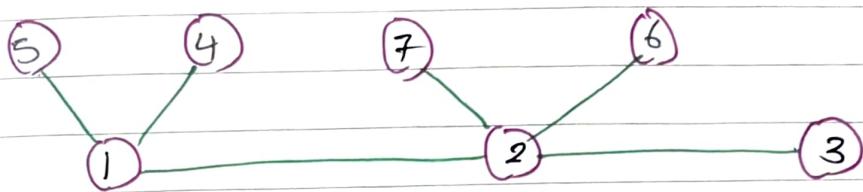


## AI Unit 2

→ BFS and DFS

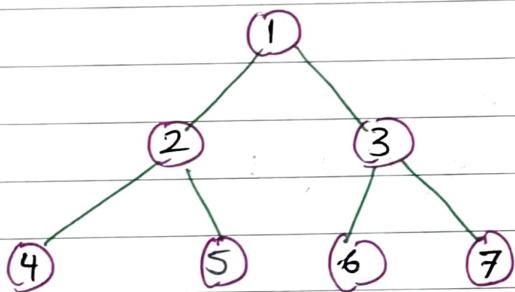
1]



BFS: 1, 2, 4, 5, 3, 7, 6

DFS: 1, 2, 3, 4, 6, 7, 4, 5

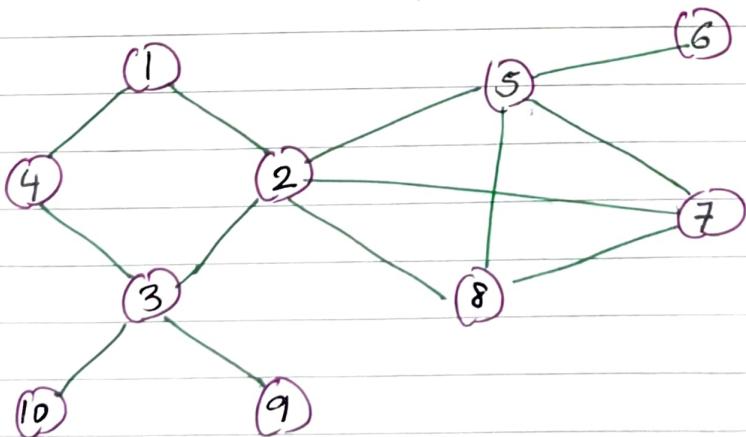
2]



BFS: 1, 2, 3, 4, 5, 6, 7 [Level order]

DFS: 1, 2, 4, 5, 3, 6, 7 [Preorder]

3]

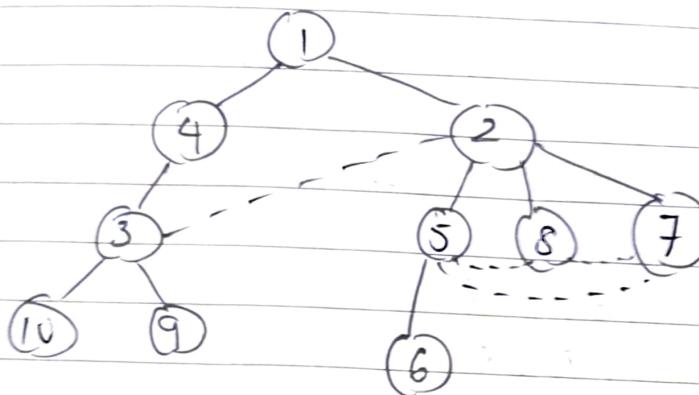


BFS:

Queue:  $\boxed{1 \ 4 \ 2 \ 3 \ 5 \ 7 \ 8 \ 10 \ 9 \ 6}$

Ans: 1, 4, 2, 3, 5, 7, 8, 10, 9, 6

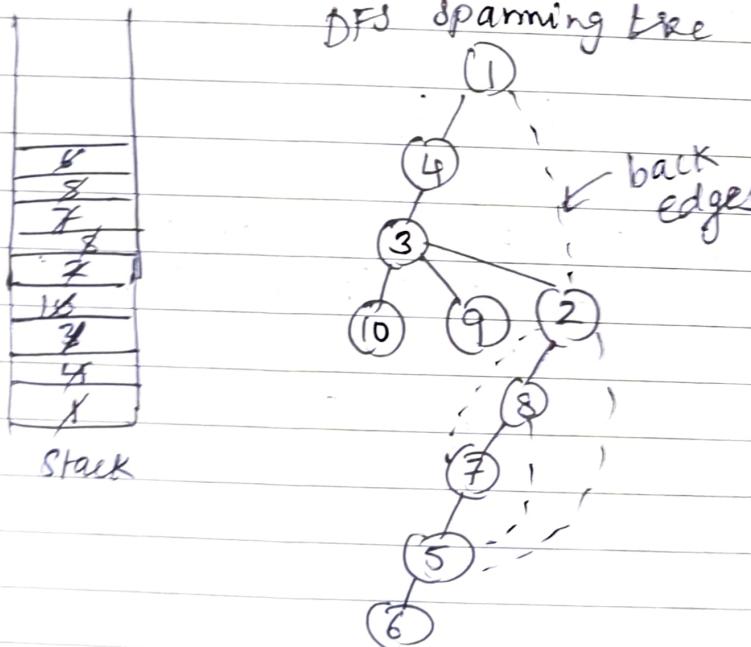
BFS Spanning tree:



DFS:

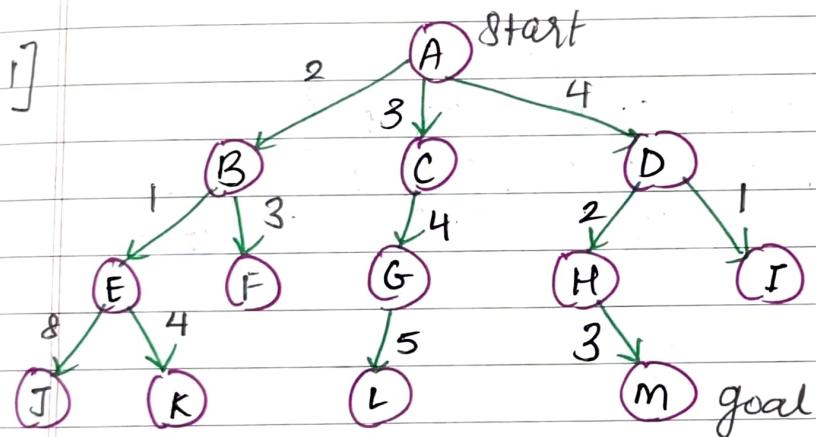
Ans: 1, 4, 3, 10, 9, 2, 8, 7, 5, 6

DFS Spanning tree

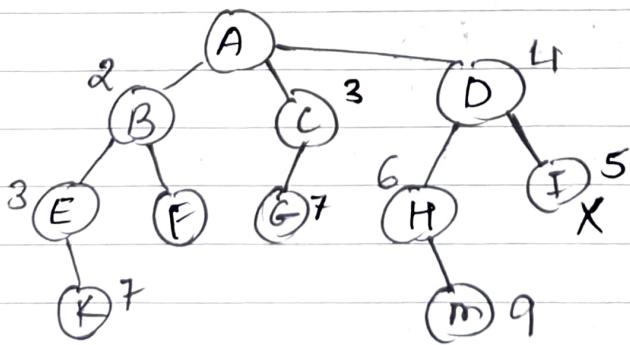


### → Uniform Cost Search

- 1] Optimal solution when costs are non-negative
- 2] Priority queue is used (min heap).
- 3] It is an uninformed search algorithm
- 4] Used to find the least-cost path from a start to goal node in a weighted graph.
- 5] Variant of Dijkstra's algorithm.
- 6] Explores nodes with **lowest cumulative cost first**.
- 7] The optimal solution is not guaranteed within reasonable time and can get stuck in an infinite loop.

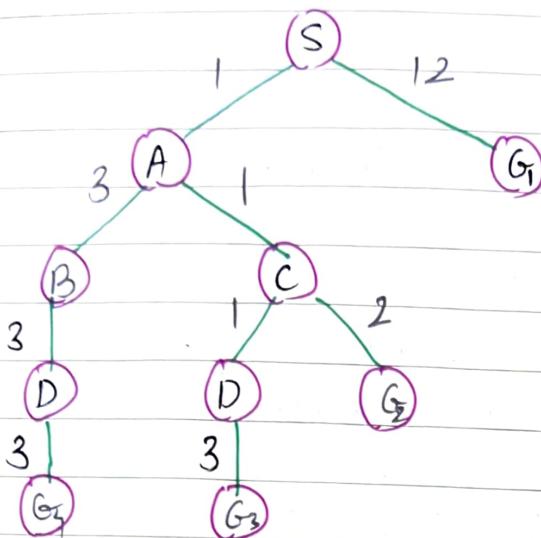


~~Open PQ: (B, 2), (C, 3), (D, 4), (E, 3), (F, 5), (J, 11), (K, 7), (G, 7), (H, 6), (I, 5), (M, 9), (L, 12)~~



$A \rightarrow D \rightarrow H \rightarrow M$       cost = 9.

2]



Initialization:  $\{(S, 0)\}$

Iteration 1:  $\{(A, 1), (G_1, 12)\}$

Iteration 2:  $\{(B, 4), (C, 2), (G_1, 12)\}$

Iteration 3:  $\{(B_1, 4), (D, 3), (G_2, 4), (G_1, 12)\}$

Iteration 4:  $\{(B_1, 4), (G_3, 6), (G_2, 4), (G_1, 12)\}$

Iteration 5:

$\therefore$  Ans:  $S \rightarrow A \rightarrow C \rightarrow G_2$

### $\rightarrow$ A\* Algorithm

1] Informed searching technique (or heuristic)

2] Informed search means that there is prior knowledge of the problem, this knowledge is called **heuristic value**. The goal state is kept into consideration.

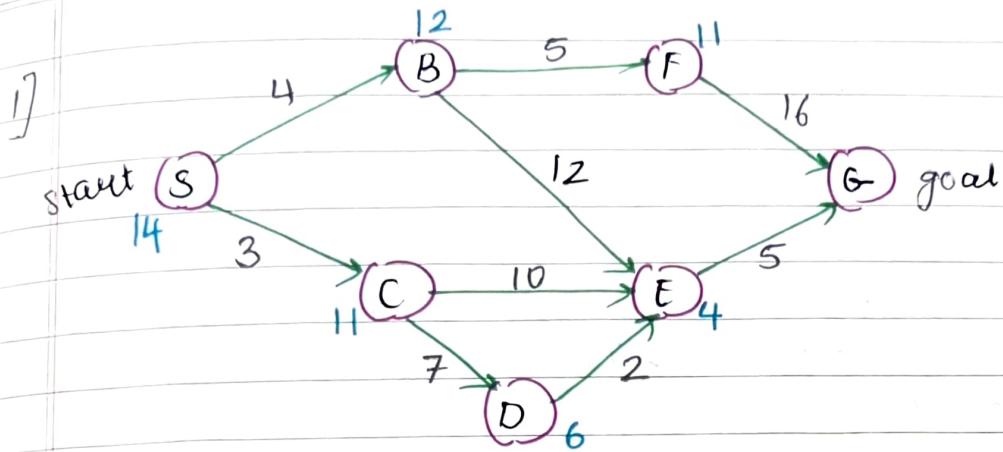
$$f(N) = g(N) + h(N)$$

$\downarrow$   
Actual cost  
from start  
node to n

$\downarrow$   
Estimation cost  
from n to  
goal node

4] It is an admissible algorithm i.e. an optimal solution is guaranteed.

$$5] T.C. = O(V+E) \text{ or } O(b^d)$$



$$f(S) = 0 + 14 = 14$$

$$S \rightarrow B : f(B) = 4 + 12 = 16 \checkmark$$

$$S \rightarrow C : f(C) = 3 + 11 = 14 \checkmark$$

$$SC \rightarrow E : f(E) = 3 + 10 + 4 = \cancel{17}$$

$$SC \rightarrow D : f(D) = 3 + 7 + 6 = \cancel{16} 16 \checkmark$$

$$SB \rightarrow F : f(F) = 4 + 5 + 11 = 20$$

$$SB \rightarrow E : f(E) = 4 + 12 + 4 = \cancel{20}$$

$$SCD \rightarrow E : f(E) = 3 + 7 + 2 + 4 = 16 \checkmark$$

$$SCDE \rightarrow G : f(G) = 3 + 7 + 2 + 5 = 17 \rightarrow \text{Min value.}$$

$\therefore$  Path =  $S \rightarrow C \rightarrow D \rightarrow E \rightarrow G$

