IOWA STATE UNIVERSITY **Department of Computer Science**

A Comparative Study of Image Generation Models

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Introduction

What is image generation?

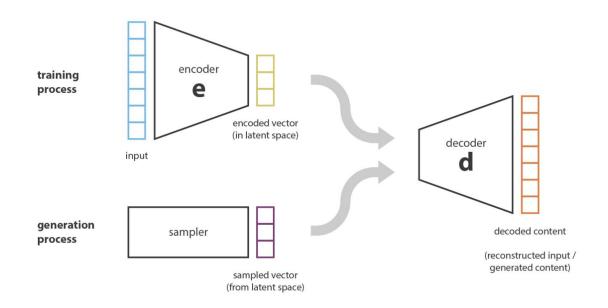
- Improving image resolution
- Restoring missing data
- Denoising
- Artificial face generation
- Image editing

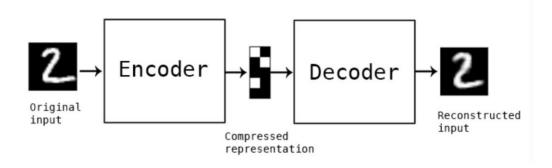




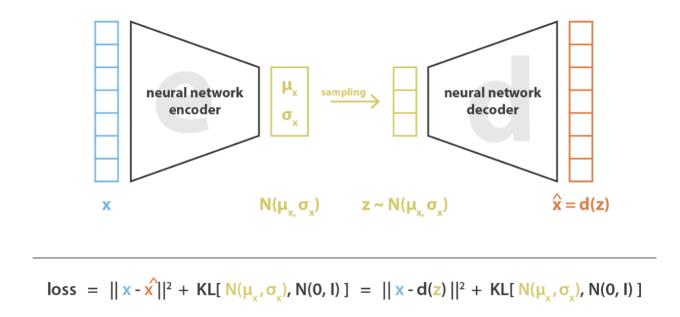


AutoEncoders





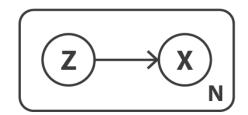
Variational AutoEncoders



In variational autoencoders, the loss function is composed of a reconstruction term and a regularization term.

VAEs from a probabilistic point of view

- Prior distribution p(z)
- Likelihood distribution p(x|z)
- Redefine our notions of encoder and decoder:



$$p(z) \equiv \mathcal{N}(0, I)$$

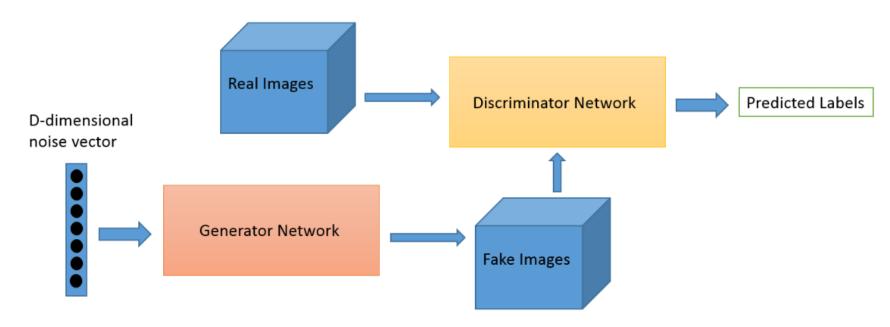
$$p(x|z) \equiv \mathcal{N}(f(z), cI) \qquad f \in F \qquad c > 0$$

$$f^* = \underset{f \in F}{\operatorname{arg\,max}} \mathbb{E}_{z \sim q_x^*} (\log p(x|z))$$

$$= \underset{f \in F}{\operatorname{arg\,max}} \mathbb{E}_{z \sim q_x^*} \left(-\frac{||x - f(z)||^2}{2c} \right)$$

Generative Adversarial Network

- The concept of GAN is to have two competing neural networks the generator and the discriminator.
- The weights of both these networks are updated by backpropagation.



Generative Adversarial Network – contd.

- The networks are a collection of layers the weights of which are manipulated using the loss generated to get an accurate image generated or for accurate classification.
- The losses can be calculated using the following equation

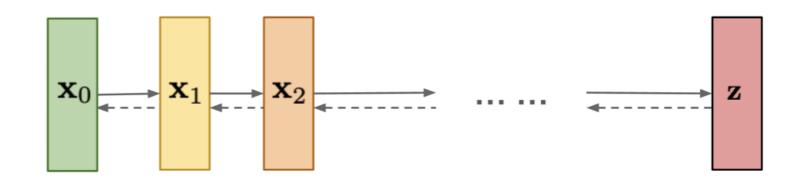
$$\min_{G} \max_{D} V(D, G) = \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}(\boldsymbol{x})}[\log D(\boldsymbol{x})] + \mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{z}}(\boldsymbol{z})}[\log(1 - D(G(\boldsymbol{z})))]$$

Diffusion model

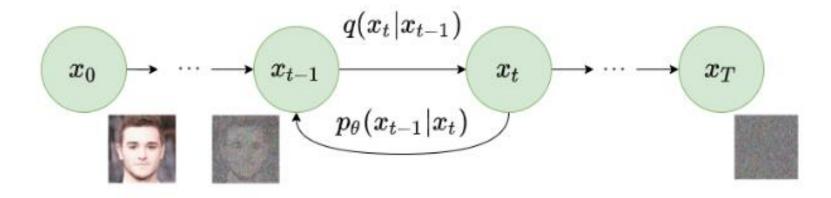
The essential idea of diffusion model is to systematically and slowly destroy structure in a data distribution through an iterative forward diffusion process. We then learn a reverse diffusion process that restores structure in data, yielding a highly flexible and tractable generative model of the data

Diffusion models:

Gradually add Gaussian noise and then reverse



Forward and reverse diffusion process



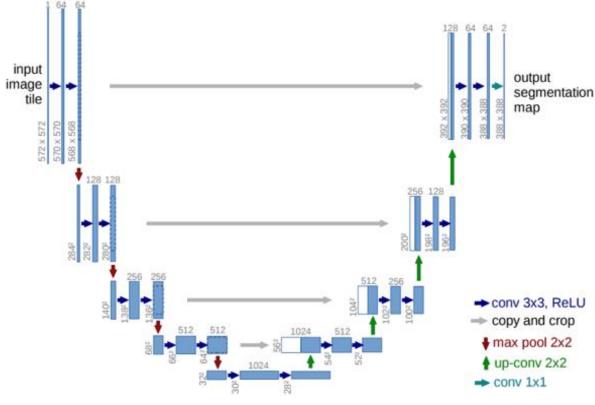
Forward diffusion process:

$$q(\mathbf{x}_{1:T}|\mathbf{x}_0) \coloneqq \prod_{t=1}^{T} q(\mathbf{x}_t|\mathbf{x}_{t-1})$$

Reverse diffusion process:

$$p_{\theta}(\mathbf{x}_{0:T}) \coloneqq p(\mathbf{x}_T) \prod_{t=1}^{T} p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)$$

U-Net neural network

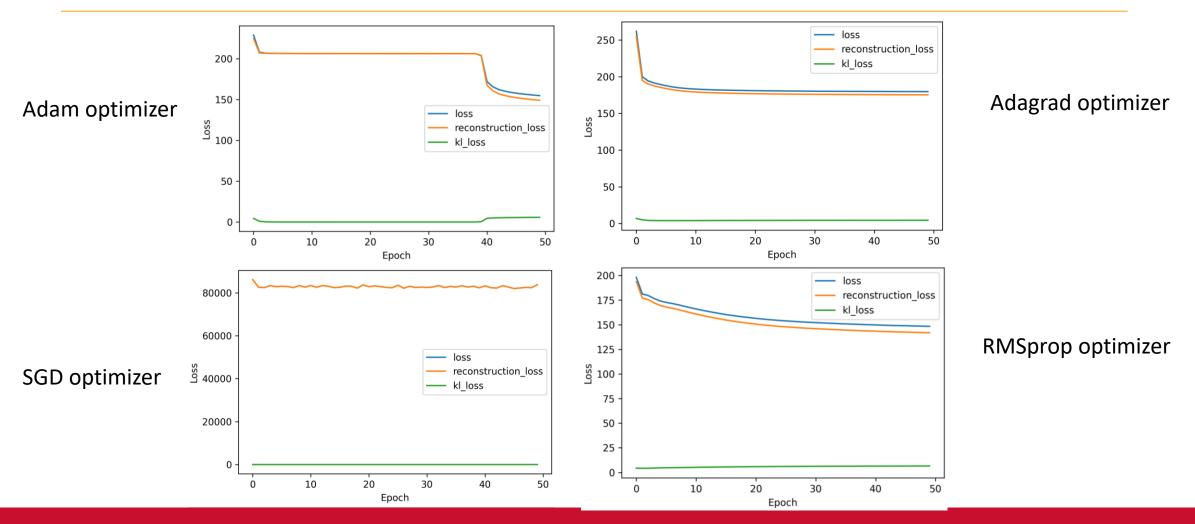


Loss:
$$L_{\text{simple}}(\theta) \coloneqq \mathbb{E}_{t,\mathbf{x}_0,\epsilon} \Big[\| \boldsymbol{\epsilon} - \boldsymbol{\epsilon}_{\theta} (\sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \boldsymbol{\epsilon}, t) \|^2 \Big]$$

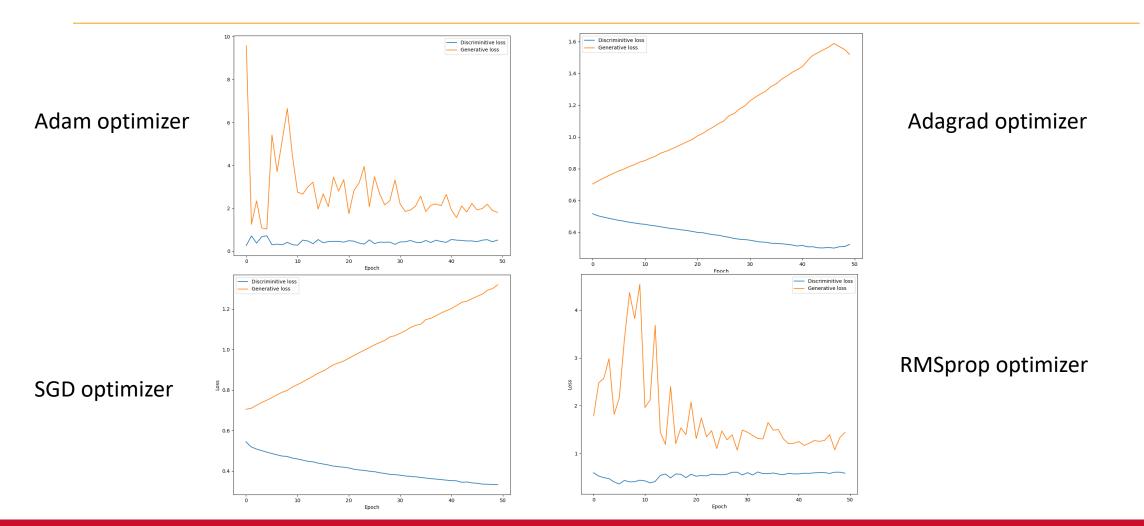
Experiments

- MNIST dataset consists of 60000 handwritten images of which 50000 training images,
 10000 test images.
- The three models were trained on the MNIST dataset using 4 different optimizers to get the best results and compare the models with the best results.
- We limited the number of epochs to 50.
- Adam optimizer performed the best in all the models.
- Tensorflow and Keras python libraries were used.

