## Problem 1:

$$V_{r} = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = \frac{1}{r^{2}} \frac{\cos \theta}{r^{2}}$$

$$V_{r} = \frac{1}{r^{2}} \frac{\partial \Psi}{\partial \theta} = \frac{1}{r^{2}} \frac{\sin \theta}{r^{2}}$$

$$V_{r} = \frac{1}{r^{2}} \frac{\partial \Psi}{\partial \theta} = \frac{1}{r^{2}} \frac{\sin \theta}{r^{2}}$$

$$f(0) = g(r) = 0$$

C is an arbitrary constant that we can set to zero.

$$\phi = \frac{n}{2\pi} \frac{\cos \theta}{r}$$

HW3\_P6

## Contents

- Plot the velocity field and equipotential lines: positive mu.
- Plot the velocity field and equipotential lines: negative mu.

```
clear
close all
clc
% Create r and theta vectors
r = linspace(1/2, 10, 50)';
theta = linspace(0,2*pi,51)';
% Create a grid of (r,theta) combinations
[R, Theta] = meshgrid(r,theta);
% Calculate V r and V theta
V r = -\cos(Theta)./R.^2;
V theta = -sin(Theta)./R.^2;
V_r_neg = cos(Theta)./R.^2;
V theta_neg = sin(Theta)./R.^2;
% Convert polar (r,theta) to Cartesian (x,y)
X = R.*cos(Theta);
Y = R.*sin(Theta);
% Find the matrix size of R and use for indices
[rows, cols] = size(R);
% Step through each (r,theta) combination
for i = 1:rows
    for j = 1:cols
         % Calculate the Cartesian velocity components using a
         % transformation matrix, Q:
         % Q = [cos(theta) -sin(theta)
                sin(theta) cos(theta)]
         % then,
         % [U; V] = Q*[V_r; V_theta]
         U(i,j) = V_r(i,j)*cos(Theta(i,j)) - V_theta(i,j)*sin(Theta(i,j));
         V(i,j) = V_r(i,j)*sin(Theta(i,j)) + V_theta(i,j)*cos(Theta(i,j));
         U_neg(i,j) = V_r_neg(i,j)*cos(Theta(i,j)) - V_theta_neg(i,j)*sin(Theta(i,j));
         V_{neg(i,j)} = V_{r_neg(i,j)} * sin(Theta(i,j)) + V_{theta_neg(i,j)} * cos(Theta(i,j));
     end
 end
 % Equipotential line calculations
theta = linspace(0,2*pi,1000)';
 C_1 = 1/2;
 C 2 = 1;
 C 3 = 2;
```

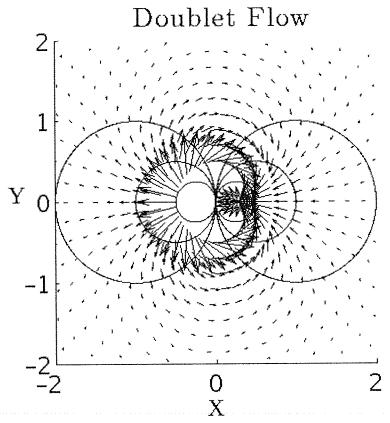
HW3\_P6

```
C 4 = -1/2;
C_5 = -1;
C_6 = -2;
r 1 = 1/C 1*cos(theta);
r 2 = 1/C_2*cos(theta);
r_3 = 1/C_3*cos(theta);
r_4 = 1/C_4 * cos(theta);
r 5 = 1/C 5*cos(theta);
r 6 = 1/C 6*cos(theta);
% Convert to Cartesian coordinates
[x_1,y_1] = pol2cart(theta,r_1);
[x_2,y_2] = pol2cart(theta,r_2);
[x 3,y 3] = pol2cart(theta,r_3);
[x_4,y_4] = pol2cart(theta,r_4);
[x_5,y_5] = pol2cart(theta,r_5);
[x_6,y_6] = pol2cart(theta,r_6);
```

## Plot the velocity field and equipotential lines: positive mu.

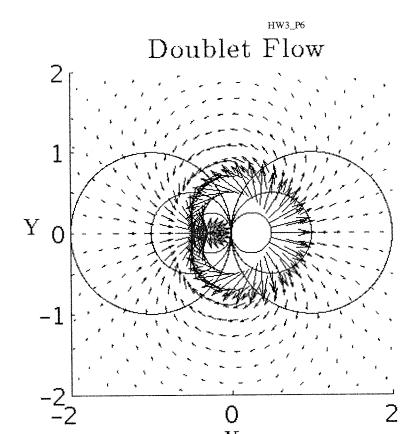
```
figure
set(gcf, 'DefaultAxesfontsize',24, 'DefaultAxesfontname', 'TimesNewRoman', 'DefaultAxesGridLineSty
le','-.')
num = 1;
hold on
    plot(x_1,y_1,'-k','LineWidth',num)
    plot(x_2,y_2,'-k','LineWidth',num)
    plot(x_3,y_3,'-k','LineWidth',num)
    plot(x_4,y_4,'-k','LineWidth',num)
    plot(x 5, y 5, '-k', 'LineWidth', num)
    plot(x_6,y_6,'-k','LineWidth',num)
    quiver(X,Y,U,V,'k')
hold off
axis equal
axis([-2 \ 2 \ -2 \ 2])
title('Doublet Flow','Interpreter','Latex','FontName','TimesNewRoman','FontSize',28)
xlabel('X','Interpreter','Latex','FontName','TimesNewRoman','FontSize',24)
ylabel('Y','Interpreter','Latex','FontName','TimesNewRoman','FontSize',24,'Rotation',0)
print('-depsc', '-r600', 'Doub_Flow_Pos.eps');
```