→ How to make A\* admissible

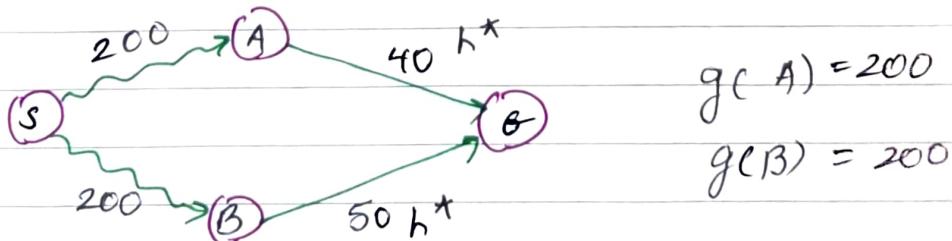
1]  $h(n) \leq h^*(n)$  - underestimation

$h(n) \geq h^*(n)$  - overestimation

Here,

$h(n)$  - estimated value

$h^*(n)$  - actual/optimal value.



### case I: overestimation

$$h(A) = 80 \quad f > h^*$$

$$h(B) = 70$$

$$f(A) = 200 + 80 = 280$$

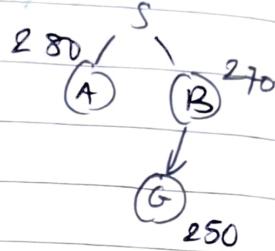
$$f(B) = 200 + 70 = 270$$

$$f(G) = g(G) + h(G)$$

$$g(G) = 200 + 50 = 250$$

$$\therefore f(G) = 250 + 0 = 250.$$

$250 \not> 270 \rightarrow$  overestimation



### Case II: underestimation

$$h(A) = 30$$

$$h(B) = 20$$

$$f(A) = 200 + 30 = 230$$

$$f(B) = 200 + 20 = 220$$

$$g(G) = 200 + 50 = 250$$

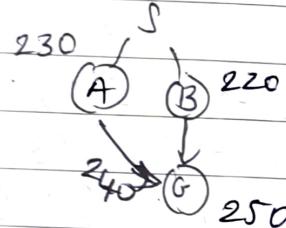
$$f(G) = 250 + 0 = 250$$

~~250~~ through B.  $250 > 220, 230$ .

$$f(G) = 200 + 40 = 240$$

↳ through A

$\therefore S \rightarrow A \rightarrow G$

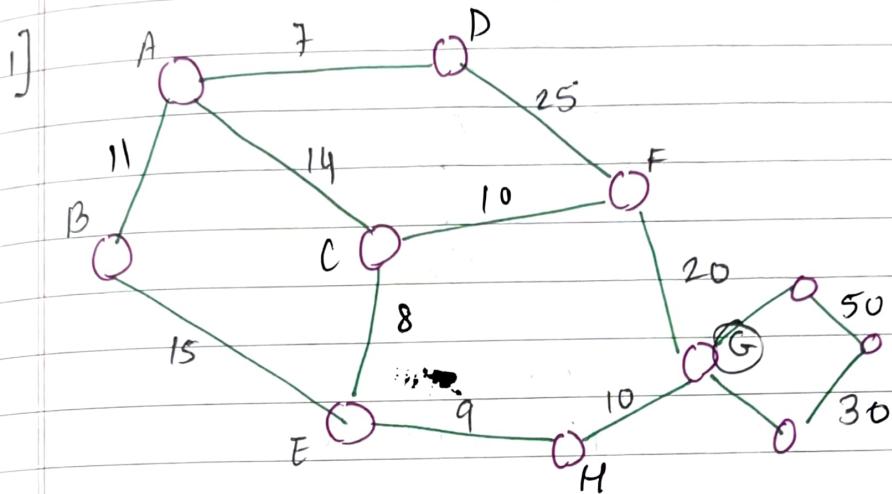


**Conclusion:** Use underestimation for accurate results than and more optimal solution.

## → Greedy Best First Search Algorithm

i] Informed, Heuristic algorithm

ii]  $f(n) = h(n)$ .



Straight Line dist.  $= \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$

$$A \rightarrow G = 40$$

$$B \rightarrow G = 32$$

$$C \rightarrow G = 25$$

$$D \rightarrow G = 35$$

$$E \rightarrow G = 19$$

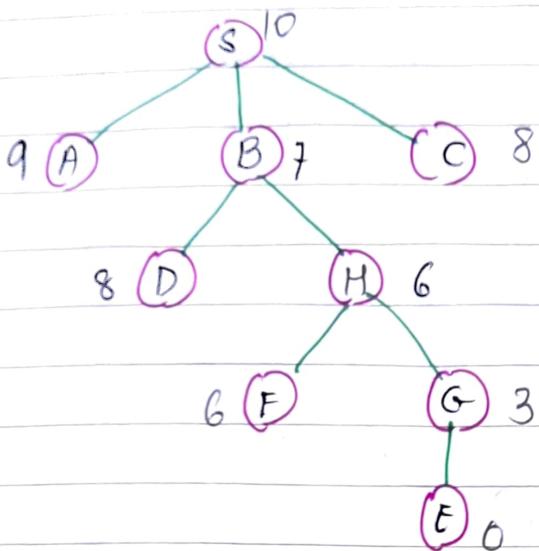
$$F \rightarrow G = 17$$

$$H \rightarrow G = 10$$

$$G \rightarrow G = 0$$

Answer:  $A \rightarrow C \rightarrow F \rightarrow G$

2]



open

Node h(h)

