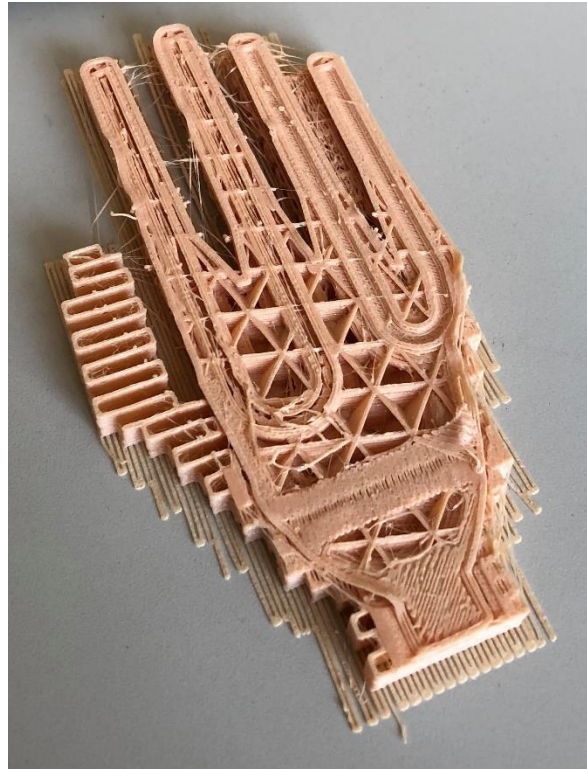
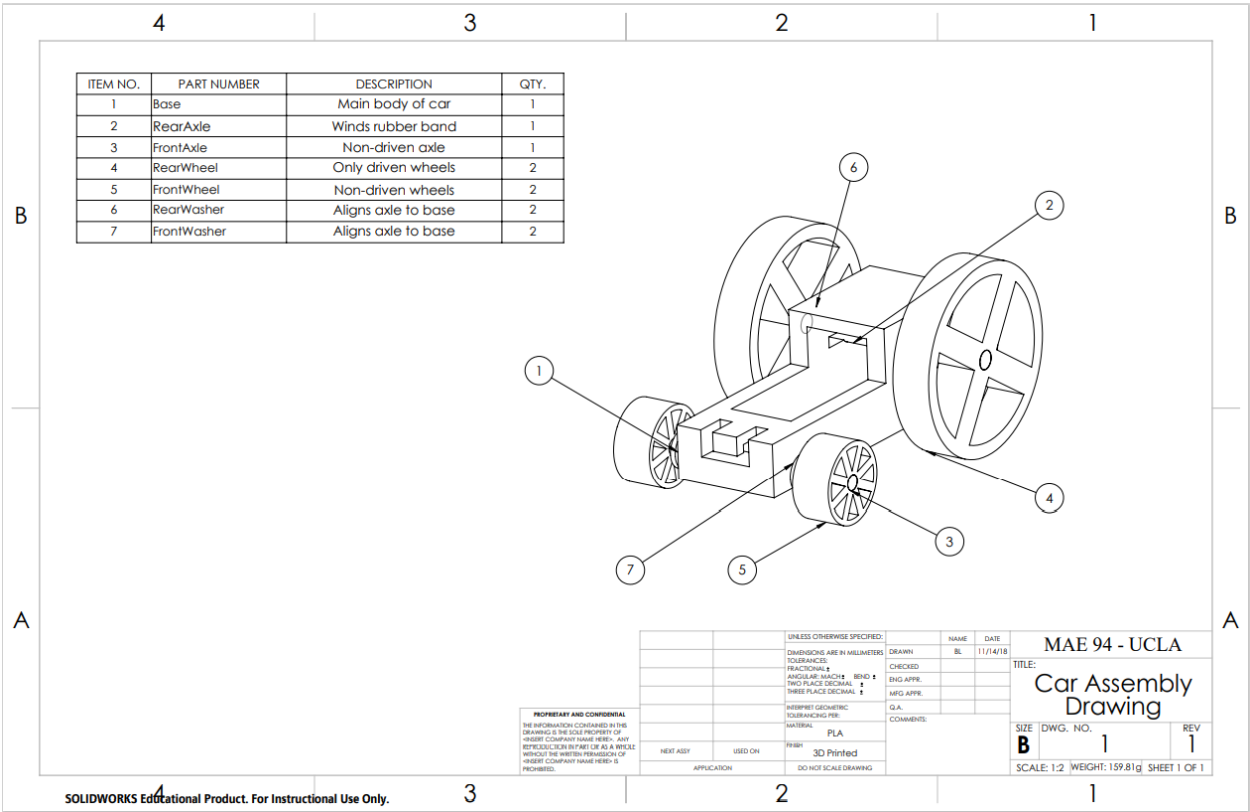
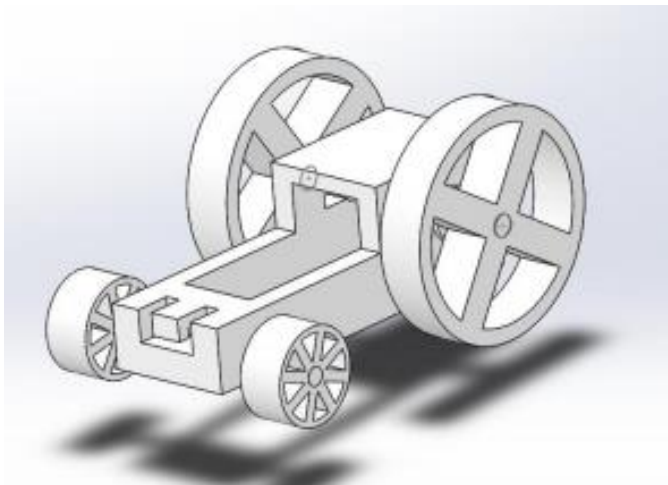
