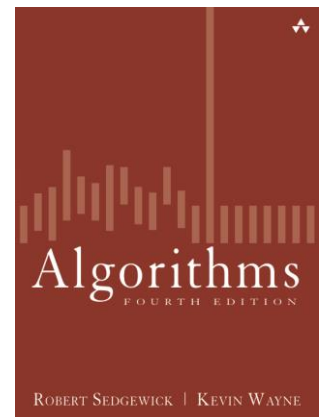


# ID1020: Priority Queues

Dr. Per Brand  
perbrand@sics.se

kap 2.4




Slides adapted from Algorithms 4<sup>th</sup> Edition, Sedgewick.

# Priority Queues

- Collections. Insert, delete and retrieve items.
- Stack. Retrieve the newest item (most recently added).
- Queue. Retrieve the oldest item
- Randomized queue. Retrieve a random item.
- Priority queue. Retrieve the largest (or smallest) item.

# Priority Queue API

Key must be Comparable  
(bounded type parameter)



```
public class MaxPQ<Key extends Comparable<Key>>
```

---

```
    MaxPQ()
```

*create an empty priority queue*

```
    MaxPQ(Key[] a)
```

*create a priority queue with given keys*

```
    void insert(Key v)
```

*insert a key into the priority queue*

```
    Key delMax()
```

*return and remove the largest key*

```
    boolean isEmpty()
```

*is the priority queue empty?*

```
    Key max()
```

*return the largest key*

```
    int size()
```

*number of entries in the priority queue*

# How to implement?

- Naive methods
  - Unordered array representation
    - Stack
    - Insert = push
    - Remove the maximum = search array and exchange with last entry
  - Ordered array representation
    - Use insertion sort to keep array in order
- Can we do better ?

# Unordered and ordered arrays

operation	argument	return value	size	contents (unordered)					contents (ordered)				
insert	P		1	P					P				
insert	Q		2	P	Q				P	Q			
insert	E		3	P	Q	E			E	P	Q		
remove max		Q	2	P	E				E	P			
insert	X		3	P	E	X			E	P	X		
insert	A		4	P	E	X	A		A	E	P	X	
insert	M		5	P	E	X	A	M	A	E	M	P	X
remove max		X	4	P	E	M	A		A	E	M	P	
insert	P		5	P	E	M	A	P	A	E	M	P	P
insert	L		6	P	E	M	A	P	L	E	M	P	P
insert	E		7	P	E	M	A	P	L	E	M	P	P
remove max		P	6	E	M	A	P	L	E	E	M	P	

A sequence of operations on a priority queue

# Unordered array implementation

```
public class UnorderedMaxPQ<Key extends Comparable<Key>>
{
    private Key[] pq;    // pq[i] = ith element on pq
    private int N;       // number of elements on pq

    public UnorderedMaxPQ(int capacity)
    { pq = (Key[]) new Comparable[capacity]; }

    public boolean isEmpty()
    { return N == 0; }

    public void insert(Key x)
    { pq[N++] = x; }

    public Key delMax()
    {
        int max = 0;
        for (int i = 1; i < N; i++)
            if (less(max, i)) max = i;
        exch(max, N-1);
        return pq[--N];
    }
}
```

← Less, exch  
from sorting

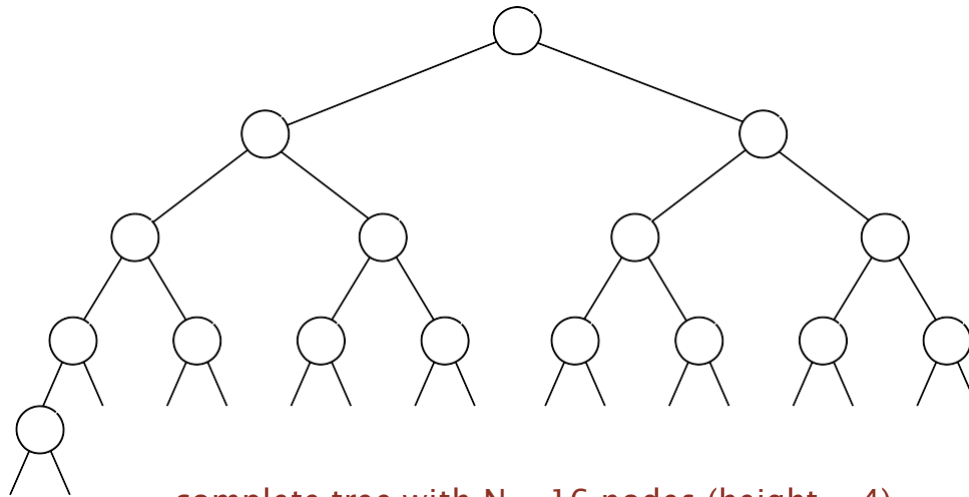
# Properties

order of growth of running time for priority queue with  $N$  items

implementation	insert	del max	max
unordered array	1	$N$	$N$
ordered array	$N$	1	1
goal	$\log N$	$\log N$	$\log N$

# Binary tree

- Each node has one parent and up to two children
- Complete tree – balanced (except for bottom layer)



complete tree with  $N = 16$  nodes (height = 4)

- Depth of tree is  $O(\lg N)$
- By convention computer scientist draw their trees upside down

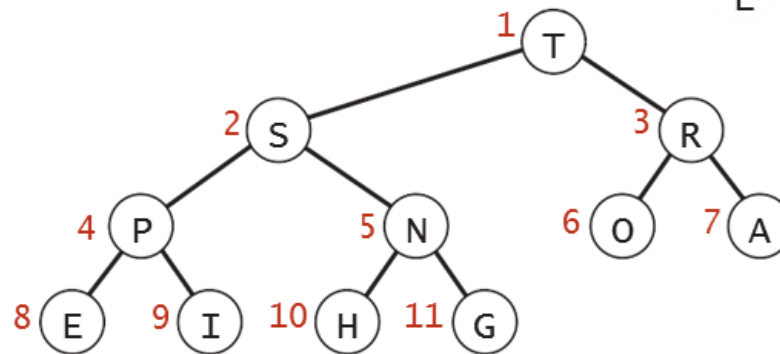
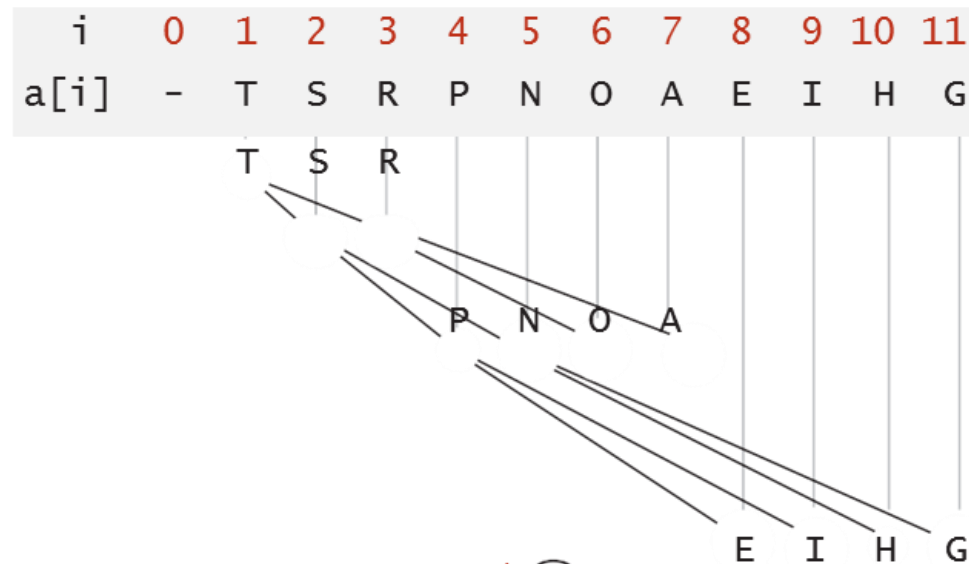


# Heap-ordered

- Definition: Binary tree is heap-ordered if key in each node is larger (or equal) to the keys in its two children
  - Largest key in root
- How to implement?
  - Method 1: Linked representation.
    - Data structure is a node
    - Three links (parent, left child, right child)
  - Method 2: Use an array with implicit links
    - Children of element  $i$  are in element  $2i$  and  $2i+1$
  - Book prefers method 2. Why?