9/30/13 HW3\_P6



## Plot the velocity field and equipotential lines: negative mu.

```
figure
set(gcf, 'DefaultAxesfontsize',24,'DefaultAxesfontname', 'TimesNewRoman', 'DefaultAxesGridLineSty
le','-.')
num = 1;
hold on
    plot(x_1,y_1,'-k','LineWidth',num)
    plot(x_2,y_2,'-k','LineWidth',num)
    plot(x_3,y_3,'-k','LineWidth',num)
    plot(x_4,y_4,'-k','LineWidth',num)
    plot(x_5,y_5,'-k','LineWidth',num)
    plot(x_6,y_6,'-k','LineWidth',num)
    quiver(X,Y,U_neg,V_neg,'k')
hold off
axis equal
axis([-2 \ 2 \ -2 \ 2])
title('Doublet Flow', 'Interpreter', 'Latex', 'FontName', 'TimesNewRoman', 'FontSize', 28)
xlabel('X', 'Interpreter', 'Latex', 'FontName', 'TimesNewRoman', 'FontSize', 24)
ylabel('Y','Interpreter','Latex','FontName','TimesNewRoman','FontSize',24,'Rotation',0)
print('-depsc', '-r600', 'Doub_Flow_Neg.eps');
```



Published with MATLAB® R2013a

Home work #5: Solutions

Problem 1

Follow Anderson text from page 200-273 or follow Knethe text from page 104-106

$$V_{\theta} = -\frac{\delta 4}{\delta r} = -U_{\infty} \sin \theta + \frac{1}{2\pi r}$$

$$2\pi r = -\frac{R}{2\pi u_{\infty} \sin \theta} = -\frac{\Gamma}{2\pi u_{\infty} \sin \theta}$$

There is one stagnation point 
$$G$$
  $(r,o) = \left(\frac{\Gamma}{2\pi \mu_{00}}\right)^{-\frac{T}{2}}$ 

- (b) The velocity of a vertex, Vo, decays as F gets larger. At some point r, the velocity from the vertex will be larger enough to cancel the free-stream velocity at a point (Stag. pt.). If the flow speed is transfer increased then the Stagnation point should move obser to the vertex care. Equally if the vertex strength is increased we would expect the Vo to be greater at some location r and the stagnation point should move away from the vertex care.
- (c) Stagration streamline equation:

$$\begin{aligned}
\Psi &= U_{\infty} \Gamma \sin \theta + \frac{\Gamma}{2\pi} \ln \Gamma \quad \Theta \left( \Gamma, 0 \right) = \left( \frac{\Gamma}{2\pi} U_{\infty} \right) - \frac{T}{2} \\
\Psi &= Y_{\infty} \left( \frac{\Gamma}{2\pi V_{\infty}} \right) \frac{1}{2\pi} \left( \frac{\Gamma}{2\pi} \right) + \frac{\Gamma}{2\pi} \ln \left( \frac{\Gamma}{2\pi V_{\infty}} \right) \\
\Psi &= -\frac{\Gamma}{2\pi} + \frac{\Gamma}{2\pi} \ln \left( \frac{\Gamma}{2\pi V_{\infty}} \right) \\
\Psi &= \frac{\Gamma}{2\pi} \left[ \ln \left( \frac{\Gamma}{2\pi V_{\infty}} \right) - 1 \right] = Constant
\end{aligned}$$

The stagnation streamline follows the relationship:

$$U_{\infty} r sine + \frac{\Gamma}{2\pi r} lnr - \frac{\Gamma}{2\pi r} \left[ ln \left( \frac{\Gamma}{2\pi r loo} \right) - 1 \right] = 0$$

$$e = sin^{-1} \left\{ \frac{\Gamma'}{2\pi r loor} \left[ ln \left( \frac{\Gamma}{2\pi r loo} \right) - 1 \right] - \frac{\Gamma'}{2\pi llor} lnr \right\} \right]$$

given r > find o

(d) Using Bernoulli: 
$$P_{\infty} + \frac{1}{2}\rho U_{0}^{2} = P(r,e) + \frac{1}{2}\rho \left(V_{r}^{2} + V_{e}^{2}\right)$$

$$P(r,e) = P_{\infty} + \frac{1}{2}\rho U_{0}^{2} - \frac{1}{2}\rho \left[U_{\infty}^{2}\cos^{2}\theta + U_{\infty}^{2}\sin^{2}\theta + \frac{2U_{0}\Gamma}{2\pi r}\sin^{2}\theta + \frac{\Gamma^{2}}{4\pi^{2}r^{2}}\right]$$

$$P(r,e) = P_{\infty} + \frac{1}{2}\rho U_{\infty}^{2} - \frac{1}{2}\rho U_{\infty}^{2} - \frac{\rho U_{\infty}\Gamma}{2\pi r}\sin^{2}\theta - \frac{\rho \Gamma^{2}}{8\pi^{2}r^{2}}$$

$$P(r,e) = P_{\infty} - \frac{\rho U_{\infty}\Gamma}{2\pi r}\sin^{2}\theta - \frac{\rho \Gamma^{2}}{8\pi^{2}r^{2}}$$