is detected on a readout strip and the data is stored, the information is extracted from it during offline reconstruction. The reconstruction process of the FMT closely resembles that of the DC.

To begin with, when a signal is detected in a strip, it undergoes digitisation, processing, and is transformed into an FMT Hit. A set of FMT hits is then processed using a Cluster Finding algorithm, where a Cluster is defined as a group of hits that likely originate from the same particle track. Groups of clusters from different layers are subjected to a DC Track Matching algorithm, where they are matched to DC tracks generated by the DC Reconstruction process. Subsequently, a Track Refitting algorithm is employed for each DC track using the data from the clusters, resulting in updated tracks known as FMT tracks. An overview of this entire process is provided in Figure 24.

3.2 FMT Alignment

In an ideal scenario, the target and each detector would be installed precisely in their required positions. However, in the real world, there are inevitable misalignments in their placements. These misalignments must be accounted for and incorporated into the reconstruction process to ensure meaningful results.

Within the CLAS collaboration, the Calibration and Commissioning group is responsible for the alignment and calibration of each detector. The shifts and rotations necessary for alignment are included in the Calibration and Conditions Database (CCDB), which is then utilised during reconstruction.

The alignment work aimed to achieve three primary goals. Firstly, to provide FMT alignment tables to Run Group F (RG-F) for use in reconstruction. Secondly, to assess whether the resolution improvement obtained from the FMT justifies the additional material introduced into the CLAS12 detector. Lastly, to offer detailed information about these improvements, enabling Run Group E (RG-E) and other run groups to make informed decisions on whether to include the detector in their runs.

Alignment shifts can be performed in any of the three global axes: z , which is aligned with the beamline; x , which runs parallel to the ground; and y , which points upwards from the ground. Additionally, alignment rotations can be carried out around these axes. Specifically, for the purposes of this work, rotations around the z axis are referred to as ϕ rotation (roll), while rotations around the x and y axes are termed pitch and yaw, respectively.

To quantify misalignment, the DOCA between a reconstructed DC track and an FMT cluster is defined as a Residual. Due to the geometry of each layer (as depicted in Figure 25), only the residuals in the local y axis of a layer (perpendicular to the strips) can be measured. This implies that global z and ϕ alignment can be performed independently for each layer. However, global x , global y , pitch, and yaw alignment must be carried out simultaneously for the entire detector.

To minimise residuals, they are plotted for a specific shift or rotation in the relevant axes. An example of such a plot is illustrated in Figure 26. Since the residuals are expected to follow a Gaussian distribution, a Gaussian fit is applied to them.

For z and ϕ alignment, the goodness of fit is heuristically evaluated by comparing the standard deviation (σ) of the Gaussian fits and selecting the shift with the smallest σ . For x , y , pitch, and yaw alignment, the goodness of fit is heuristically evaluated by choosing the fit with the mean closest to zero. It is important to consider a reasonable error margin when selecting the minima.

Examples of the distributions of goodness of fit for z and xy alignment can be observed in Figure 27.

3.2.1 Fiducial Cuts

To mitigate background noise, fiducial cuts are applied to the DC tracks and FMT clusters. This process enhances data quality, ensuring more meaningful alignment results.

For DC tracks, the following cuts are implemented:

- $\text{track}.z < \text{layer}.z$: This cut removes tracks with a vertex z position further downstream than the FMT layer prior to swimming. Such occurrences result from reconstruction errors where the particle origin is outside the target.
- $|\text{track}.z - \text{layer}.z| < 0.05\text{cm}$: This eliminates tracks that are too far from the FMT layer after swimming, caused by bugs in the swimmer process that will be discussed in the subsequent section.
- $5\text{cm} < \sqrt{x^2 + y^2} < 25\text{cm}$: This removes tracks outside the active region of the layer.
- $\theta < 66.42^\circ$: This excludes tracks with excessively high θ angles. When this occurs, a single particle affects multiple strips, rendering the detector's data less reliable for alignment purposes.

The implemented fiducial cuts applied to the FMT clusters are:

- $50\text{ns} < \text{Tmin} < 500\text{ns}$: This cut removes clusters with illogical values for Tmin , which represents the time of the first hit in the cluster.

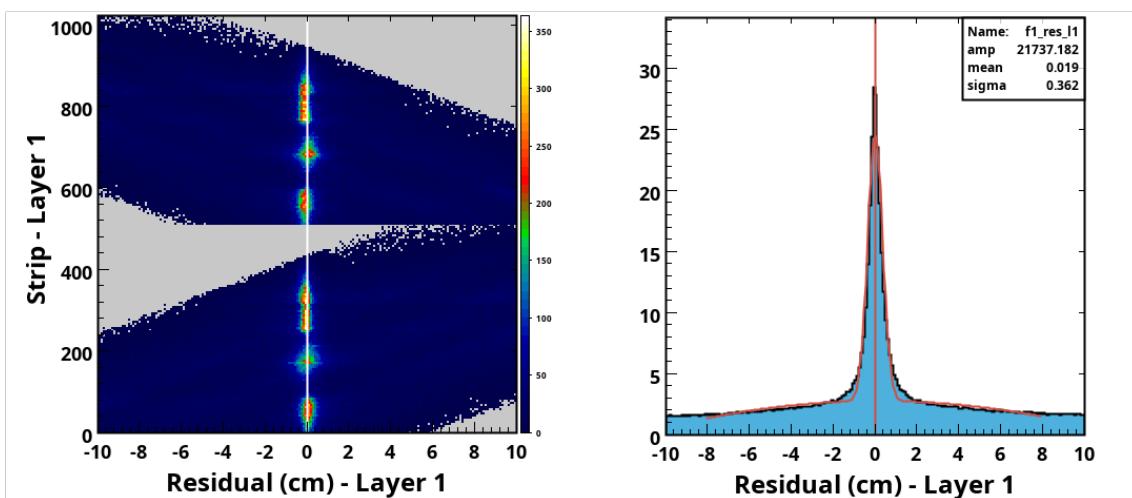


Figure 26: Example FMT residuals plot. Source: CLAS12 alignment software.

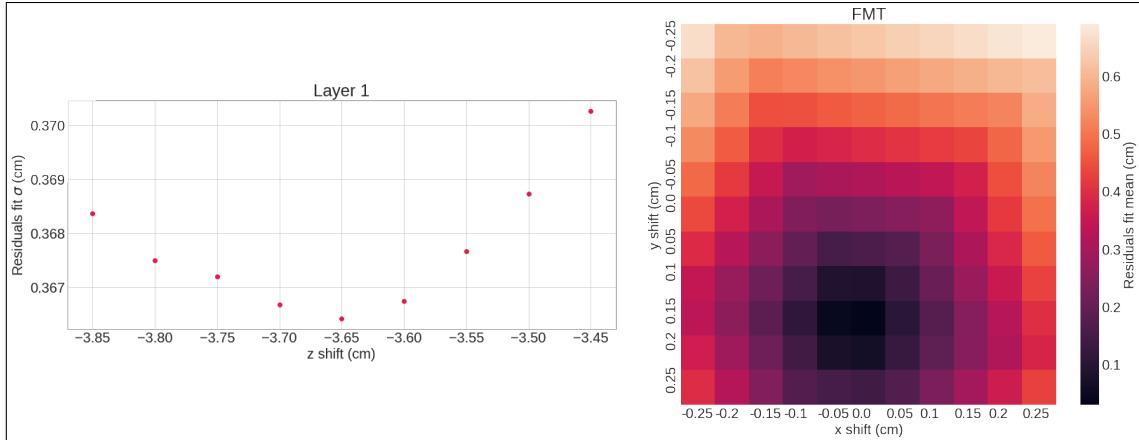


Figure 27: Examples of residuals goodness of fit plots. Source: CLAS12 alignment software.

- size > 1 & E > 100 : This eliminates small clusters with high energy, as they are generally considered to be of poor quality.
- size < 5 : This discards large clusters, as they are deemed to be less useful for analysis purposes.

3.2.2 Residuals Improvements

To validate the proposed alignment algorithm, it was applied to the data from RG-F, specifically Run 11983. The improvement in residuals is readily apparent when comparing the before and after alignment results, as depicted in Figure 28. It is important to note the difference in scale between the top and bottom plots, which further highlights the significant improvement achieved through the alignment process.

As depicted in the figure, the z and ϕ alignment significantly reduces the background, resulting in a higher concentration of residuals around the mean of the distribution. Moreover, the x and y alignment effectively aligns the mean of the distribution closer to zero, improving the overall alignment. However, for the pitch and yaw alignment, meaningful results could not be obtained. This can be attributed to the limited data available from the three layers, combined with the small rotations around the x and y axes, making it challenging to achieve precise alignment.

To determine the mean and standard deviation (σ) of the distribution, a Gaussian fit was applied. The parameters of the Gaussian fit are

$$\left(\text{amp} \cdot \text{gaus}(\mu, \sigma) \right) + \left(p_0 + p_1 \cdot x + p_2 \cdot x^2 \right)$$

gaussian + background

The results obtained are included in the CCDB at

clasweb.jlab.org/cgi-bin/ccdb/versions?table=/geometry/fmt/alignment

Alignment was successfully performed for the data from Run Group M, demonstrating that the alignment procedure is not specific to a particular run. This indicates the general applicability and effectiveness of the alignment procedure across different runs in the CLAS12 detector.

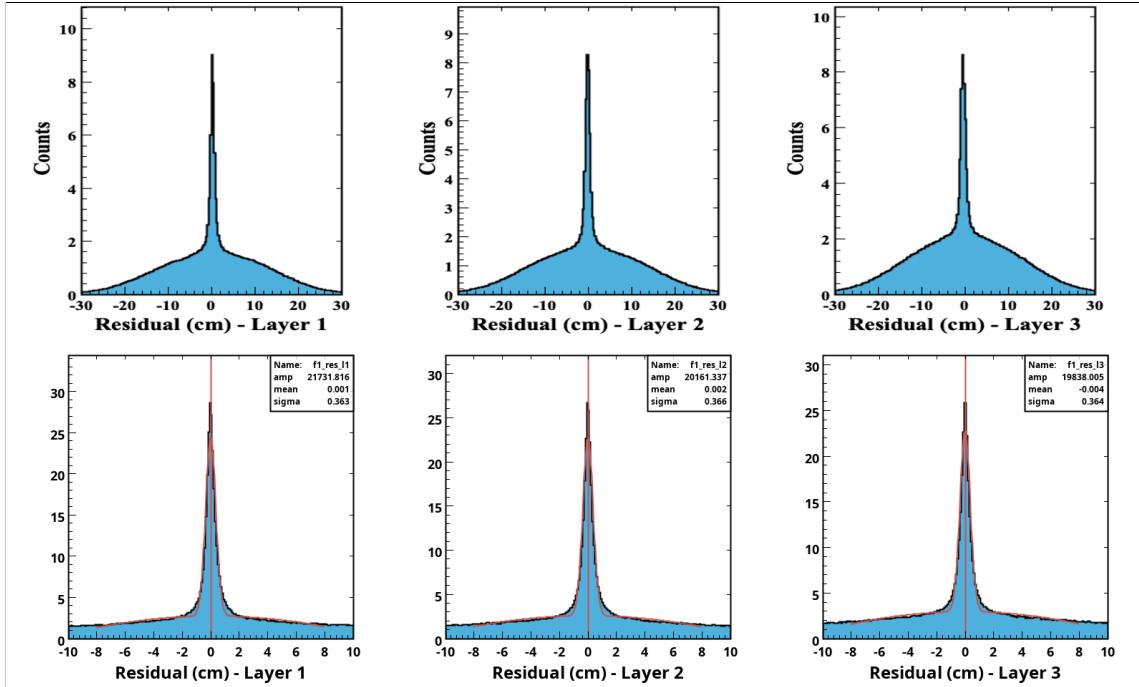


Figure 28: Residuals distribution before (upper image) and after (lower image) alignment. Source: CLAS12 alignment software.