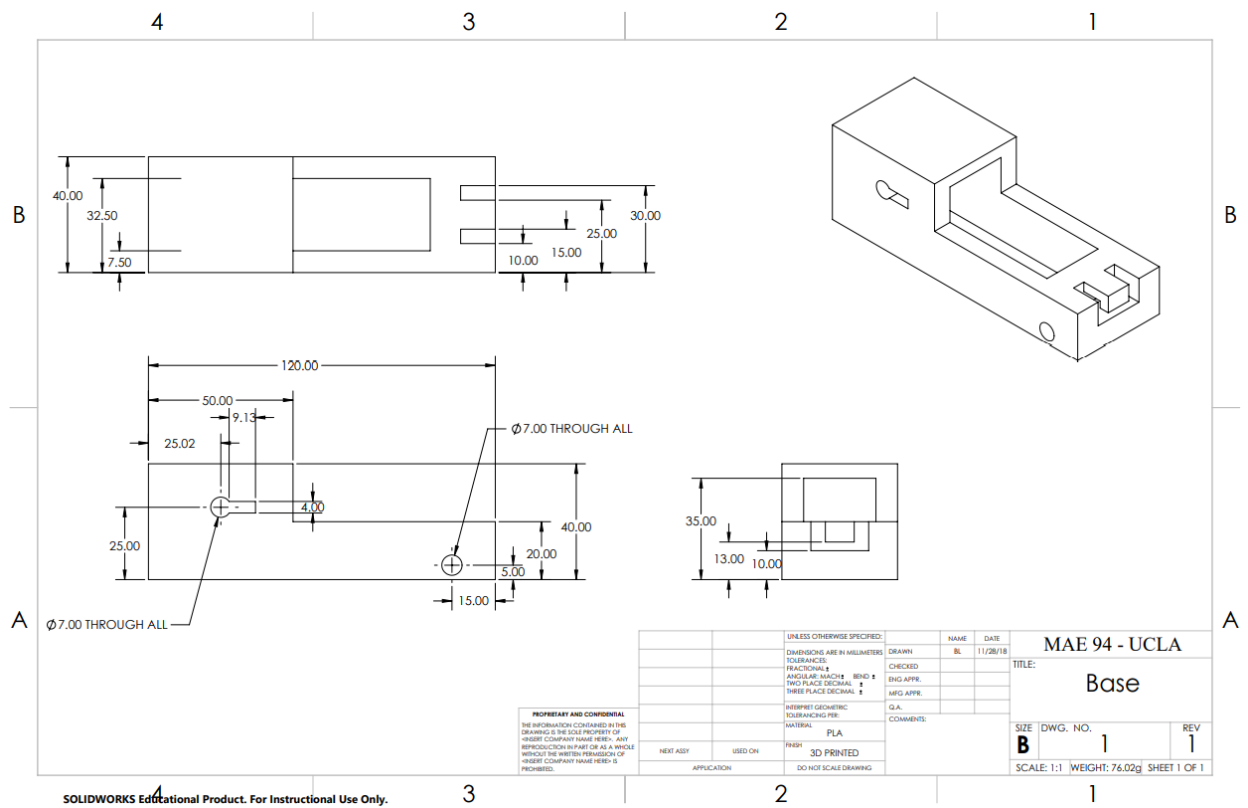
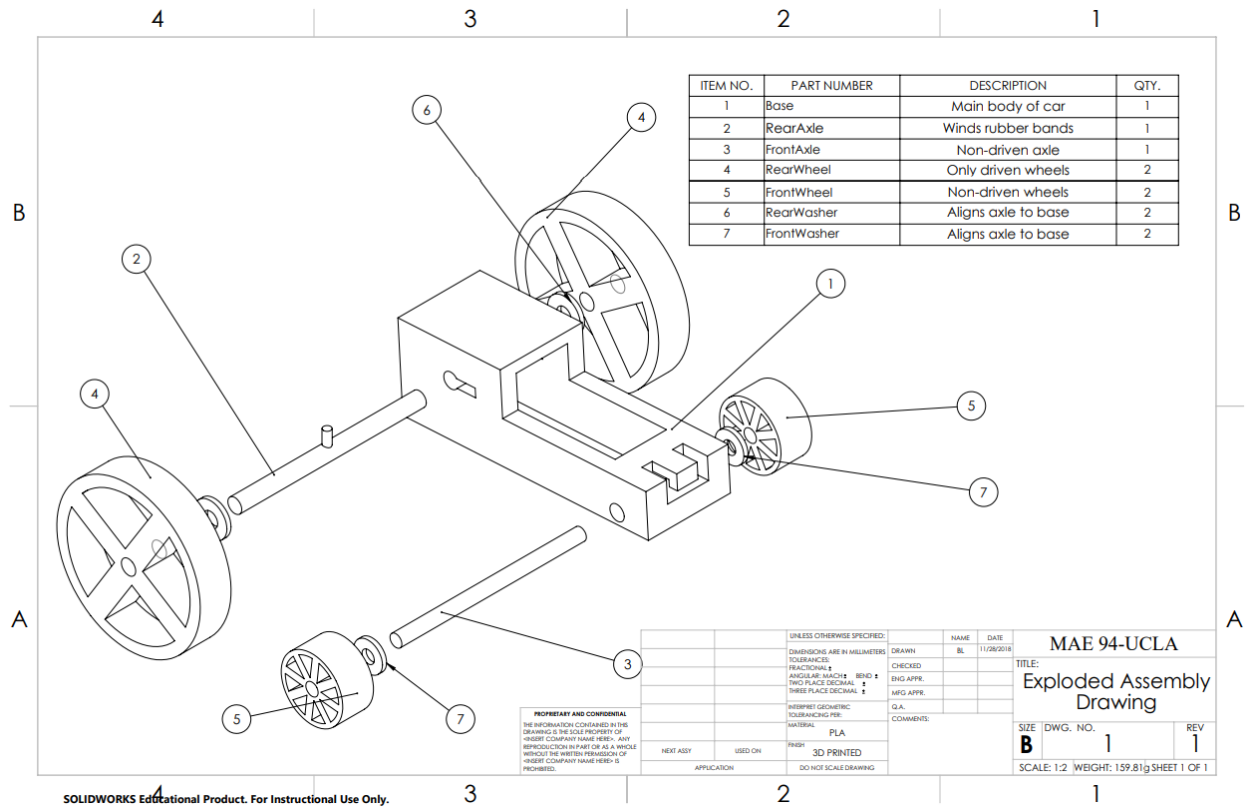


