

# Math 151B Homework No. 3

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```
In [104]: import numpy as np
import matplotlib.pyplot as plt
plt.style.use("ggplot")
```

## Section 5.5

Below we implement the Runge-Kutta-Fehlberg method. It will be used to approximate solutions to ODEs in the following problems.

```

In [86]: def RKF(f, a, b, y_0, tol, h_max, h_min):
    """
    """

    t = a
    w = y_0
    h = h_max
    flag = 1
    d = 0

    T = np.array([t])
    Y = np.array([w])
    H = np.array([h])

    #print(T)
    #print(Y)
    #print(H)

    while flag == 1:
        k1 = h*f(t,w)
        k2 = h*f(t + .25*h, w + .25*k1)
        k3 = h*f(t + (3/8)*h, w + (3/32)*k1 + (9/32)*k2)
        k4 = h*f(t + (12/13)*h, w + (1932/2197)*k1 - (7200/2197)*k2 + (7
296/2197)*k3)
        k5 = h*f(t + h, w + (439/216)*k1 - 8*k2 + (3680/513)*k3 - (845/4
104)*k4)
        k6 = h*f(t + .5*h, w - (8/27)*k1 + 2*k2 - (3544/2565)*k3 + (1859
/4104)*k4 - (11/40)*k5)

        R = (1/h)*np.abs((1/360)*k1 - (128/4275)*k3 - (2197/75240)*k4 +
(1/50)*k5 + (2/55)*k6)

        #print("R = ", R)

        if R <= tol:
            t = t + h
            w = w + (25/216)*k1 + (1408/2565)*k3 + (2197/4104)*k4 - (1/5
)*k5

            T = np.append(T,t)
            Y = np.append(Y,w)
            H = np.append(H,h)

            #print("appended arrays")

            d = .84*(tol/R)**.25
            #print("d = ", d)

            if d <= .1:
                h = .1*h

            elif d >= 4:
                h = 4*h

            else:
                h = d*h

```

```

    if h > h_max:
        h = h_max

    if t >= b:
        flag = 0

    elif t + h > b:
        h = b - t

    elif h < h_min:
        flag = 0
        print("minimum h exceeded!")

    #print("done!")

    return T, Y, H

```

## 1.) (a)

```

In [133]: def f1(t,y):
            return t*np.exp(3*t) - 2*y

            def f1_exact(t):
                return (1/5)*t*np.exp(3*t) - (1/25)*np.exp(3*t) + (1/25)*np.exp(-2*t)
            )

```

```

In [134]: T,Y,H = RKF(f1,a = 0, b = 1, y_0 = 0, tol = 10**-4, h_max = .25, h_min =
            .05)

```

```

In [135]: print("t vals: \n", T, "\n")
            print("w vals: \n ", Y, "\n")
            print("h vals: \n ", H, "\n")

```

```

t vals:
[0.          0.20939    0.38329721 0.56104685 0.71068396 0.83877443
 0.95132633 1.          ]

w vals:
[0.          0.02981836 0.13432603 0.40164379 0.87083725 1.58940614
 2.61402262 3.21904974]

h vals:
[0.25        0.20939    0.17390722 0.17774964 0.1496371  0.12809048
 0.1125519   0.04867367]

```

```

In [136]: Y_exact = f1_exact(T)
            print("y vals: \n", Y_exact, "\n")

```

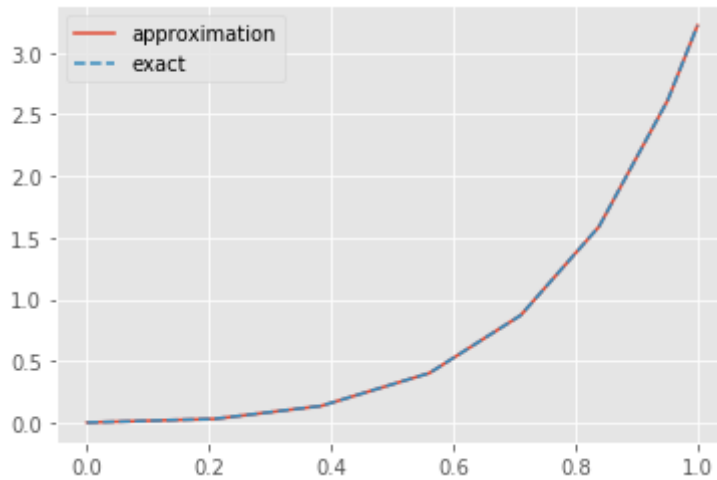
```