The impact of this alignment procedure on the resolution of the entire CLAS12 detector will be further investigated and discussed in the concluding subsection of the section.

The procedure described in this section is documented and shared publicly. It can be seen at:

github.com/JeffersonLab/clas12alignment/tree/master/fmt

3.3 FMT Reconstruction Work

As the work on FMT alignment progressed, certain modifications were required in FMT reconstruction. These modifications primarily involved incorporating the alignment shifts determined during the alignment process into the reconstruction. Additionally, some fixes were made to address issues that were identified during the alignment work. These changes ensure that the reconstruction process takes into account the alignment information and addresses any related issues that were encountered.

First, the loading of shifts from the CCDB was included in the standard geometry class of the FMT reconstruction package. Then, standard methods to include the shifts in any frame of reference change were implemented. Finally, the code was studied in detail, and the shifts were added in all instances where they were required since the package originally didn't consider their application.

“Crossmaking” is the process of matching clusters in different layers to obtain an accurate 3D estimate of the position of a track [Ziegler et al., 2020]. This process was initially included in FMT reconstruction to facilitate the reconstruction for the six FMT layers. However, as mentioned before, only three FMT layers were installed for the RG-F run, and future runs may also use three layers due to concerns with the Lorentz angle when using six layers. To simplify the reconstruction process and make better use of the available number of layers, crossmaking was removed from the reconstruction.

Outside of FMT reconstruction, some minor changes were also required in the DC

reconstruction package since some of its components depend on the FMT layers' positions. Additionally, the swim package diagnostic was updated as it failed to properly reconstruct the positions of tracks near the FMT layers.

A detailed list of the updates applied can be found in the following pull request to the `clas12-offline-software` repository

github.com/JeffersonLab/clas12-offline-software/pull/726.

3.4 Validation and Results

Just like the residuals validation, the results presented in this document are based on the application of this work to RG-F data. It is important to note that the RG-F target is approximately 55 centimetres long, which is much larger than the average CLAS12 target [Hattawy et al., 2019]. Specifically, the runs used for testing and validation are presented in Table 4, and the run used to obtain the data displayed in this section was 011983.

Run Number	Energy (MeV)	Current (nA)	Configuration	Target
011983	10389.4	50	Inbending	D2
012016	10389.4	250	Inbending	D2
012439	2186.4	15	Inbending	H2
012461	10196.6	20	Inbending	D2

Table 4: RG-F runs used for validation.

3.4.1 Cuts

Some additional cuts are applied to the tracks to obtain the plots presented in this section. These cuts are used to remove very poor tracks that would not be suitable for analysis

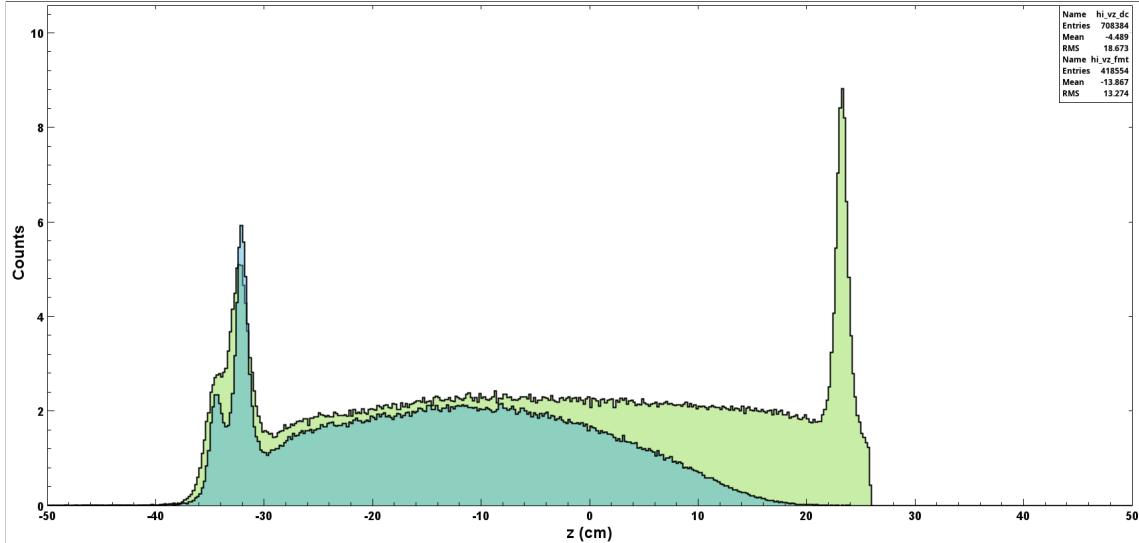


Figure 29: DC vs FMT vertex z for electrons without any geometric correction. DC tracks are shown in green while FMT tracks are shown in blue. Note that the dark cyan colour comes from the overlap. Source: `fmtVertex.groovy` script in CLAS12 alignment software.

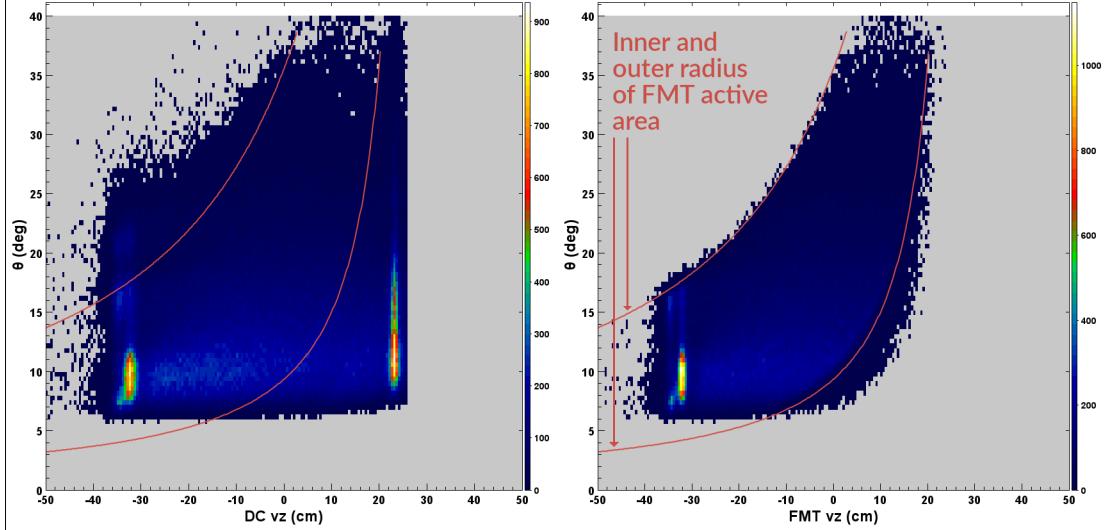


Figure 30: z vs θ for DC and FMT for electrons without any geometry correction. FMT’s active area are shown in red lines. Source: `fmtVertex.groovy` script in CLAS12 alignment software.

regardless. The applied cuts are as follows:

- `abs(chi2pid) < 5`: This cut removes tracks that do not provide sufficient certainty regarding the particle’s PID.
- `vz < fmtZ`: This cut removes tracks located further downstream than the FMT.
- `chi2/ndf < 15`: This cut excludes tracks with excessively high uncertainty.

3.4.2 Geometry Effect

To evaluate the enhancement in vertex resolution, we will compare the vertex positions of tracks that underwent only DC reconstruction with those that underwent both DC and FMT reconstruction. For convenience, we will refer to the former as DC tracks and the latter as FMT tracks. Considering that the z axis is aligned with the beamline, Figure 29 illustrates the z positions of the vertex for DC tracks versus FMT tracks.

To comprehend the plot in Figure 29, it is valuable to examine the RG-F target. The target consists of a large gas-filled chamber with a varying composition across different runs. The distance between the chamber windows measures 553.32 millimetres. Furthermore, it was observed that the upstream window of the target is positioned approximately 24 millimetres away from the beam window. All windows are constructed from aluminium and have a thickness of 15 micrometers. A detailed depiction of the target can be found in Addendum 1.

Based on Figure 29, it is evident that the FMT detector solely detects the upstream windows, completely overlooking the downstream one. This issue stems from a geometric constraint: the downstream window falls outside the active detection area of the FMT. This effect is clearly illustrated in Figure 30, where the θ angle is plotted against the vertex z coordinate. The two red lines in the plots represent the FMT’s active area, and it is apparent that the downstream window lies outside this region, thereby explaining its absence.

To compensate for this geometric effect, we introduce an additional cut based on the plotted curves. The curves can be described by the following equations

$$c_1(z) = 57.29 \cdot \arctan\left(\frac{r_{\text{inner}}}{z_0 - z}\right), \quad c_2(z) = 57.29 \cdot \arctan\left(\frac{r_{\text{outer}}}{z_0 - z}\right). \quad (3)$$

Here, r_{inner} represents the radius of the hole at the center of the FMT, r_{outer} denotes the radius of the outer circumference of the FMT, and z_0 corresponds to the z position of the first FMT layer plus the drift distance. All these parameters are obtained from the CCDB.

3.4.3 Vertex Resolution Improvement

Furthermore, an additional cut has been introduced. As of the FMT alignment work, beam alignment for RG-F data had not been carried out, resulting in a decrease in vertex resolution. To mitigate the impact of this alignment issue on reconstruction accuracy, we have implemented a cut to utilise only one sector of the detector.