1. S 10

closed

Node parent

	S	
2.	-	S
A	9	
B	7 ✓	
C	8	

3. B S

C	8
A	9
H	6 ✓
D	8

4. ← 8 H B

B	8
D	8
A	9

G	3 ✓
F	6

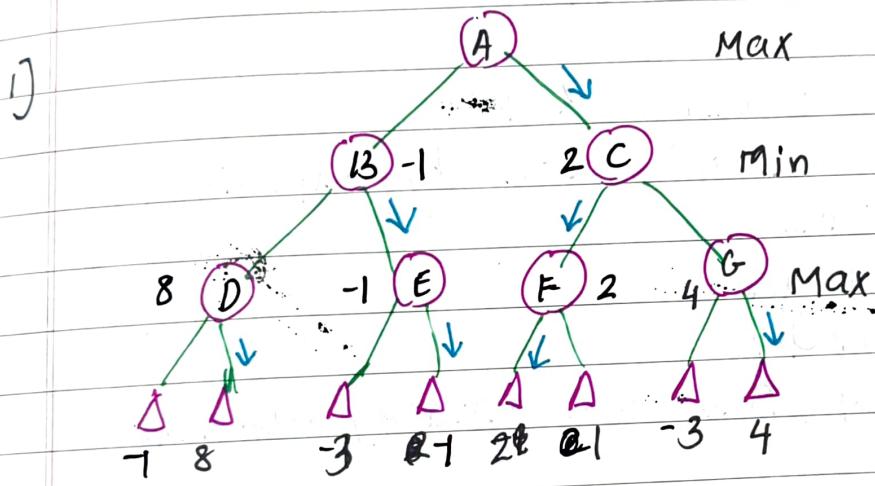
5. F 6 G H

D	8
A	9
E	0 ✓

Answer: S → B → H → G → E

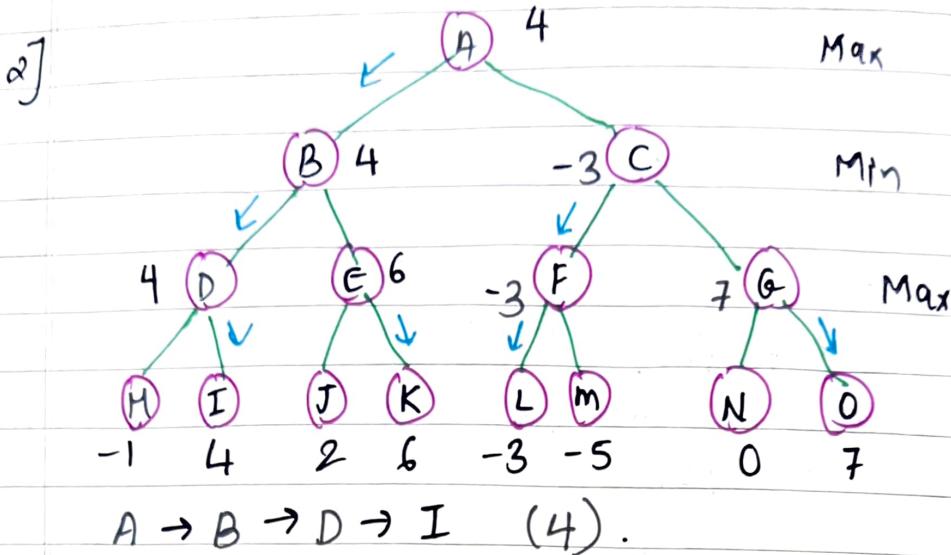
## → Minimax Algorithm

- 1] Back tracking algorithm
  - 2] Best move strategy used
  - 3] Max → Best move (maximize utility)
  - 4] Min → worst move (minimize utility)
  - Time complexity:  $O(b^d)$
- b - branching factor (no. of possible children).  
d - depth



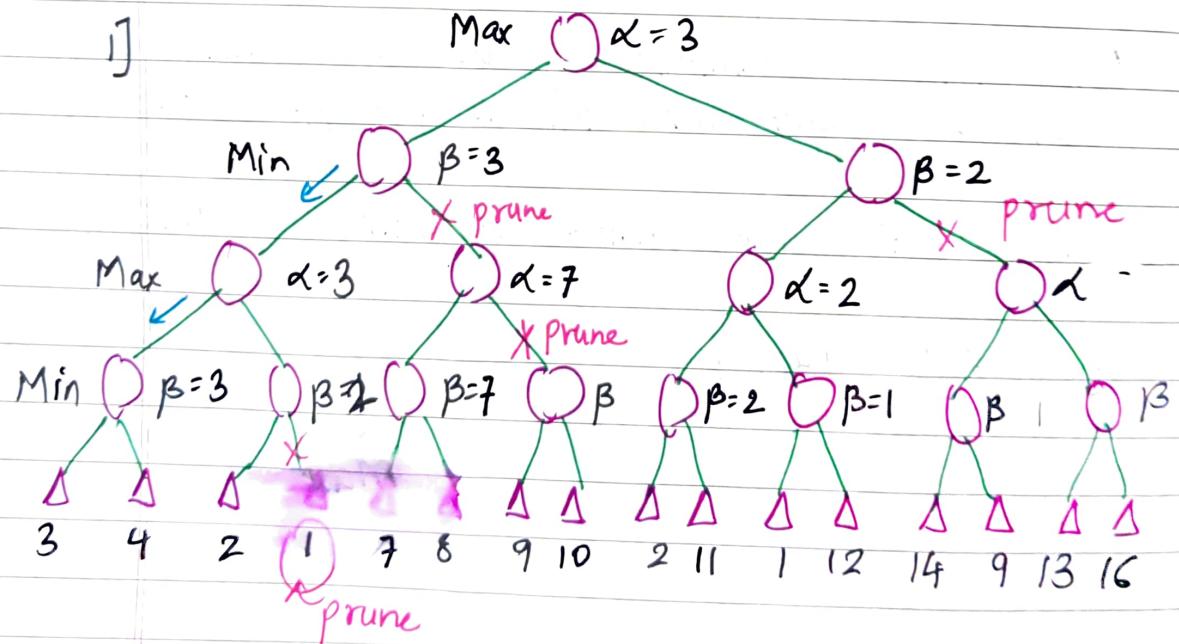
\* Min tried to minimize your own utility so that you can't win. Min is the opponent.

$A \rightarrow C \rightarrow F$  (guaranteed of getting 2 utility).