# Binary heap

- Array representation of a heap-ordered complete binary tree
- Indices start at 1
- Order top down and left to right

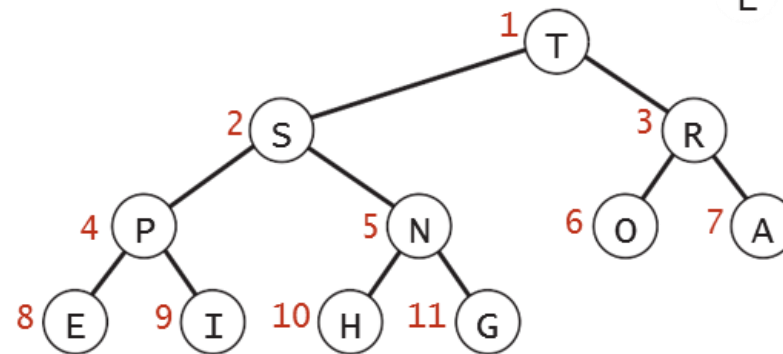


Heap  
representations

# Binary heap (2)

- Largest key at index 1  
the root
- Parent is  $[i/2]$
- Children at  $2i$  and  $2i+1$

i	0	1	2	3	4	5	6	7	8	9	10	11
a[i]	-	T	S	R	P	N	O	A	E	I	H	G



Heap  
representations

# How to keep it ordered

- Disorder introduced by
  - Removing an item (typically the root)
    - Replace the element by the last item
    - Array kept compact
  - Adding an item (new last item)
  - Changing the key of an item
- Two violations
  - The key in a node becomes larger than parent
  - The key in a node becomes smaller than one (or both) of its children
- Question: Which operations (may) produce which violations?

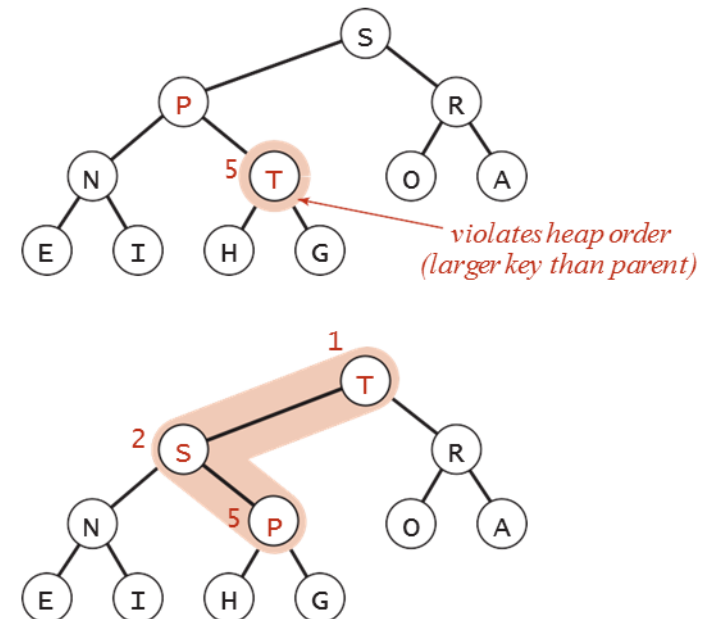
# Bottom-up reheapify

- When a child's key becomes larger than its parent's
- Algorithm
  - Exchange child with parent
  - Then move up the tree repeating until in order
  - Possibly all the way to the root

Also called *promotion* or *swim*

```
while (k > 1 && less(k/2, k))  
{  
    exch(k, k/2);  
    k = k/2;  
}  
}
```