The resolution plot, comparing DC and FMT tracks after applying all the previously mentioned cuts, is depicted in Figure 31. To evaluate the resolution for both DC and FMT tracks, we utilise a fit consisting of two Gaussian curves combined with a quadratic curve to account for the background. The fit is defined as follows

$$\text{amp}_1 \cdot \text{gaus}(z, z_{\text{max}}, \sigma) + \text{amp}_2 \cdot \text{gaus}(z, z_{\text{max}} - 2.4, \sigma) + p_1 + p_2 \cdot z + p_3 \cdot z^2,$$

where

- amp_1 represents the amplitude of the largest peak, and z_{max} corresponds to its z position,
- amp_2 signifies the amplitude of the leftward peak, which has been measured to be at a position of 2.4 centimetres, and

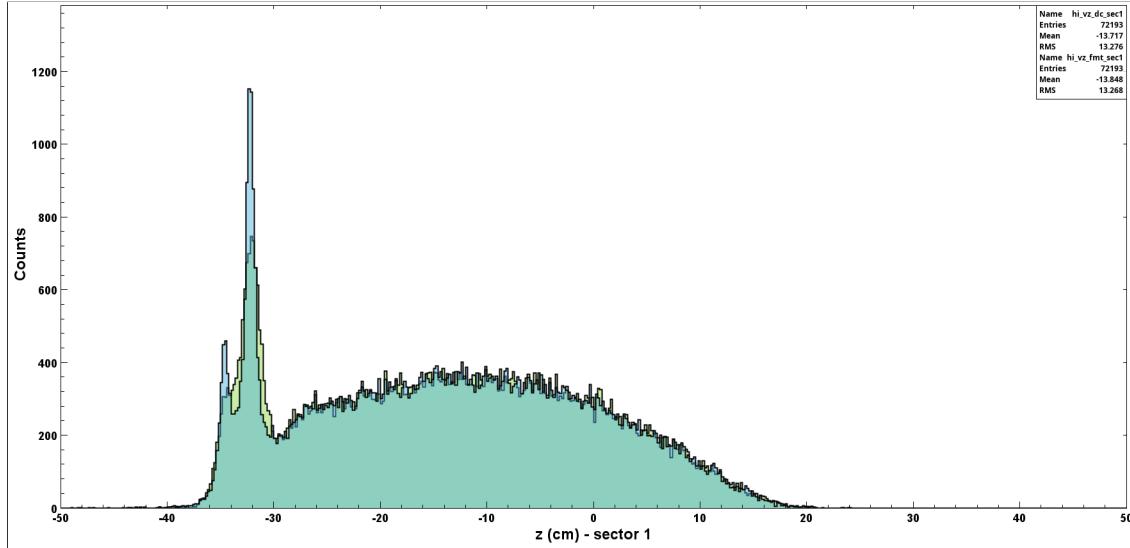


Figure 31: DC vs FMT vertex z for electrons with a geometric correction. DC tracks are shown in green while FMT tracks are shown in blue. Data from only one CLAS12 sector was used to obtain this plot. Source: `fmtVertex.groovy` script in CLAS12 alignment software.

- the remaining parameters, p_1 , p_2 , and p_3 , are obtained through the fitting process.

For electrons in run 011983 (low luminosity, 50 nA), the analysis yields a DC resolution of $\sigma_{DC} = 0.875$ cm and an FMT resolution of $\sigma_{FMT} = 0.387$ cm. This indicates a doubling of the resolution achieved with the inclusion of the FMT detector.

Similarly, for electrons in run 012016 (production luminosity, 250 nA), the analysis shows a DC resolution of $\sigma_{DC} = 1.009$ cm and an FMT resolution of $\sigma_{FMT} = 0.596$ cm.

3.4.4 Conclusions

Although the improvement in resolution is not as significant as initially anticipated for the detector, it remains an encouraging result. The enhanced resolution enables more precise measurements of the target position. As a practical implication, it allows for double targets to be positioned closer to each other, thereby benefiting the derived physics from experiments like the RG-E run.

The reason for the smaller-than-predicted improvement in resolution can be attributed to the initial projection, which assumed the presence of six FMT layers. The inclusion of six layers would provide additional positional data along the particle's track, thereby enhancing the accuracy of the vertex position measurement during the fitting process.

Furthermore, due to the limited number of layers and their close proximity in the FMT detector, it exhibits a small lever arm. As a result, the detector's contribution to the vertex momentum resolution is not significant, as it does not provide sufficient additional data to accurately determine the track's momentum.

In order to gain a better understanding of the FMT detector, we conducted a brief study on its efficiency. The efficiency is defined as the ratio of the number of FMT tracks to the number of DC tracks, representing how many of the DC tracks were also detected by the FMT.

For the three-layer configuration, the efficiency is approximately 88.96%. Figure 32 illustrates the layer-by-layer efficiency, showing no anomalous geometric effects. The observed gaps in efficiency are solely a result of the CLAS12 detector's geometry, which is divided into six sectors.

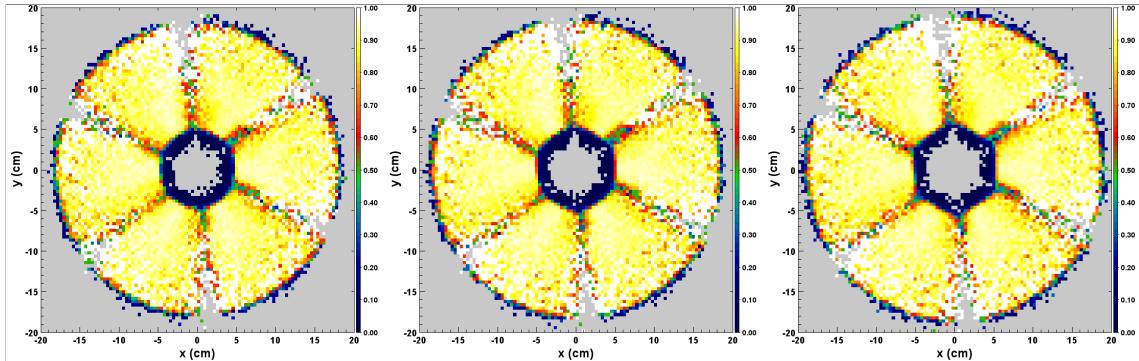


Figure 32: Efficiency of each FMT layer. Source: `fmtVertex.groovy` script in CLAS12 alignment software.

4 Data Analysis

The first section describes a C program developed by the author to perform the analysis in this thesis. The second section discusses the DIS kinematics, which define the cuts made to the data. The third section provides detailed information about the approach used to include the sampling fraction in the analysis. Finally, the last section describes the simulations produced and the acceptance study conducted based on them.

4.1 clas12-rge-analysis

To perform the acceptance analysis reported in this thesis, the author developed an extensive C/C++ program that runs on the ROOT library. The purpose of this program is not only to conduct the analysis described in this thesis but also to be used for RG-E analysis in general. The program and its source code are freely available under the GNU LGPLv3 license and can be accessed on GitHub at: github.com/bleaktwig/clas12-rge-analysis. Issues and pull requests are welcomed, as they are crucial for maintaining the program and facilitating collaborative development in the repository.

After compiling the program using `make`, five executables are obtained in the `bin` directory. The following sections provide a description of each executable.

4.1.1 hipo2root

The CLAS12 reconstruction process utilises a custom file format called High-Performance Input Output (HIPO) format, developed by Gagik Gavalian [Chekanov et al., 2021]. The CLAS collaboration provides a set of tools that enable working with HIPO files, allowing users to read, write, and generate plots from these files. However, users at RG-E are generally more familiar with traditional ROOT files. Therefore, a conversion tool was developed.

The tool, called `hipo2root`, filters through a HIPO file's data and creates a ROOT file that includes pre-selected sections of storage known as banks. The selection of banks is based on data that is relevant to RG-E analysis, and users can easily add additional banks by modifying the program's source files. The output of the `hipo2root` executable is a ROOT file that contains the selected banks represented as trees, which are standard ROOT array-like variables.

Its manual entry is:

```
Usage: hipo2root [-hfn:w:] infile
* -h          : show this message and exit.
* -f          : set this to true to process FMT::Tracks bank. If this
                is set and FMT::Tracks bank is not present in the HIPO
                file , the program will crash .
* -n nevents : number of events.
* -w workdir : location where output root files are to be stored .
                Default is root_io .
* infile     : input HIPO file . Expected format is <text>run_no.hipo .
```

Convert a file from hipo to root format. This program only conserves the banks that are useful for RG-E analysis, as specified in the ‘lib/rge_hipo_bank.h’ file. It’s important for the input hipo file to specify the run number at the end of the filename (‘<text>run_no.hipo’), so that ‘hipo2root’ can get the beam energy from the run number.

Since simulation files don't have a run number, we use a convention for specifying the beam energy. For this files, the filename should be '>999XXX.hipo', where 'XXX' is the beam energy used in the simulation in [0.1*GeV].

4.1.2 extract_sf

To obtain the sampling fraction of the detector's calorimeters, certain analyses from CLAS12 are required. This is accomplished using the `extract_sf` executable, which utilises the momenta of particles and the corresponding deposited energy. The detailed methodology and the results obtained from this analysis are discussed in Section 4.3.

The manual entry of the program is:

```
Usage: extract_sf [-hn:w:d:] infile
* -h          : show this message and exit .
* -n nevents  : number of events
* -w workdir  : location where output root files are to be stored .
                  Default is root_io .
* -d datadir  : location where sampling fraction files are stored .
                  Default is data .
* infile      : input ROOT file . Expected file format:
<text>run_no.root .
```

Obtain the EC sampling fraction from an input file. An alternative to using this program is to fill the output file corresponding to the studied run (by default stored in the 'data' directory) with the data obtained from [CCDB](https://clasweb.jlab.org/cgi-bin/ccdb/versions?table=calibration/eb/electron_sf). The function used to fit the data is

$$[0]*\text{Gaus}(x,[1],[2]) + [3]*x*x + [4]*x + [5]$$

where *[0]* is the amplitude of the Gaussian, *[1]* and *[2]* its mean and sigma, and *[3]*, *[4]*, and *[5]* the *p0*, *p1*, and *p2* used to fit the background.

The output of the program is the 'sf_params_<run_no>.txt', which contains a table with the sampling fractions and their errors. The table is formatted like the one at CCDB, as in

	sf0	sf1	sf2	sf3	sfs1	sfs2	sfs3	sfs4
sector 1	%11.8f							
sector 2	%11.8f							
sector 3	%11.8f							
sector 4	%11.8f							
sector 5	%11.8f							
sector 6	%11.8f							

4.1.3 acc_corr

The `acc_corr` executable is used to count the number of thrown and simulated events from two different ROOT files. Based on the program's input, it separates the data into appropriate 5-dimensional bins, counts the entries for all available particles in the

generated file, and exports the results into a text file. The results and plots presented in Section 5.2 were generated using the data obtained from this program.