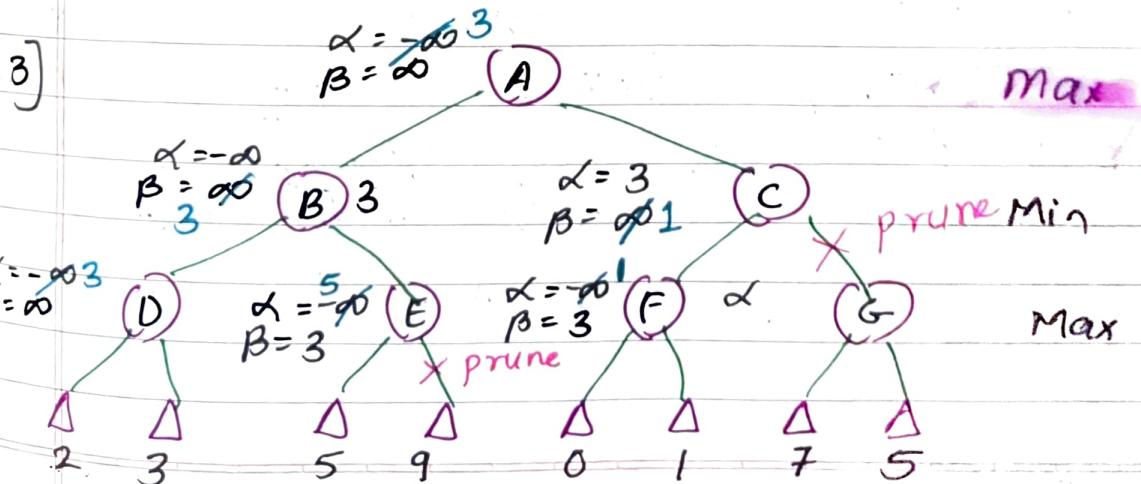
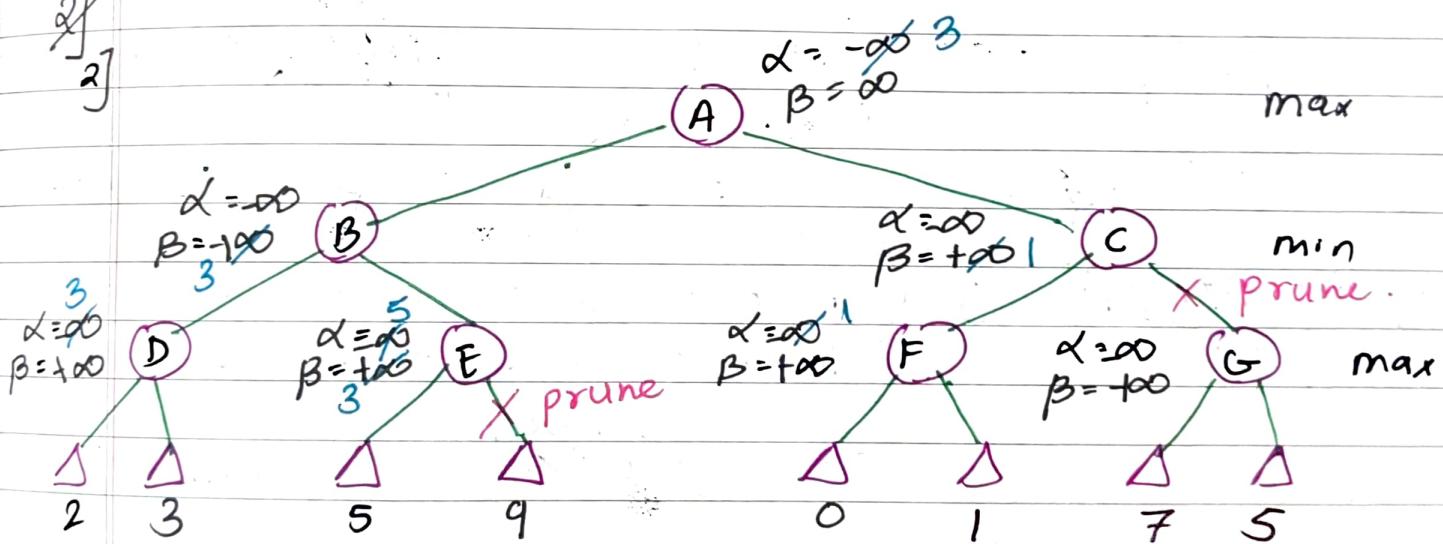
→ Alpha Beta Pruning ( $\alpha - \beta$ )

- 1] It helps to cut off search by exploring less no. of nodes.
- 2)  $\alpha$  - Max nodes  
 $\beta$  - Min nodes.
- 3] Backtracking, Best move strategy algorithm.