parent of node at k is at k/2

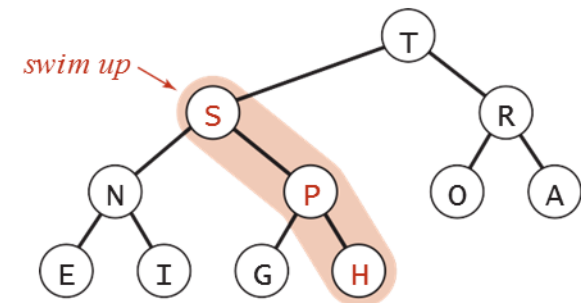
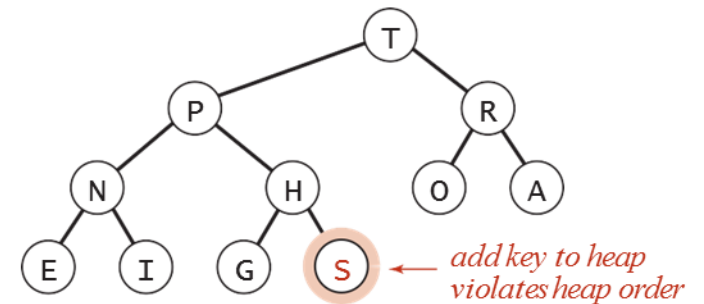
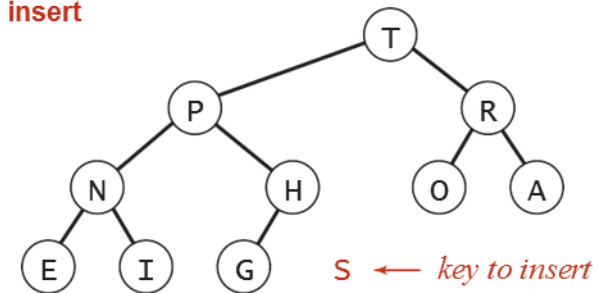


# Insertion

- Add node to end and promote
- Cost: At most  $1 + \lg N$  operations

```
public void insert(Key x)
{
    pq[++N] = x;
    swim(N);
}
```

insert



# Top-down reheapify

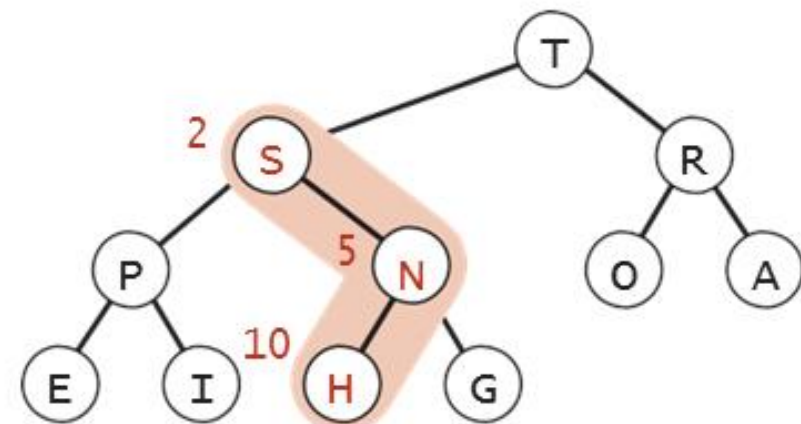
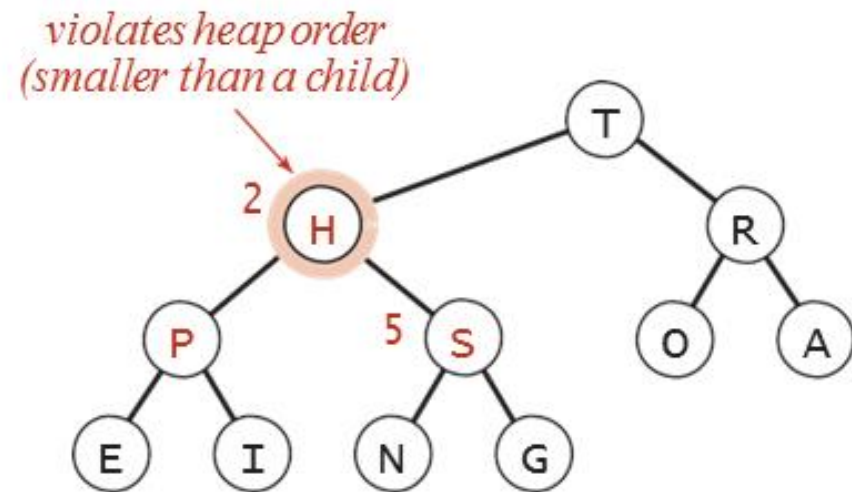
- When a node becomes smaller than one or both of its children
- Algorithm:
  - Exchange with largest child
  - Repeat moving down until order is found
- Why with largest child?

```
private void sink(int k)
{
    while (2*k <= N)
    {
        int j = 2*k;
        if (j < N && less(j, j+1)) j++;
        if (!less(k, j)) break;
        exch(k, j);
        k = j;
    }
}
```

