



JOHNS HOPKINS

WHITING SCHOOL
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Introduction to Neural Networks

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Module 8.2: Hebbian Learning Continued

This Sub-Module Covers ...

- Performance evaluation.
- Proper training does not merely involve minimizing the error function using the training data.
- Must have some appropriate way of gauging how well the network performs using data it hasn't seen during the training phase.

Network to Matrix

Each output x_i for a node i with N perceptrons can be written as:

$$x_i = \sum_{j=1}^N w_{ij} x_j$$

But this is just the definition of the i^{th} element of a vector after a matrix/vector multiplication!

$$\mathbf{x}_{k+1} = \mathbf{W} \mathbf{x}_k$$

where index k corresponds to the iterate number.

Network to Matrix

$$\mathbf{x}_{k+1} = \mathbf{W}\mathbf{x}_k$$

But how should we define \mathbf{W} ?

**Sometimes in order to answer a question relating to a problem,
we must change the problem!**

$$\mathbf{p} = \mathbf{W}\mathbf{p}$$

**Instead of deciphering a general dynamical system,
let's examine a special case --- a fixed point!**

A Test Exemplar

Given some input pattern (or exemplar)

$$p = \left\{ \begin{array}{ccc} \oplus & \cdot & \cdot \\ \cdot & \oplus & \cdot \\ \cdot & \cdot & \oplus \end{array} \right\},$$

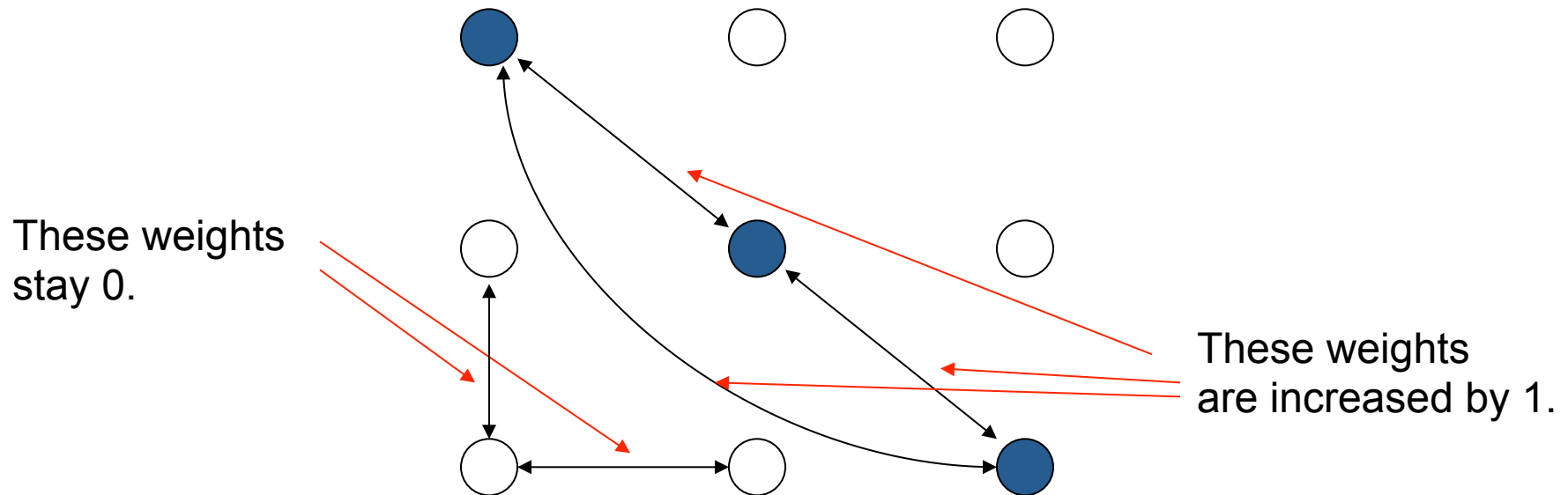
where $\oplus = \text{On}$ and $\cdot = \text{Off}$

We want to design a network that will converge to a set of exemplars given a partial or noisy representation of the exemplars.

Mutual Reinforcement ala Hebbian Learning

The ● represent a 1 input, the ○ represent a 0 input.

Initially, all weights are 0.



Note: This doesn't show all the edges (weights).

How can we model this mathematically?

Change the input pattern into a vector of 1's and 0's.

$$\begin{aligned}\mathbf{p}^T &= \{ \oplus \cdots | \cdot \oplus \cdot | \cdots \oplus \} \\ &= (100 \quad 010 \quad 001)\end{aligned}$$

Now we compute a matrix **W** such that **Wp = p**.

