

# 物理实验教学中心

*Physics Experiment Center*





## Purposes:

1. Observation and measurement of the equal thickness interference image.
2. The basic regulation and measurement operation of the microscope.
3. Measure the curvature radius of lens using **Newton ring**.
4. Learn to use graphical method and differential method for data analysis.

# Principles

$o$  is the touch point,  $e = 0$  at  $o$  point.

Optical path difference (OPD):  $\delta$

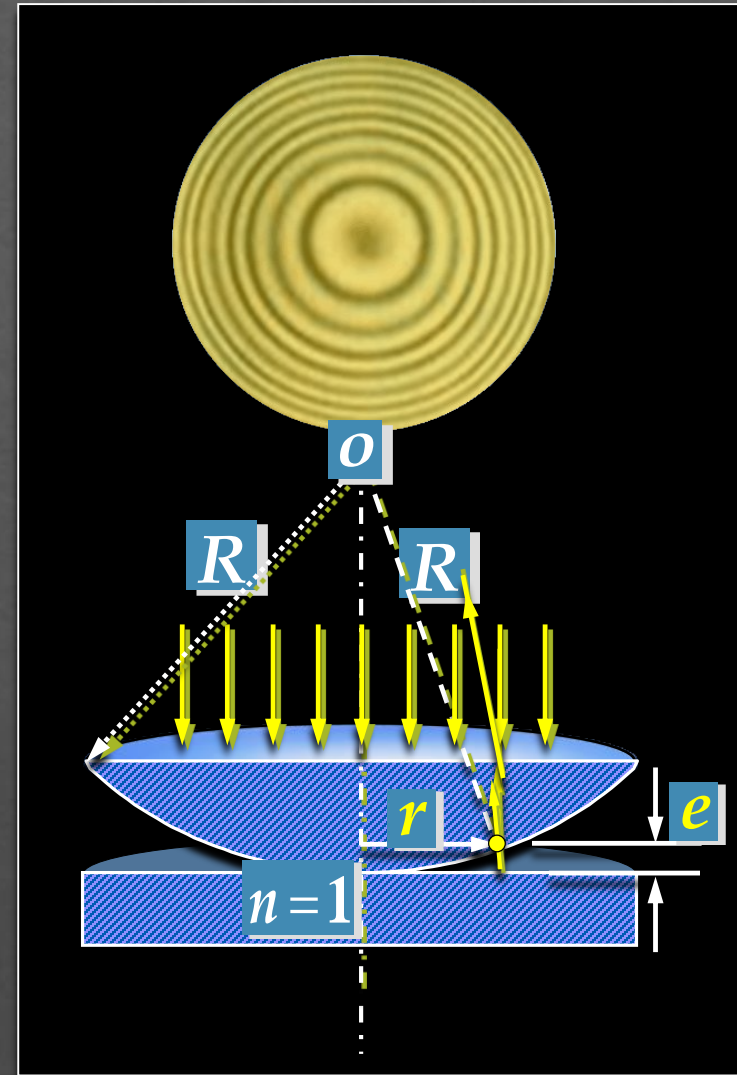
$$\delta = 2e + \frac{\lambda}{2} = 2Re - e^2$$

$$r^2 = R^2 - (R - e)^2 \approx 2Re \quad , \text{ because } R \gg e$$

$$\delta = \frac{r^2}{R} + \frac{\lambda}{2} = \begin{cases} 2k\frac{\lambda}{2} \\ (2k+1)\frac{\lambda}{2} \end{cases}$$

Bright  
rings  
Dark  
rings

## Newton ring



Convex lens



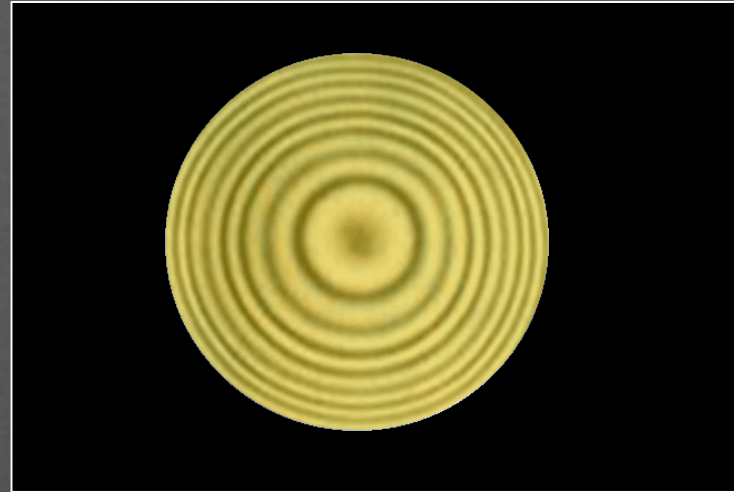
## Measurement of the curvature radius ( $R$ ) of convex lens using Newton ring