children of node at k  
are  $2k$  and  $2k+1$

# Top-down reheapify (2)

- Also called demotion and sink



**Top-down reheapify  
(sink)**



# Removing the maximum

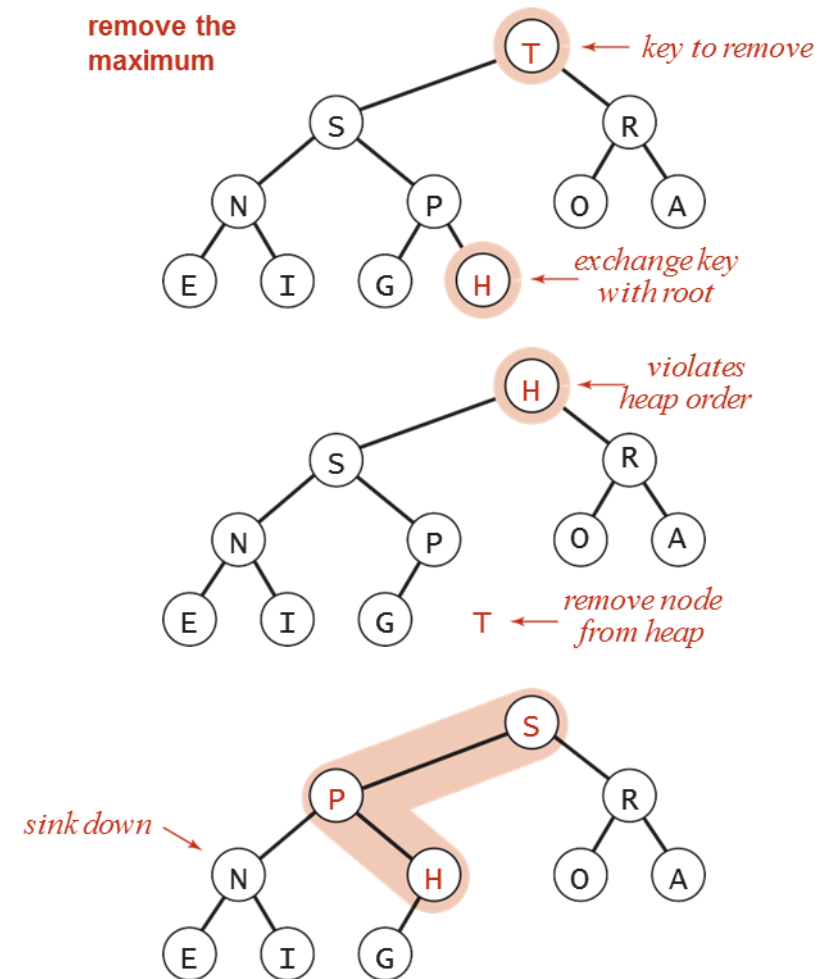
- Exchange root node with last node
  - top-down reheapify

- Cost:
  - At most  $2 \lg N$  compares
  - **Why 2?**

```
public Key delMax()
{
    Key max = pq[1];
    exch(1, N--);
    sink(1);
    pq[N+1] = null;
    return max;
}
```

**Why ?**

20



# Binary heap implementation

```
public class MaxPQ<Key extends Comparable<Key>>
{
    private Key[] pq;
    private int N;
```

```
    public MaxPQ(int capacity)
    {    pq = (Key[]) new Comparable[capacity+1];    }
```

← fixed capacity  
(for simplicity)

```
    public boolean isEmpty()
    {    return N == 0;    }
    public void insert(Key key)
    public Key delMax()
    {    /* see previous code */    }
```

← PQ ops

```
    private void swim(int k)
    private void sink(int k)
    {    /* see previous code */    }
```

← heap helper functions

```
    private boolean less(int i, int j)
    {    return pq[i].compareTo(pq[j]) < 0;    }
    private void exch(int i, int j)
    {    Key t = pq[i]; pq[i] = pq[j]; pq[j] = t;    }
```

← array helper functions

```
}
```

# Odds and Ends

- Ternary trees (multiway heaps)
  - Generalization: Each node has  $D$  children
  - Children of node  $i$  can be found at
    - ...  $D_i - 2$ ,  $D_i - 1$ ,  $D_i$ ,  $D_i + 1$
- Array resizing
  - Just like we did with stacks
  - Invisible to client
  - Upon need doubles the heap size
  - Cost amortized
- Removing arbitrary item
  - Left as an exercise