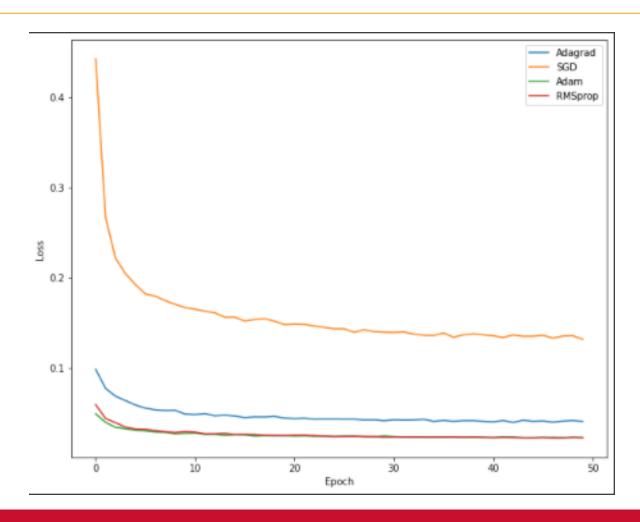
Experiments – VAE graph



Experiments – GAN graph



Experiments – Diffusion Model graph



Results – VAE Model

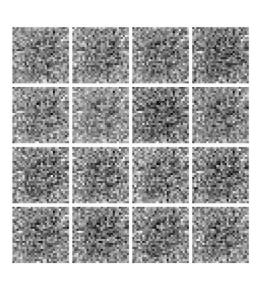
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Results – GAN Model

Images generated in the 50th epoch during GAN training



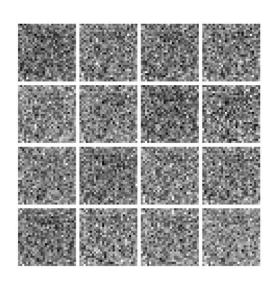
Adam optimizer



Adagrad optimizer

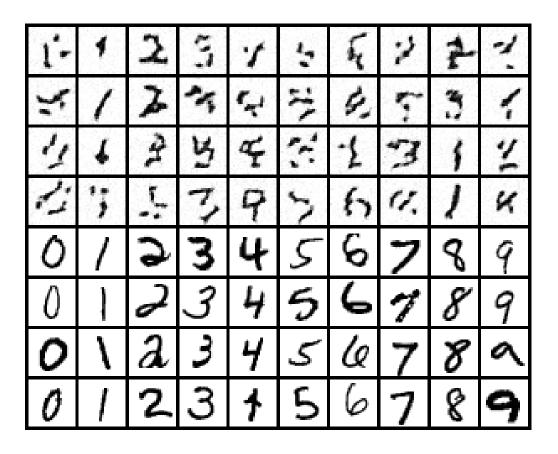


RMSprop optimizer



SGD optimizer

Results – Diffusion Model

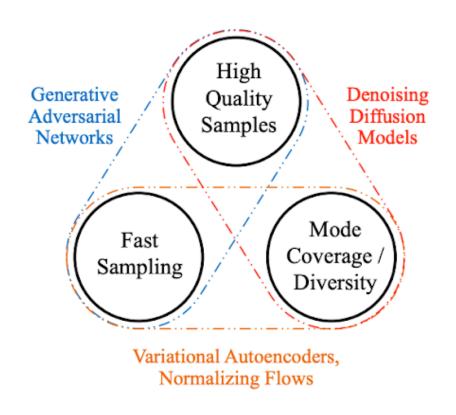


Conclusion

 The models have a clear precedence in terms of performance.

VAE < GAN < Diffusion model

 Each model has its own shortcoming which are eliminated by the other model.



Thank you!