**For Dark rings:**

$$D_k^2 = (4R\lambda)k$$

$$R = \frac{D_m^2 - D_n^2}{4(m-n)\lambda}$$

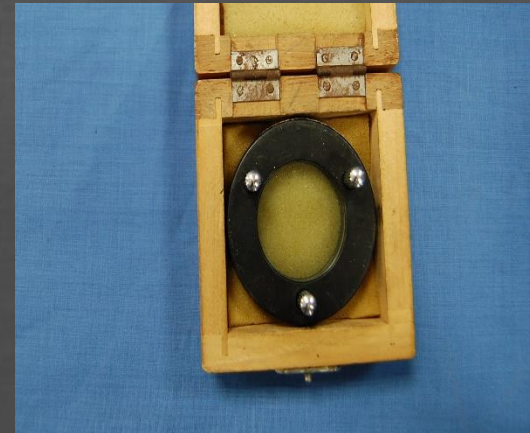
$m, n$  is the order



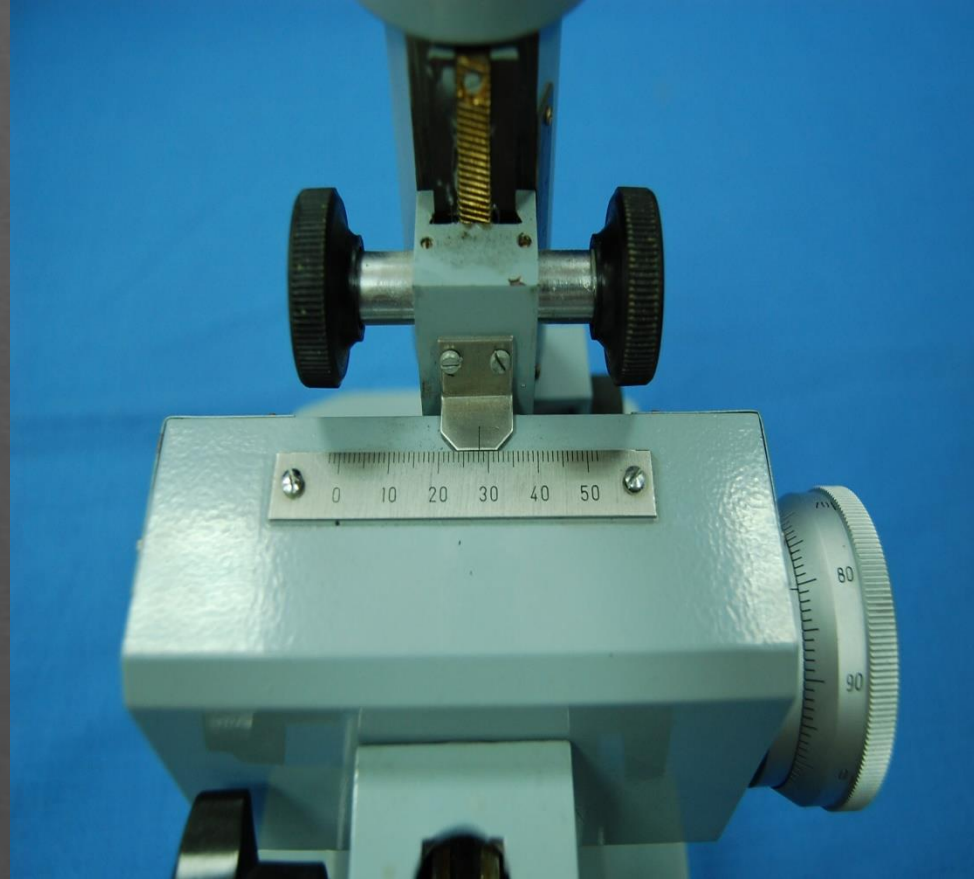
**Features:** Bigger the level  $k$ , more dense the stripes. ( $k = 0$  at center)

# Instruments

Microscope, Newton ring, Natrium lamp ( $\lambda = 589.3\text{nm}$ )