# Immutability

- Our assumption: items are immutable
  - Best practice keys are immutable
- If clients can update objects in heap
  - Could violate ordering constraints
- Especially important across interfaces/APIs

*“ Classes should be immutable unless there's a very good reason to make them mutable... If a class cannot be made immutable, you should still limit its mutability as much as possible. ”*

*— Joshua Bloch (Java architect)*

# Immutable data types

- Advantages
  - Simplifies debugging
  - Safer in the presence of hostile code
    - Hostility may be inadvertent
  - Simplifies concurrent programming
  - Safe to use as keys in data structures
    - Priority queue, symbol tables, etc.
- Disadvantage
  - Must create a new data object for each data type value
  -

# Example in Java

```
public final class Vector {  
    private final int N;  
    private final double[] data;
```

← can't override instance methods

← all instance variables private and final

```
    public Vector(double[] data) {  
        this.N = data.length;
```

```
        this.data = new double[N];  
        for (int i = 0; i < N; i++)  
            this.data[i] = data[i];
```

← defensive copy of mutable  
instance variables

```
    }
```

```
    ...
```

← instance methods don't change  
instance variables

```
}
```

# Cost summary

• Implementation	Insert	Remove Max	Retrieve Max
• Unordered array	1	N	N
• Ordered array	N	1	1
• Binary heap	$\log N$	$2 \log N$	1
• D-ary heap	$\log_D N$	$D \log_D N$	1
• Impossible	1	1	1

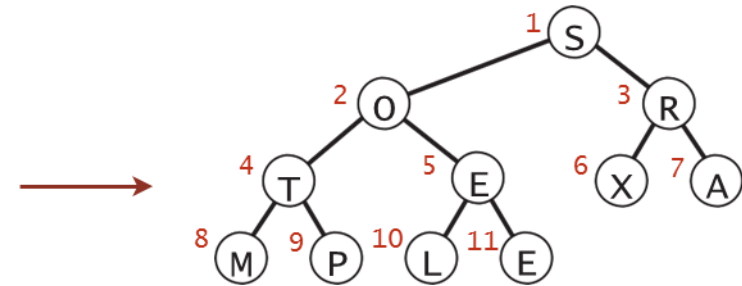
# Revisit sorting

- We can use a priority queue to sort
  - Insert items one by one into a minimum-oriented priority queue
  - Then repeatedly remove the minimum
- Use an unordered array priority queue
  - Turns into selection sort
- Use an ordered array
  - Turns into insertion sort
- What happens if we use a heap?

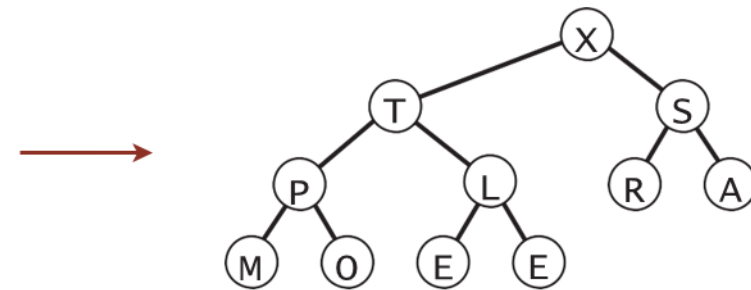


# In place sorting

30



build a max-heap  
(in place)



sorted result  
(in place)



# Heapsort

- Given an unordered array how can we convert it to an binary heap
- For simplicity we use maximum (reverse order sorting)
- Method 1:
  - Move down the array and use successive swims (promotions)
  - Items to left of scanning pointer are in order
  - Next item may be moved up the tree
  - $O(N \log N)$

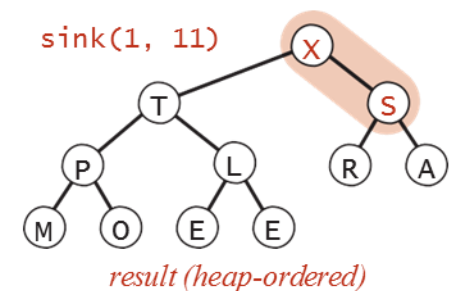
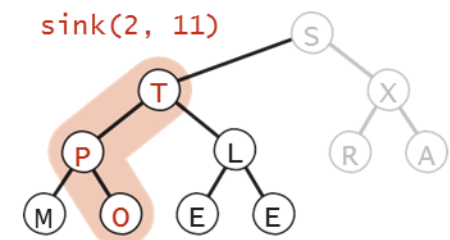
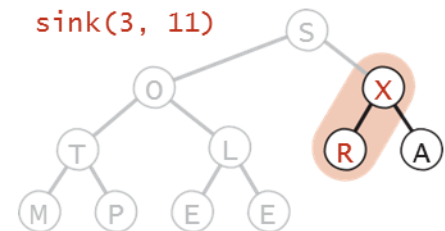
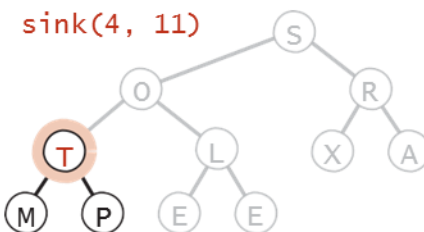
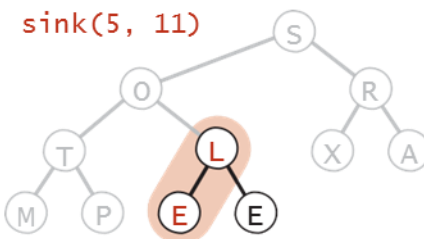
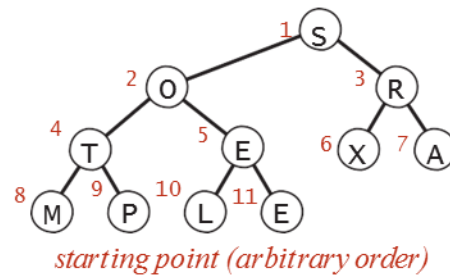
# Heapsort (2)

- Method 2:
  - Build heap right to left
  - Consider parent of two ordered subheaps
  - Use sink to create an ordered larger subheap
  - Move one step to left (towards beginning)
  - Start halfway through

# First pass

- Build heap bottom up

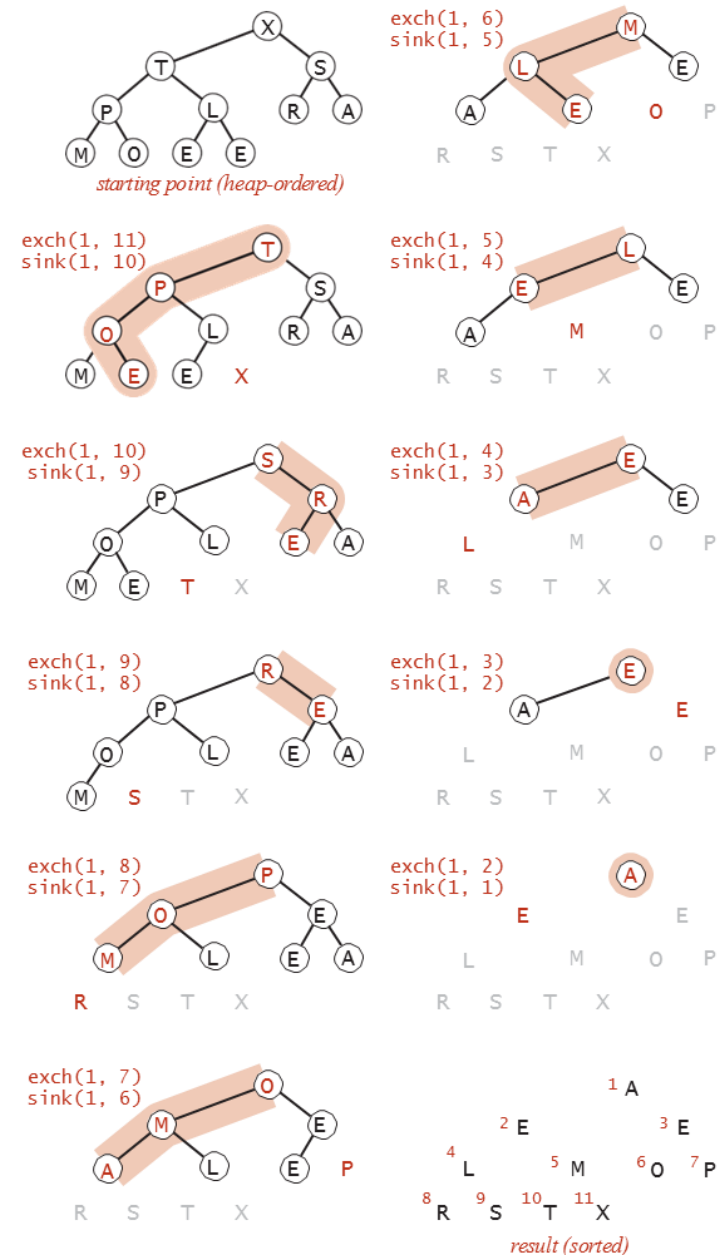
```
for (int k = N/2; k >= 1; k--)  
    sink(a, k, N);
```