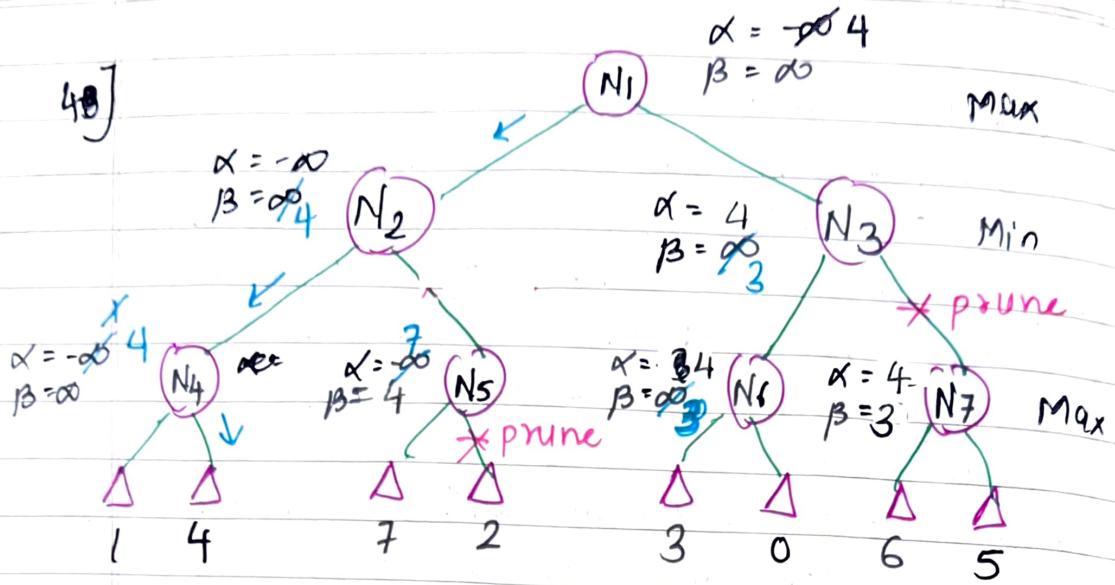


Pruning condition:  $\alpha \geq \beta$

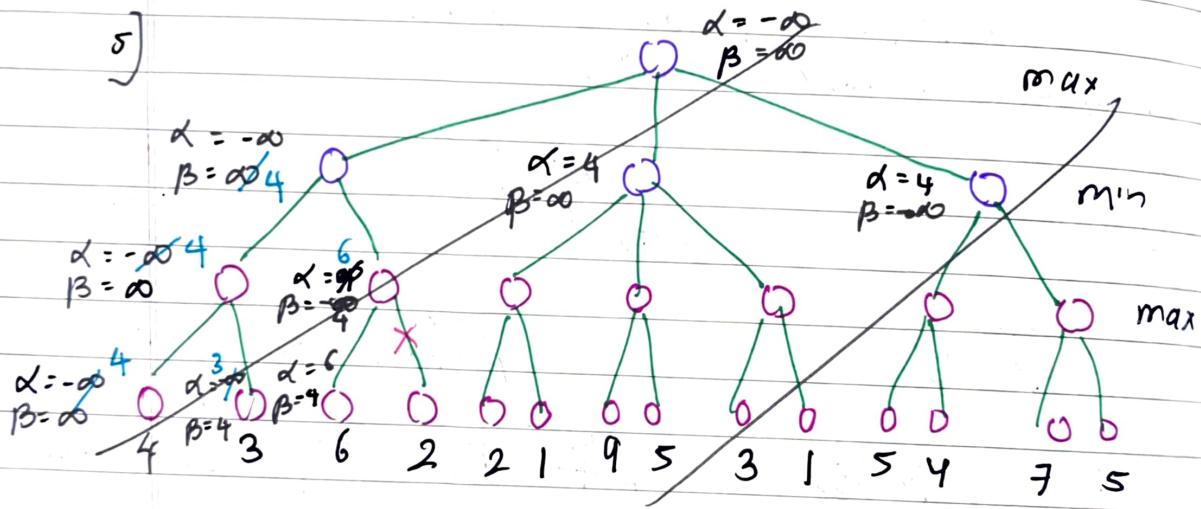
- 1] If (Max, Min) is not given start from Max at root.
- 2] Give  ~~$\alpha = -\infty$~~ ,  $\beta = \infty$  from root and keep giving some values to the left child.
- 3] Fill the entire leftmost tree with these values.
- 4] Change  $\alpha$  values at max level and  $\beta$  values at min level.
- 5] Start from the leaf node and of leftmost tree, check its left child compare acc. to the level and update with respective value then compare the right child & update.
- 6] If  $\alpha \geq \beta$ , then prune the path.
- 7] Time complexity =  $O(b^{d/2})$ .



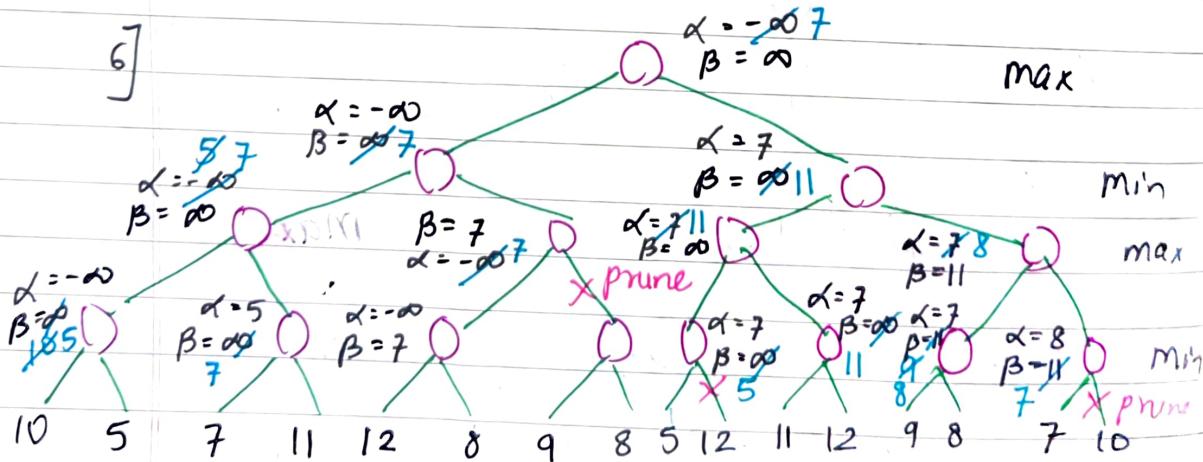
4)