How should such a matrix be defined?

$$\mathbf{W} = ?$$

$$\mathbf{W} = \mathbf{I}?$$

Trivial and generic!

Hint: Must be somehow linked to the vector \mathbf{p} to facilitate the calculation
 $\mathbf{W}\mathbf{p} = \mathbf{p}.$

Can we create a matrix from the vector \mathbf{p} ?

$$\mathbf{pp}^T = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} (100010001) = \begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{pmatrix}$$

We will need to get rid of the 1's on the diagonal. Can't have a node reinforce itself. Why?

We will create/introduce a function Z which operates on matrices and sets diagonal elements to 0.

So let $\Delta \mathbf{W} = Z(\mathbf{p}\mathbf{p}^T)$ and

$$\mathbf{W}_{\text{new}} = \mathbf{W}_{\text{old}} + Z(\mathbf{p}\mathbf{p}^T)$$

We will also use a hard-limiting activation function: $F_h(x) = \begin{cases} 1, & \text{if } x > 0 \\ 0, & \text{if } x \leq 0 \end{cases}$

So does $\mathbf{W}_{\text{new}}\mathbf{p} = \mathbf{p}$?

What is the Z function?

- For any 1, 0 vector \mathbf{p} producing $\mathbf{p}\mathbf{p}^T$ we want to subtract a **modified identity matrix** to get rid of entries on the diagonal with a 1.

E.g., $\mathbf{p} = (1 \ 0 \ 1)$ then $\mathbf{p}\mathbf{p}^T =$

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

Thus we must subtract the $\mathbf{I}^* =$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Note the diagonal is the same as the vector \mathbf{p} and that $\mathbf{I}^*\mathbf{p} = \mathbf{p}$ for any \mathbf{p} .

Another example

$$p^T = (1 \ 0 \ 1 \ 0 \ 1) \text{ then } pp^T = \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \quad I^* = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\text{and } I^*p = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

Define $\Delta \tilde{\mathbf{W}} = \mathbf{p}\mathbf{p}^T$; hence $\Delta \mathbf{W} = Z(\mathbf{p}\mathbf{p}^T)$

$$\begin{aligned}\mathbf{W}_{\text{new}} &= \mathbf{W}_{\text{old}} + Z(\mathbf{p}\mathbf{p}^T) \\ &= \Delta \mathbf{W} + \mathbf{W}(0) \\ &= \Delta \mathbf{W}\end{aligned}$$

So does $F_h(\mathbf{W}_{\text{new}}\mathbf{p}) = \mathbf{p}$?

$$\begin{aligned}F_h(\mathbf{W}_{\text{new}}\mathbf{p}) &= F_h[\Delta \mathbf{W}\mathbf{p}] \\ &= F_h\left[\left(\Delta \tilde{\mathbf{W}} - \mathbf{I}_n^*\right)\mathbf{p}\right] \\ &= F_h\left[\Delta \tilde{\mathbf{W}}\mathbf{p} - \mathbf{p}\right] \\ &= F_h\left[\mathbf{p}\mathbf{p}^T\mathbf{p} - \mathbf{p}\right]\end{aligned}$$



$$\begin{aligned} F_h(\mathbf{W}_{\text{new}}\mathbf{p}) &= F_h[\mathbf{p}\mathbf{p}^T\mathbf{p} - \mathbf{p}] \\ &= F_h[d\mathbf{p} - \mathbf{p}] \\ &= F_h[(d-1)\mathbf{p}] \end{aligned}$$

where $\mathbf{p}^T\mathbf{p} = d$, a scalar equal to the number of 1's in the vector (do you see why?)

Note that $d \geq 1$ in non-trivial cases. Therefore, the above

$$= \mathbf{p}$$

What About Noisy Inputs?

$$I_3 = \sum_{j=1}^9 w_{3j} x_j \quad \text{with } w_{33} = 0. \quad \text{In general, } I_i = \sum_{j=1}^N w_{ij} x_j$$

for N = number of neurons = number of elements in a pattern.