y vals:
[0.          0.02983366 0.13434875 0.40168601 0.87088816 1.58946002
 2.61407705 3.21909932]

```

```
In [137]: plt.plot(T,Y,label="approximation")
plt.plot(T,Y_exact,label = "exact",linestyle="--")

plt.legend()
plt.show()
```



## 2.) (a)

```
In [92]: def f2(t,y):
         return (y/t)**2 + (y/t)
```

```
In [93]: T,Y,H = RKF(f2,a = 1, b = 1.2, y_0 = 1, tol = 10**-4, h_max = .05, h_min
         = .02)
```

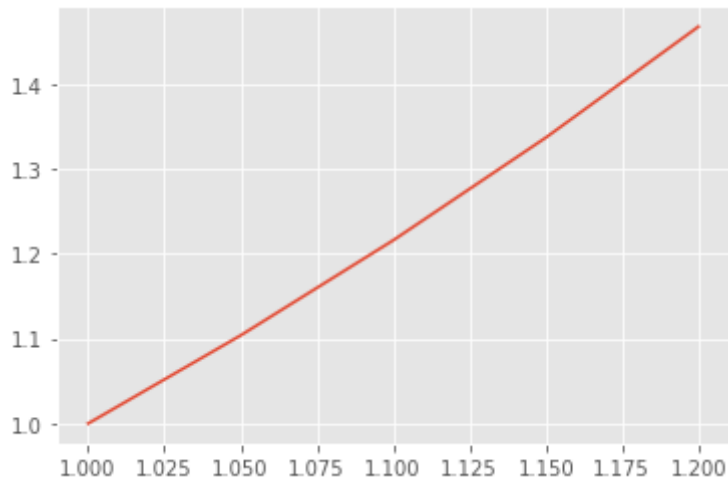
```
In [94]: print("t vals: \n", T, "\n")
print("w vals: \n ", Y, "\n")
print("h vals: \n ", H, "\n")
```

```
t vals:
[1.    1.05 1.1   1.15 1.2 ]
```

```
w vals:
[1.          1.10385741 1.2158864  1.33683935 1.46756971]
```

```
h vals:
[0.05 0.05 0.05 0.05 0.05]
```

```
In [95]: plt.plot(T,Y)
plt.show()
```



## Section 5.6

Below we implement the Adams Fourth-Order Predictor-Corrector method. It is used to approximate the solutions to ODEs in the following problem.

```
In [112]: def AB_Predictor_Corrector(f, a, b, y_0, N):
    h = (b-a)/N

    #t = np.arange(a, b+h, h)
    t = np.array([a + n * h for n in range(N + 1)])

    y = np.zeros((N+1,))

    y[0] = y_0

    for i in range(0,N):
        if i in range(0,3):
            k1 = h * f(t[i],y[i])
            k2 = h * f(t[i] + (h/2.0), y[i] + (k1/2.0))
            k3 = h * f(t[i] + (h/2.0), y[i] + (k2/2.0))
            k4 = h * f(t[i] + h, y[i] + k3)

            y[i + 1] = y[i] + (k1 + 2.0*k2 + 2.0*k3 + k4)/6.0

        else:
            y[i + 1] = y[i] + h*(55.0 * f(t[i],y[i]) - 59.0 * f(t[i-1],
y[i-1]) + 37.0 * f(t[i-2],y[i-2]) - 9.0 * f(t[i-3],y[i-3]))/24.0

            y[i + 1] = y[i] + h*(9.0 * f(t[i+1], y[i + 1]) + 19.0 * f(t
[i],y[i]) - 5.0 * f(t[i-1],y[i-1]) + f(t[i-2],y[i-2]))/24.0