The manual entry of the program is:

```
Usage: acc_corr [-hq:n:z:p:f:g:s:d:FD]
* -h          : show this message and exit.
* -q ...      : Q2 bins.
* -n ...      : nu bins.
* -z ...      : z_h bins.
* -p ...      : Pt2 bins.
* -f ...      : phi_PQ bins (in degrees).
* -g genfile : generated events ROOT file.
* -s simfile : simulated events ROOT file.
* -d datadir : location where sampling fraction files are found.
               Default is data.
* -F          : flag to tell program to use FMT data instead of DC data
               from the simulation file.
* -D          : flag to tell program that generated events are in
               degrees instead of radians.
```

Get the 5-dimensional acceptance correction factors for *Q2*, *nu*, *z_h*, *Pt2*, and *phi_PQ*. For each optional argument, an array of doubles is expected. The first double will be the lower limit of the leftmost bin, the final double will be the upper limit of the rightmost bin, and all doubles between them will be the separators between each bin.

The output will be written to the ‘acc_corr.txt’ file, by default in the ‘data’ directory, which is formatted to make it easy to read by the ‘draw_plots’ program:

- * First line contains five integers; the size of each of the five binnings.
- * The next five lines are each of the binning schemes, in order *Q2*, *nu*, *z_h*, *Pt2*, and *phi_PQ*.
- * The following line contains one integer which is the size of the list of PIDs, followed by a line containing each of these PIDs.
- * Finally, a number of lines equal to the number of PIDs follows. Each line contains a list of the bins, ordered as ‘[Q2][nu][z_h][Pt2][phi_PQ]’.

4.1.4 `make_ntuples`

This executable operates on one or more files generated by `hipo2root` and produces a ROOT file that contains a set of `ntuples` relevant to the analysis. Furthermore, based on the specific requirements of this thesis’ analysis, the executable generates two sets of `ntuples`. Both sets have the same `ntuple` format, but the former utilises only DC tracking data while the latter incorporates both DC and FMT tracking data.

For each event, the program executes the following algorithm:

1. First, the program identifies the TOF of the trigger electron. The hits of the trigger electron in the FD scintillators and FD calorimeters are listed in order of priority based on the precision of each detector’s TOF measurement. The detectors are prioritised as follows: FTOF panel-1b, FTOF panel-1a, FTOF panel-2, PCAL, ECIN, and ECOU, as described in Section 2.2.1. Next, the program iterates over the list of hits, extracting the TOF value from the earliest hit in the most precise available layer.

Table 5: Particle identification matrix for the FD. The rows show the PID assigned by reconstruction while the columns the one assigned by the `make_ntuples` program. The diagonal elements are correctly identified, while the off-diagonal elements are misidentified.

	e	π	K	p	n	γ
e	1.00					
π		1.00	0.09	0.02		
K			0.91			
p				0.98		
n					1.00	
γ						1.00

2. Next, for each available track, two particle objects are instantiated. These objects contain the relevant data for the particle, including its vertex position, vertex momentum, charge, beta, and the CLAS12 sector through which it passed. The first object corresponds to the tracking data obtained from the DC, while the second object incorporates both the DC and the FMT tracking data. The assignment of the particle's PID will be carried out later in the process.
3. The program computes and stores the particle's deposited energy in the calorimeters. This involves summing up the energy deposited by all the hits associated with the particle's track for each calorimeter.
4. The program counts the number of produced photoelectrons in the HTCC and LTCC for the particle. Furthermore, the particle's TOF is computed using the same procedure as the one employed for the trigger electron's TOF, considering the hits in the detectors prioritised by their precision.
5. The program assigns the Particle Identification PID to the particle. The process is very similar to the PID assignment in reconstruction, as described in Section 2.2.3. However, the assigned PID is not directly used in order to allow users to modify parameters and define new criteria for the PID assignment.

Although this process typically yields the same results as reconstruction, there is a slight error in the PID assignment. This error is presented in Table 5. As shown in the table, some kaons and protons are misidentified as pions, but the degree of misidentification is not significant. Apart from that, all identifications are accurate.

6. Finally, two `ntuples` objects are created: one for the particle generated from the DC tracking data and another for the particle generated from both the DC and FMT data. These `ntuple` objects are then saved in an output file, which can be used directly for analysis or processed by the `draw_plots` program discussed in the next section.

The manual entry of the program is:

```
Usage: make_ntuples [-hDf:cn:w:d:] infile
* -h : show this message and exit.
* -D : activate debug mode.
* -f fmtlyrs : define how many FMT layers should the track have hit.
              Options are 0 (tracked only by DC), 2, and 3. If set to
              something other than 0 and there is no FMT::Tracks bank
              in the input file , the program will crash. Default is
              0.
* -c : apply FMT geometry cut on data.
* -n nevents : number of events.
* -w workdir : location where output root files are to be stored.
              Default is root_io.
* -d datadir : location where sampling fraction files are. Default is
              data.
* infile : input ROOT file. Expected file format:
            <text>run_no.root .
```

Generate ntuples relevant to SIDIS analysis based on the reconstructed variables from CLAS12 data. The output of the program is the ‘ntuples_<run_no>.root’ file, which contains all relevant ntuples for RG-E analysis. This file can be studied directly in root or through the ‘draw_plots’ program.

4.1.5 draw_plots

The purpose of including the `draw_plots` executable is to save the user from rewriting similar code repeatedly to obtain plots. Using the `draw_plots` program is relatively straightforward: after running the program, the user is prompted with a series of questions to define various attributes related to the plots. This includes specifying any cuts and corrections to apply, setting up the binning, and selecting the variables to be plotted. Unless stated otherwise, the plots presented in Section 5 were generated using this executable.

The executable’s manual entry is:

```
Usage: draw_plots [-hp:cn:o:a:w:] infile
* -h : show this message and exit.
* -p pid : skip particle selection and draw plots for pid.
* -c : apply all cuts (general, geometry, and DIS) instead of
      asking which ones to apply while running.
* -n nentries : number of entries to process.
* -o outfile : output file name. Default is plots_<run_no>.root .
* -a accfile : apply acceptance correction using acc_filename.
* -A : get acceptance correction plots without applying
      acceptance correction. Requires -a to be set.
* -w workdir : location where output root files are to be stored.
              Default is root_io.
* infile : input file produced by make_ntuples .
```

Draw plots from a ROOT file built from ‘make_ntuples’. File should be named ‘<text>run_no.root’. This tool is built for those who don’t enjoy using root too much, and should be able to get most basic plots needed in SIDIS analysis.

4.2 Cuts

In order to enhance the relevance of particles for the analysis presented in this work, three types of cuts are applied:

- General cuts: These cuts are designed to exclude poorly reconstructed particles.
- Geometry cuts: These cuts define the region from which the reconstruction data is considered valid and useful for the analysis.
- DIS cuts: These cuts narrow down the analysis region to focus specifically on DIS.

By applying these cuts, the analysis can be focused on particles that meet the criteria for good reconstruction, fall within the desired geometry range, and are relevant to the DIS process.

4.2.1 General Cuts

For this analysis, only two cuts are considered as “general”. The first cut involves filtering out particles with PID values of 0 or 45. In CLAS12 reconstruction, these specific PID values are assigned to particles whose identification could not be successfully determined.

The second cut aims to exclude particles with imprecise tracking and is defined as follows:

$$\frac{\chi^2}{\text{NDF}} < 15,$$

where χ^2 represents the final result from the χ^2 -test used in the Kalman filter fit of the tracking algorithm, as described in Section 2.2.3. The term NDF denotes the number of degrees of freedom associated with this same fit.

By applying these two cuts, particles with undetermined or uncertain identification (PID values of 0 or 45) and those with poor tracking precision (exceeding the specified χ^2/NDF threshold) are excluded from the analysis.

4.2.2 Geometry Cuts

Three geometry cuts are derived to constrain the reconstructed particle’s vertex position. The first two cuts ensure that the vertex is located along the beamline, while the third cut restricts it to the acceptance region of the FMT.

The first cut guarantees that the vertex is close to the beamline and is defined as:

$$\sqrt{v_x^2 + v_y^2} < 4 \text{ cm},$$

where v_x and v_y represent the x and y coordinates of the vertex position, respectively.

The second cut ensures that the vertex originates from the target and is given by:

$$-40 \text{ cm} < v_z < z_0 \text{ cm},$$

where v_z corresponds to the z coordinate of the vertex position, and z_0 represents the z position of the first FMT layer. For the RG-F Spring 2020 run, $z_0 = 26.12 \text{ cm}$.

The third and final cut ensures that the vertex falls within the FMT acceptance region, as defined in Section 3.4.2. It removes all particles whose v_z and θ values lie outside the region bounded by the two lines defined by Equation (3).

4.2.3 DIS Cuts

Three DIS cuts are applied to the scattered electron to restrict the phase space to that of DIS. If the trigger electron fails to pass these cuts, all particles in the event are disregarded.

The first cut is based on the invariant mass of the virtual photon, Q^2 , and is defined as:

$$Q^2 > 1 \text{ GeV}^2.$$

This ensures that the process falls within the DIS domain.

The second cut is imposed on the squared mass of the hadronic final state, W^2 , given by:

$$W^2 > 4 \text{ GeV}^2.$$

Here, W^2 is defined as:

$$W^2 = M^2 + 2M\nu - Q^2,$$

where M represents the mass of the nucleon and ν is the energy fraction of the virtual photon. This cut is applied to exclude nucleon resonances.

