# **Supervised Learning**

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Introduction to Machine Learning



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- 1. Our Datasets for Supervised Learning
- 2. Data Generating Processes and Noise
- 3. How Does Supervised Learning Work?





# Handwritten Digit Classification (MNIST)



our goal: assign the correct digit class to images 5 0 419 2131435

input X: 28x28 = 784 pixels with values between 0 (black) and 1 (white) output Y: digit class 0, 1, . . . , 9





# Spam Detection with the Enron Dataset

#### spam

Subject: follow up

here 's a question i' ve been wanting to ask you, are you feeling down but too embarrassed to go to the doc to get your m / ed 's?

here 's the answer , forget about your local p harm . acy and the long waits , visits and embarassments . . do it all in the privacy of your own home , right now . http://chopin.manilamana . com / p / test / duet it 's simply the best and most private way to obtain the stuff you need without all the red tape .

#### ham

Subject: darrin presto

amy:

please follow up as soon as possible with darrin presto regarding a real time interview. i forwarded his resume to you last week. he can be reached at 509 - 946 - 7879 thanks greq

Our goal: classify new emails as spam or "ham" (not spam).

input X: sequences of characters (emails), output Y: label spam or ham



## Wind Speed Prediction

- ➤ SwissMeteo data: hourly measurements for 5 years from different stations (Bern, Basel, Luzern, Lugano, etc.).
- ➤ Our goal: given measurements at different stations, predict wind speed in Luzern 5 hours later.





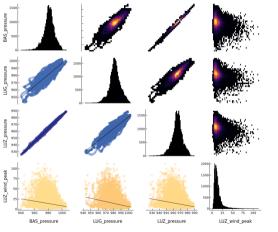
## Wind Speed Prediction

time	BAS_pressure	LUG_pressure		LUZ_pressure	LUZ_wind_peak
$x_{11} = 2015010100$	$x_{12} = 997.1$	$x_{13} = 998.6$		$x_{1p} = 980.0$	$y_1 = 13.0$
$x_{21} = 2015010101$	$x_{22} = 997.3$	$x_{23} = 998.8$		$x_{2p} = 979.9$	$y_2 = 6.8$
:	:	:	٠.	:	
$x_{n1} = 2017123123$	$x_{n2} = 972.7$	$x_{n3} = 981.5$		$x_{np} = 957.5$	$y_n = 11.9$

- ▶ p input variables  $X = (X_1, X_2, ..., X_p)$ e.g.  $X_1$  time,  $X_2$  BAS\_pressure,  $X_3$  LUG\_pressure also called: predictors, independent variables, features
- output variable Y e.g. LUZ\_wind\_peak also called: response, dependent variable
- n measurements or data points



## Always Look at Raw Data!



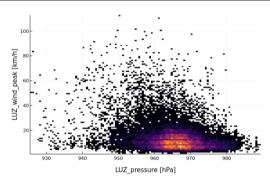
- on diagonal: 1D histogram
- lower triangle: scatter plot & trend line
- upper triangle: 2D histogram

#### **Observations**

- 1. LUZ\_wind\_peak has a long tail.
- 2. For low pressures there are outliers of strong wind.
- 3. Pressure in Basel and Luzern is highly correlated.
- 4. ...



# **Wind Speed Prediction**



- ▶ The higher the pressure in Luzern, the less probable it is to have strong winds.
- There is no function LUZ\_wind\_peak =  $f(LUZ_pressure)$  that can describe this data; instead we use conditional probability densities  $p(LUZ_wind_peak | LUZ_pressure)$ .



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## **Data Generating Processes**

It is useful to think of our datasets as samples from **data generating processes** for the input X and the conditional output Y|X.

- MNIST X: people write digits → people take standardized photos thereof. Y|X: different people label the same photo X.
- Spam X: people write emails.
  Y|X: different people classify the same email X as spam or not.
- ▶ Weather X: the weather acts on sensors in weather stations. Y|X: the weather evolves from X and is measured again 5 hours later.

Using samples from these data generating processes, supervised learning aims at learning something about the conditional processes, i.e how Y depends on X.



### Where Does Noise Come From?

For most data generating processes we **cannot measure all factors** that determine the outcome.