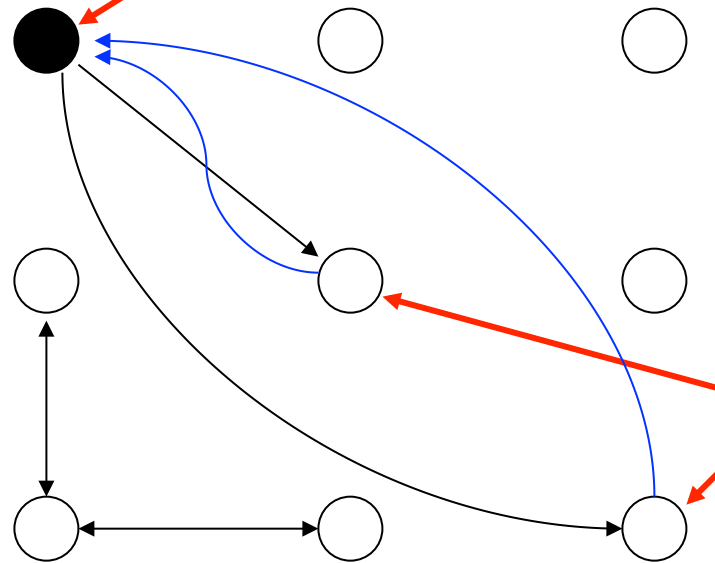
Now make a noisy version of the pattern p :

$$\tilde{p} = \left\{ \begin{array}{ccc} \oplus & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{array} \right\} = (100 \mid 000 \mid 000)^T$$

$$\mathbf{W}_{\text{new}} \tilde{\mathbf{p}} = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

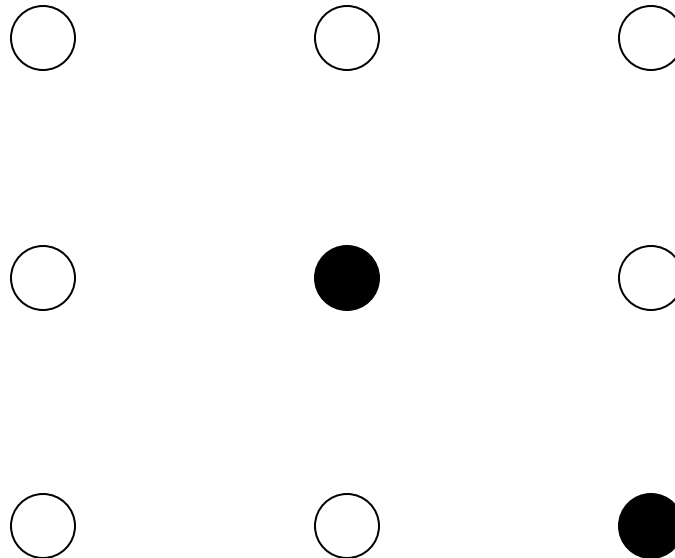
Putting this into F_h produces no change.

This “on” node turns on these other two nodes.



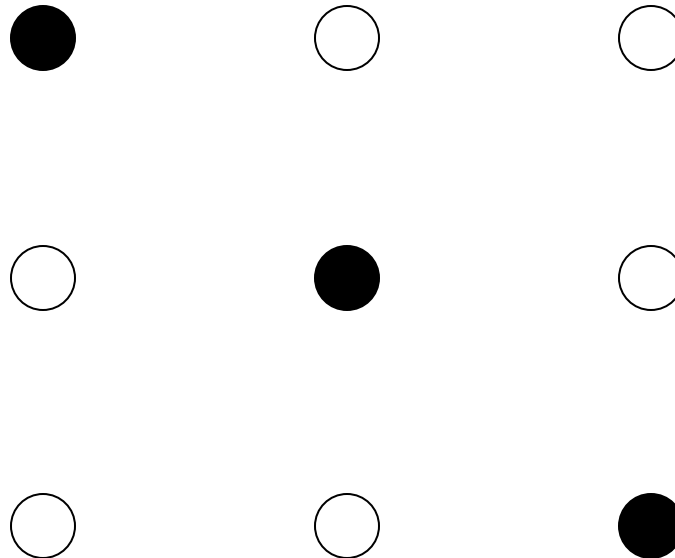
- These “off” nodes turn off the first “on” node.

The resulting pattern:



Now using this as the input in a second iteration, and using the same logic, we get

Our original pattern.



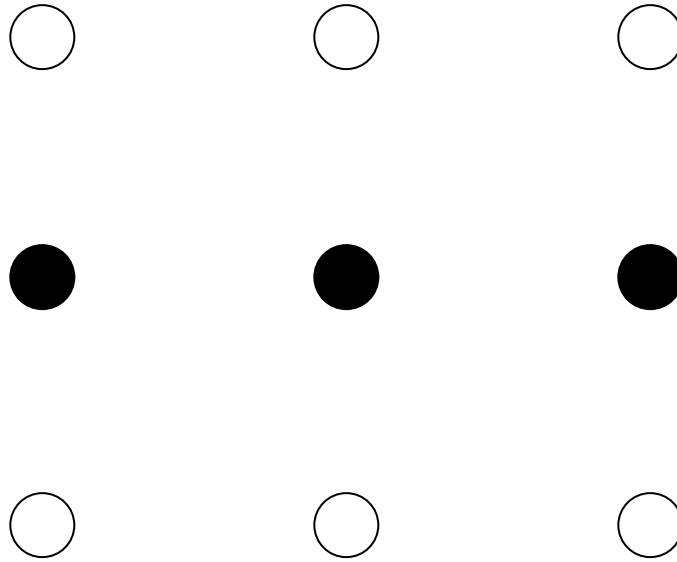


But hold on. Not all input patterns result in our “trained” pattern.

$$\mathbf{W} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \text{and in fact } \mathbf{W} \begin{pmatrix} 0 \\ \times \\ \times \\ \times \\ 0 \\ \times \\ \times \\ \times \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

This is because the 1 in the first vector was **not associated with** any 1 in the exemplar, hence, the other 0s turned this 1 to off (0).

What About Another Exemplar?


$$= \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Delta \mathbf{W} = \mathbf{Z}(\mathbf{q}\mathbf{q}^T)$$

$$\mathbf{q}\mathbf{q}^T = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} (000111000) = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$Z(\mathbf{q} \mathbf{q}^T) = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\mathbf{W}_{\text{new}} = \mathbf{W}_{\text{old}} + Z(\mathbf{q}\mathbf{q}^T) = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{pmatrix}$$

This system “knows” (is trained for) the two exemplars.

$$F_h(\mathbf{W}_{\text{new}} \tilde{\mathbf{p}}) = F_h \left(\begin{array}{ccc|cc|cc} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{array} \right) \left(\begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right) = \left(\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{array} \right)$$



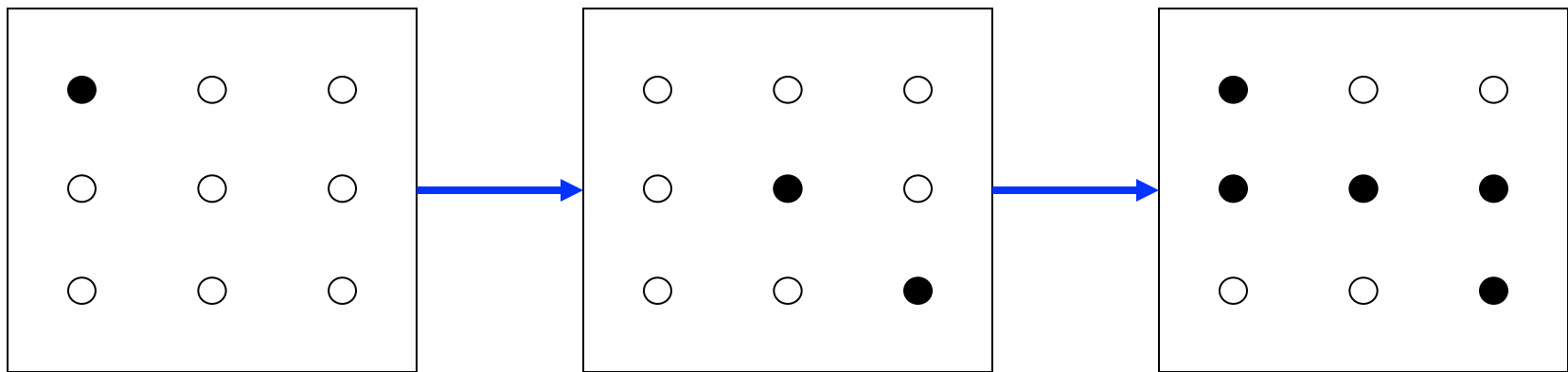
$$F_h(\mathbf{W}_{\text{new}} \tilde{\mathbf{p}}) = F_h \left(\begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right) = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

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$$F_h(\mathbf{W}_{\text{new}} \tilde{\mathbf{p}}_1) = F_h \begin{pmatrix} 2 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \tilde{\mathbf{p}}_2$$

$$F_h(\mathbf{W}_{\text{new}} \tilde{\mathbf{p}}_2) = F_h \left(\begin{array}{ccc|cc|cc} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{array} \right) \left(\begin{array}{c} 1 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 1 \end{array} \right) = \left(\begin{array}{c} 1 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 1 \end{array} \right)$$



All exemplar patterns “on”. This is an example of “heat death”.