Lastly, an additional cut is imposed on the Bjorken-Y (Y_b) of the scattered electron, given by:

$$Y_b < 0.85.$$

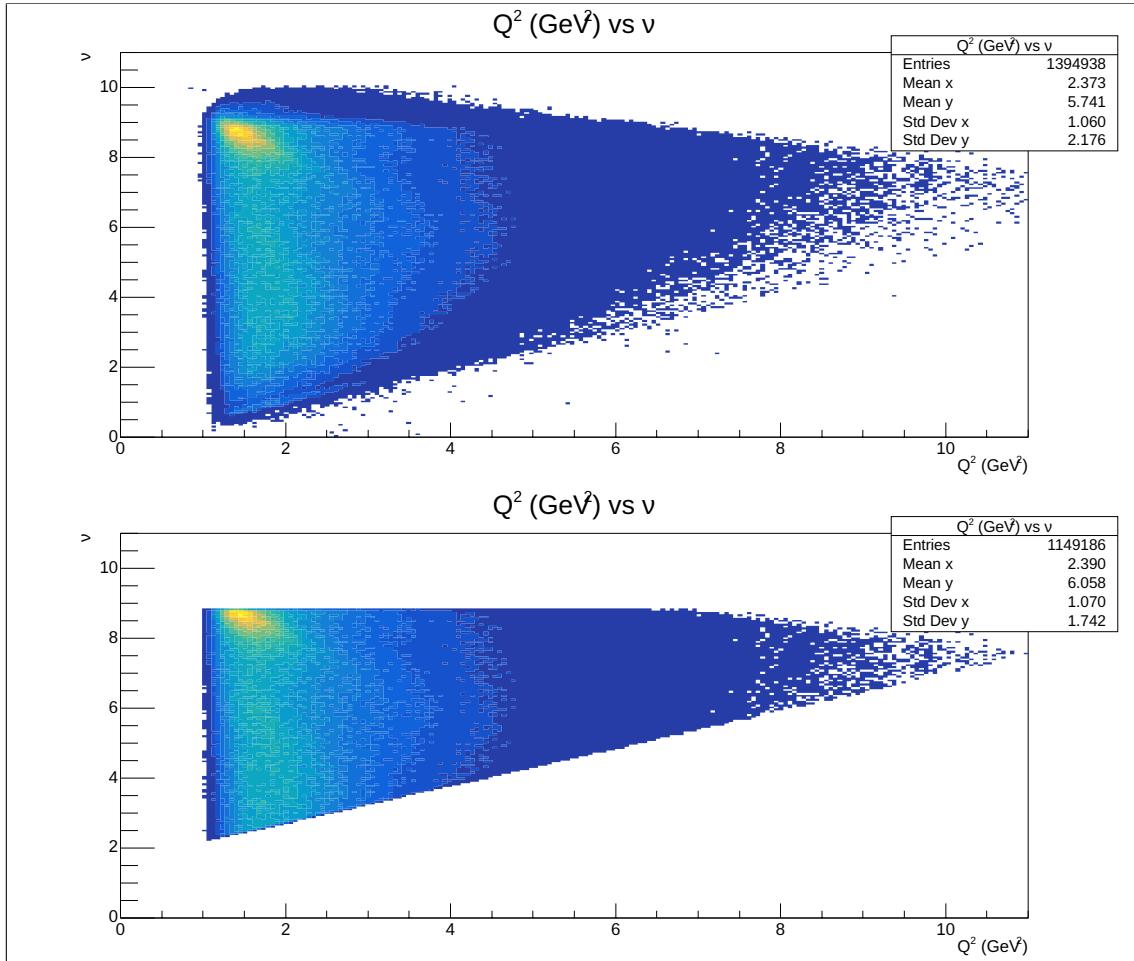


Figure 33: $e^- Q^2$ vs ν before and after applying the $Q^2 > 1 \text{ GeV}^2$, $W^2 > 4 \text{ GeV}^2$, and $Y_b < 0.85$ cuts, run 12016. Source: Own elaboration, using the clas12-rge-analysis software.

The Bjorken-Y ranges from 0 to 1 and is defined as:

$$Y_b = \frac{\nu}{E_{\text{beam}}},$$

where E_{beam} represents the energy of the incident electron beam. This cut effectively mitigates the influence of extreme radiative effects, which occur when a substantial portion of the incident electron's energy is transferred to the scattered electron.

The impact of these cuts on the Q^2 and ν of the scattered electron can be observed in plot 33.

4.3 Sampling Fraction

The energy deposited by electrons in the active area of the calorimeters is a fraction of their total energy, E_{tot} . This value is proportional to their momentum, P , for energies above a few hundred MeV. Heavier particles, due to their reduced penetration capabilities, tend to lose an amount of energy independent of their momentum. The electron sampling fraction measures the amount of energy lost depending on the momentum of a particle. This allows for both the measurement of the electron's energy and the differentiation of electrons from other particles [Wigmans and Wigmans, 2000].

To obtain the sampling fraction, the hits of each calorimeter by itself (PCAL, ECIN, and ECOU) are separated into arrays, with an additional array containing the union of the other three. Then, these arrays of hits are separated into 20 momentum bins. Each bin has a size of 0.4 GeV, starting at 1.0 GeV and ending at 9.0 GeV.

1-dimensional histograms are then created from the data in these arrays, measuring the deposited energy divided by the vertex momentum (E/p). A Gaussian fit plus a quadratic background is then applied, following the function described as

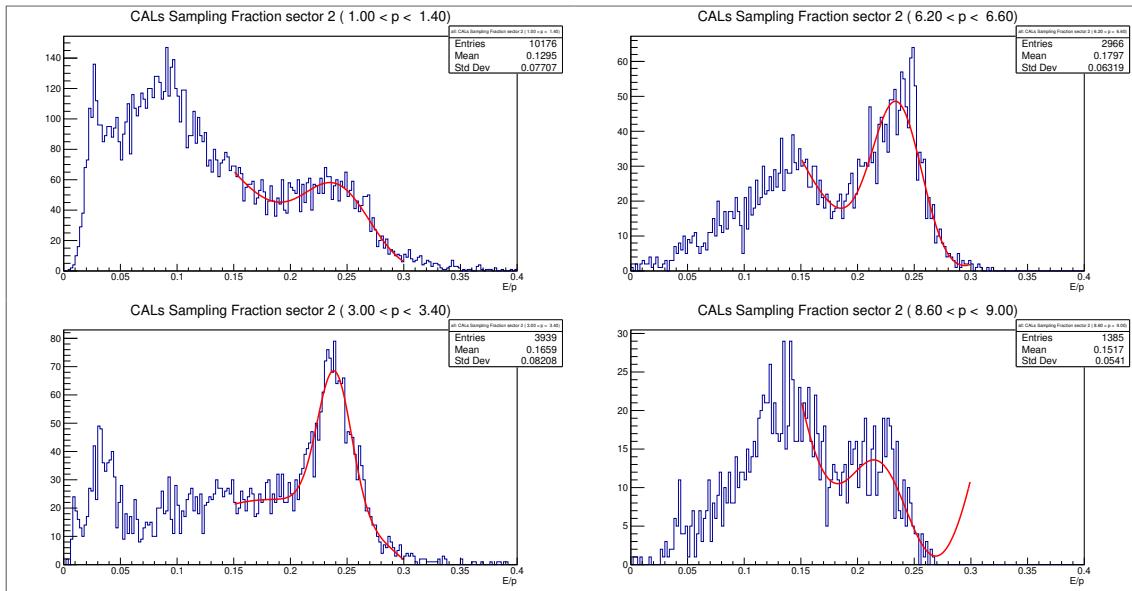


Figure 34: Four E/p plots describing the sum of the deposited energy per particle on all calorimeters (PCAL, ECIN, and ECOU). The particles' momentum is obtained from tracking and the event builder. As can be seen in the northwest and the southeast plots, the corner bins – 1.00 to 1.40 and 8.60 to 9.00 GeV respectively – are not very reliable. Source: Own elaboration, using the clas12-rge-analysis software.

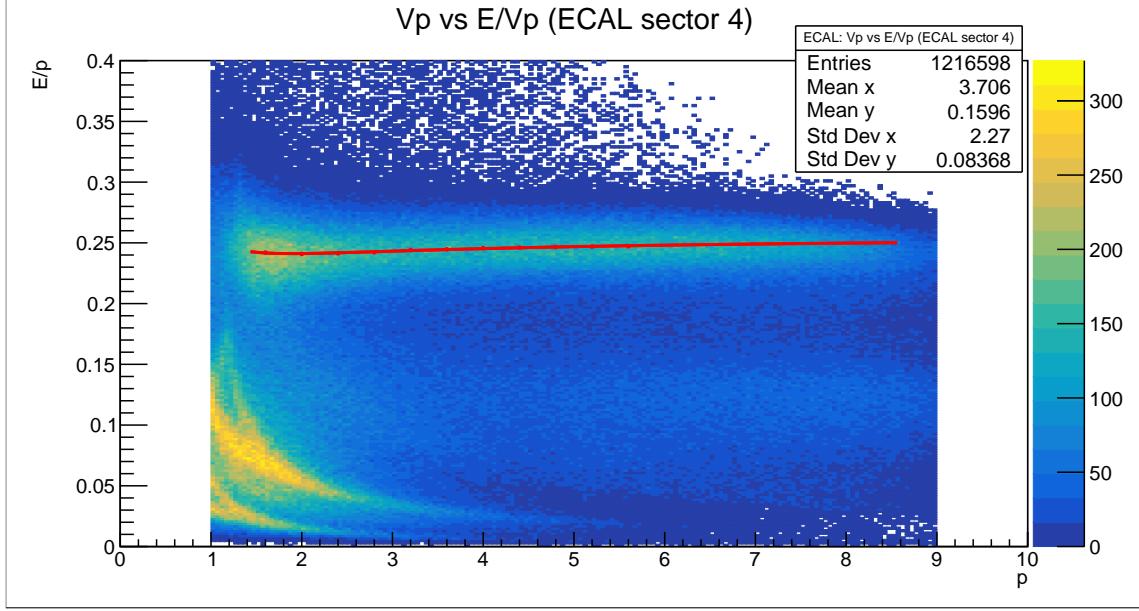


Figure 35: A 2d plot showing momentum p vs deposited energy divided by momentum E/p . The particle's deposited energy on all calorimeters is measured. Its momentum is obtained from tracking and the event builder. The fit follows the deposited energy of electrons to find their sampling fraction. Source: Own elaboration, using the clas12-rge-analysis software.

$$f(x) = p_0 g(x, \mu, \sigma) + p_1 x^2 + p_2 x + p_3, \quad \text{where } g(x, \mu, \sigma) = \frac{1}{\sigma \sqrt{2\pi}} \exp \left(-\frac{1}{2} \frac{(x - \mu)^2}{\sigma^2} \right),$$

where μ and σ represent the mean and standard deviation of the distribution, respectively. The fit is limited to the range between 0.15 and 0.30 for the expected E/p values for electrons based on theory.

Examples of these plots are shown in Figure 34. From the figure, it can be observed that there are not enough electrons in the extreme momentum ranges, such as from 1 to 1.4 GeV or from 8.6 to 9 GeV. Consequently, the sampling fraction fit, described in Equation (4), only considers data within the range of 1.4 to 8.6 GeV.

The mean of each of these fits is then extracted to serve as data points for a sampling fraction fit. A polynomial fit is employed since it effectively captures the shape of these points and aligns with the reconstruction software. The fit is described as

$$f(x) = p_0 \cdot \left(p_1 + \frac{p_2}{x} + \frac{p_3}{x^2} \right). \quad (4)$$

The E/p distribution vs p is depicted in Figure 35, together with this fit.