June – September 2018: Prosthetic Hand Research Project at San Jose State University:



December 2018: Final project for CAD Class:





September 2018 – June 2019: Automated Cell Plate Washer Design Project:

UCLA

Samueli
Bioengineering

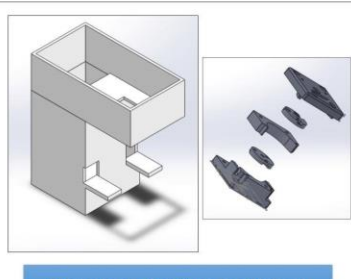
Automated Cell Washer

Philip Lue, Brendan Lin, Linnet Chang, Alison Tran, Sam Esperon



Background

- Any wet lab that works with cell culture requires washing and changing media in a cell dish
- This is a tedious and time consuming process
- Wanted to create a single machine that could be placed within a lab setting and used to simplify lab work
 - This would allow researchers to focus more time on other tasks
- Industrial 96-well plate washers exist, but can cost several thousand dollars
 - Also wanted to design a plate washer that could handle a larger dish of cells, since a "stock" of cells will often be grown in a larger area for convenience



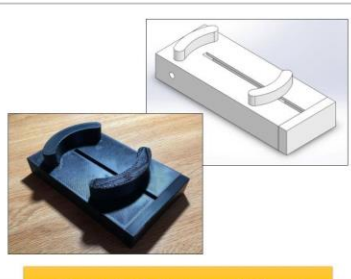
Prototypes for Base and Pump

Skills Developed

- Circuitry**
 - Configured stepper motor components with motor driver and power supply for peristaltic pump
 - Connected simple circuits to control servo motors
- Coding**
 - Created a single program with separate classes to control different parts of the pump
 - Coded using Arduino (C++) language
- Computer-Aided Design**
 - Learned how to design many of the cell washer parts using Solidworks
 - 3D printed components at UCLA Boelter Makerspace

