## Coluna: An Open-Source Branch-Cut-and-Price **Framework**

T. Bulhões, G. Marques, V. Nesello, A. Pessoa, E. Uchoa, R. Sadykov, I. Tahiri, F. Vanderbeck





JuMP-dev 2019. Santiago March 2019

#### Contents

What is Coluna.jl?

Decomposition approaches

Using Coluna to decompose and solve a model

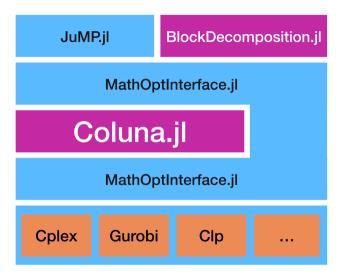
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#### What is Coluna.jl?



## Coluna.jl

- What:
  - A Column-and-Row generation code
  - ► Open-Source: MPLicence
  - Written in Julia (1.1)
  - Uses JuMP.jl (0.19), MathOptInteface.jl and BlockDecomposition.jl
- Uses:
  - Dantzig-Wolfe & Benders decomposition
  - Robust & Stochastic Optimization
  - Machine Learning
- ► First release: Jan. '19
- Support: Math Optimization Society (MOS) & JuliaOpt
- ▶ URL https://github.com/atoptima/Coluna.jl

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#### Decomposition Approaches

On a subset of constraints (Dantzig-Wolfe): multi-resources

On a subset of variables (Benders): multi-decision-levels

# The Cutting Stock Problem (CSP): Block-diagonal structure



min  $< W y_k$  $\forall i, k$ 

Number of rolls : 88 Total waste : 5090

Assume a bounded integer integer problem with structure:

$$[F] \equiv \min \quad cx : \\ Ax \geq a \\ x \in X = \{ Bx \geq b \\ x \in \mathbb{N}^n \}$$

Assume that subproblem

$$[\mathsf{SP}] \equiv \min\{c \, x : \, x \in X\}$$

is "relatively easy" to solve compared to problem [F].

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$$X = \{x^q\}_{q \in Q}$$

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$$X = \{x^q\}_{q \in Q}$$

$$\operatorname{conv}(X) = \{x \in \mathbb{R}_+^n : x = \sum_{q \in Q} x^q \lambda_q, \sum_{q \in Q} \lambda_q = 1, \lambda_q \ge 0 \ q \in Q\}$$

Assume a bounded integer integer problem with structure:

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$$[\mathsf{F}] \equiv \min\{\sum_{q \in Q} c x^q \lambda_q : \sum_{q \in Q} A x^q \lambda_q \ge a, \sum_{q \in Q} \lambda_q = 1, \sum_q x^q \lambda_q \in \mathbb{N}^n\}$$

### The Cutting Stock Problem (CSP): Decomposition



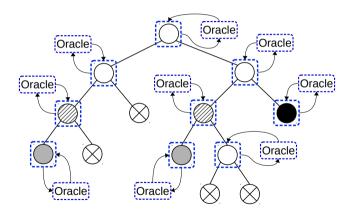
min  $\sum_{k=1}^{K} y_k$ s.t.  $\sum_{k=1}^{K} x_{ik} \geq d_i \quad \forall i$   $\sum_{i} w_i x_{ik} \leq W y_k \quad \forall k$   $x_{ik} \in \mathbb{N} \quad \forall i, k$  $y_k \in \{0,1\} \quad \forall k$ 

$$\min \sum_{q} \lambda_{q}$$

$$\sum_{q} x_{i}^{q} \lambda_{q} \geq d_{i} \qquad i = 1, \cdots, n$$
 $\lambda_{r} \in \mathbb{N} \quad \forall q$ 

### Solving decomposed problems

- Choose node
- Solve chosen node
  - Solve master lp
  - Check if converged
  - Generate row/columns
  - Repeat
- Create children nodes



### Coluna log: Solving a node

```
*************************
Preparing node 6 for treatment. Parent is 5.
Elapsed time: 174.96061992645264 seconds.
Current primal bound is 1931.99999999998
Subtree dual bound is 1929,8571428571377
Branching constraint: x[3.76] >= 1.0
2 open nodes. Treating node 6.
Current best known bounds: [ 1929.8571428571377 . 1931.99999999998 ]
**************************
<it=1> <et=175.0> <mst= 0.021> <sp= 0.206> <cols=5> <mlp=1930.4839> <DB=1921.7871> <PB=1932.0>
<it=2> <et=175.0> <mst= 0.015> <sp= 0.234> <cols=5> <mlp=1930.25> <DB=1925.4306> <PB=1932.0>
<it=3> <et=176.0> <mst= 0.015> <sp= 0.264> <cols=5> <mlp=1930.25> <DB=1925.8393> <PB=1932.0>
<it=4> <et=176.0> <mst= 0.015> <sp= 0.242> <cols=5> <mlp=1930.25> <DB=1926.4267> <PB=1932.0>
<it=5> <et=176.0> <mst= 0.011> <sp= 0.27> <cols=5> <mlp=1930.25> <DB=1926.7257> <PB=1932.0>
<it=6> <et=176.0> <mst= 0.014> <sp= 0.206> <cols=5> <mlp=1930.25> <DB=1927.9531> <PB=1932.0>
<it=7> <et=177.0> <mst= 0.014> <sp= 0.266> <cols=5> <mlp=1930.25> <DB=1928.8538> <PB=1932.0>
<it=14> <et=179.0> <mst= 0.017> <sp= 0.288> <cols=5> <mlp=1930.25> <DB=1929.7722> <PB=1932.0>
<it=15> <et=179.0> <mst= 0.014> <sp= 0.325> <cols=5> <mlp=1930.25> <DB=1930.0> <PB=1932.0>
<it=16> <et=180.0> <mst= 0.01> <sp= 0.347> <cols=5> <mlp=1930.25> <DB=1930.125> <PB=1932.0>
<it=17> <et=180.0> <mst= 0.014> <sp= 0.376> <cols=5> <mlp=1930.25> <DB=1930.25> <PB=1932.0>
<Coluna. AlgToPrimalHeurByRestrictedMip> <mlp=1930.249999999993> <PB=1960.0000000000005>
[ Info: Generated 2 child nodes.
```

#### Interest

#### **Integer Programming Decomposition**

- A powerful way to exploit the combinatorial structure.
- Benders & Dantzig Wolfe decomposition are generic schemes to derive & handle strong reformulations
- ➤ Size can be coped with using dynamic generation: a small % of variables and constraints are needed; hence it scales up to real-life applications.
- With efficiency enhancement features, these approaches can be highly competitive
- Implementation can be generic, with tools such as Coluna.jl

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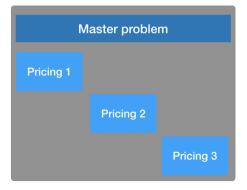
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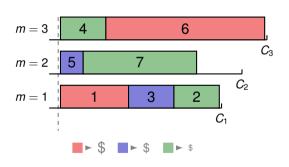
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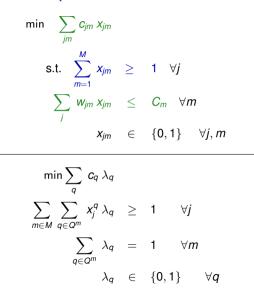
#### General idea

- Write a model using JuMP
- Use variable and constraint indices to define the decomposition
- Store extra information in the indices -> axis macro
- Create a decomposition tree based on the memberships defined in the extra information -> dantzig\_wolfe\_decomposition macro

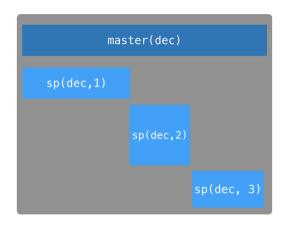


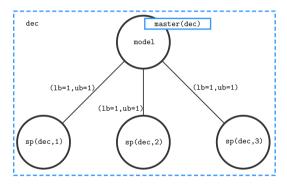
# Generalized Assignment Problem: The simple case





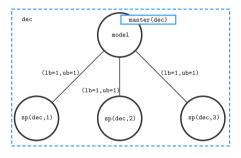
# Generalized Assignment Problem: The simple case



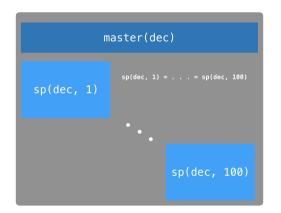


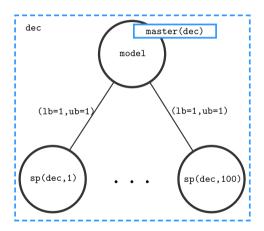
# Generalized Assignment Problem: The simple case

```
function generalized_assignment()
   @axis(Machines, 1:3)
   model = BlockModel() # Defines a JuMP model with a hook
   @variable(model, x[i in jobs, m in Machines], Bin)
   @constraint(
        model, cov[j in jobs],
        sum(x[i, m] for m in Machines) >= 1
   @constraint(
        model, knp[m in Machines],
        sum(weights[j, m] * x[j, m] for j in jobs)
        <= capacities[m]</pre>
   @objective(
        model. Min.
        sum(costs[i, m] * x[i, m] for i in jobs, m in Machines)
   @dantzig wolfe decomposition(model, dec. Machines)
end
```

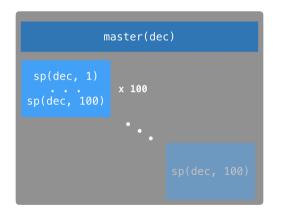


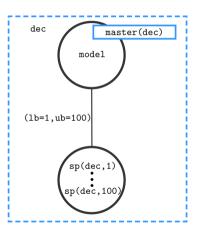
# **Cutting Stock: Different subproblems**





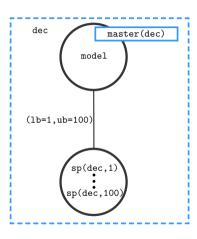
# Cutting Stock : Different subproblems





# **Cutting Stock: Identical subproblems**

```
function cutting_stock()
   @axis(Patterns, 1:100, Identical)
   model = BlockModel()
   @variable(
        model, 0 <=
        x[i in items, s in Patterns] <= demands[i]. Int
   @variable(model, y[s in Patterns], Bin)
   @constraint(
        model, cov[i in items].
        sum(x[i, s] for s in Patterns)
        >= demands[i]
   @constraint(
        model, knp[s in Patterns],
        sum(widths[i] * x[i, s] for i in items)
        <= sheets_sizes[1] * y[s]</pre>
   @objective(model, Min, sum(y[s] for s in Patterns))
   @dantzig wolfe decomposition(model, dec, Patterns)
end
```

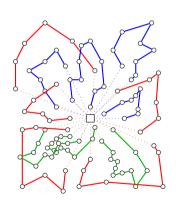


# **Cutting Stock: Getting the solution**

```
function cutting_stock()
   @axis(Patterns, 1:100, Identical)
   model = BlockModel()
   @variable(
        model, 0 <=
        x[i in items, s in Patterns] <= demands[i]. Int
   @variable(model, y[s in Patterns], Bin)
   @constraint(
        model, cov[i in items].
        sum(x[i, s] for s in Patterns)
       >= demands[i]
   @constraint(
        model, knp[s in Patterns],
        sum(widths[i] * x[i, s] for i in items)
        <= sheets_sizes[1] * y[s]</pre>
   @objective(model, Min, sum(y[s] for s in Patterns))
   @dantzig wolfe decomposition(model, dec, Patterns)
end
```

```
for s in active_indices(Patterns)
    for i in items
        @show value(x[s, i])
    end
end
```

# CVRP: Expression & ad-hoc pricing solver



$$\begin{array}{llll} \min & \displaystyle \sum_{e,r} c_e x_e^r \\ \\ \text{s.t.} & \displaystyle \sum_{e \in \delta(i),r} x_e^r & \geq & \mathbf{2} & \forall i \\ \\ & x^r & \in & X^r & \forall r \end{array}$$

#### CVRP : Ad-hoc pricing solver

```
function cvrp()
   G = GraphOfInstance()
   @axis(model. Routes. 1:max routes. Identical)
   @variable(model, x[r in Routes, e in edges(G)] >= 0)
   @expression(model, y[e in edges(G)], sum(x[r,e] for r in Routes), Int)
   @constraint(model, deg[i in nodes(G)], sum(x[r,e] for e in incidents(G, i), r in Routes) == 2.0)
   @objective(model, Min, sum(c[e] * y[e] for e in edges(G)))
   @dantzig wolfe decomposition(model, dec. Routes)
    build network(model, G, sp(dec, 1))
    add_pricing_callback(model, dec, PricingCallBack::Function)
end
```

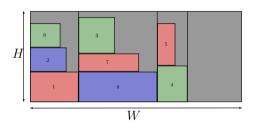
#### CVRP : Ad-hoc pricing solver

```
function build_network(subproblem)
    r = getsubproblemid(subproblem)
    net = Network(nb_nodes, source = 1, sink = nb_nodes)
    capacity_res = addmainresource!(net, max_capacity, stepsize = 1)
    for e in edges(G)
        edge_id = add_edge!(net, e, var = x[r,e])
              edgeconsumption!(net, edge_id, capacity_res, value = conso[e])
    end
    return net
end
```

#### CVRP: Ad-hoc pricing solver

```
function pricing callback(cb)
    r = getsubproblemid(cb)
    reduced_costs = [getreducedcost(cb, x[r, e]) for e in edges(G)]
    solution vectors = compute shortest groute(G. reduced costs)
    for solution in solution vectors
        solution_reduced_cost = getreducedcost(cb, getsubproblem(dec, r))
        path_x_vector = zeros(Int, length(edges(G)))
        for edge in solution
            path x vector[edge] += 1
            solution reduced cost += reduced costs[edge]
        end
        if solution_reduced_cost < - 0.001</pre>
            for e in edges(G)
                x[r, e] = path x vector[e]
            end
                recordsubproblemsolution(cb, getsubproblem(dec, r), x[r, :])
        end
   end
end
```