Finally, the parameters of the fit are saved in plain text files, following the convention used in the CCDB. These parameters can be utilised later for particle identification purposes, specifically for electrons and photons. Furthermore, they are employed to determine the energy of electrons and photons since, as mentioned previously, not all of their energy is deposited in the calorimeters.

4.4 Acceptance Correction

When discussing radiation detection, it is customary to distinguish between two types of efficiency: absolute efficiency and intrinsic detection efficiency. The former is defined as the fraction of events emitted by the source that are actually detected by the detector, expressed as

$$\xi_{\text{tot}} = \frac{\text{events registered}}{\text{events emitted by source}}.$$

This efficiency is influenced by the detector's geometry and the probability of an interaction occurring within the detector. The total efficiency is also referred to as the detector acceptance.

The total efficiency can be further decomposed into two components: the intrinsic efficiency, ξ_{int} , and the geometric efficiency, ξ_{geom} . The total efficiency is then given by

$$\xi_{\text{tot}} = \xi_{\text{int}} \cdot \xi_{\text{geom}}.$$

The intrinsic efficiency represents the fraction of events that actually reach and are detected by the detector

$$\xi_{\text{int}} = \frac{\text{events registered}}{\text{events impinging on detector}}.$$

This probability is dependent on the interaction cross-sections of the incident radiation with the detector medium. The intrinsic efficiency thus varies with the type of radiation, its energy, and the detector material [Leo, 1987].

Acceptance correction involves compensating for the total efficiency of the detector. To estimate this detector efficiency, a comparison is made between the total number of generated events, denoted as N_{thrown} , and the number of accepted events in a simulation of the detector, denoted as N_{simul} . This allows us to calculate an estimation of the detector efficiency, represented by $\tilde{\xi}_{\text{tot}}$, using

$$\tilde{\xi}_{\text{tot}} = \frac{N_{\text{simul}}}{N_{\text{thrown}}}.$$

Naturally, the value of $\tilde{\xi}_{\text{tot}}$ is influenced by the accuracy and reliability of the event generator and simulation programs employed in the study.

The acceptance of the detector exhibits variations across the phase space of the kinematic variables. Therefore, in order to achieve accurate acceptance correction, the ratio $\tilde{\xi}_{\text{tot}}$ needs to be divided into bins in a five-dimensional space. These bins correspond to the five variables under investigation: Q^2 , ν , z_h , p_T^2 , and ϕ_{PQ} . To simplify the analysis process and facilitate interpretation of the results, it is advantageous to have bins of the same size for each variable.

- $Q^2 = 4E_b E' \sin^2(\theta_C/2)$ is the 4-momentum transferred by the lepton probe in the lab frame, where E_b is the beam energy, E' is the scattered electron's energy, and θ_C is the polar angle of the scattered electron. The chosen bin edges are 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 GeV^2 .
- $\nu = E_v - E'$ is the energy transferred by the lepton probe in the lab frame. The chosen bin edges are 2, 3, 4, 5, 6, 7, 8, 9, and 10 GeV .
- $z_h = E_h/\nu$ is the virtual photon energy fraction carried by the measured hadron, with E_h being this hadron's energy. The chosen bin edges are 0, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, and 1.

- p_T^2 is the hadron’s transverse momentum measured with respect to the virtual photon direction. The chosen bin edges are 0, 0.2, 0.4, 0.6, 0.8, 1, 1.2, 1.4, 1.6, 1.8, and 2 GeV².
- ϕ_{PQ} is the angle between the leptonic plane – the plane where the paths of the initial and scattered electrons lie – and the hadronic plane, which contains the virtual photon and the measured hadron. The chosen bin edges are −180, −140, −100, −60, −20, 20, 60, 100, 140, and 180 degrees.

To calculate the acceptance, 10 million events were initially generated in deep inelastic kinematics using LEPTO, a Monte Carlo generator specifically designed for deep inelastic lepton-nucleon scattering [Ingelman et al., 1997]. Subsequently, these events were simulated under the experimental conditions of the RG-F experiment in CLAS12 using `gemc`, which is the standard tool for CLAS12 event simulation [Ungaro et al., 2020b]. The simulation took into account a torus field polarity of −1 and a solenoid field polarity of −0.745033.

Finally, the simulated events were reconstructed using `coatjava`, which is the standard tool for CLAS12 event offline reconstruction [Ziegler et al., 2020]. Further details regarding the offline reconstruction process can be found in Section 2.2.3. The outcomes of the acceptance correction procedure are discussed in Section 5.2.

5 Results and Conclusions

The FMT efficiency is discussed in the first section, including a brief study of it. Then, the second section delves into the acceptance correction results, based on the methodology described in Section 4.4. Following that, the study results are discussed in detail, and the conclusions of the study follow shortly thereafter.

5.1 FMT Efficiency

Compared to the alignment work described in Section 3, a low FMT is observed in this analysis. This is evident in Figure 36. Upon inspection, three causes can be attributed to this: the application of incorrect alignment constants, a geometry effect, and a general FMT offline reconstruction issue.

In this section, we extensively discussed the efficiency of the FMT detector, addressing alignment issues, as well as the impact of implementing a geometry cut. The key findings can be summarised as follows: despite applying corrections, the FMT efficiency for 3-layer tracks remained low, rendering them impractical for exclusive use. However, by switching to Spring 2020 data and applying the geometry cut, significant improvements were observed in the detection of trigger electrons and pions. Moreover, we thoroughly examined the correlation between efficiency and various variables, namely v_z , θ , ϕ , and p . The results were as anticipated: strong correlations were observed for v_z and θ , while no significant correlation was found for ϕ or p . These findings provide valuable insights into the performance and limitations of FMT, paving the way for an acceptance correction study and the following work.

5.1.1 Alignment Effect

The data from the RG-F experiment is divided based on the season in which the runs take place, namely Spring 2020 and Summer 2020. According to the run group's guidelines, it is recommended to use Summer data as it has undergone more calibration compared to the Spring data. However, the calibration work conducted so far does not include the FMT detector, resulting in a significant misalignment effect.

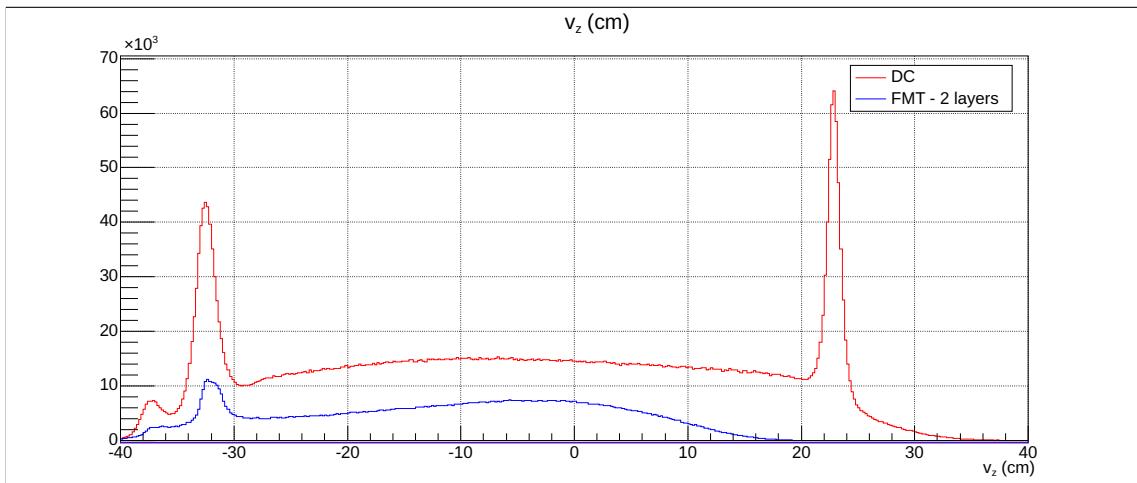


Figure 36: v_z for DC (in red) and FMT (in blue). Summer 2020 data, run 12933. The wide peaks in FMT suggest an uncorrected misalignment.

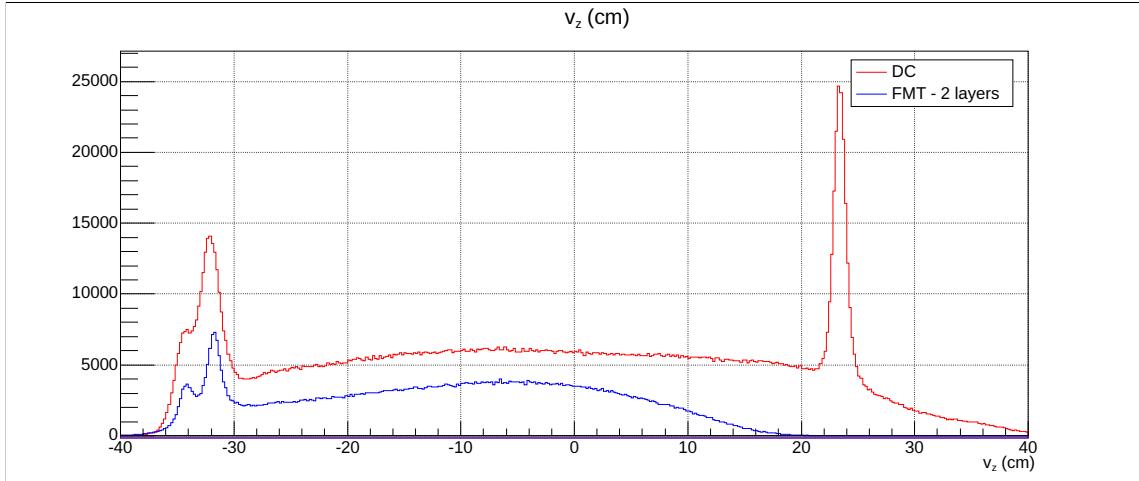


Figure 37: v_z for DC (in red) and FMT (in blue). Spring 2020 data, run 12016. The upstream twin peaks can be clearly distinguished, suggesting a correct misalignment correction. Source: Own elaboration, using the clas12-rge-analysis software.

Through simple visual inspection, two distinct peaks can be clearly observed between $z = -36$ cm and $z = -30$ cm in Figure 29. The leftmost peak corresponds to the scattering chamber window, while the second peak corresponds to the RG-F target window. These peaks appear merged in Figure 36. As discussed in Section 3, this issue arises due to the lack of correction for FMT misalignments.

The simplest solution is to utilise Spring data. Although more calibration work has been performed on the Summer data, it mainly pertains to the CD, which is not used in this analysis. Figure 37 depicts the same v_z plot from Spring 2020 run 12016, where both peaks are clearly visible. This indicates that the misalignment issue has been appropriately addressed in that particular run.

