## CECS 274: Data Structures Binary Trees

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## Example

- Mathematical Expressions
- We can check if the following expression is valid using a Stack (Array-based, Linked-List based)

$$(a+b)*(c*d) + (a+(b*(c/d))$$

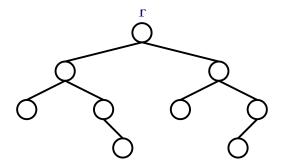
 We can replace the terms with the actual values efficiently using a USet (ChainedHashTable)

$$a = 5413.13, b = 243.12, c = 4212.12, d = 421.3$$

► The next natural question is how it can be evaluated.



## Binary Tree



## **Binary Trees**

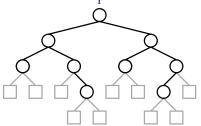
- ► A binary tree is a connected, undirected, finite graph with no cycles, and no vertex of degree greater than three.
- For most computer science applications, binary trees are rooted:
  - A special node, r, of degree at most two is called the root of the tree.
  - For every node,  $u \neq r$ , the second node on the path from u to r is called the *parent* of u.
  - ► Each of the other nodes adjacent to *u* is called a *child* of *u*.
  - Most of the binary trees we are interested in are ordered, so we distinguish between the left child and right child of u.

## Terminology

- ► The depth of a node, u, is the length of the path from u to the root of the tree.
- ▶ If a node, w, is on the path from u to r, then w is called an ancestor of u and u a descendant of w.
- ► The subtree of a node, u, is the binary tree that is rooted at u and contains all of u's descendants.
- ► The *height* of a node, *u*, is the length of the longest path from *u* to one of its descendants.
- ► The *height* of a tree is the height of its root.
- ▶ A node, u, is a leaf if it has no children.

#### External nodes

- We sometimes think of the tree as being augmented with external nodes.
- Any node that does not have a left child has an external node as its left child, and, correspondingly, any node that does not have a right child has an external node as its right child
- It is easy to verify, by induction, that a binary tree with  $n \ge 1$  real nodes has n+1 external nodes.



## **Auxiliary Structure Node**

- Node
  - State variables:
    - ▶ *left*: Points to the left node
    - right: Points to the right node
    - parent: Points to the parent node
    - x: The data to store
    - ▶ v: The value to store. It is used in the BinarySearchTree
  - Invariant: If left is not present, left = nilIf right is not present, right = nilIf parent is not present, parent = nil

## Auxiliary Structure Node (auxiliar methods)

```
set\_val(key, value)
  x = key
  v = value
insert\_left()
  left = BinaryTree.Node(")
  left.parent = this
   return left
insert\_right()
  right = BinaryTree.Node('')
  right.parent = this
   return right
```

## BinaryTree: The Basics

- BinaryTree
  - State variables:
    - r: the root of the binary tree
  - ▶ Invariant: r = nil if the BinaryTree is empty

```
\begin{array}{c} \text{initialize()} \\ r \leftarrow nil \end{array}
```

## BinaryTree: depth(u)

▶ depth(u): Returns the depth of the node u in the BinaryTree

```
depth(u)
```

Check preconditions

Count the steps on the path from  $\boldsymbol{u}$  to the root

## BinaryTree: depth(u)

```
\begin{aligned} \operatorname{depth}(u) & & \text{if } u = nil \text{ return } -1 \\ d \leftarrow 0 & & \text{while } (u \neq r) \text{ do} \\ & & u \leftarrow u.parent \\ d \leftarrow d + 1 & & \text{return } d \end{aligned}
```

How many operations?

## BinaryTree: size(u) (Recursive)

▶ size(): Return the number of elements in the BinaryTree

```
\begin{array}{c} \operatorname{size}(u) \\ \text{If } u \text{ is nil, then return 0} \\ \text{Else return 1 plus the size of left and right subtree} \end{array}
```

 Recursive methods solve a problem where the solution depends on solutions of smaller instances of the same problem

## BinaryTree: size(u) (Recursive)

```
\begin{aligned} &\operatorname{size}(u) \\ & \text{if } u = nil \text{ then return } 0 \\ & \text{return } 1 + \operatorname{size}(u.left) + \operatorname{size}(u.right) \end{aligned}
```

How many operations?