Concepts and Prototyping

- Dispensing mechanism
 - Several different ways to pump liquid
 - Decided on peristaltic pump for practicality and functionality
- Aspirating mechanism
 - Wanted to either utilize the vacuum in laboratory biosafety cabinets or use a reverse pump mechanism
- Cell plate shaking
 - Needed to find mechanism to spread solution across all cells in plate
- Aseptic technique
 - Wanted a way to allow researcher to switch out pipettes or pipette tips to keep them sterile



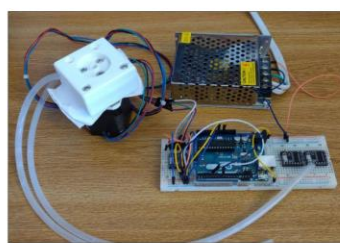
Cell Plate Platform and Clamp

Future Directions

- Several further additions can be made to improve current design
 - Automatic cell plate sorter that feeds cell plates into the washer
 - Add more pumps to allow for different solutions to be used to wash
 - Add another peristaltic pump for more continuous liquid flow
 - Develop a method to aspirate and dispense using one rotating pump only
 - Create better cell plate shaking and securing mechanism

Execution

- Peristaltic pump used for dispensing PBS and/or media
 - Good for aliquoting accurate amounts (mL) and is rate is easily controlled**
- Servo motors used to rotate shaking platform and to move aspirating/dispensing pipette
- SolidWorks implemented to **3D print parts of pump, base, and shaking platform**
- Used **Arduino Uno/Nano as microcontroller**
 - Connected to driver boards to control motors
- Design included aseptic technique** in mind
 - O-ring clamping allows for easy switching of pipettes or pipette tips



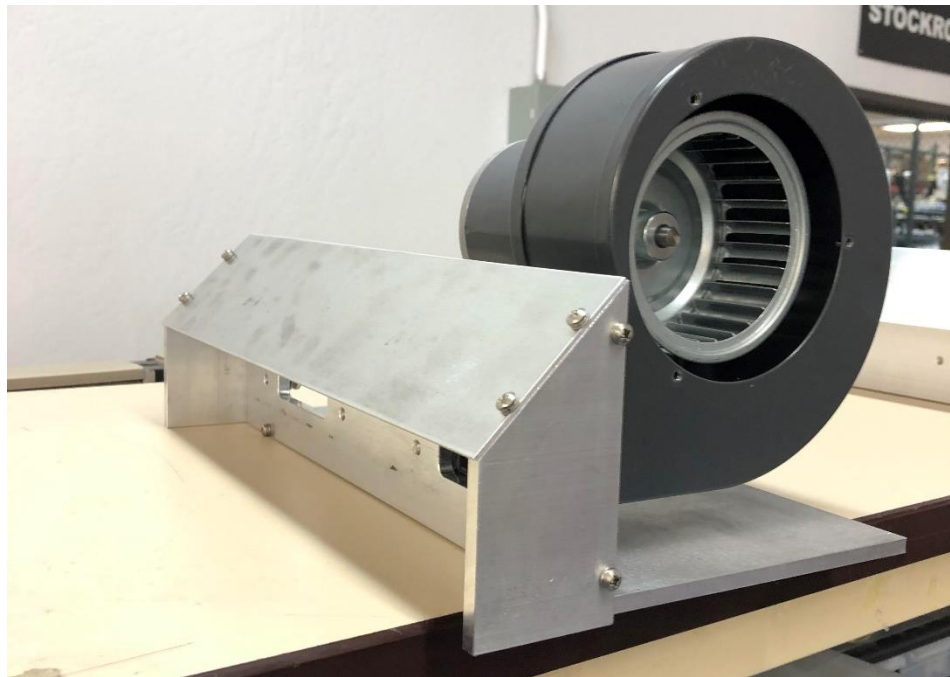
Completed Circuitry and Pump

References & Acknowledgments

- Materials and supplies were funded by UCLA's Department of Bioengineering
- Technical mentorship was provided from Design Team Project Managers Ryan Tsang, Smiti Narayanan, and Willie Wu, and Build Team Project Manager Gregory Suematsu
- Support was provided by UCLA's chapter of Biomedical Engineering Society
- Materials and equipment courtesy of UCLA Engineering Innovation Lab

June – September 2020: Internship Project at dB Control

Blower Test Fixture:



Variac Transformers:





Power Supply Test Fixture:

