

# Data Science and Machine Learning 2187 & 2087: Unsupervised Learning

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# Goals of this lecture

- ▶ Understand the difference between unsupervised- and supervised learning
- ▶ Understand the definition of hard clustering
- ▶ Understand clustering cost from different similarity measures
- ▶ Understand the K-means algorithm
- ▶ Understand the K-medoids algorithm

Feature vectors  $x$ , labels  $y$

$$x \in \mathbb{R}^d$$
$$y \in \{-1, 1\}$$

Training set

$$S_n = \{(x^{(i)}, y^{(i)}), i = 1, \dots, n\}$$

Classifier

$$h : \mathbb{R}^d \rightarrow \{-1, 1\}$$

# Supervised Learning vs. Unsupervised Learning

- ▶ In supervised learning we have labeled data:  $S_n = \{(x^{(i)}, y^{(i)}), i = 1, \dots, n\}$  and want to learn to correctly classify unseen data
  - ▶ Think of:
  - ▶ A gazillion of photos with a “cat” and “not cat” classification.
  - ▶ etc.
- ▶ In clustering we only have feature vectors:  $S_n = \{x^{(i)} | i = 1, \dots, n\}$  and want to find structures in unlabeled data
  - ▶ Think of:
  - ▶ Clustering a data set of customer into groups
  - ▶ Find spatial patterns, e.g. crime hotspots
  - ▶ Find similar news stories
  - ▶ Recommend products to customers “like you”
  - ▶ Create labels for supervised learning algorithms
  - ▶ Exploratory data analysis
- ▶ Types
  - ▶ Hard clustering
  - ▶ Soft clustering
  - ▶ Hierarchical clustering

# Clustering as Partitioning

Clustering input:  $S_n = \{x^{(i)} | i = 1, \dots, n\}, K$

Number of clusters:  $K$

The output of the clustering algorithm are indexes that partition the data:  $C_1, \dots, C_k$ ; where  $C_1 \cup C_2 \cup \dots \cup C_K = \{1, 2, \dots, n\}$  and  $C_i \cap C_j = \emptyset$  {for any  $i \neq j$  in  $\{1, \dots, k\}$ .

In other words: the union of all  $C_j$  's is the original set and the intersection of any  $C_i$  and  $C_j$  is an empty set.

In plain English:

We want to assign each element of the training data set  $S_n$  into  $K$  separate clusters in a way that each element only belongs to one cluster.

Clustering input:  $S_n = \{x^{(i)} | i = 1, \dots, n\}, K$

Number of clusters:  $K$

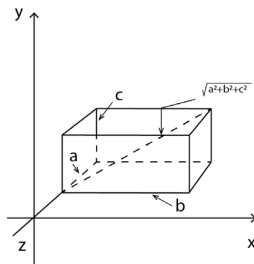
Select the best representatives of each cluster:  $z^{(1)}, \dots, z^{(k)}$ .

# Similarity Measures-Cost functions

- ▶ Cost of partitioning
  - ▶ Sum of costs of all individual clusters:  $cost(C_1, \dots, C_k) = \sum_{j=1}^k cost(C_j)$ .
- ▶ Cost of a single cluster
  - ▶ Sum of distances from data points to the representative of the cluster:  
 $Cost(C, z) = \sum_{i \in C} distance(x^{(i)}, z)$
- ▶ Total Cost to be minimized
  - ▶  $Cost(C_1, \dots, C_K) = \sum_{j=1}^K Cost(C_j) = \sum_{j=1}^K \sum_{i \in C_j} \|x_i - z_j\|^2$

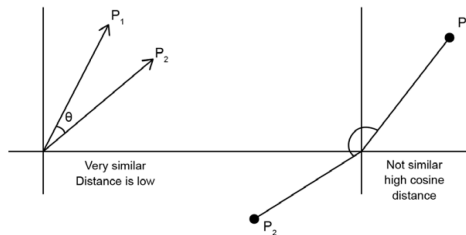
## Two common distance measures

- ▶ Cosine similarity:  $cos(x^{(i)}, x^{(j)}) = \frac{x^{(i)} \cdot x^{(j)}}{\|x^{(i)}\| \|x^{(j)}\|}$ 
  - ▶ Is not sensitive of magnitude of vector (will not react to length).
- ▶ Euclidean squared distance:  $dist(x^{(i)}, x^{(j)}) = \|x^{(i)} - x^{(j)}\|^2$ .
  - ▶ Will react to length of the vectors

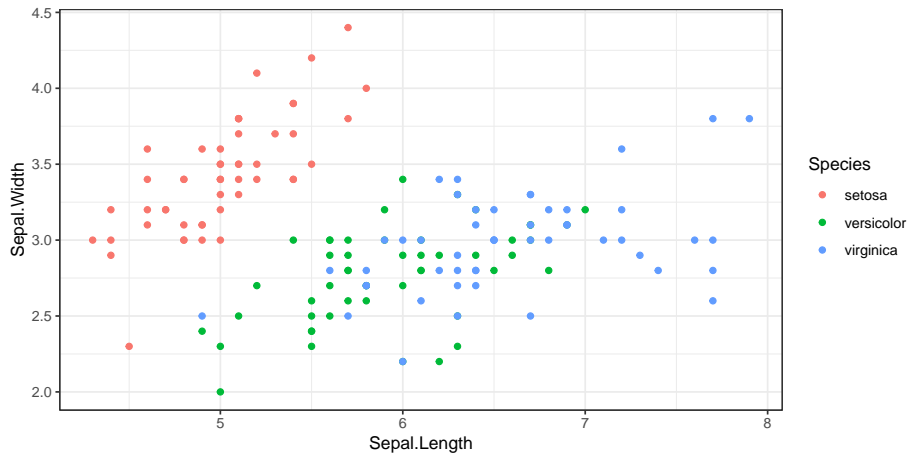


- ▶ The Euclidean distance between any two points is the square root of the sum of squares of differences between the coordinates. Straight line distance between any two points (pythagorean theorem)
- ▶ In two dimensions:  $dist(p, q) = \sqrt{(p_1 - q_1)^2 + (p_2 - q_2)^2}$ .
- ▶ Squared Euclidean distance is the sum of squares:  $dist^2(p, q) = (p_1 - q_1)^2 + (p_2 - q_2)^2$
- ▶ Generalizes to n-dimensions but loses meaning in very high dimensional data

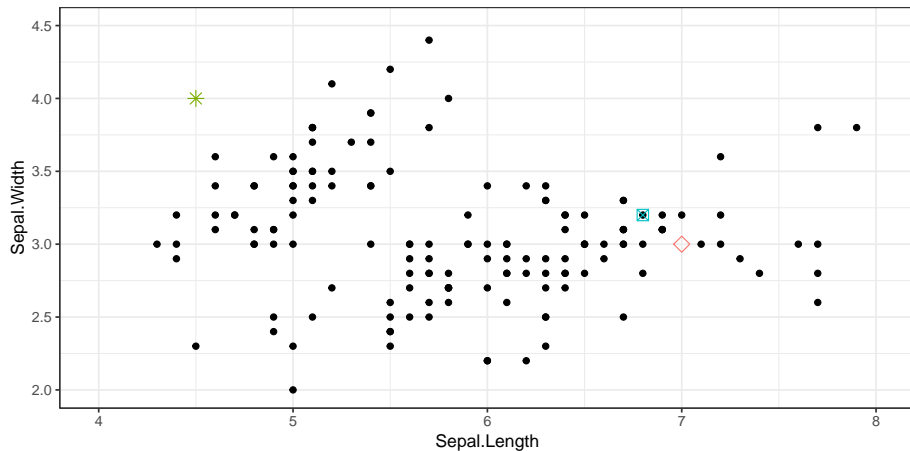




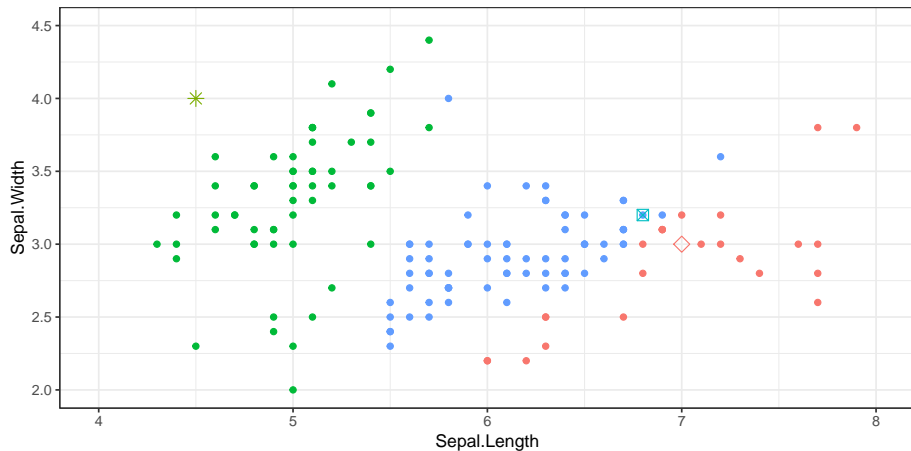
- ▶ Cosine similarity between any two points is defined as the cosine of the angle between any two points with the origin as its vertex.
- ▶ Cosine distance is defined as:  $1 - \text{cosine similarity}$
- ▶ Cosine distance varies from 0 to 2, whereas cosine similarity varies between -1 to 1.