5.1.2 Geometry Effect

This problem has already been extensively discussed in Section 3.4.2. In summary, the FMT detector is located at approximately $z \approx 26$ cm, and it exhibits poor performance for targets located too close to it. The strength of this effect can be quantified by applying the geometry cut described by Equation (3) to both the DC and FMT tracks. Figure 38 illustrates the impact of this cut on both the DC and FMT tracks when applied to Figure 37. The effect of the cut on a v_z vs θ plot can be observed in Figure 30.

Based on this cut and the FMT's position along the z -axis, subsequent plots will be confined to the range $-30\text{cm} < v_z < 20\text{cm}$. In addition, unless otherwise specified, the cut is applied for all subsequent plots.

5.1.3 Reconstruction Effect

Even after correcting for both the alignment and geometry issues, the FMT still exhibits lower efficiency compared to what was observed during alignment (compare figures 38 with 31). After conducting a thorough study, it was determined that this effect is not correlated with the run number, beam energy, or beam luminosity. Consequently, it can be concluded that the issue is not caused by hardware problems or run conditions.

Based on these findings, the logical conclusion is that the effect stems from a general issue in the FMT offline reconstruction. Identifying and rectifying this issue would require

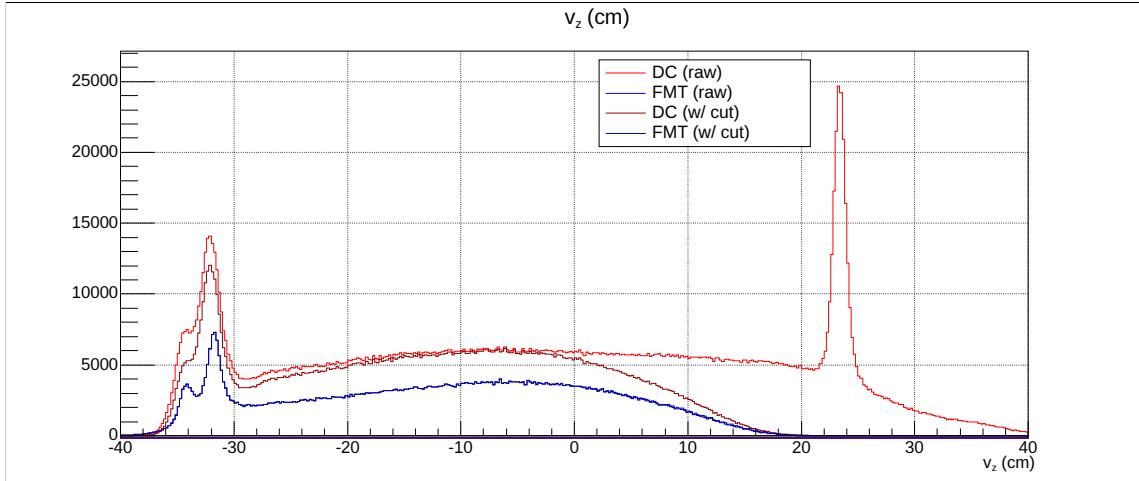


Figure 38: v_z for DC without the geometry cut (in red), with it (in dark red), for FMT without it (in blue), and with it (in dark blue). Spring 2020 data, run 12016. The effect is very clear on DC tracks, yet it almost doesn't affect FMT tracks. Source: Own elaboration, using the clas12-rge-analysis software.

a larger project beyond the scope of this thesis and is therefore left as future work. For the purposes of this analysis, we will rely on a large number of events to minimize any statistical deficiencies.

5.1.4 Efficiency Study

With all these effects accounted for, we can proceed to study the efficiency in detail. First, if we define FMT efficiency as the percentage of DC tracks that get accepted by FMT, we get the results in Table 5.1.4 for runs 12933 (Summer 2020) and 12016 (Spring 2020).

Run 12933			Run 12016	
	raw	w/ cut	raw	w/ cut
e^-	2 layers	25.1%	37.5%	32.7%
	3 layers	5.6%	8.5%	9.9%
π^+	2 layers	6.5%	13.7%	11.1%
	3 layers	0.3%	0.7%	1.0%
π^-	2 layers	5.6%	14.2%	8.9%
	3 layers	0.3%	0.7%	0.9%

Integrating all variables, it becomes evident that even with the corrections, the pion efficiency for 3-layer tracks does not exceed 3%. Consequently, it is not practical to work exclusively with FMT tracks that traverse all three FMT layers. For the remainder of the document, tracks detected by 2 or 3 layers will be collectively referred to as FMT tracks.

The table illustrates the positive impact of switching to Spring 2020 data and applying the geometry cut. The switch results in a 30.1% increase in detected trigger electrons, as well as a 70.8% increase for positive pions and a 58.9% increase for negative pions. Furthermore, by applying the geometry cut based on v_z and θ , an additional 64.2% increase in trigger electrons is achieved, resulting in a total increase of 113.9%. The pion yield experiences a substantial enhancement, with positive pions increasing by 150.2% and

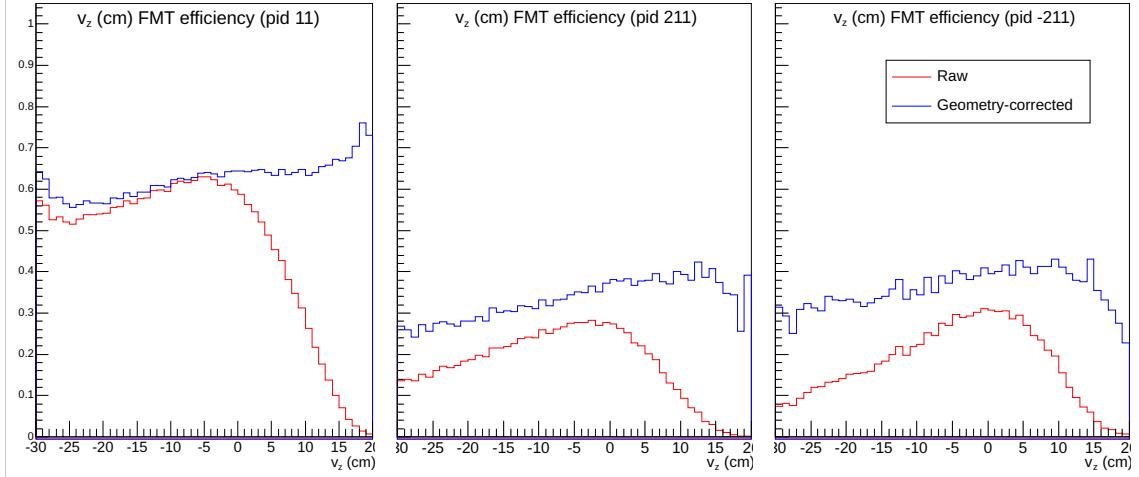


Figure 39: v_z FMT efficiency for e^- , π^+ , and π^- . FMT efficiency is defined as the percentage of DC tracks that are detected by 2 FMT layers. Run 12016. Source: Own elaboration, using the clas12-rge-analysis software.

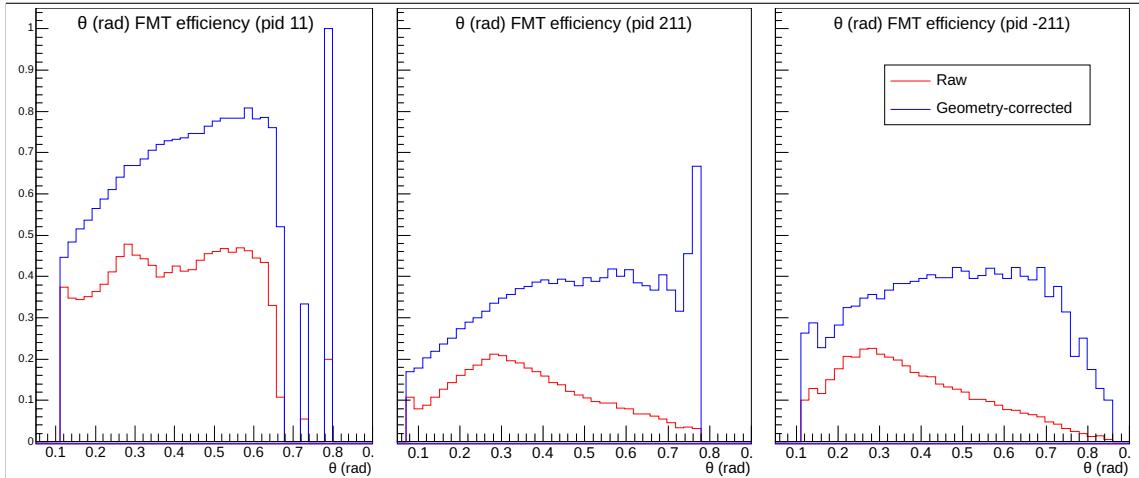


Figure 40: θ FMT efficiency for e^- , π^+ , and π^- . FMT efficiency is defined as the percentage of DC tracks that are detected by 2 FMT layers. Run 12016. Source: Own elaboration, using the clas12-rge-analysis software.

negative pions increasing by 231.5%, resulting in a total increase of 330.8% and 426.8%, respectively.

Next, we need to ensure that we are not introducing a systematic error by applying these corrections. To achieve this, we must investigate the effect of the geometry cut on different detected variables for electrons (e^-), positive pions (π^+), and negative pions (π^-). Based on the definition of the cut, we anticipate a strong correlation between efficiency and v_z and θ , and at most a weak correlation with ϕ and p .

Our prediction is validated by Figures 39 and 40. The efficiency displays a pronounced dependence on both v_z and θ for all three particles under study. It is worth noting that the dependence is more pronounced for electrons compared to pions. This outcome aligns with expectations, as the only accepted pions are those detected in events where an electron is also detected. Thus, the “final” pion efficiency incorporates the combined detector efficiencies for electrons and pions.

Next, we examine the ϕ efficiency, as depicted in Figure 41. Our prediction holds true

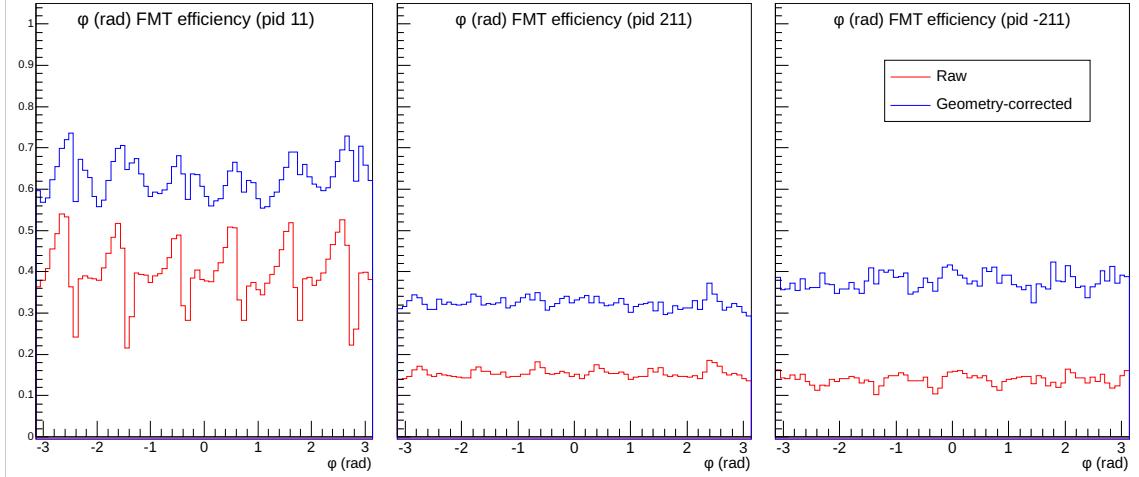


Figure 41: ϕ FMT efficiency for e^- , π^+ , and π^- . FMT efficiency is defined as the percentage of DC tracks that are detected by 2 FMT layers. Run 12016. Source: Own elaboration, using the clas12-rge-analysis software.

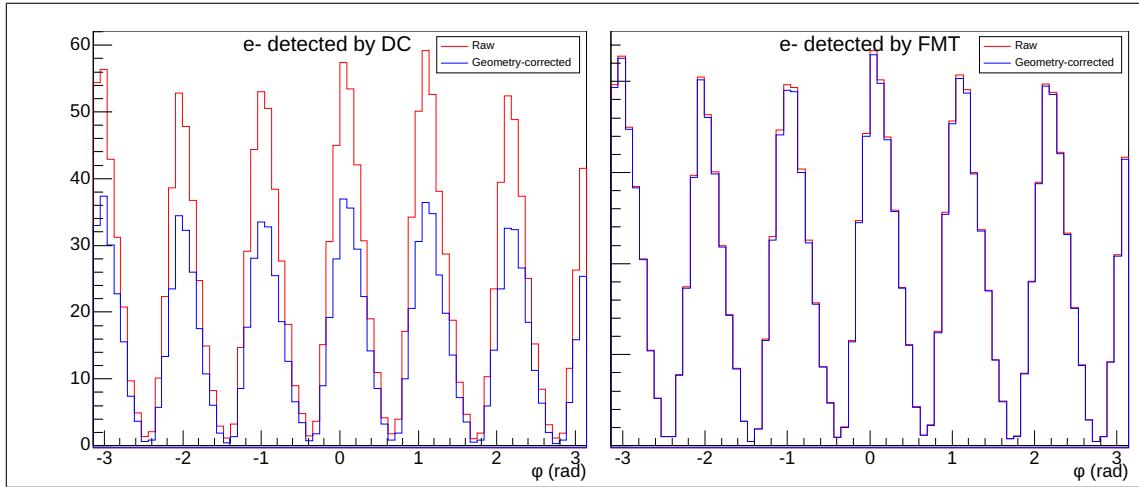


Figure 42: Number of electrons detected in terms of ϕ for DC and FMT. Run 12016. Source: Own elaboration, using the clas12-rge-analysis software.

for both positive and negative pions, as the efficiency demonstrates no dependence on the value of ϕ . However, in the case of electrons, upon initial inspection, the sharp valleys appear less prominent after applying the geometry cut.

Nevertheless, this is merely a visual effect. When we tally the number of electrons detected by the DC and FMT, the valleys become more pronounced in the DC, while they remain the same in the FMT. Consequently, the increase in FMT efficiency becomes more pronounced in these valleys, as demonstrated in Figure 42.

Finally, Figure 43 confirms our expectation that there is no strong correlation between efficiency and momentum.

5.2 Acceptance Correction Results

DC and FMT acceptances were obtained by following the procedure described in Section 4.1.3.

5.2.1 Electron Variables

First, we'll study the Q^2 and ν acceptances for the scattered e^- . Q^2 and ν acceptances are presented in Figures **TODO** and **TODO**, respectively. Each one is presented in integrated kinematical region for the other variable.

5.2.2 Hadronic Variables

Next, we'll look at z_h , P_T^2 , and ϕ_{PQ} acceptances for π^+ and π^- . We can see z_h acceptance in Figure **TODO**, where... (TODO).

Next, P_T^2 acceptance is presented in Figure **TODO**, where we see that... (TODO).

Finally, ϕ_{PQ} acceptance is studied in Figure **TODO**. Here, we see... (TODO).

5.3 Study Results

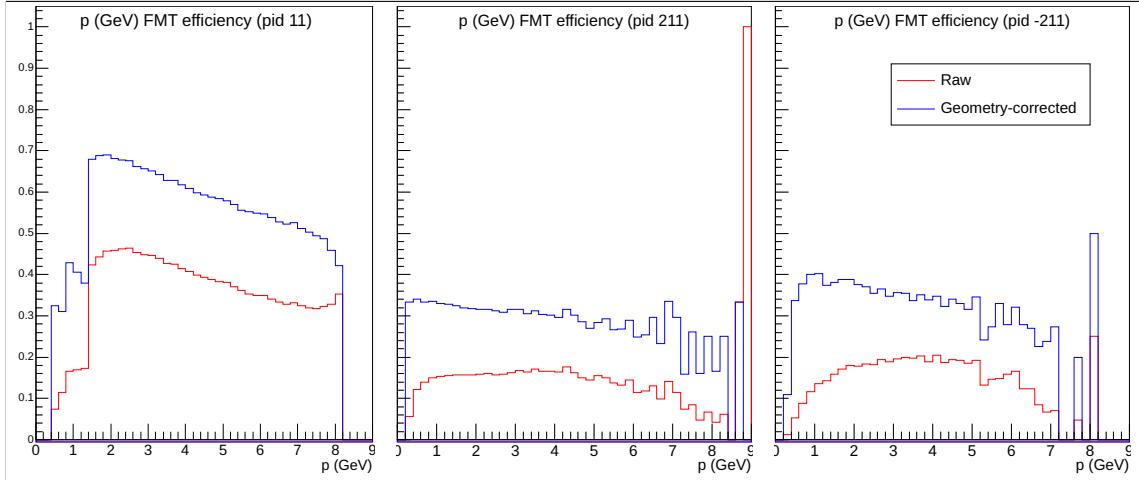
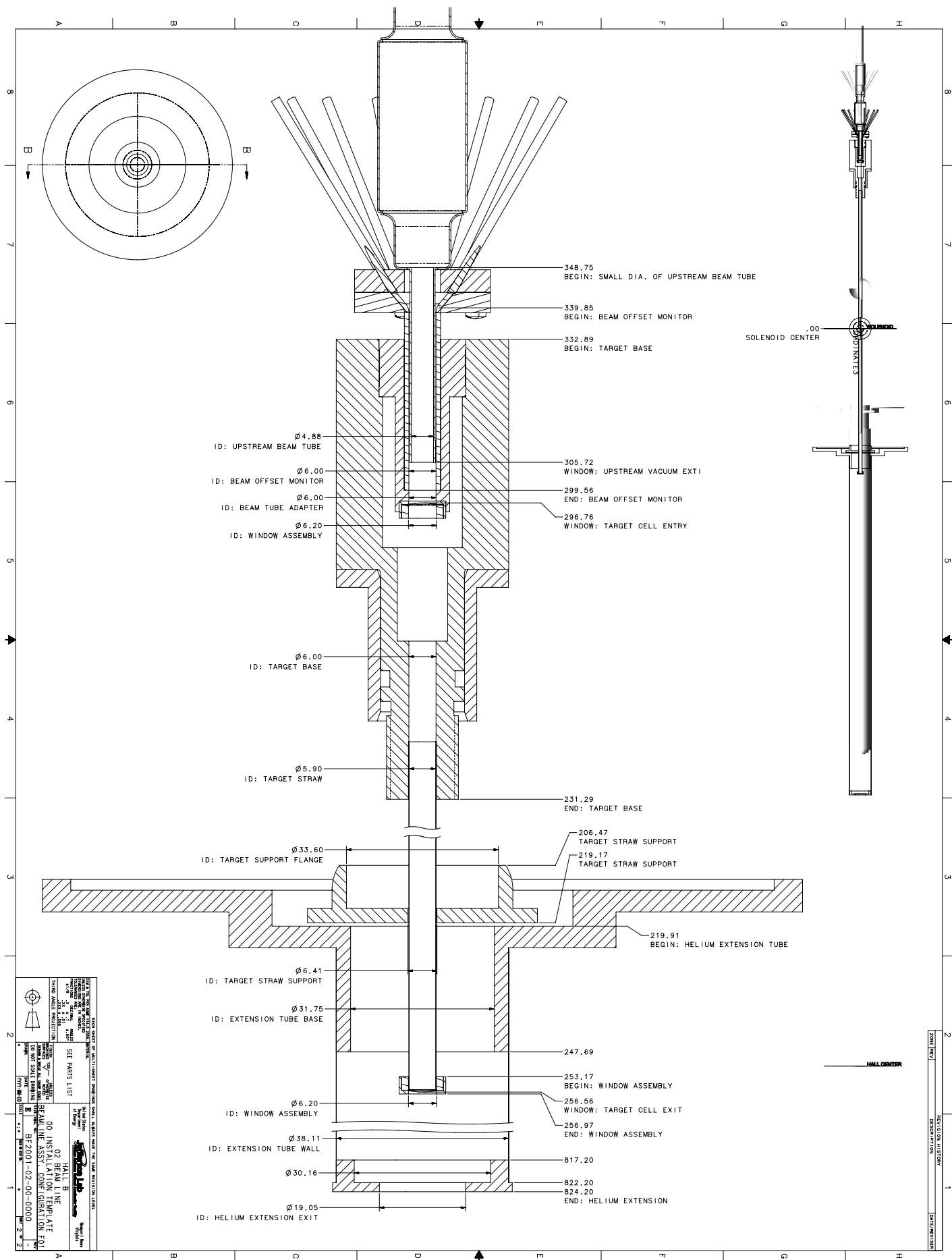


Figure 43: p FMT efficiency for e^- , π^+ , and π^- . FMT efficiency is defined as the percentage of DC tracks that are detected by 2 FMT layers. Run 12016. Source: Own elaboration, using the clas12-rge-analysis software.

Addendum 1: RG-F Target Layout



Addendum 2: Replicability

TODO.

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