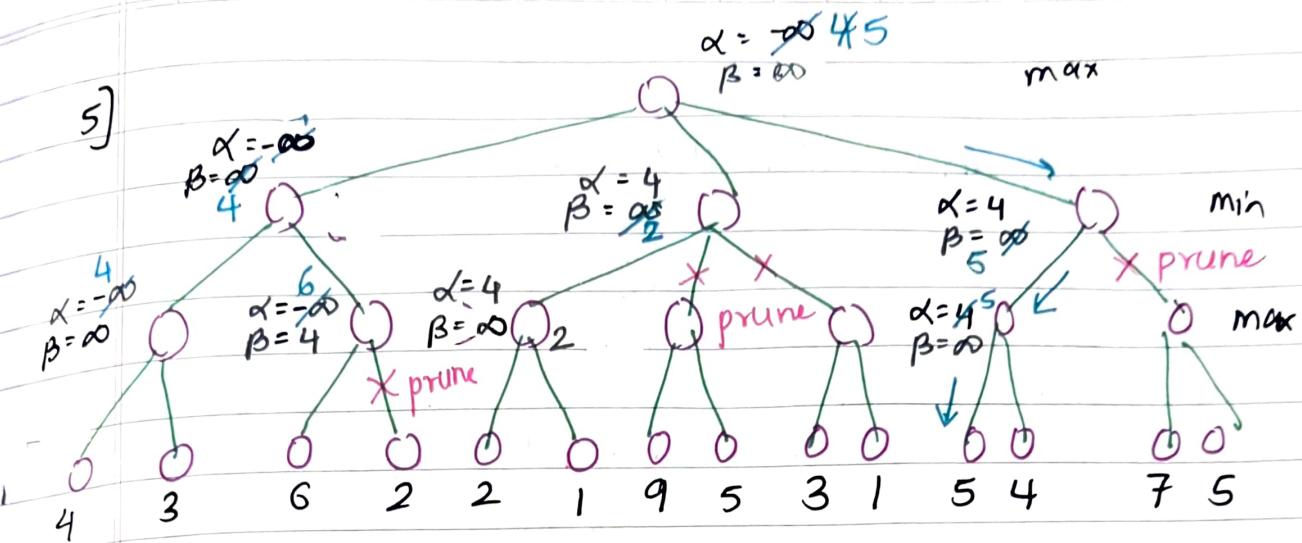


5)



6)





### → Hill Climbing Algorithm

1] Evaluate the initial state.

2] Loop until a solution is found or there are no options left.

(i') Select and apply a new operation.

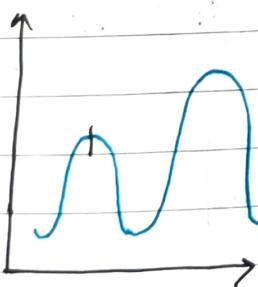
(ii') Evaluate the new state.

(iii') If goal is reached then quit.

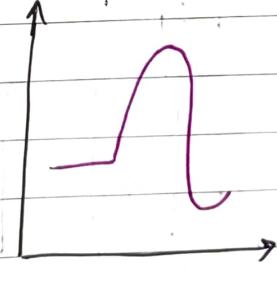
(iv') If new state is better than the current state then it becomes the current state.

3] Limitations

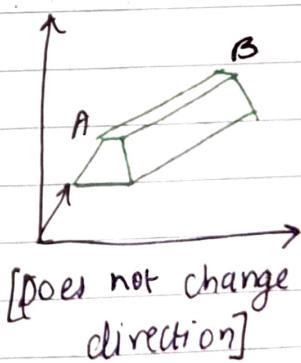
(i) Local Maxima



(ii) Plateau

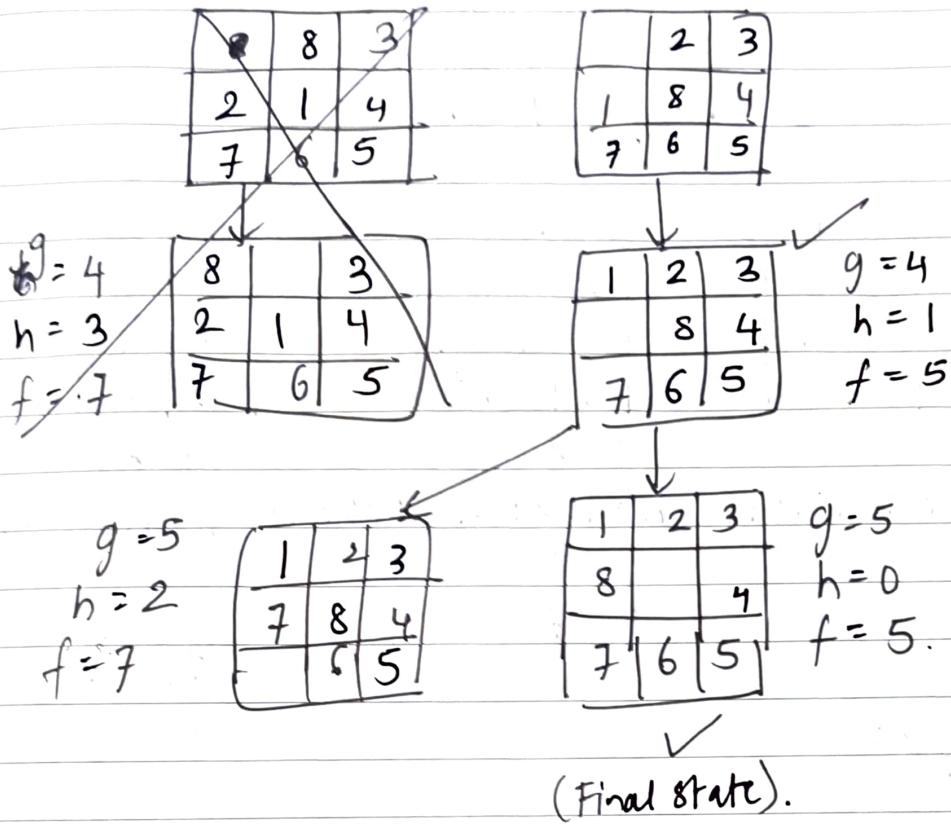


(iii) Ridge





Step 4:



2] Initial

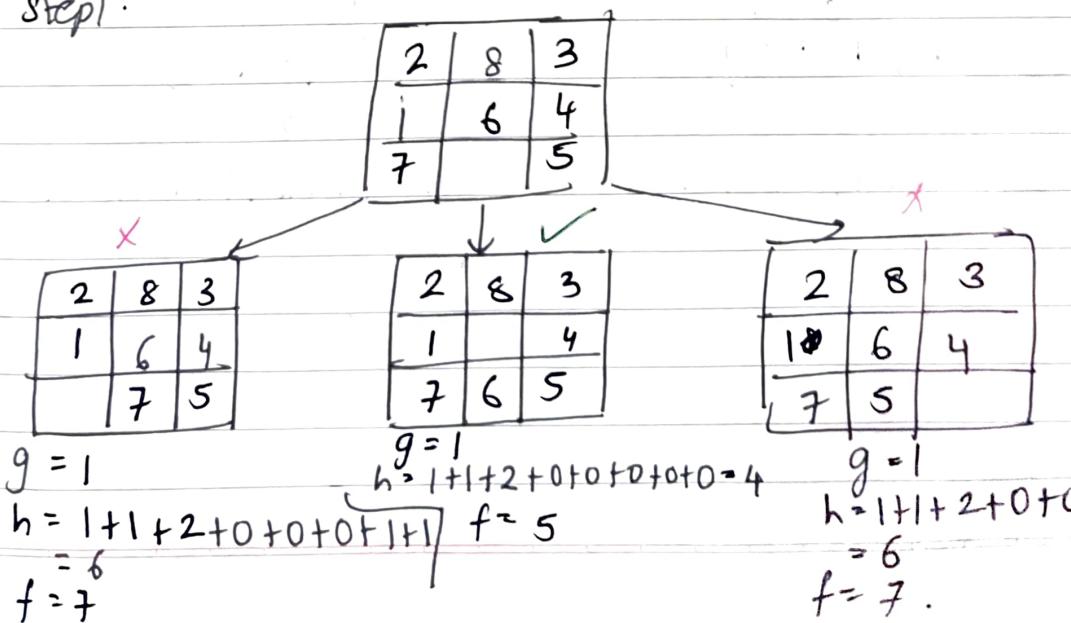
2	8	3
1	6	4
7	5	

Final

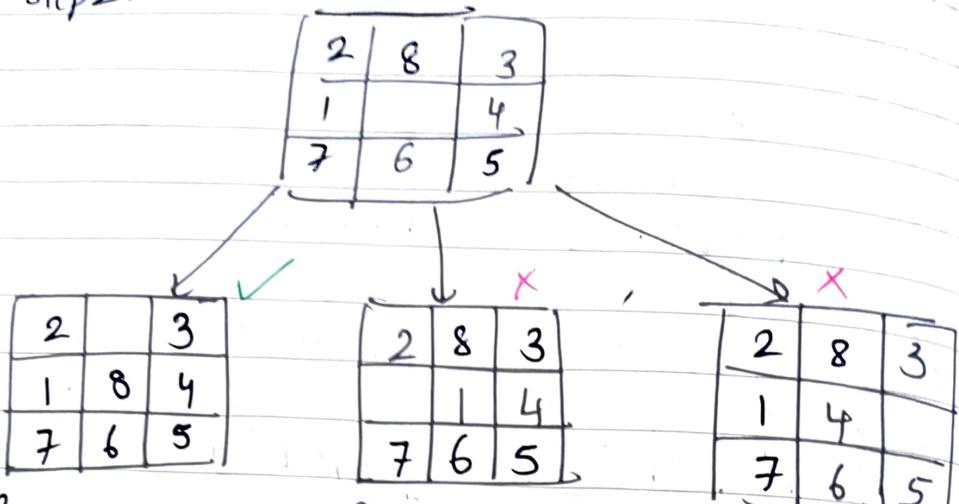
1	2	3
8		4
7	6	5

Using Manhattan dist.

Step 1:



Step 2:

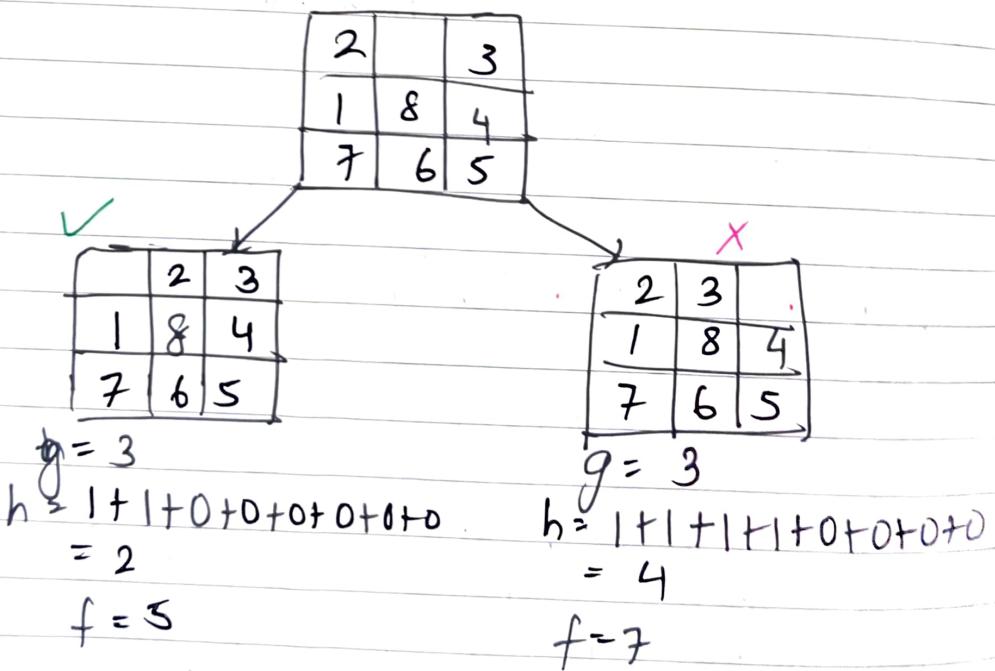


$$\begin{aligned}
 g &= 2 \\
 h &= 1+1+0+0+0+0+0+0+0 \\
 &= 3 \\
 f &= 5
 \end{aligned}$$

$$\begin{aligned}
 g &= 2 \\
 h &= 1+2+2+0+0+0+0+0 \\
 &= 5 \\
 f &= 7
 \end{aligned}$$

$$\begin{aligned}
 g &= 0 \\
 h &= 1+1+2+1+0+0+0 \\
 &= 5 \\
 f &= 7
 \end{aligned}$$

Step 3:



Step 4:

	2	3
1	8	4
7	6	5

1	2	3
8	4	
7	6	5

$$g = 4$$

$$h = 0+0+0+1+0+0+0+0+0$$

$$f = 5$$

1	2	3
7	8	4
6	5	

$$\begin{aligned} g &= 5 \\ h &= 2 \\ f &= 7 \end{aligned}$$

1	2	3
8		4
7	6	5

final ↗



$$g = 5$$

$$h = 0$$

$$f = 5 //$$