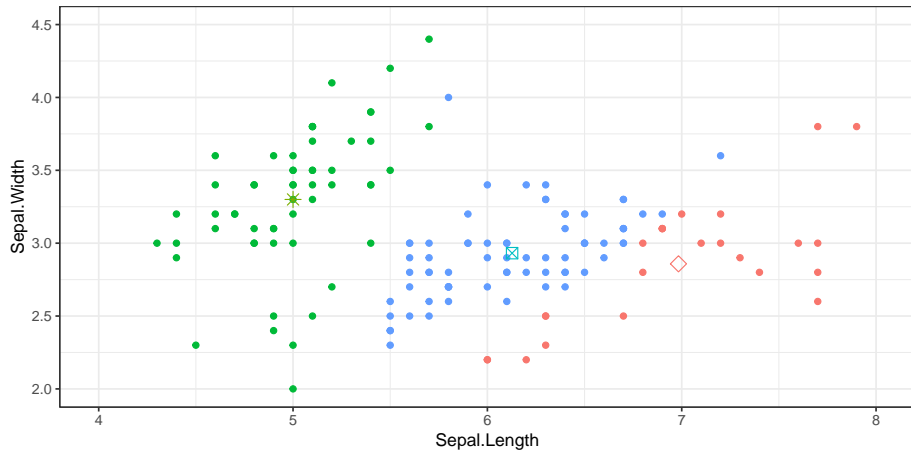
# Assign random initialization points (representatives $z_j$ )



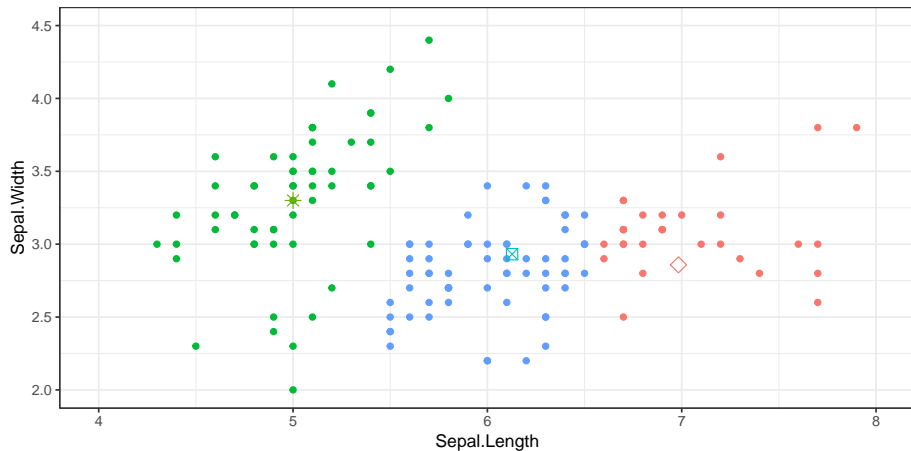
# Calculate nearest points to representatives $z_j$ (1st round)



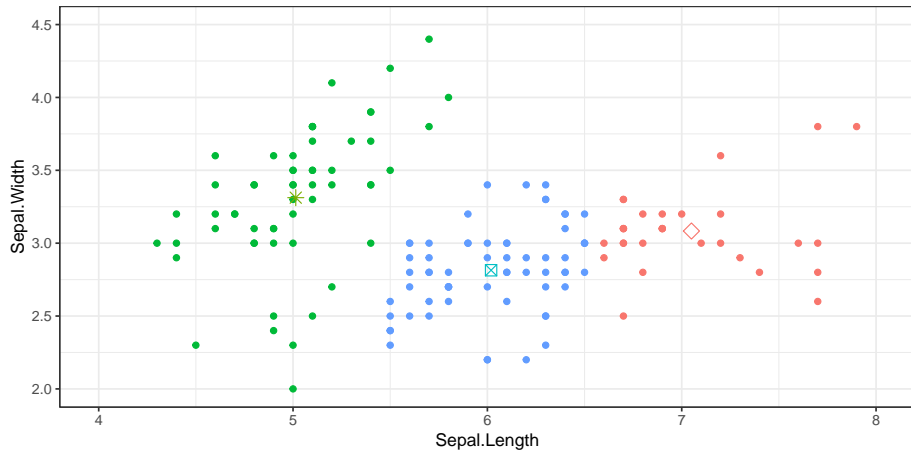
# Recalculate representatives $z_j$ as centroids of the new cluster (1st round)