## BinaryTree: $in\_order(u)$

- ➤ To visit the binary search in order, first we visit left, root and then right
- $ightharpoonup in\_order(u)$ : left, root, right

```
\begin{split} &in\_order(u)\\ &\textbf{if } u.left = nil \textbf{ then } in\_order(u.left)\\ & \texttt{\# Visit } u\\ &\textbf{if } u.right = nil \textbf{ then } in\_order(u.right) \end{split}
```

## BinaryTree: $pre\_order(u)$

- How should we traverse a binary tree to create a copy?
- Copy first root, then left and then right
- $ightharpoonup pre\_order(u)$ : root, left, right

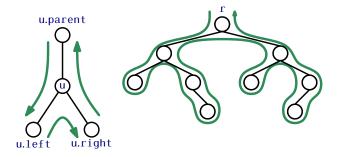
```
\begin{split} pre\_order(u) \\ & \text{ \# Visit } u \\ & \text{ if } u.left = nil \text{ then } pre\_order(u.left) \\ & \text{ if } u.right = nil \text{ then } pre\_order(u.right) \end{split}
```

## BinaryTree: $post\_order(u)$

- How should we traverse a binary tree to delete a tree?
- ightharpoonup delete first left, then right and then root nodes
- $ightharpoonup post\_order(u)$ : left, right, root

```
\begin{array}{l} post\_order(u) \\ \textbf{if } u.left = nil \textbf{ then } post\_order(u.left) \\ \textbf{if } u.right = nil \textbf{ then } post\_order(u.right) \\ \textbf{\# Visit } u \end{array}
```

## Traversing a tree in order without recursion



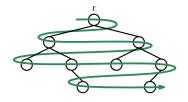
### Traversing a tree

```
traverse2()
   Let u be the node being visited. Initially, the root
   Let prev be the previous node being visited. Initially, nil
   While there are no nodes without being visited
      If we arrive at a node u from u.parent
         Let nxt be the next node to visit: left if exists
            otherwise right otherwise parent
      Else if we arrive at a node u from u.left
         Let nxt be the next node to visit: right if exists
           otherwise parent
      Else if we arrive at a node u from u.right
         Let nxt be the next the parent
      Update prev with u
      Update u with next
```

## Traversing a tree

```
traverse2()
   u \leftarrow r
   prv \leftarrow nil
   while u \neq nil do
       if prv = u.parent then
           # visit u for first time
           if u.left \neq nil then nxt \leftarrow u.left
           else if u.right \neq nil \ nxt \leftarrow u.right
           else nxt \leftarrow u.parent
       else if prv = u.left
           if u.right \neq nil then nxt \leftarrow u.right
           else nxt \leftarrow u.parent
       else
           nxt \leftarrow u.parent
       prv \leftarrow u
       u \leftarrow nxt
```

#### Breadth-first traversal



► The nodes are visited level-by-level starting at the root and moving down, visiting the nodes at each level from left to right

#### Breadth-first traversal

```
bf_traverse()
Insert the root in a queue
While the queue is not empty
Remove the next node in the queue
Insert the left child if it exits
Insert the right child if it exits
```

#### Breadth-first traversal

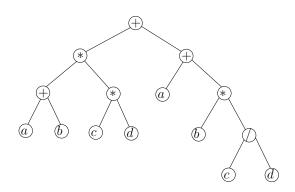
```
\begin{array}{l} \mathrm{bf\_traverse}() \\ q \leftarrow \mathrm{ArrayQueue}() \\ \mathbf{if} \ r \neq nil \ \mathbf{then} \ q.\mathrm{add}(r) \\ \mathbf{while} \ q.\mathrm{size}() > 0 \ \mathbf{do} \\ u \leftarrow q.\mathrm{remove}() \\ \mathbf{if} \ u.left \neq nil \ \mathbf{then} \ q.\mathrm{add}(u.left) \\ \mathbf{if} \ u.right \neq nil \ \mathbf{then} \ q.\mathrm{add}(u.right) \end{array}
```

How many operations?