# Second pass

- Sortdown
  - Move down
  - Exchange current item (largest) with last item
  - Use sink on the item

```
while (N > 1)
{
    exch(a, 1, N--);
    sink(a, 1, N);
}
```



# Java implementation

```
public class Heap
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;
        for (int k = N/2; k >= 1; k--)
            sink(a, k, N);
        while (N > 1)
        {
            exch(a, 1, N);
            sink(a, 1, --N);
        }
    }

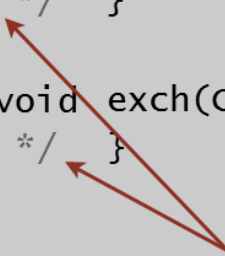
    private static void sink(Comparable[] a, int k, int N)
    { /* as before */ }

    private static boolean less(Comparable[] a, int i, int j)
    { /* as before */ }

    private static void exch(Comparable[] a, int i, int j)
    { /* as before */ }

    }

    but convert from
    1-based indexing to
    0-base indexing
```



# A trace

		a[i]											
N	k	0	1	2	3	4	5	6	7	8	9	10	11
<i>initial values</i>		S	O	R	T	E	X	A	M	P	L	E	
11	5	S	O	R	T	L	X	A	M	P	E	E	
11	4	S	O	R	T	L	X	A	M	P	E	E	
11	3	S	O	X	T	L	R	A	M	P	E	E	
11	2	S	T	X	P	L	R	A	M	O	E	E	
11	1	X	T	S	P	L	R	A	M	O	E	E	
<i>heap-ordered</i>		X	T	S	P	L	R	A	M	O	E	E	
10	1	T	P	S	O	L	R	A	M	E	E	X	
9	1	S	P	R	O	L	E	A	M	E	T	X	
8	1	R	P	E	O	L	E	A	M	S	T	X	
7	1	P	O	E	M	L	E	A	R	S	T	X	
6	1	O	M	E	A	L	E	P	R	S	T	X	
5	1	M	L	E	A	E	O	P	R	S	T	X	
4	1	L	E	E	A	M	O	P	R	S	T	X	
3	1	E	A	E	L	M	O	P	R	S	T	X	
2	1	E	A	E	L	M	O	P	R	S	T	X	
1	1	A	E	E	L	M	O	P	R	S	T	X	
<i>sorted result</i>		A	E	E	L	M	O	P	R	S	T	X	

Heapsort trace (array contents just after each sink)

# Properties of heapsort

- Heap building  $2N$  compares and exchanges
- Sortdown uses  $2N \log N$  compares and exchanges
- Heapsort  $O(N \log N)$  and in-place
- Used mainly in embedded systems where space is limited
- Disadvantages
  - Poor cache performance
  - Inner loop longer than quicksort



# Applications of priority queues

- Just some examples
- The more obvious
  - Storing and sorting large amounts of data
  - Commercial companies, sorting by name, account number, order time, etc.
- Slightly less obvious
  - Continuously streaming massive input
  - Too large to store as is
  - Priority queue used to store, while concurrently stored information is analyzed, filtered and compactified.

# Discrete Event Simulation

- Even less obvious application
- Some problems not amenable to analysis
- Modelling complex processes to understand bottlenecks
- Observing the macro from the micro
- Simulation
  - Time is discrete
  - Priority queue holds upcoming events ordered by increasing time
  - Next event at time  $t$  taken from queue and then processed.  
Typically causes one or more events at times  $t+X$ 
    - These events added to priority queue.