- ⇒ same values of the measured factors can cause different outcomes.
- MNIST Different persons may label the same handwritten digit differently.
- ▶ **Spam** What is spam for somebody, may not be spam for someone else.
- ▶ **Weather** Even when all considered weather stations measure exactly the same values at time  $t_1$  and  $t_2$ , the full state of the weather at  $t_1$  differs most likely from the one at  $t_2$ .

In machine learning we treat the effect of unmeasured factors as noise with certain probability distributions.

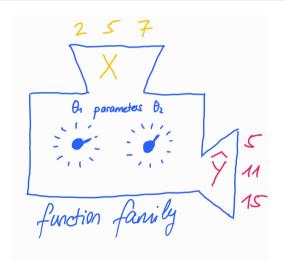


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# **How Does Supervised Learning Work?**



### **Function Family**

- We change the parameters.
- The machine computes  $\hat{y}$  given parameters  $\theta$  and x.

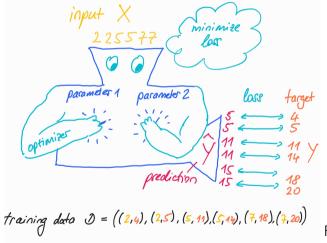
For example

$$\hat{y} = f_{\theta}(x) = \theta_{O} + \theta_{1}x$$

When we change the parameters  $\theta_0$  and  $\theta_1$ , we change the way  $\hat{y}$  depends on x.



# **How Does Supervised Learning Work?**



## Loss Minimizing Machine

- We specify
  - 1. the training data
  - the function family (model)
  - 3. the loss function  $L(y, \hat{y})$
  - 4. the optimizer
- The machine changes the parameters with the help of the optimizer until the loss is minimal.

For example: linear regression



# Training Loss and Test Loss

- ▶ **Training Set**  $\mathcal{D}$ : Data used by the machine to tune the parameters.
- ▶ Training Loss of Function  $f: \mathcal{L}(f, \mathcal{D}) = \frac{1}{n} \sum_{i=1}^{n} \mathcal{L}(y_i, f(x_i))$
- ► Test Loss of Function f at x for a Conditional Data Generating Process:  $\mathbb{E}_{Y|x}[L(Y, f(x))] = \text{expected loss under the conditional generating process.}$
- ► Test Loss of Function f for a Joint Data Generating Process:  $E_{X,Y}[L(Y, f(X))] = \text{expected loss under the joint generating process.}$
- ▶ **Test Set**  $\mathcal{D}_{test}$ : Data from the same generating process as the training set, not used for parameter tuning.
- ▶ Test Loss of Function f for a Test Set  $\mathcal{D}_{test}$ :  $\mathcal{L}(f, \mathcal{D}_{test})$  = same computation as for the training loss but for a test set.



# Blackboard: Linear Regression as a Loss Minimizing Machine

Data Generating Process

$$y = 2x - 1 + \varepsilon$$
,  $F[\varepsilon] = 0 \quad Var[\varepsilon] = \sigma^{-2}$ 

Training Data

 $(x_1 = 0, y_1 = -1), (x_2 = 2, y_2 = 4), (x_3 = 2, y_3 = 3))$ 

Function Family

 $\hat{y} = \theta_0 + \theta_1 \times L$ 

Loss Function

 $L(\theta) = L(\theta_1, \theta_2) = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2 = \frac{1}{n} \sum_{i=1}^{n} (y_i - \theta_0 - \theta_0 - \theta_0)^2 + (3 - \theta_0 - 2\theta_0)^2)$ 

Optimizer: Default

Solution: 
$$\hat{\theta}_{o} = -1$$
,  $\hat{\theta}_{i} = 2.25$ ,  $L(\hat{\theta}) = \frac{e}{3} \cdot 0.5^{2}$ 

Test Low at  $x_{o}$ :

$$E[(2x_{o}-4+\epsilon+1-2.25x_{o})^{2}] = (0.25x_{o})^{2} + 0^{2}$$

Test Data:
$$((x_{o}=1, y_{o}=0), (x_{z}=2, y_{z}=3), (x_{o}=3, y_{o}=5), (x_{o}=0, y_{o}=1))$$

$$\Rightarrow (Empirical) Test Low = \frac{1}{4}(0.25^{2}+0.5^{2}+0.75^{2}+0^{2})$$

## Quiz

Suppose we have training data  $\mathcal{D} = ((0,1),(2,9))$  and test data  $\mathcal{D}_{test} = ((0,0),(3,20))$ , define a function family  $f(x) = \theta_0 + \theta_1 x^2$  and loss function  $L(y,\hat{y}) = |y - \hat{y}|$ .