# Calculate nearest points to representatives $z_j$ (2nd round)



# Recalculate representatives $z_j$ as centroids of the new cluster (2nd round)



Given a set of feature vectors  $S_n = \{x^{(i)} | i = 1, \dots, n\}$  and the number of clusters  $K$  we can find cluster assignments  $C_1, \dots, C_K$  and the representatives of each of the  $K$  clusters  $z_1, \dots, z_K$ :

1. Randomly select  $z_1, \dots, z_K$

2. Iterate until no change in cost

- 2.1 Given  $z_1, \dots, z_K$ , assign each data point  $x^{(i)}$  to the closest  $z_j$ , such that

$$\text{Cost}(z_1, \dots, z_K) = \sum_{i=1}^n \min_{j=1, \dots, K} \|x^{(i)} - z_j\|^2$$

- 2.2 Given  $C_1, \dots, C_K$  find the best representatives  $z_1, \dots, z_K$ , i.e. find  $z_1, \dots, z_K$  such that

$$z_j = \operatorname{argmin}_z \sum_{i \in C_j} \|x^{(i)} - z\|^2$$



# Minimizing the cost in K-means

K-means only works with Euclidean square distance!

The best representative is found by optimization (gradient with respect to  $z^{(j)}$ , setting to zero and solving for  $z^{(j)}$ ).

$$\nabla_{z_j} \left( \sum_{i \in C_j} \|x^{(i)} - z_j\|^2 \right) = 0$$

$$\sum_{i \in C_j} -2(x^{(i)} - z_j) = 0$$

$$z^{(j)} = \frac{\sum_{i \in C_j} x^{(i)}}{|C_j|}$$

It is the centroid of the cluster, where  $C_j$  is the size of the respective cluster.

The clustering output that the K-Means algorithm converges to depends on the initialization!  
 Suboptimal initializations are possible.

1. Choose any two random coordinates,  $z_1$  and  $z_2$ , on the scatter plot as initial cluster centers.
2. Calculate the distance of each data point in the scatter plot from coordinates  $z_1$  and  $z_2$
3. Assign each data point to a cluster based on whether it is closer to  $z_1$  or  $z_2$
4. Find the mean coordinates of all points in each cluster and update the values of  $z_1$  and  $z_2$  to those coordinates respectively.
5. Start again from Step 2 until the coordinates of  $z_1$  and  $z_2$  stop moving significantly, or after a certain pre-determined number of iterations of the process.

- ▶ Algorithm is only guaranteed to converge to local minimum
- ▶ Initialization matters
  - ▶ Bad initialization can lead to suboptimal clusters in pathological cases
- ▶ Unclear how many clusters we should plug into the algo (more about that next lecture)
- ▶ Only works with euclidean distance

Any distance measure possible!

Gives actual data points as representatives.

Finds the cost-minimizing representatives  $z_1, \dots, z_K$  for any distance measure. Uses real data points for initialization.

1. Randomly select  $\{z_1, \dots, z_K\} \subseteq \{x_1, \dots, x_n\}$
2. Iterate until no change in cost
  - 2.1 Given  $z_1, \dots, z_K$ , assign each data point  $x^{(i)}$  to the closest  $z_j$ , so that
$$\text{Cost}(z_1, \dots, z_K) = \sum_{i=1}^n \min_{j=1, \dots, K} \|x^{(i)} - z_j\|^2$$
  - 2.2 Given  $C_j \in \{C_1, \dots, C_K\}$  find the best representative  $z_j \in \{x_1, \dots, x_n\}$  such that
$$\sum_{x^{(i)} \in C_j} \text{dist}(x^{(i)}, z_j)$$
 is minimal

1. Choose  $k$  data points from the scatter plot as starting points for cluster centers.
2. Calculate their distance from all the points in the scatter plot.
3. Classify each point into the cluster whose center it is closest to.
4. Select a new point in each cluster that minimizes the sum of distances of all points in that cluster from itself.
5. Repeat Step 2 until the centers stop changing.