## 2D Cutting Stock : Nested decomposition



min 
$$\sum_{s \in S} z_s$$
  
s.t.  $\sum_{s \in S, p \in P} x_{jps} \geq 1 \quad \forall j$   
 $\sum_{p} w_{ps} \leq W z_s \quad \forall s$   
 $w_{ps} \geq w_j x_{jps} \quad \forall j, p, s$   
 $\sum_{j} h_j x_{jps} \leq H y_{ps} \quad \forall p, s$   
 $x_{jps} \in \{0, 1\} \quad \forall j, p, s$   
 $y_{ps} \in \{0, 1\} \quad \forall p, s$   
 $z_s \in \{0, 1\} \quad \forall s$ 

# 2D Cutting Stock: Original & master reformulations

$$\min \sum_{s \in S} z_{s}$$
s.t. 
$$\sum_{s \in S, p \in P} x_{jps} \geq 1 \quad \forall j$$

$$\sum_{p} w_{ps} \leq W z_{s} \quad \forall s$$

$$\sum_{p} w_{ps} \geq w_{j} x_{jps} \quad \forall j, p, s$$

$$\sum_{j} h_{j} x_{jps} \leq H y_{ps} \quad \forall p, s$$

$$\sum_{j} k_{jps} \in \{0, 1\} \quad \forall j, p, s$$

$$y_{ps} \in \{0, 1\} \quad \forall p, s$$

$$z_{s} \in \{0, 1\} \quad \forall s$$

# 2D Cutting Stock: Pricing problem and its reformulation

$$\min 1 - \left(\sum_{j} \pi_{j}\left(\sum_{p} x_{jp}\right)\right)$$
s.t. 
$$\sum_{p} x_{jp} \leq 1 \quad \forall j$$

$$\sum_{p} w_{p} \leq W \quad \forall$$

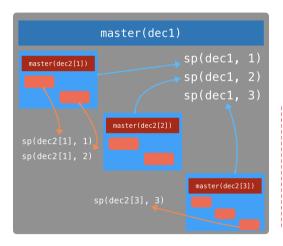
$$w_{p} \geq w_{j} x_{jp} \quad \forall j, p$$

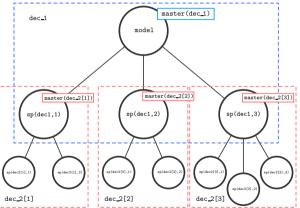
$$\sum_{j} h_{j} x_{jp} \leq H \quad \forall p$$

$$x_{jp} \in \{0, 1\} \quad \forall j, p$$

$$\min \sum_{
ho} \lambda_{
ho}$$
 $\sum_{
ho} x_{j}^{
ho} \lambda_{
ho} \leq 1 \quad \forall j$ 
 $\sum_{
ho} w_{
ho} \lambda_{
ho} \leq W$ 
 $\lambda_{
ho} \in \mathbb{N} \quad \forall 
ho$ 

## 2D Cutting Stock : Nested decomposition





# 2D Cutting Stock : Nested decomposition

```
model
function 2D cutting stock()
    @axis(model, S, 1:3, Identical) # Defines Sheets
   @axis(model, P[s in S], 1:4, Identical) # Defines Patterns
                                                                                               master(dec 2[2])
                                                                                  master(dec 2[1])
                                                                                                           master(dec 2[3])
                                                                                sp(dec1.1)
                                                                                             sp(dec1,2)
                                                                                                          sp(dec1.3)
   @variable(model. 0 \le z[s in S] \le 1. Bin)
   @variable(model. 0 \le v[s in S. p in P[s]] \le 1. Bin)
   @variable(model, 0 \le w[s in S, p in P[s]] \le 1)
   @variable(model, 0 <= x[i in items, p in P[s], s in S] <= 1, Bin)</pre>
                                                                            dec_2[1]
                                                                                         dec 2[2]
   @constraint(model, cov[j in items], sum(x[j, p, s] for s in S, p in P[s]) >= 1)
    @constraint(model, sheet_cap[s in S], sum(w[s, p] for p in P[s]) \leq z[s] * sheet\_width
    @constraint(model, strip_width[s in S, p in P[s], j in items], w[p, s] >= x[j, p, s] * items[j].width)
    @constraint(model, strip cap[s in S, p in P[s]].
                 sum(x[i, p, s] * items[i].height for i in items) <= v[p, s] * sheet height)
   @objective(model, Min, sum(z[s] for s in S))
   @dantzig_wolfe_decomposition(model, dec1, S)
   @dantzig_wolfe_decomposition(sp(dec1, s), dec2[s in S], P[s])
end
```

master(dec 1)

dec\_1

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