    return (t,y)
```

5.)

(a)

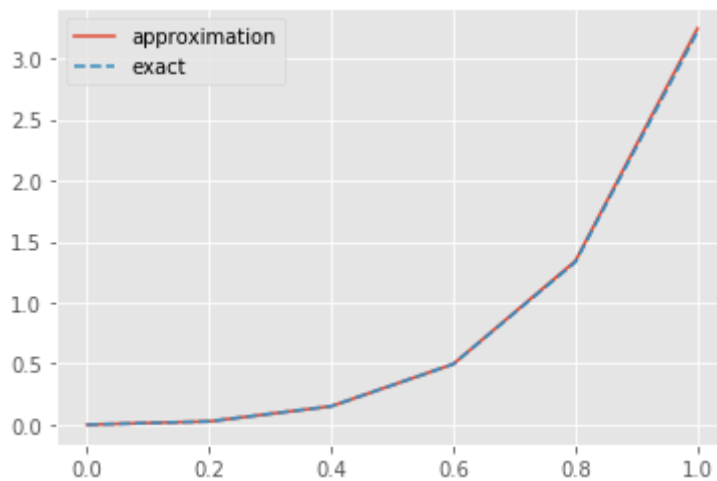
```
In [138]: T,Y = AB_Predictor_Corrector(f1,0,1,0,5)
Y_exact = f1_exact(T)

print("t vals: ", T)
print("w vals: ", Y)
print("y vals: ", Y_exact)

plt.plot(T,Y,label="approximation")
plt.plot(T,Y_exact,label="exact",linestyle="--")

plt.legend()
plt.show()
```

```
t vals: [0.  0.2  0.4  0.6  0.8  1. ]
w vals: [0.          0.02690591  0.15104685  0.49664786  1.3408657   3.2450
8812]
y vals: [0.          0.0268128   0.15077784  0.49601957  1.33085703  3.2190
9932]
```



(b)

```
In [120]: def f3(t,y):
            return 1 + (t-y)**2

def f3_exact(t):
    return t + 1/(1-t)
```

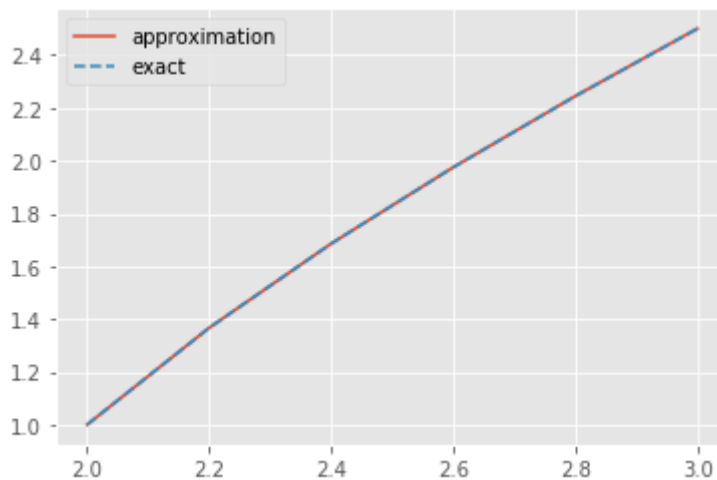
```
In [129]: T,Y = AB_Predictor_Corrector(f3,2,3,1,5)
Y_exact = f3_exact(T)

print("t vals: ", T)
print("w vals: ", Y)
print("y vals: ", Y_exact)

plt.plot(T,Y,label="approximation")
plt.plot(T,Y_exact,label="exact",linestyle="--")

plt.legend()
plt.show()
```

```
t vals: [2.  2.2 2.4 2.6 2.8 3. ]
w vals: [1.          1.36666096 1.68570787 1.97499411 2.24469946 2.5003
083 ]
y vals: [1.          1.36666667 1.68571429 1.975          2.24444444 2.5
]
```



**(c)**

