

### Focus Session 52

Pathways towards nature-based adaptation and transformation in mountains

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# Characterising non-stationarity in predictive models of land use in Swiss mountain parks to inform scenarios for deliberative transformation.

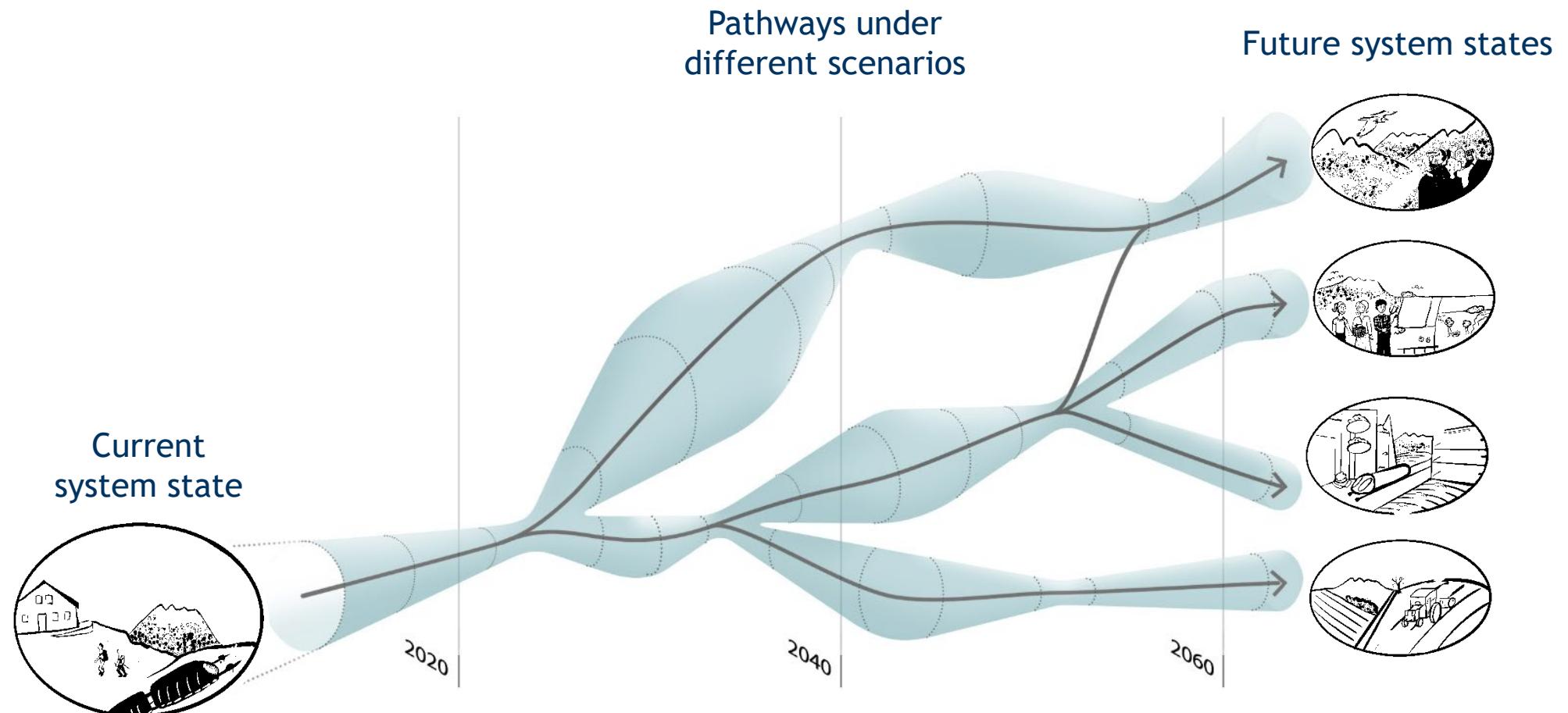
Benjamin Black, Sergio Wicki & Prof. Dr. Adrienne Grêt-Regamey

Planning of Landscape and Urban Systems, Swiss Federal Institute of Technology (ETH)



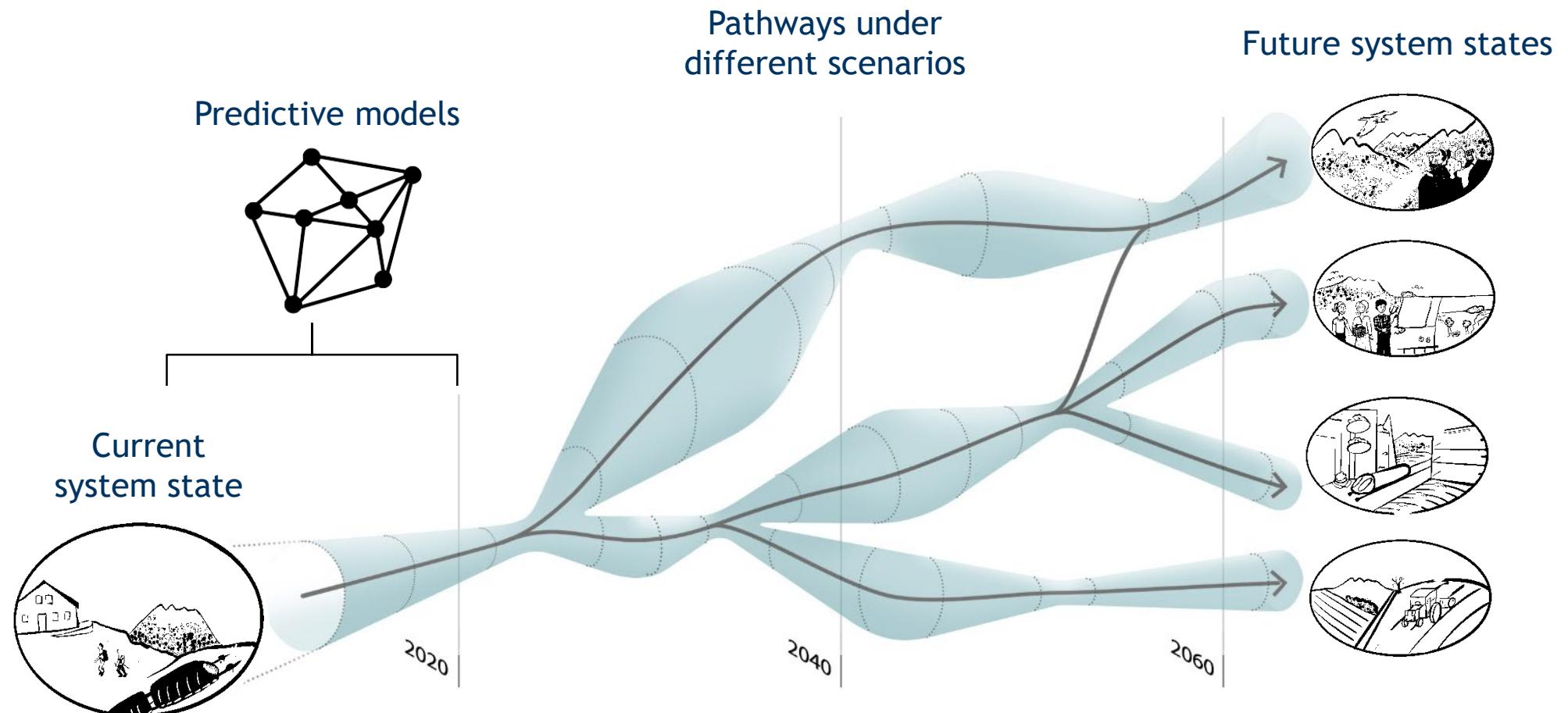


# Scenario modelling of Socio-Ecological systems

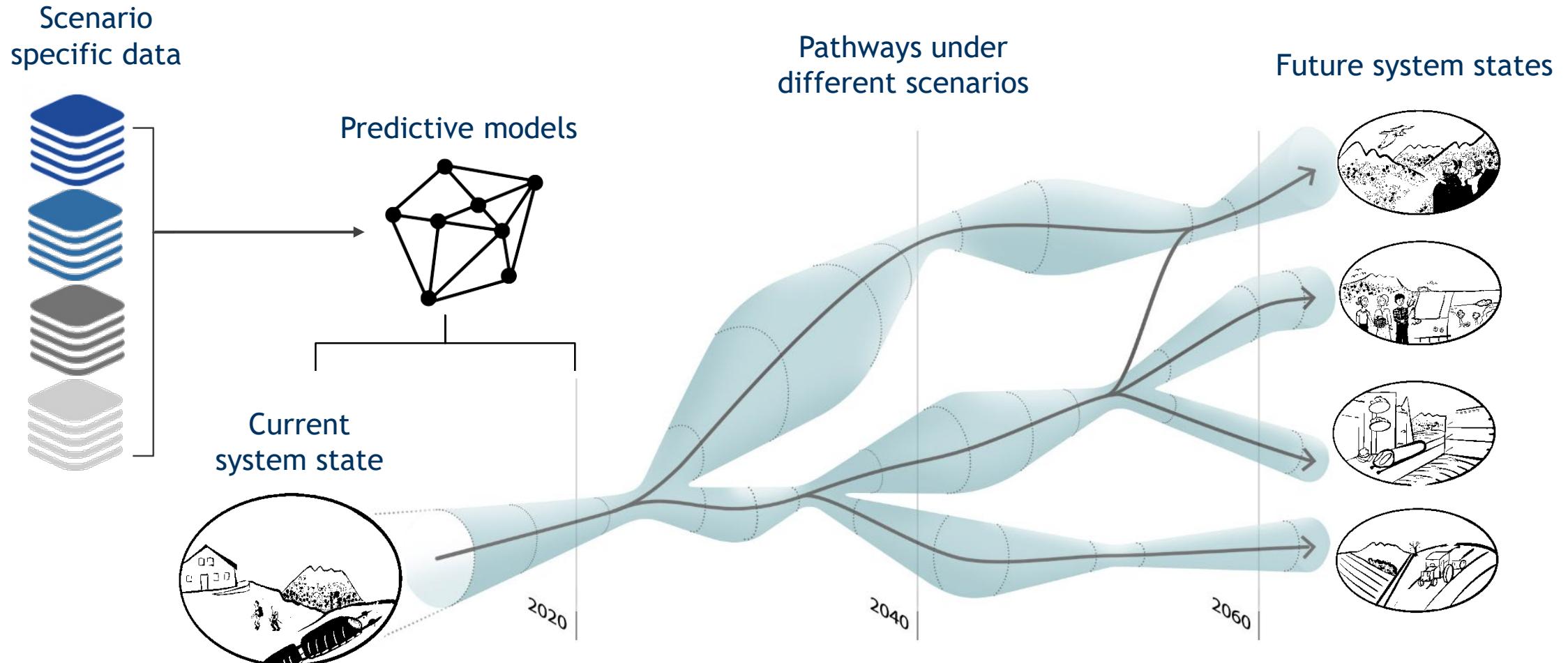




# Scenario modelling of Socio-Ecological systems

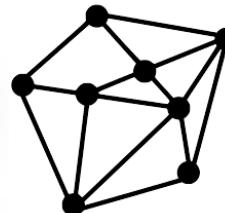


# Scenario modelling of Socio-Ecological systems



# Scenario modelling of Socio-Ecological systems

Predictive models



- Models are trained on historic data
- **Assumption:** Relationships remain stationary in time
- **BUT:** With multiple historical periods we can quantitatively demonstrate non-stationarity
- **Problem:** Non-stationarity will lead to decreased model performance + increased uncertainty of predictions
- **No solution only mitigation:** Characterize non-stationarity and address in modelling/scenarios

# Characterizing Non-stationarity

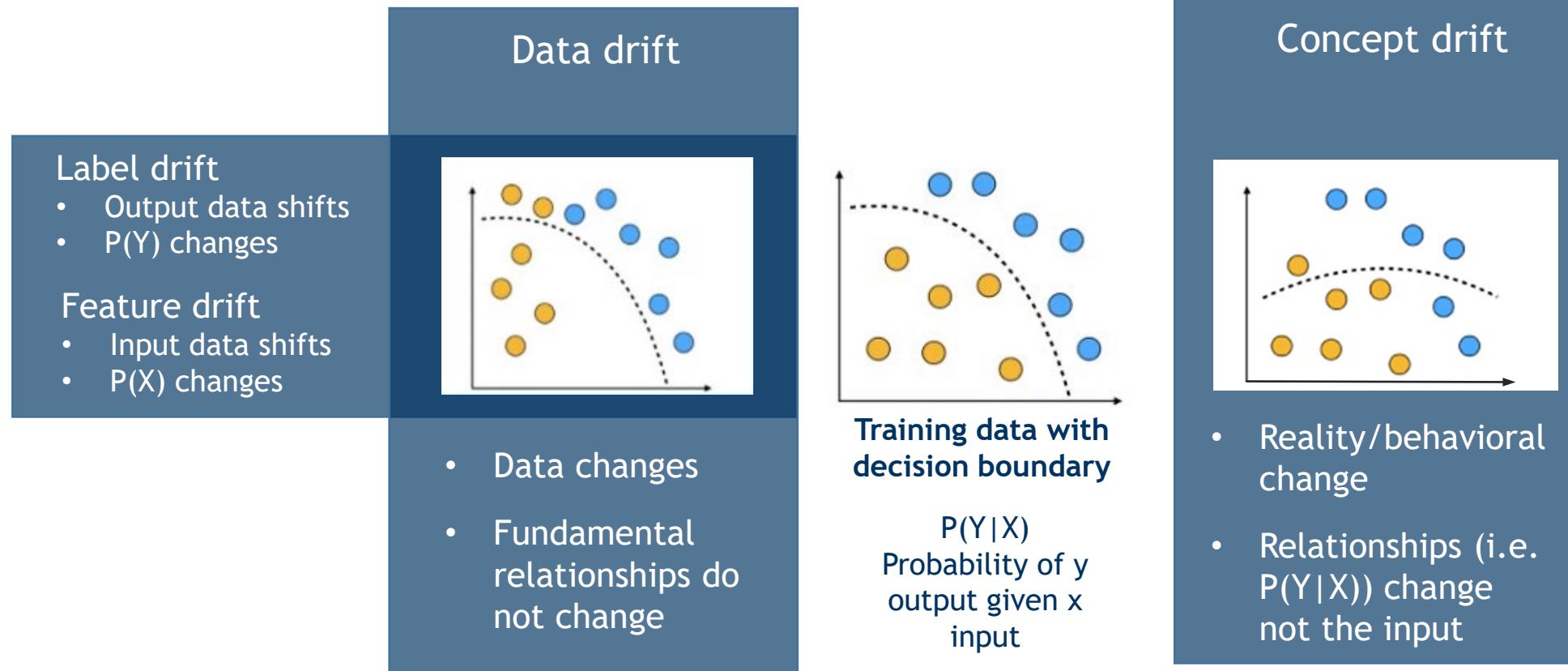
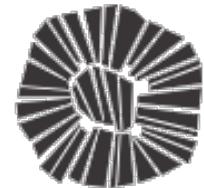


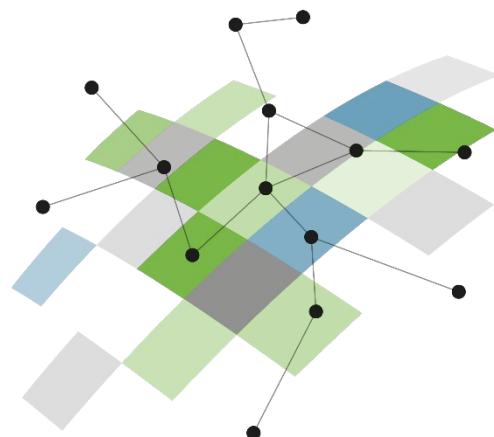
Figure adapted from Hodler 2022



# Case study



Parc  
**Gruyère**  
Pays-d'Enhaut

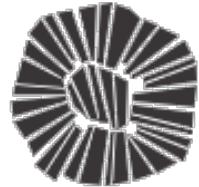


ValPar.CH





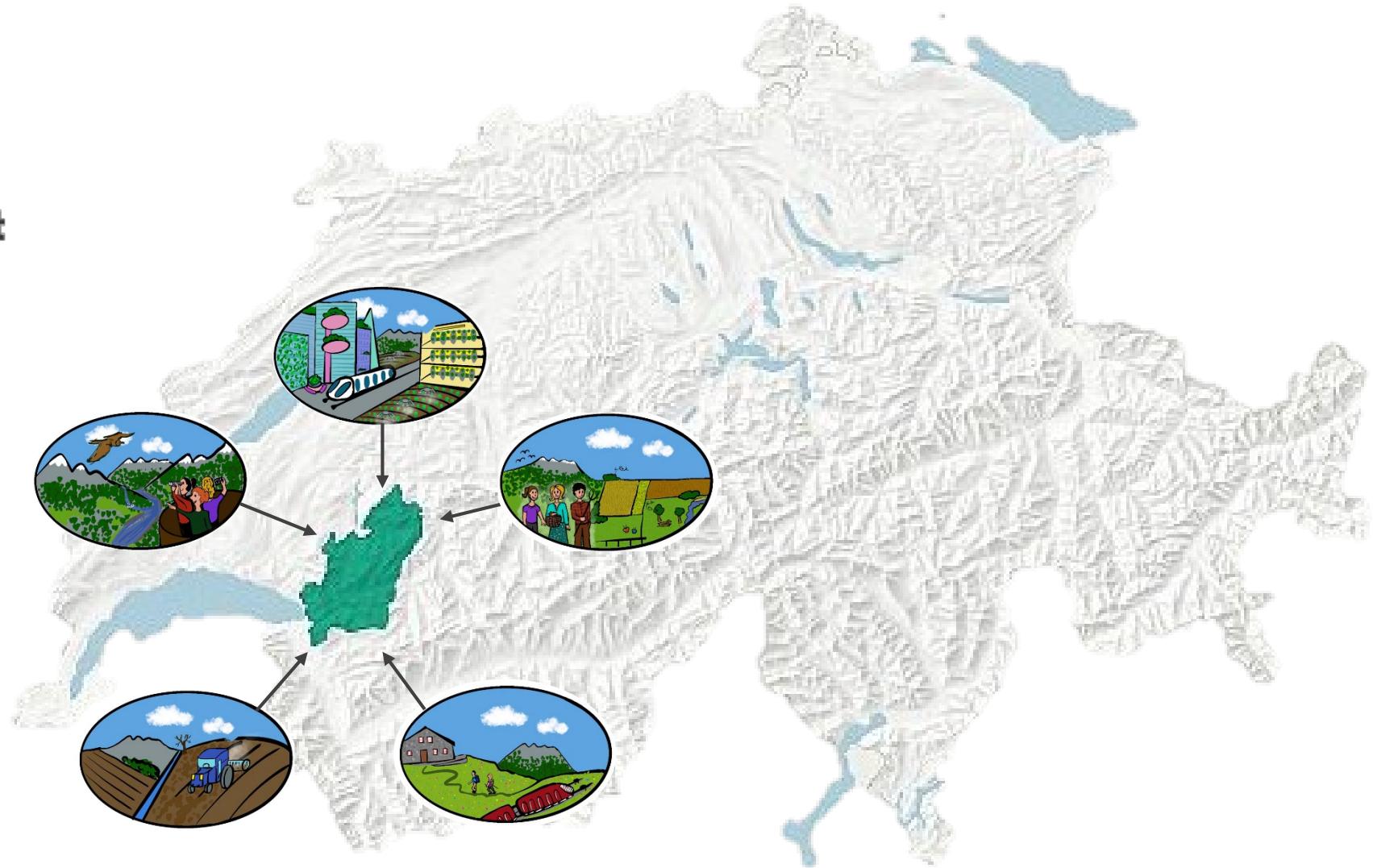
# Case study



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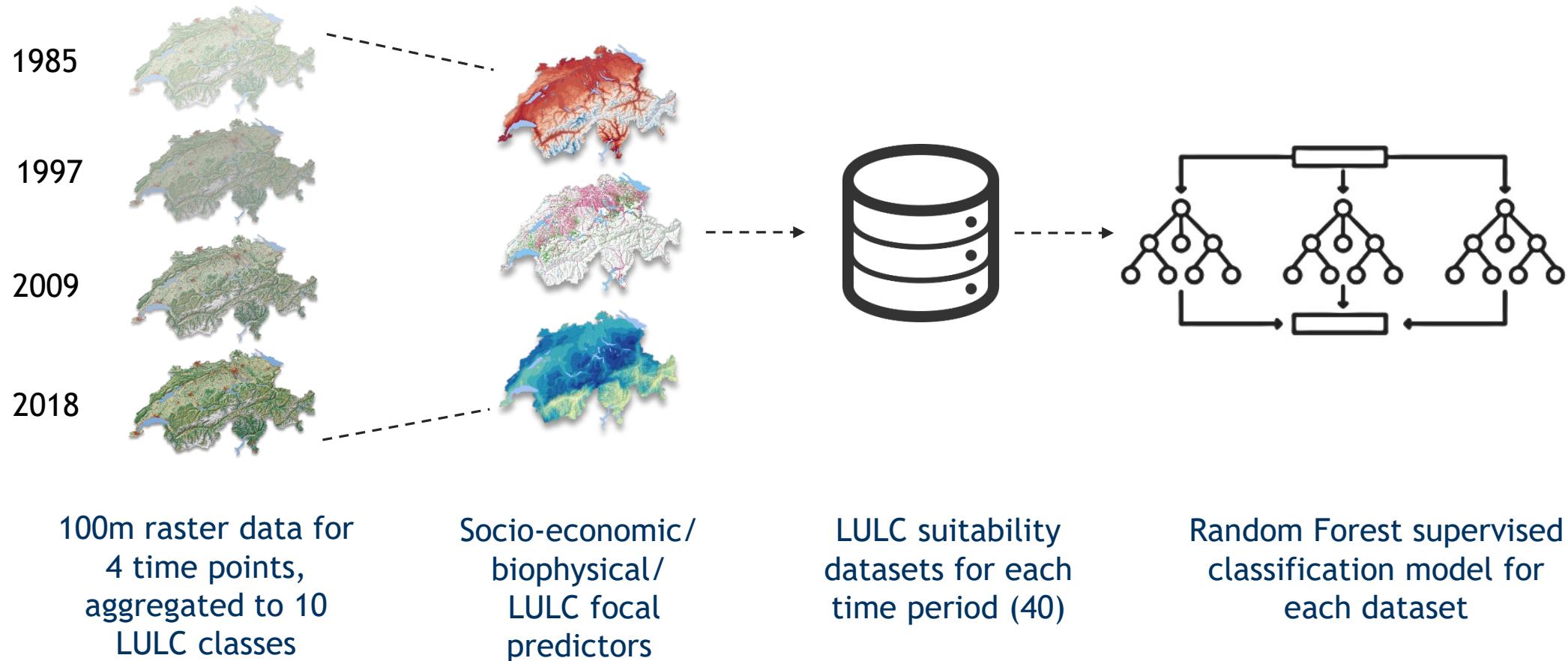
## Scenarios:

- Biodiversity-promoting Switzerland
- Switzerland with diverging rural and urban areas
  - Switzerland with conditions for a desired future of Ecological Infrastructure