# How to use microscope?





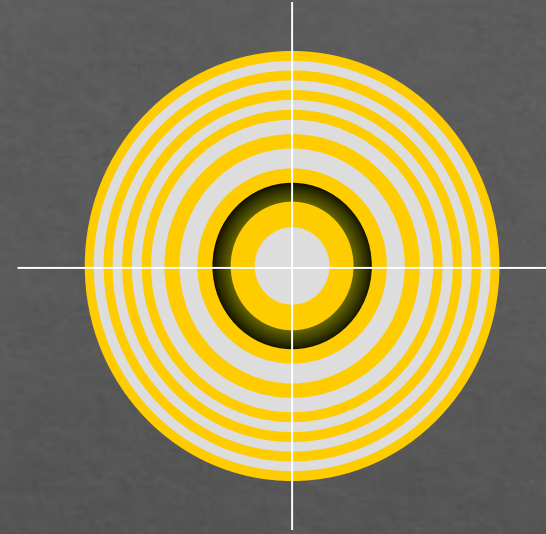


## ① Corse adjustment

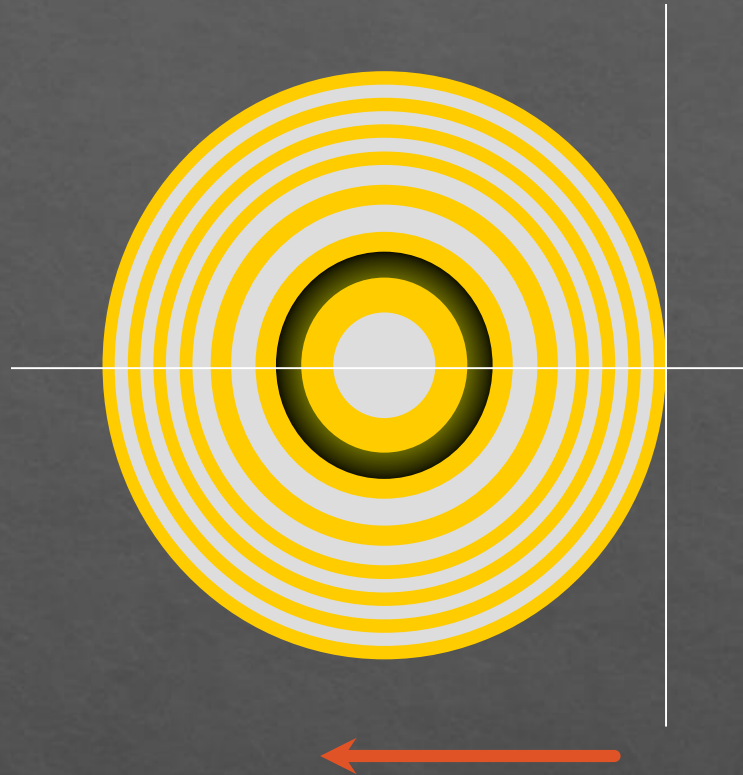
## ② Fine adjustment

- a. Regulate **eyepiece**, make the cross wire clear
- b. Rotate **transparent mirror**, make the view of the microscope most bright.





*c. Rotating hand wheel from bottom to top **slowly** until the stripes clear.*



To **eliminate the return difference**, we firstly move the cross wire to **35<sup>th</sup>** dark ring on the **right side**, then **turn back** to the **30<sup>th</sup>** dark ring, start to record the data as  $X_{30}$ ,  $X_{25}$ ,  $X_{20}$ ,  $X_{15}$ ,  $X_{10}$ ,  $X_5$  of both sides (Right to Left).

# Table I

Order		5	10	15	20	25	30
Data(cm)	Left $X_K$						
	Right $X_K'$						
Diameter of rings $D_K=   X_K-X_K'  $ cm							
$D_K^2(\text{cm}^2)$							
$D_m^2-D_n^2(\text{cm}^2) \ (m-n=15)$							
$\overline{D_m^2-D_n^2}(\text{cm}^2)$							
$\overline{R} \ (\text{cm})$							

$$R = \frac{D_m^2 - D_n^2}{4(m-n)\lambda}$$

$$\lambda = 589.3\text{nm}$$



## Uncertainty (*Not required*)

$$u_{cR} = \bar{R} \sqrt{\left(\frac{u_{c\lambda}}{\lambda}\right)^2 + \left(\frac{u_{cmn}}{m-n}\right)^2 + \left(\frac{S_{D_m^2 - D_n^2}}{D_m^2 - D_n^2}\right)^2}$$

$\lambda = 589.3 \text{ nm}$ ,  $u_{\lambda} = 0.3 \text{ nm}$ ,  $u_{mn} = 0.2$ ,  $D_m^2 - D_n^2$  : uncertainty of A class

**Calculate the curvature radius ( $R$ ) of lens using graphical method (not required)**

$$D_k^2 = (4R\lambda)k$$

**Use  $k$  as  $x$  axis,  $D_k^2$  as  $y$  axis, plot  $D_k^2 \sim k$  graph, calculate the slope of the line, then find out the value of  $R$ .**

END