### Correct or wrong?

- 1. The training loss is minimal for  $\hat{\theta}_0 = 1$  and  $\hat{\theta}_1 = 2$ .
- 2. The test loss of  $f(x) = 1 + 2x^2$  at x = 0 for the conditional data generating process is 1.
- 3. The test loss of  $f(x) = 1 + 2x^2$  for the test set is 1.

## Supervised Learning with MLJ: Linear Regression

```
model = LinearRegressor()  # function family, loss function and optimizer
mach = machine(model, X, y)  # training data with input X and output y
fit!(mach)  # fit the machine
fitted_params(mach)  # inspect the fitted parameters
ŷ = predict(mach)  # make predictions on the training data
ŷtest = predict(mach, Xtest)  # make predictions on the test data
```



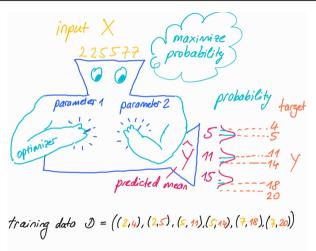
## Which Loss Functions Should We Use?

- Is the mean squared error always a good loss?
- What kind of loss would be good in a classification setting (e.g. MNIST)?
- ► How should we choose the loss when we know something about the noise distribution?

All these questions have a straight-forward answer, if we use a **family of probability distributions** (instead of a family of functions) and estimate the parameters with a **maximum likelihood approach** (instead of minimizing a hand-picked loss).



# **How Does Supervised Learning Work?**



### **Likelihood Maximizing Machine**

- We specify
  - the training data
  - the family of probability distributions (model)
  - 3. the optimizer
- The machine changes the parameters with the help of the optimizer until the likelihood of the parameters is maximal.

For example: linear regression



## The Likelihood Function

For a family of conditional probability distributions  $P(y|x, \theta)$  and training data  $\mathcal{D} = ((x_1, y_1), (x_2, y_2), \dots, (x_n, y_n))$  the **likelihood function** is defined as

$$\ell(\theta) = \prod_{i=1}^n P(y_i|x_i,\theta).$$

This is the probability of all the responses  $y_i$  given all the inputs  $x_i$  for a given value of the parameters  $\theta$ .

In practice it is usually more convenient to work with the log-likelihood function

$$\log \ell(\theta) = \sum_{i=1}^{n} \log P(y_i|x_i,\theta)$$



# The Normal, Bernoulli and Categorical Distribution

### Normal



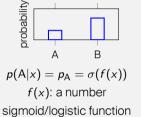
$$p(y|x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y-f(x))^2}{2\sigma^2}}$$

f(x): a number mean: f(x)

variance:  $\sigma^2$ 

mode: f(x)

### Bernoulli

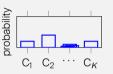


$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

$$p(B|x) = 1 - p_A = \sigma(-f(x))$$

mode: A if  $p_A > p_B$ 

## Categorical



$$p(C_i|x) = p_{C_i} = s(f(x))_i$$

f(x): a vector of K numbers softmax function

$$s(x)_i = \frac{e^{x_i}}{\sum_{j=1}^K e^{x_j}}$$

mode: X with largest  $p_X$ .



# Blackboard: The Normal, Bernoulli and Categorical Distribution

Normal
$$f(x) = 1, \ r = 2$$

$$Pr(y \in [-0.05, 0.05]) \approx 0.1; \frac{1}{\sqrt{2\pi^2 \cdot 2}} e^{-\frac{(0-1)^2}{2 \cdot 2^2}} \approx 0.017$$

$$Essnowlli$$

$$f(x) = 3 \qquad Pr(y = A) = \frac{1}{1 + e^{-3}} \approx 0.95$$

$$Pr(y = B) \approx \frac{1}{1 + e^3} \approx 0.05$$

$$f(x) = \begin{pmatrix} -3 \\ 1 \\ 0 \end{pmatrix} \qquad Pr(y = A) = \frac{e^3}{e^3 + e^2 + e^4 + e^6} \approx 0.84$$

$$Pr(y = D) = \frac{e^0}{e^3 + e^{-2} + e^4 + e^6} \approx 0.04$$

## Blackboard: Maximum Likelihood Estimation

Data Generating Procest

$$P(y=\lambda|x) = \text{Bernoulli}(2x-1)$$
 $y=A$  if  $P(2x-1) > E$ ,  $E \sim Uniform([0,1])$ 

Training Data

 $\{(x_1=0, y_1=8), (x_2=2, y_2=A), (x_3=3, y_3=8)\}$ 

Family of Distributions

 $P(y=A|x,\theta) = O(\theta_0+\theta_1x)$ 

Log-Likelihood Function
$$\log \ell(\theta) = \log \ell(\theta_{\bullet}, \theta_{\bullet}) = \sum_{i=1}^{n} \log P(y_i | x_i, \theta)$$

$$= \log V(-\theta_{\bullet}) + \log V(\theta_{\bullet} + 2\theta_{\bullet}) + \log V(-\theta_{\bullet} - 3\theta_{\bullet})$$

$$Optimizer : Default$$

$$Solution : \hat{\theta}_{\bullet} \approx -1.3 \quad \hat{\theta}_{\bullet} \approx 0.3 \quad \log \ell(\hat{\theta}) \approx -1.3$$

$$Test Log-Likelihood \quad at x_0 : E[\log P(Y|X_{\bullet})]$$

$$V(2x_{\bullet} - 1) \cdot \log V(0.3x_{\bullet} - 1.3) + V(-2x_{\bullet} + 1) \cdot \log V(-0.3x_{\bullet} + 1.3)$$

$$P(Y = A|X_{\bullet}) \quad P(Y = A|X_{\bullet}, \hat{\theta}) \quad P(Y = B|X_{\bullet}) \quad P(Y = B|X_{\bullet}, \hat{\theta})$$

# Supervised Learning with MLJ: Linear Classification

```
model = LogisticClassifier() # distribution family and optimizer
mach = machine(model, X, y) # training data with input X and output v
fit!(mach)
                           # fit the machine
                           # inspect the fitted parameters
fitted_params(mach)
  = predict(mach)
                            # predicted probabilities on the training data
\hat{p}_a = pdf.(\hat{p}_a, "A") # predicted probabilities of class "A"
v = predict_mode(mach)
                           # class with highest predicted probability
```



## Nomenclature

For some models (families of probability distributions) with linear function f(x) we see occasionally specific names for the likelihood maximizing machine.

- Gaussian (normal distribution): Linear Regression
- Bernoulli: Logistic Regression or Linear Binary Classification
- Categorical: Multinomial Logistic Regression or Multiclass Linear Regression (or Classification)
- ▶ Poisson: Poisson Regression

Later we will see that there are natural generalizations for all these models with non-linear f(x), where f(x) is for example given by a neural network.



# **Summary**

We use a training set to find a conditional distribution that captures some regularities of the conditional data generation process. The goal is to find a conditional distribution that minimizes the test loss of the joint data generation process. With a test set we can assess how close we are at reaching this goal.

Supervised Learning as Lo	oss Minimization
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Supervised Learning as Likelihood Maximization

#### We provide

- training data
- 2. function family
- 3. loss function
- optimizer

It is not (always) obvious what kind of loss function to take for classification problems or regression problems with a specific noise distributions

#### We provide

- training data
- 2. probability distribution family
- optimizer

The negative log-likelihood function of the parameters implicitly defines a loss function.

We take the binomial for binary classification problems and the categorical for other classification problems. Regression with other noise distribution is also possible.



# **Suggested Reading**

The following chapters from "An Introduction to Statistical Learning" (second edition, https://www.statlearning.com) are complementary to the material presented in this lecture. It is not mandatory to read them, but maybe it helps to better understand the material of this lecture.

- ➤ 3.1 Simple Linear Regression
- 4.1 An Overview of Classification
- 4.2 Why Not Linear Regression?
- 4.3 Logistic Regression