```
In [116]: def f4(t,y):
            return 1 + y/t

def f4_exact(t):
    return t*np.log(t) + 2*t
```

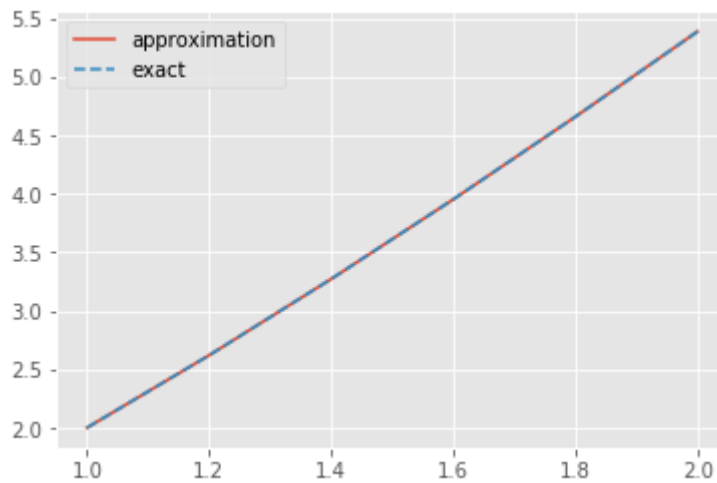
```
In [117]: T,Y = AB_Predictor_Corrector(f4,1,2,2,5)
Y_exact = f4_exact(T)

print("t vals: ", T)
print("w vals: ", Y)
print("y vals: ", Y_exact)

plt.plot(T,Y,label="approximation")
plt.plot(T,Y_exact,label="exact",linestyle="--")

plt.legend()
plt.show()
```

```
t vals: [1.  1.2 1.4 1.6 1.8 2. ]
w vals: [2.          2.6187787  3.27104908  3.95198996  4.65799685  5.3862
7155]
y vals: [2.          2.61878587  3.27106113  3.95200581  4.658016    5.3862
9436]
```



(d)

```
In [118]: def f5(t,y):
            return np.cos(2*t) + np.sin(3*t)

def f5_exact(t):
    return .5*np.sin(2*t) - (1/3)*np.cos(3*t) + 4/3
```



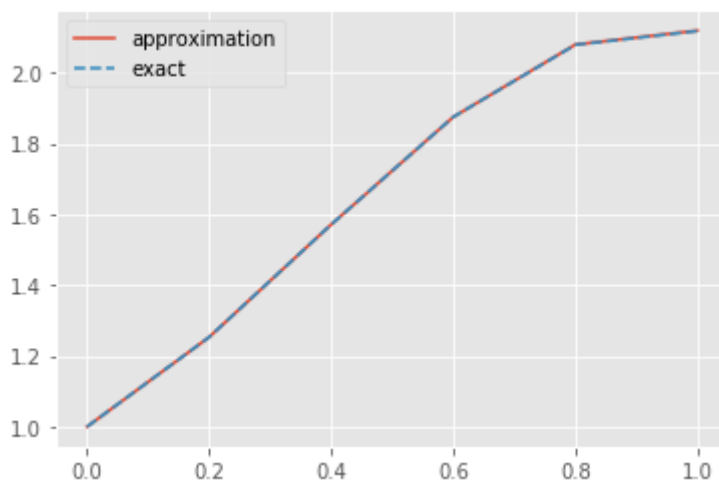
```
In [119]: T,Y = AB_Predictor_Corrector(f5,0,1,1,5)
Y_exact = f5_exact(T)

print("t vals: ", T)
print("w vals: ", Y)
print("y vals: ", Y_exact)

plt.plot(T,Y,label="approximation")
plt.plot(T,Y_exact,label="exact",linestyle="--")

plt.legend()
plt.show()
```

```
t vals: [0.  0.2  0.4  0.6  0.8  1. ]
w vals: [1.          1.25293502  1.57123833  1.87510968  2.07966176  2.1192
5748]
y vals: [1.          1.25293063  1.57122546  1.87508691  2.07891804  2.1179
7955]
```



In [ ]: