

1) If we convert the affine geodesic equation to one with respect to λ , we get

$$\frac{D}{d\sigma} \frac{dx^\mu}{d\sigma} = \frac{d\lambda}{d\sigma} \frac{D}{d\lambda} \left(\frac{dx^\mu}{d\lambda} \frac{d\lambda}{d\sigma} \right) = \frac{d\lambda}{d\sigma} \left(\frac{D}{d\lambda} \left(\frac{dx^\mu}{d\lambda} \right) \frac{d\lambda}{d\sigma} + \frac{D}{d\lambda} \left(\frac{d\lambda}{d\sigma} \right) \frac{dx^\mu}{d\lambda} \right) = \left(\frac{d\sigma}{d\lambda} \right)^{-1} \left(\alpha(\lambda) \frac{dx^\mu}{d\lambda} \left(\frac{d\sigma}{d\lambda} \right)^{-1} + \frac{dx^\mu}{d\lambda} \left(\frac{d\sigma}{d\lambda} \right)^{-2} \frac{d^2\sigma}{d\lambda^2} \right) = 0$$

where the last step above uses the first equation and writes all terms with respect to λ .

Define $g(\lambda) \equiv \frac{d\sigma}{d\lambda}$ and rewrite the equation above as $0 = \frac{1}{g(\lambda)} \left(\frac{\alpha(\lambda)}{g(\lambda)} + \frac{1}{(g(\lambda))^2} \frac{dg}{d\lambda} \right) \frac{dx^\mu}{d\lambda}$.

Thus, $\frac{\alpha(\lambda)}{g(\lambda)} + \frac{1}{(g(\lambda))^2} \frac{dg}{d\lambda} = 0$ and $\alpha(\lambda) g(\lambda) = \frac{dg}{d\lambda}$. Solving for $g(\lambda)$, $\frac{dg}{g} = \alpha d\lambda \Rightarrow \int \frac{dg}{g} = \int \alpha d\lambda$

$\ln g = \int \alpha d\lambda + C \Rightarrow g = C e^{\int \alpha d\lambda}$. Now remember that $g(\lambda) = \frac{d\sigma}{d\lambda}$, so integrating once again,

$\sigma(\lambda) = C \int \left(e^{\int \alpha(\lambda) d\lambda} \right) d\lambda$ where C is an arbitrary constant. This works for any function $\alpha(\lambda)$, so this proves $\sigma(\lambda)$ can always exist.

2) a) For a point p on the surface of a unit sphere with an orthonormal tangent vector \hat{k}^μ , you can form a great curve using the parameterization of a circle. Here, $x^\mu(\lambda) = \cos \lambda p^\mu + \sin \lambda \hat{k}^\mu$. To check if this behavior is expected, consider $x^\mu(0) = p^\mu$. This motivates mapping p^μ as x and \hat{k}^μ as y for a unit circle. Now to prove $x^\mu(\lambda)$ is a geodesic, evaluate $\frac{d^2 x^\mu}{d\lambda^2} = -\cos \lambda p^\mu - \sin \lambda \hat{k}^\mu = -x^\mu(\lambda)$. This means $\frac{d^2 x^\mu}{d\lambda^2}$ is proportional to $x^\mu(\lambda)$ itself, which is a curve of vectors normal to the surface of the sphere, meaning $\frac{d^2 x^\mu}{d\lambda^2}$ has no tangential component and $x^\mu(\lambda)$ is a geodesic of the sphere.

To summarize, $x^\mu(\lambda) = \cos \lambda p^\mu + \sin \lambda \hat{k}^\mu$ describes a great curve on a sphere and is the geodesic for point p

b) The metric for the surface of a unit sphere is $ds^2 = d\theta^2 + \sin^2 \theta d\varphi^2$. Mapping this to Euclidean space, $x = \sin \theta \cos \varphi$ and $y = \sin \theta \sin \varphi$. Evaluating in a local space around the north pole ($\theta = 0$) allows us to use the first-order approximation $\sin \theta \approx \theta$ to define local RNC. Thus, $x \approx \theta \cos \varphi$ and $y \approx \theta \sin \varphi$, so $dx = d\theta \cos \varphi - d\varphi \theta \sin \varphi$ and $dy = d\theta \sin \varphi + d\varphi \theta \cos \varphi$. Therefore,

$$dx^2 + dy^2 = d\theta^2 \cos^2 \varphi + d\varphi^2 \theta^2 \sin^2 \varphi - d\theta d\varphi \theta \cos \varphi \sin \varphi + d\theta^2 \sin^2 \varphi + d\varphi^2 \theta^2 \cos^2 \varphi + d\theta d\varphi \theta \cos \varphi \sin \varphi$$

$$= d\theta^2 + \theta^2 d\varphi^2. \text{ Note that } x = \theta \cos \varphi \text{ and } y = \theta \sin \varphi \text{ form a polar mapping, so referring}$$

$$\text{back to the spherical coordinates, } ds^2 = d\theta^2 + \sin^2 \theta d\varphi^2 = dx^2 + dy^2 + (\sin^2 \theta - \theta^2) d\varphi^2$$

$$\approx dx^2 + dy^2 + \left(\theta^2 - \frac{2\theta^4}{6} + \mathcal{O}(\theta^6) - \theta^2 \right) d\varphi^2 = dx^2 + dy^2 - \frac{\theta^4}{3} d\varphi^2 + \mathcal{O}(\theta^6) d\varphi^2. \text{ Note that } \theta^2 = x^2 + y^2$$

$$\text{and } (x dy - y dx) = \theta^2 d\varphi, \text{ so } d\varphi^2 = \frac{(x dy - y dx)^2}{(x^2 + y^2)^2} \text{ and } -\frac{\theta^4}{3} d\varphi^2 = -\frac{(x^2 + y^2)^2}{3} \frac{(x dy - y dx)^2}{(x^2 + y^2)^2} = -\frac{(x dy - y dx)^2}{3}$$

Therefore, spherical $ds^2 = dx^2 + dy^2 - \frac{1}{3} (x dy - y dx)^2$, which is Euclidean space with quadratic terms ($dx^2, dx dy, dy^2$)

3) Using the diagonal Christoffel equations (3.213)-(3.216), and the metric $g = \begin{pmatrix} -r^2 & 0 \\ 0 & 1/r^2 \end{pmatrix}$, we have

$$\Gamma_{tt}^r = -\frac{1}{2} (g_{rr})^{-1} \partial_r g_{tt} = -\frac{1}{2} r^2 \frac{\partial}{\partial r} (-r^2) = r^3$$

$$\Gamma_{rr}^t = -\frac{1}{2} (g_{tt})^{-1} \partial_t g_{rr} = -\frac{1}{2} \left(-\frac{1}{r^2} \right) \frac{\partial}{\partial t} \left(\frac{1}{r^2} \right) = 0$$

$$\Gamma_{tr}^r = \Gamma_{rt}^r = \partial_t (\ln \sqrt{|g_{rr}|}) = \frac{\partial}{\partial t} \ln \frac{1}{r} = 0$$

$$\Gamma_{rt}^t = \Gamma_{tr}^t = \partial_r (\ln \sqrt{|g_{tt}|}) = \frac{\partial}{\partial r} \ln r = \frac{1}{r}$$

$$\Gamma_{rr}^r = \partial_r (\ln \sqrt{|g_{rr}|}) = \frac{\partial}{\partial r} \ln \frac{1}{r} = -\frac{\partial}{\partial r} \ln r = -\frac{1}{r}$$

$$\Gamma_{tt}^t = \partial_t (\ln \sqrt{|g_{tt}|}) = \frac{\partial}{\partial t} \ln r = 0$$

To find the Riemann tensor, we use (3.113).

$$R^r_{t r t} = \partial_r \Gamma^r_{t t} - \partial_t \Gamma^r_{t r} + \Gamma^r_{\lambda t} \Gamma^{\lambda}_{t t} - \Gamma^r_{t \lambda} \Gamma^{\lambda}_{t t} = \partial_r \Gamma^r_{t t} - \cancel{\partial_t \Gamma^r_{t r}} + \Gamma^r_{r t} \Gamma^r_{t t} - \cancel{\Gamma^r_{t r} \Gamma^r_{t t}} + \cancel{\Gamma^r_{t t} \Gamma^t_{t t}} - \cancel{\Gamma^r_{t t} \Gamma^t_{t t}}$$

$$= \partial_r r^3 + \left(-\frac{1}{r}\right)(r^3) - (r^3)\left(\frac{1}{r}\right) = 3r^2 - r^2 - r^2 = r^2$$

If we then consider symmetries, it helps to lower the first index, so

$$R_{r t r t} = g_{r \lambda} R^{\lambda}_{t r t} = g_{r r} R^r_{t r t} + \cancel{g_{t t} R^t_{t r t}} = \left(\frac{1}{r^2}\right)(r^2) = 1$$

Since $R_{\mu\nu\sigma\tau} = R_{\sigma\tau\mu\nu} = -R_{\tau\sigma\nu\mu}$, $R_{t t r r} = R_{r r t t} = -R_{r t r t} = -1$ ($R_{\mu\nu\sigma\tau} = R_{\sigma\tau\mu\nu}$)

Also, $R_{\tau[\sigma\mu\nu]} = 0$, so $R_{r t r t} + R_{r r t t} + R_{t t r r} = 1 + R_{r r t t} - 1 = 0$. Thus, $R_{r r t t} = R_{t t r r} = 0$

Finally, the same cyclic equation means $R_{t r t r} = -R_{t r r t} - R_{t r r t} = 1$

Therefore, $R^t_{r t r} = g^{t t} R_{t r t r} = -\frac{1}{r^2}$

$$R^r_{t t r} = -R^r_{t r t} = -r^2$$

$$R^t_{r r t} = -R^t_{r t r} = \frac{1}{r^2}$$

$$R^r_{t t t} = R^t_{t r r} = 0$$

and all Riemann tensors with more than 2 r or t terms evaluate to zero due to the symmetry of the Christoffel symbols or the Riemann tensor definition.

Now, the Ricci tensor is given as $R_{\mu\nu} = R^{\lambda}_{\mu\lambda\nu}$, so $R_{rr} = R^{\lambda}_{r\lambda r} = \cancel{R^r_{r r r}} + R^t_{r t r} = -\frac{1}{r^2}$

$R_{rt} = R_{tr} = R^{\lambda}_{r\lambda t} = 0$ and $R_{tt} = R^{\lambda}_{t\lambda t} = R^r_{t r t} + \cancel{R^t_{t t t}} = r^2$

so the Ricci tensor is $R_{\mu\nu} = \begin{pmatrix} r^2 & 0 \\ 0 & -1/r^2 \end{pmatrix}$

Finally, the Ricci Scalar is given as $R = R^{\mu}_{\mu} = g^{\mu\nu} R_{\mu\nu} = g^{rr} R_{rr} + \cancel{2g^{rt} R_{rt}} + g^{tt} R_{tt}$

$$= (r^2) \left(-\frac{1}{r^2}\right) + \left(-\frac{1}{r^2}\right)(r^2) = -2$$