#### Parse Tree

Parse trees can be used to represent real-world constructions like sentences or mathematical expressions.

$$(((a+b)*(c*d)) + (a + (b*(c/d))))$$



# Building a Parse Tree from the Fully Parenthesized Mathematical Expression

Breakup the expression in tokens: left parentheses, right parentheses, operator and operands.

```
build\_parse\_tree(exp)
   Let t be a binary tree
   Let u be the root
   While there are not more tokens in exp
      If token is '(' then
         Add a left child to u and let u = u.left
      If token is either '+, -, /, *' then
         u.x = token
         Add a right child to u and let u = u.right
      If token is an operand then
         u.x = token and let u = u.parent
      If token is ')' then
         Let u = u.parent
   return t
```

#### Evaluate from a Parse Tree

```
\begin{tabular}{l} $ -evaluate(node) \\ & \textbf{If } node.left \ \textbf{and } node.right \ \textbf{are not nil} \\ & \textbf{let } op = node.x \\ & \textbf{return } evaluate(node.left) \ op \ evaluate(node.left) \\ & \textbf{else } evaluate(node.x) \\ \\ & evaluate(tree) \\ & \textbf{return } \_evaluate(tree.r) \\ \end{tabular}
```

#### Evaluate from a Parse Tree

```
import operator as oper

def _evaluate(self, node):
    op = { '+':operadd, '-':oper.sub, '*':oper.mul, '/':oper.truediv}
    if node.left != None and node.right != None:
        fn = op[node.x]
        return fn(self._evaluate(node.left), self._evaluate(node.right))
    else:
        t = self.dict.find(node.x)
        if t != None: return t
        return node.x
```

## **Autocompletion Feature**

- In many web services while writing, the system shows a suggestion to autocomplete
- Using lists takes linear time in the worst case to find the first item that matches the prefix.
- In unsorted dictionaries, we can search the complete word in expected constant time, but finding the prefix takes also linear time in the worst case
- Is there a more efficient data structure to find the prefix?
- Sorted Dictionaries are the solutions.

## Lexicographical Order

• Let  $\omega = \alpha \beta \gamma$  and  $\omega' = \alpha \delta \epsilon$ 

$$\omega < \omega'$$
 if and only if  $\beta < \delta$ 

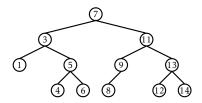
- For example  $\omega_1$  =distraction and  $\omega_2$  =distributed
  - $\omega_1 = \alpha \beta \gamma$  where  $\alpha = \text{dist}$ ,  $\beta = \text{a}$  and  $\gamma = \text{ctoin}$
  - $\omega_2 = \alpha \delta \epsilon$  where  $\alpha = \text{dist}$ ,  $\delta = \text{r}$  and  $\epsilon = \text{ibuted}$

$$\omega_1 < \omega_2$$

## BinarySearchTree: An Unbalanced Binary Search Tree

- BinarySearchTree:
  - State variables:
    - n: Number of elements in the binary search tree.
    - r: The root of the tree
  - Invariant:
    - ightharpoonup r is nil if n=0
    - ► For every node *u* in the binary search tree

$$u.left.x < u.x < u.right.x$$



## BinarySearchTree: $find_eq(x)$

▶  $find\_eq(x)$ : Return the node that contains the value x if it exits, or nil otherwise

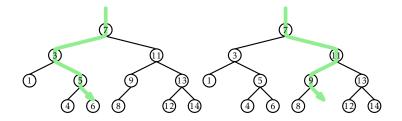
```
\begin{array}{c} \operatorname{find\_eq}(x) \\ \operatorname{Let} w \text{ be the root} \\ \operatorname{While} \text{ we don't find the value or } w \text{ is nil} \\ \operatorname{If} x \text{ is less than } w.x, \text{ then visit the left child} \\ \operatorname{If} x \text{ is greater than } w.x, \text{ then visit the right child} \\ \operatorname{If} x \text{ is equal } w.x, \text{ then we found it!} \\ \operatorname{The value is not present} \end{array}
```

## BinarySearchTree: $find_{-}eq(x)$

```
\operatorname{find}_{-\operatorname{eq}}(x)
    w \leftarrow r
    while w \neq nil do
        if x < w.x then
             w \leftarrow w.left
        else if x > w.x
             w \leftarrow w.right
        else
             return w.v
    return nil
```

How many operations?

## BinarySearchTree: Example $find_{-}eq(6)$ , $find_{-}eq(10)$



## BinarySearchTree: find(x)

- ▶ find(x): Return the node that contains the value x if it exits. Otherwise it returns the node with the smallest value greater than x.
  - If we look at the last node, u, at which x < u.x, we see that u.x is the smallest value in the tree greater than x.
  - Similarly, the last node at which x > u.x contains the largest value less than x.
  - Therefore, we keep track of the last node, z, at which x < u.x</p>

## BinarySearchTree: $add\_child(p, u)$

▶  $add\_child(p, u)$ : Add the node u as a child of p.

```
\operatorname{add\_child}(p,u)
Check Preconditions
Check Invariants
Set p as the parent of u
Increment n by one
```

## BinarySearchTree: $add\_child(p, u)$

▶  $add\_child(p, u)$ : Add the node u as a child of p.

```
\begin{array}{l} \operatorname{add\_child}(p,u) \\ \text{If } p \text{ is nil, then } u \text{ becomes the root} \\ \text{Otherwise if } u.x < p.x, \text{ then } u \text{ is the left child of } p \\ \text{Otherwise if } u.x > p.x, \text{ then } u \text{ is the right child of } p \\ \text{Otherwise if } u.x = p.x, \text{ then nothing to do} \\ \text{Set } p \text{ as the parent of } u \\ \text{Increment } n \text{ by one} \end{array}
```

## BinarySearchTree: $add\_child(p, u)$

```
add_child(p, u)
   if p = nil then
       r \leftarrow u # inserting into empty tree
   else
       if u.x < p.x then
          p.left \leftarrow u
       else if u.x > p.x
          p.right \leftarrow u
       else
          return false # u.x is already in the tree
       u.parent \leftarrow p
   n \leftarrow n + 1
   return true
```

## BinarySearchTree: $find\_last(x)$

▶  $find\_last(x)$ : Return the node w such that w.x = x if it exists, otherwise, return the previous node

```
find_last(x)
   w \leftarrow r
   prev \leftarrow nil
   while w \neq nil do
       prev \leftarrow w
       if (x < w.x) then
          w \leftarrow w.left
       else if (x > w.x)
          w \leftarrow w.right
       else
          return w
   return prev
```

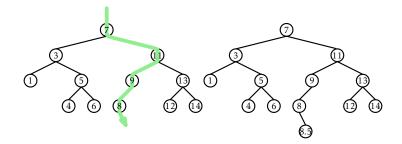
## BinarySearchTree: add(x, v)

- ▶ add(x, v): Add a node with x and value v in the binary search tree
  - Let p be the closest node to x
  - ► Insert a child to the binary search tree using add\_child(p, new\_node(x, v))

```
\begin{array}{c} \operatorname{add}(x) \\ p \leftarrow \operatorname{find\_last}(x) \\ \operatorname{\textbf{return}} \operatorname{add\_child}(p, \operatorname{new\_node}(x, v)) \end{array}
```

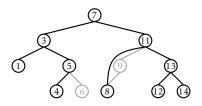
How many operations?

## BinarySearchTree: add(8.5, Nill)



## BinarySearchTree: Node removal

- ▶ If *u* is a leaf, then we can just detach *u* from its parent.
- ▶ If *u* has only one child, then we can splice *u* from the tree by having *u.parent* adopt *u*'s child



## BinarySearchTree: splice(u)

```
\operatorname{splice}(u)
    if u.left \neq nil then
        s \leftarrow u.left
    else
        s \leftarrow u.right
    if u=r then
        r \leftarrow s
        p \leftarrow nil
    else
        p \leftarrow u.parent
        if p.left = u then
            p.left \leftarrow s
        else
            p.right \leftarrow s
    if s \neq nil then
        s.parent \leftarrow p
    n \leftarrow n - 1
```

## BinarySearchTree: $remove\_node(u)$

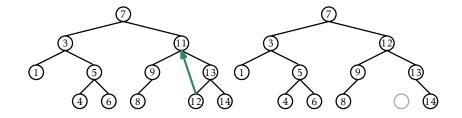
▶ remove\_node(u): Remove the node u from the binary search tree

```
\begin{array}{c} \operatorname{remove\_node}(u) \\ \text{If } u \text{ has at most one child, then call } splice(u) \\ \text{Otherwise find } w \text{ that has at most one child such that} \\ w.x > x \text{ and } w.x \text{ is the smallest} \\ \text{Replace } u.x \text{ with } w.x \\ \text{Call } splice(w) \end{array}
```

# BinarySearchTree: $remove\_node(u)$

```
\begin{aligned} & \textbf{remove\_node}(u) \\ & \textbf{if } u.left = nil \textbf{ or } u.right = nil \textbf{ then} \\ & \text{splice}(u) \\ & \textbf{else} \\ & w \leftarrow u.right \\ & \textbf{while } w.left \neq nil \textbf{ do} \\ & w \leftarrow w.left \\ & u.x \leftarrow w.x \\ & \text{splice}(w) \end{aligned}
```

# BinarySearchTree: $remove\_node(u)$



### BinarySearchTree: remove(x)

- remove(x): Remove the node with value x in the binary search tree
  - Let w be the node that  $find_{-}eq(x)$  returns.
  - ightharpoonup Call  $remove\_node(w)$

```
\begin{aligned} \text{remove}(x) \\ p &\leftarrow \text{find\_eq}(x) \\ remove\_node(w) \end{aligned}
```

### Summary

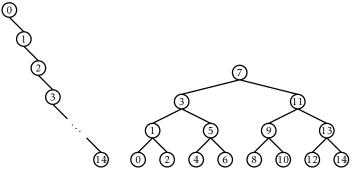
#### ▶ Theorem

BinarySearchTree implements the SSet interface and supports the operations add(x), remove(x), and find(x) in O(n) time per operation.

► The problem with the BinarySearchTree structure is that it can become *unbalanced*.

### Random Binary Trees

▶ Consider the binary trees obtained from inserting  $\langle 0,1,2,3,4,5,6,7,8,9,10,11,12,13,14 \rangle$  in any random order



➤ Only one gives the left tree and 21,964,800 that give the balanced tree

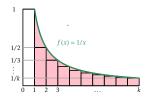


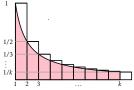
### Harmonic Function

$$H_k = 1 + 1/2 + 1/3 + \dots + 1/k$$
.

The harmonic number  $H_k$  has no simple closed form, but it is very closely related to the natural logarithm of k. In particular,

$$\ln k < H_k \le \ln k + 1 .$$





## Random Binary Trees

#### Lemma

In a random binary search tree of size n, the following statements hold:

- 1. For any  $x \in \{0, \dots, n-1\}$ , the expected length of the search path for x is  $H_{x+1} + H_{n-x} O(1)$  ( the number of elements in the tree less than or equal to x and the number of elements in the tree greater than or equal to x.)
- 2. For any  $x \in (-1, n) \setminus \{0, \dots, n-1\}$ , the expected length of the search path for x is  $H_{\lceil x \rceil} + H_{n-\lceil x \rceil}$ .

## Random Binary Trees (Proof 1/2)

Let  $I_i$  be the indicator random variable that is equal to one when i appears on the search path for x and zero otherwise. The length of the search path is given by

$$\sum_{i \in \{0, \dots, n-1\} \setminus \{x\}} I_i$$

If  $x \in \{0, \dots, n-1\}$ , the expected length of the search path is given by

## Random Binary Trees (Proof 2/2)

$$\begin{split} \mathbf{E}\left[\sum_{i=0}^{x-1}I_{i} + \sum_{i=x+1}^{n-1}I_{i}\right] &= \sum_{i=0}^{x-1}\mathbf{E}\left[I_{i}\right] + \sum_{i=x+1}^{n-1}\mathbf{E}\left[I_{i}\right] \\ &= \sum_{i=0}^{x-1}1/(\lfloor x\rfloor - i + 1) + \sum_{i=x+1}^{n-1}1/(i - \lceil x\rceil + 1) \\ &= \sum_{i=0}^{x-1}1/(x - i + 1) + \sum_{i=x+1}^{n-1}1/(i - x + 1) \\ &= \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{x+1} \\ &+ \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{n-x} \\ &= H_{x+1} + H_{n-x} - 2 \ . \end{split}$$

The corresponding calculations for a search value  $x \in (-1,n) \setminus \{0,\ldots,n-1\}$  are almost identical



### Summary

#### **Theorem**

A random binary search tree can be constructed in  $O(n \log n)$  time. In a random binary search tree, the  $\operatorname{find}(x)$  operation takes  $O(\log n)$  expected time.

In particular a random binary tree implements a sorted dictionary where find(x) add(x,v) and remove(x) take  $O(\log n)$  expected time.