# Land use land cover (LULC) modelling





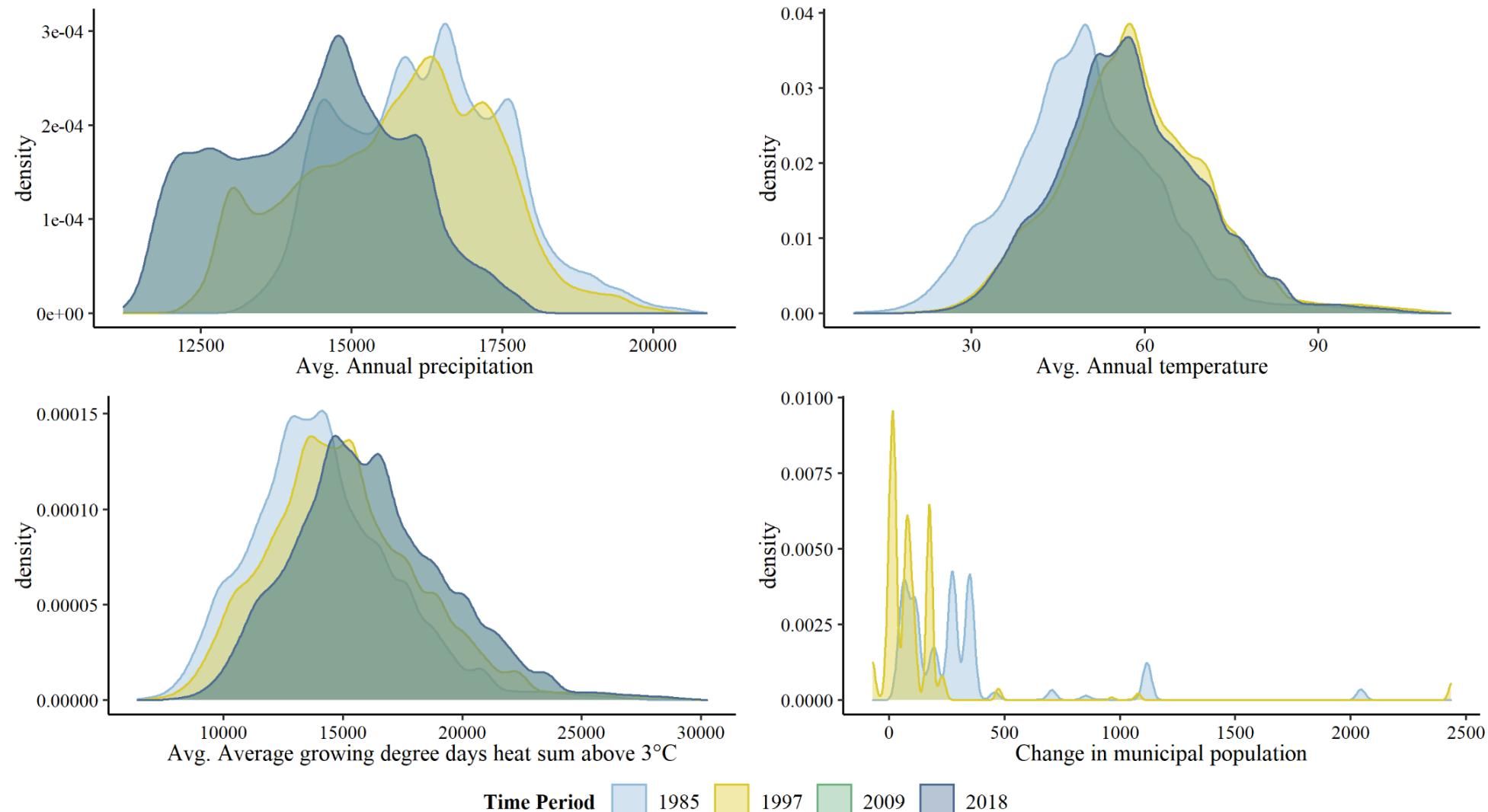
# Label drift

Coverage of LULC classes as % of total area of park Gruyère Pays-d'Enhaut

LULC class	1985	1997	2009	2018	Avg. % difference
Urban	1.16	1.38	1.5	1.63	0.157
Static	7.23	7.19	6.91	6.77	0.153
Open Forest	6.67	6.77	8.53	7.97	0.433
Closed Forest	31.48	33.01	31.91	32.87	0.463
Shrubland	8.32	7.91	7.76	7.78	0.180
Intensive Agriculture	0.26	0.27	0.12	0.11	0.050
Alpine Pasture	35.1	34.13	33.88	33.6	0.500
Grassland	9.7	9.28	9.35	9.23	0.157
Permanent crops	0.08	0.06	0.04	0.03	0.017



# Feature drift

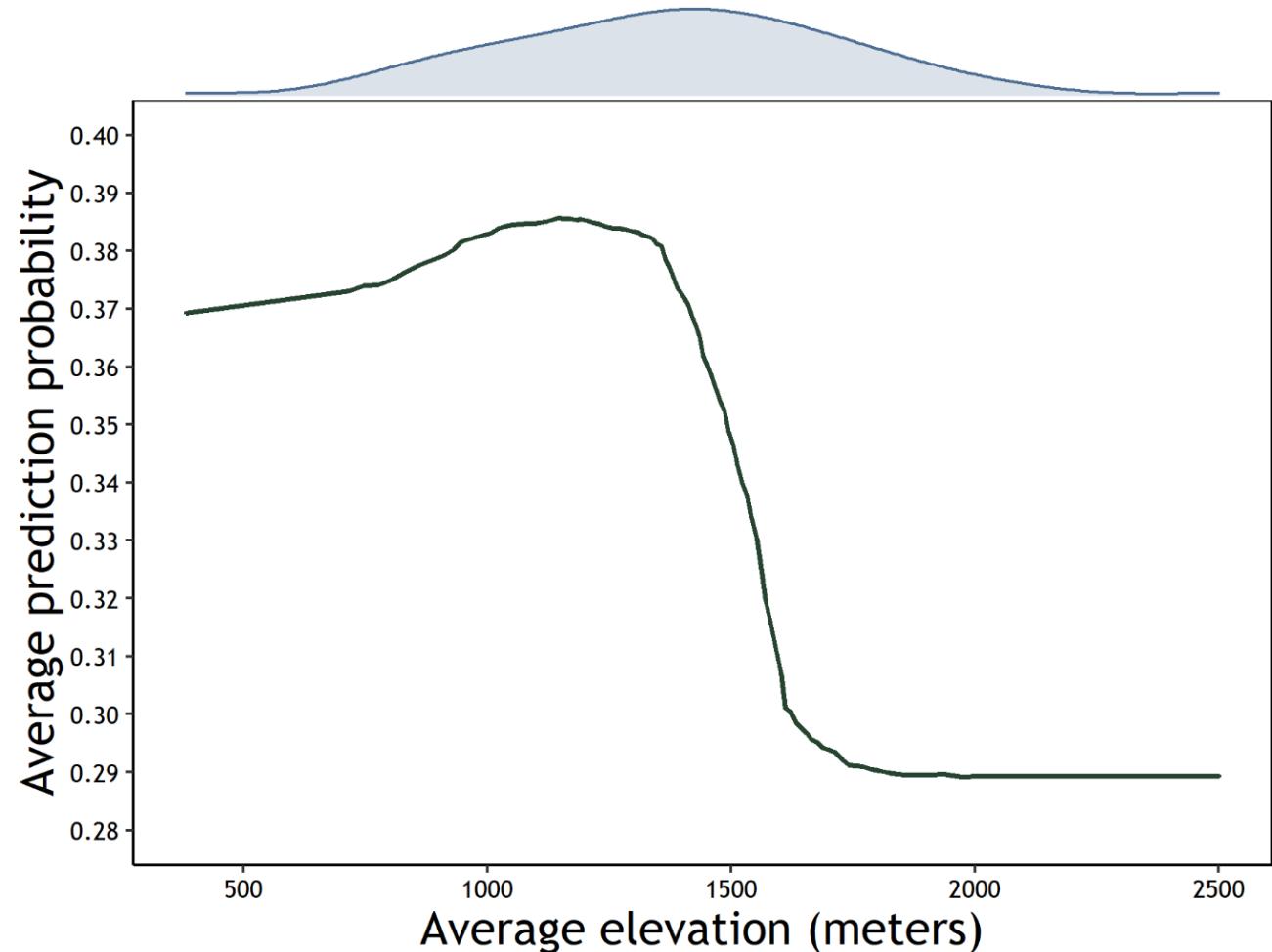




# Concept drift

How can we quantify?: Partial dependence plots (PDPs)

- Change in average prediction probability of dependent variable across the values of a single predictor
- Marginalized over all predictors i.e aggregation of all instances

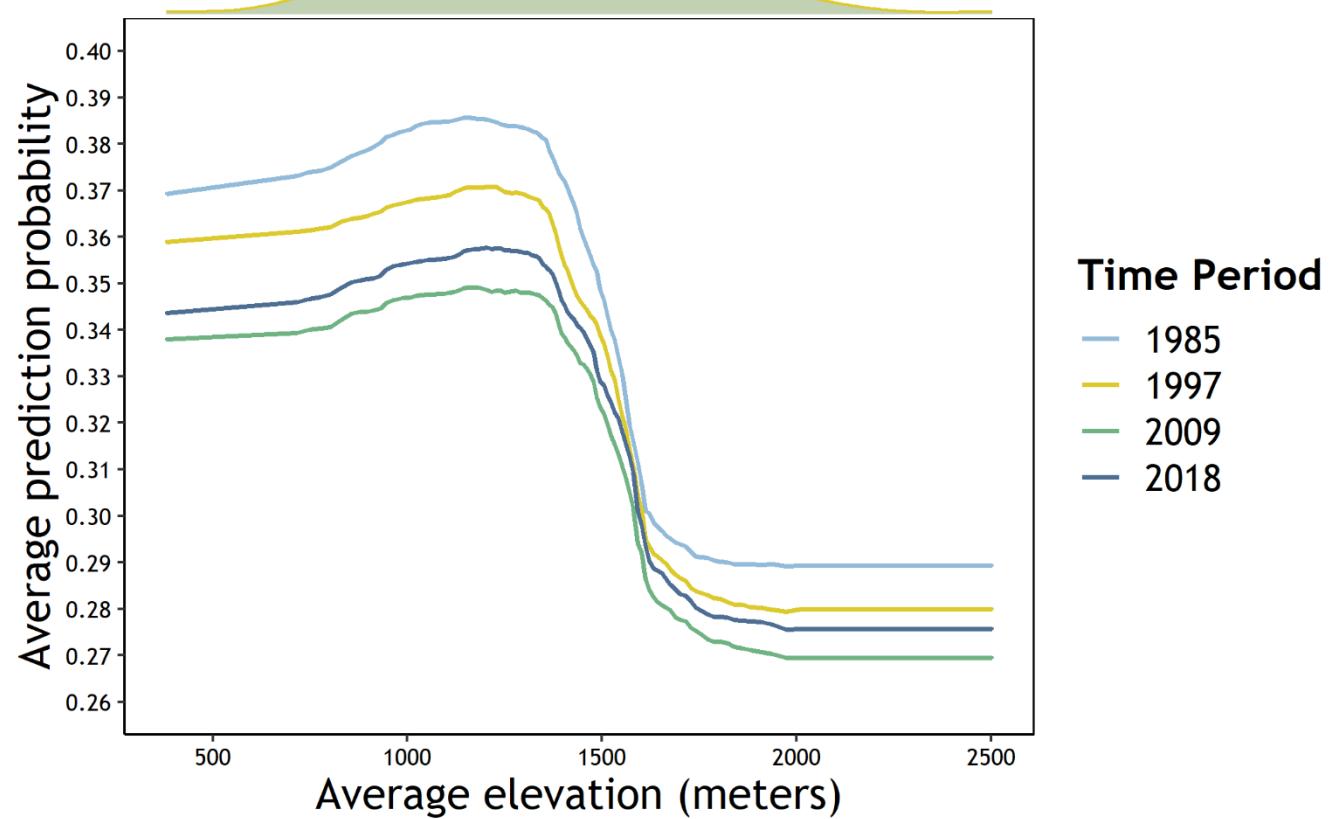




# Concept drift

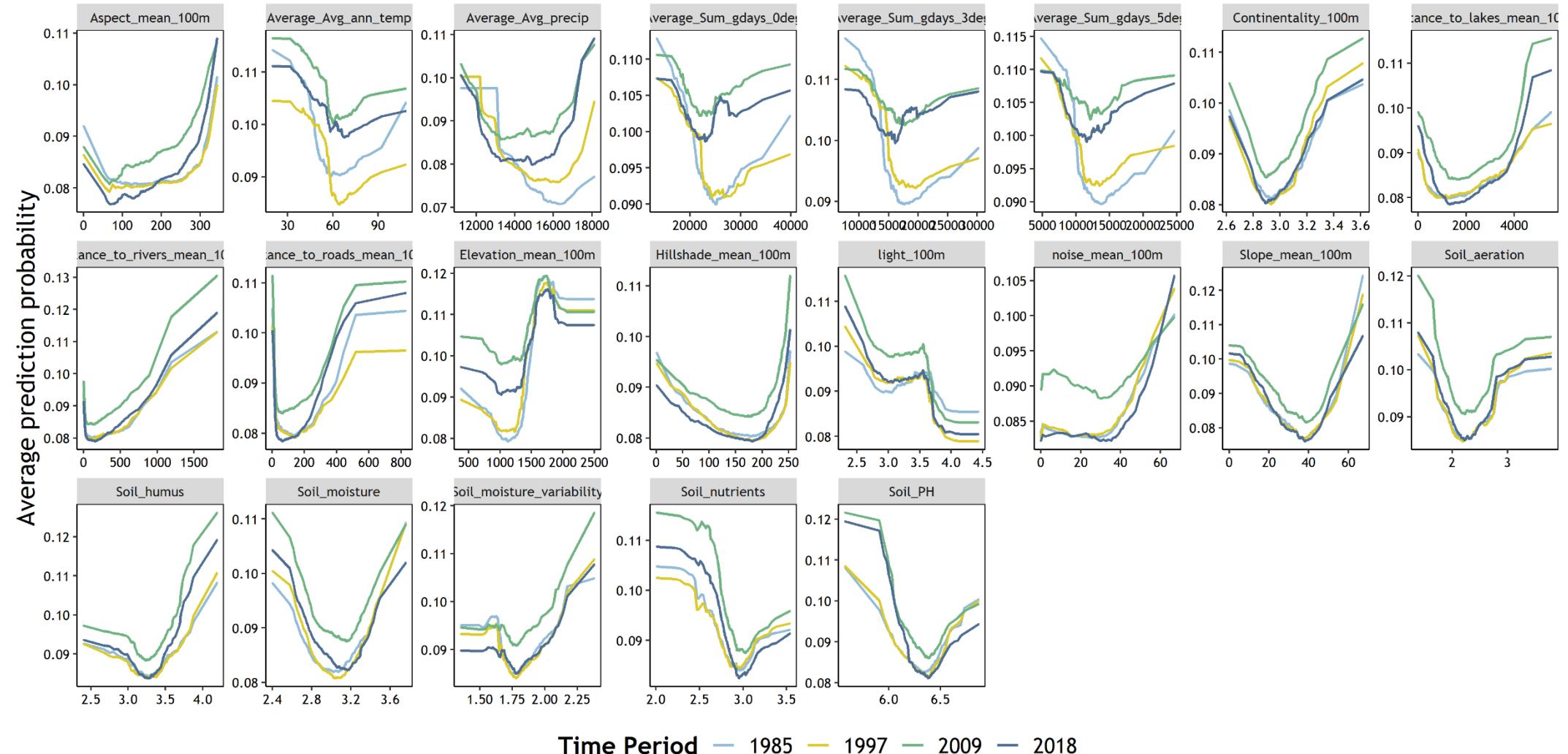
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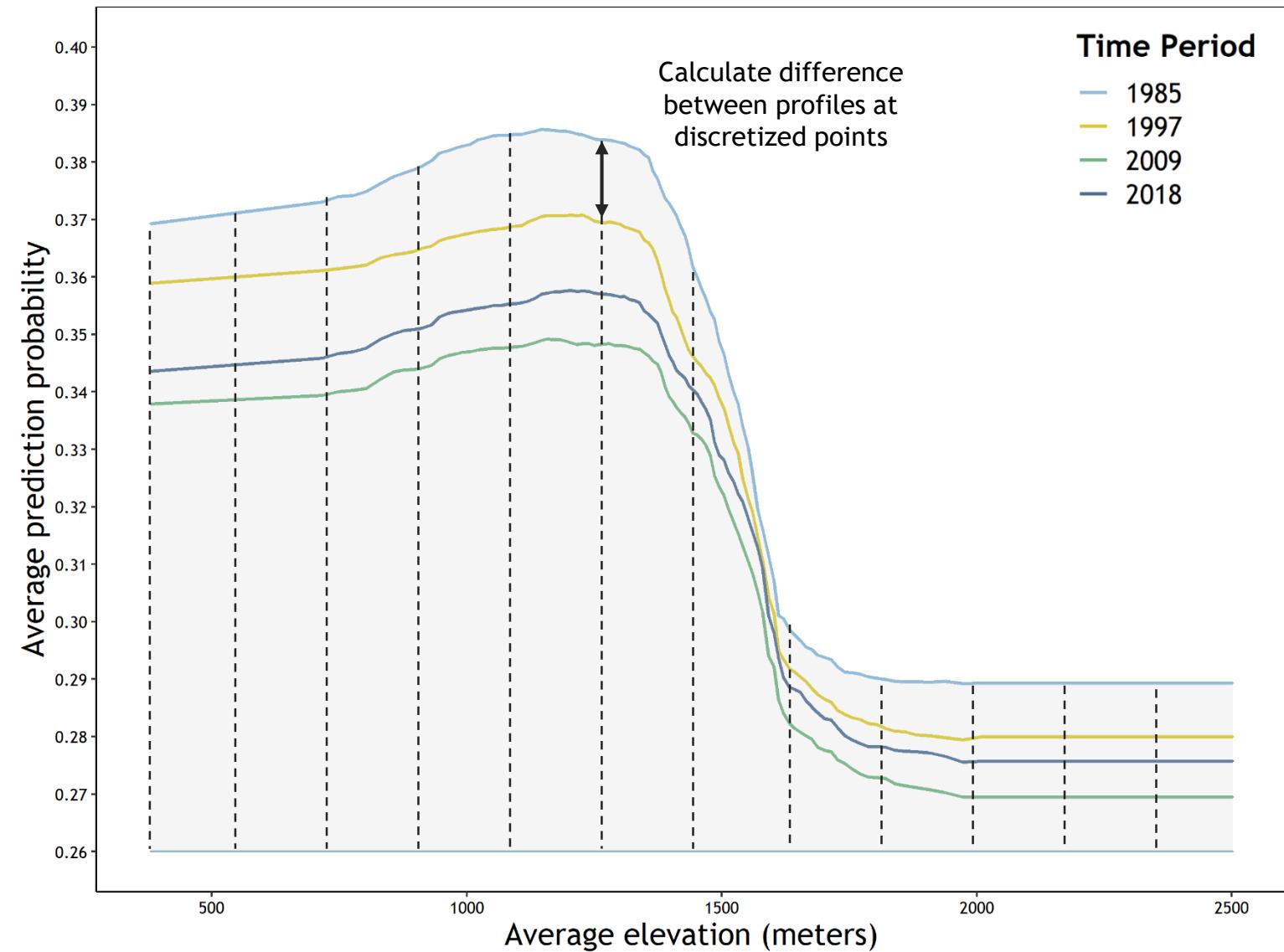
# Concept drift



# Concept drift

**Model drift** = Square root of the mean square difference(RMSD) between the PD profiles

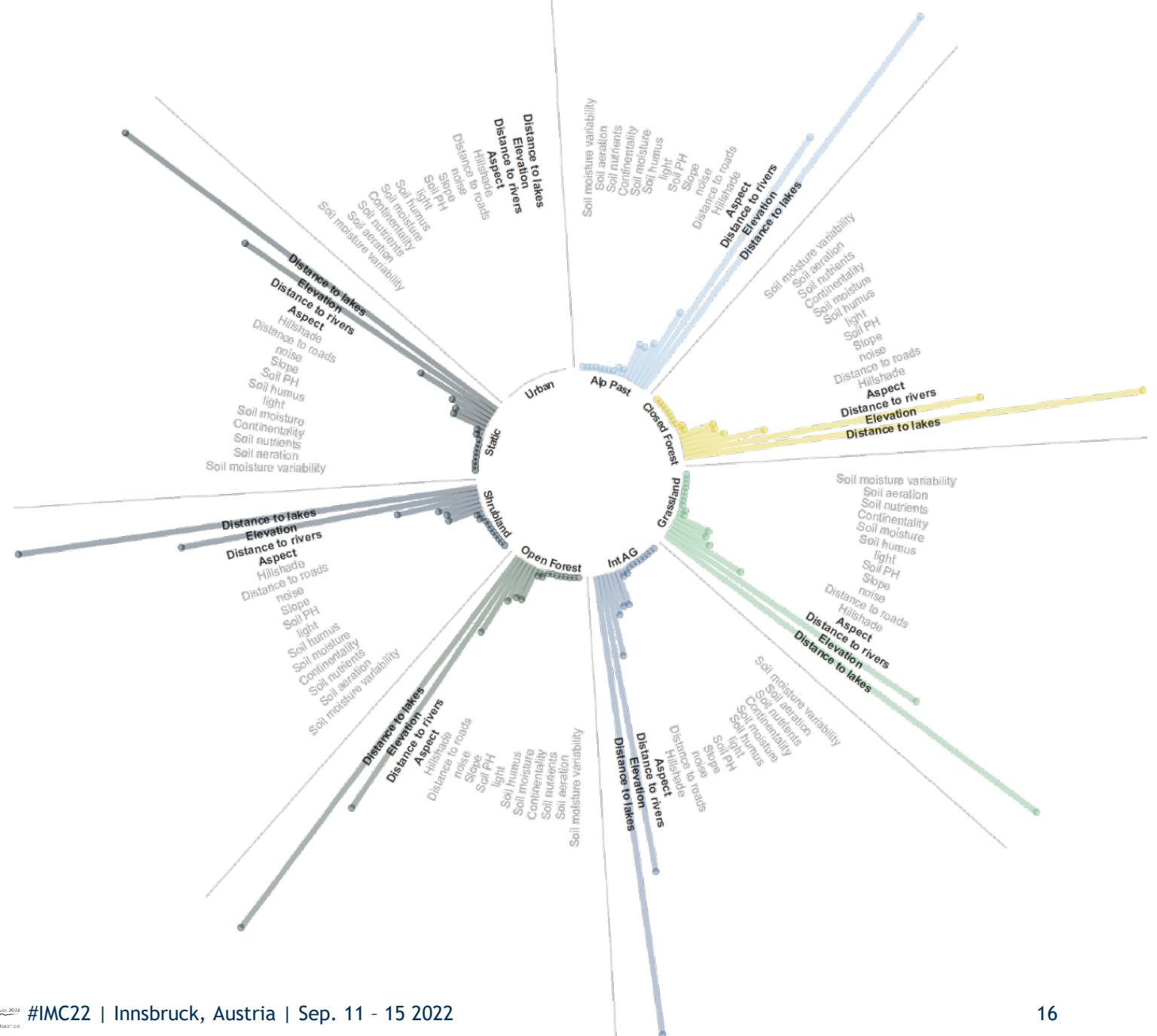
- Requires profiles to be discretized
  - Unitless
- Minimum value of RMSD = 0 (perfectly overlapping profiles)



Biecek and Pekala 2022

# Concept drift

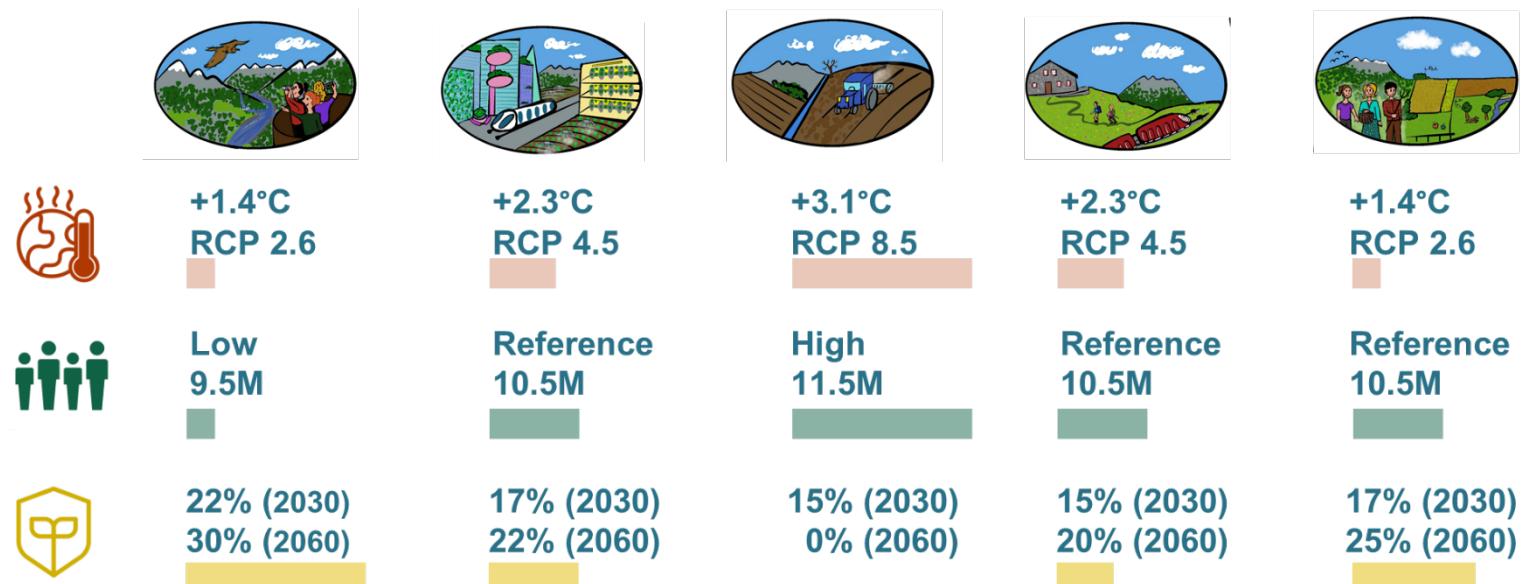
- Average drift across time periods as compared to final period (2009-2018)
  - Large range of drift values between predictors
  - Consistency in highest drift predictors across LULC classes





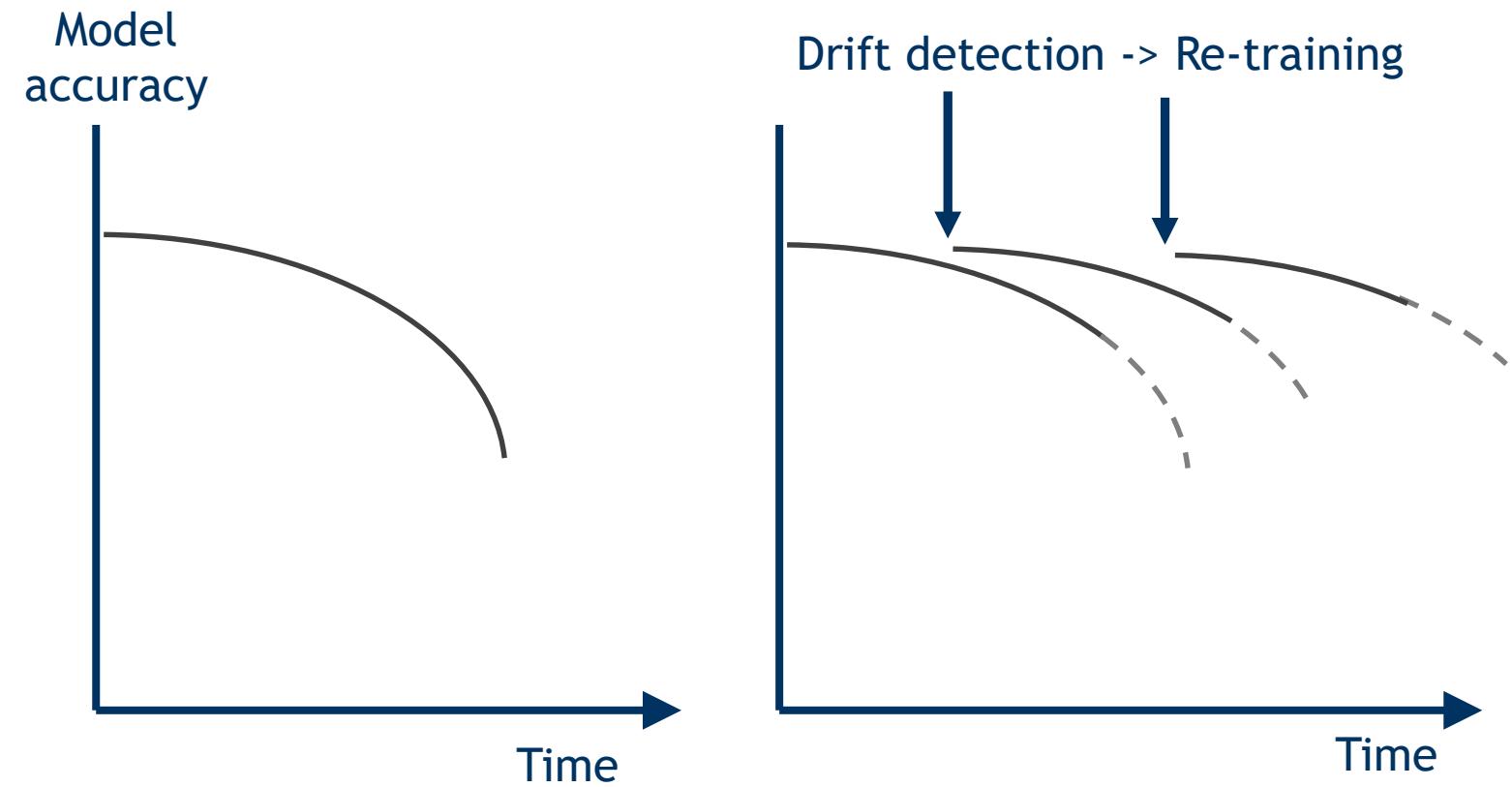
# Implications for scenarios

- Scenarios for deliberative transformation simulated top-down (i.e. planned changes to specific aspects in the system)
- Proscribing changes often based on historically characterized relationships
- Ignoring change in these relationships (exemplified by concept drift) increases uncertainty of results = flawed recommendations.

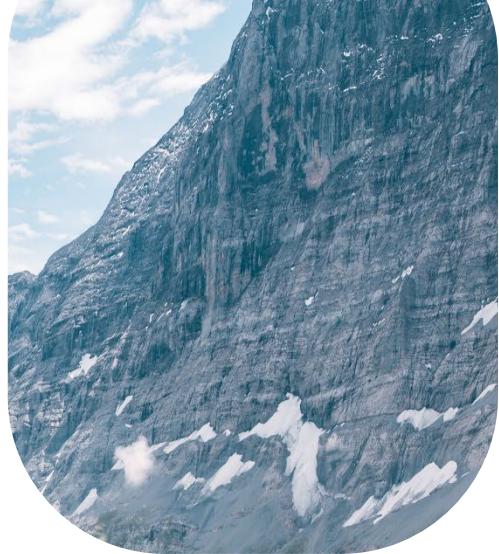
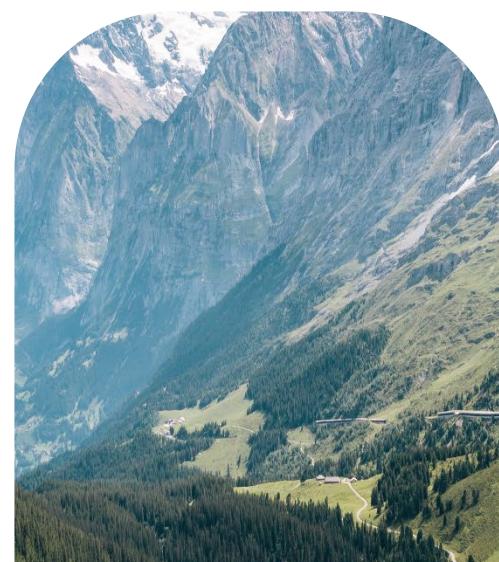


# Implications for modellers

- During calibration, detect drift and adapt predictive models to mitigate
- Temporal drift: Numerous adaptations to popular ML algorithms: **Streaming Random Forests** (Abdulsalam et al. 2011)
- Spatial drift: regionalized modelling
- Further research needed



*Figure adapted from Dral and Samuylova 2020*



# Thank you for listening

I will now take any  
questions.



**ETH**zürich

<https://plus.ethz.ch/>

ValPar.CH [https://valpar.ch/index\\_de.php](https://valpar.ch/index_de.php)



<https://www.researchgate.net/profile/Benjamin-Black-5>



@Blen\_Back

# References

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