

Math 151B Final Exam Code

March 16, 2020

```
[71]: #importing all the necessary libraries  
#these are all included in a standard installation of Anaconda  
  
import numpy as np  
import matplotlib.pyplot as plt  
plt.style.use("ggplot")
```

0.1 3.)

(a.)

```
[199]: def EulerSystem3D(f,t0,y0,h,N):  
        """  
        """  
        T = np.array([t0 + n * h for n in range(N + 1)])  
        Y = np.zeros((N+1,3))  
  
        Y[0] = y0  
  
        for n in range(N):  
            Y[n+1] = Y[n] + h * f(T[n], Y[n])  
  
        return T,Y
```

```
[219]: def f(t,y):  
        return np.array([y[1],y[2],4*y[0]+4*y[1]-y[2]])  
  
def Y_exact(t):  
    return np.exp(-t) + np.exp(2*t) + np.exp(-2*t)  
  
t0 = 0  
y0 = np.array([3,-1,9])  
h = .2  
N = 10
```

```
[230]: T,Y = EulerSystem3D(f,t0,y0,h,N)
print("T values: \n", T)
print("Approximate Y values: \n", Y[:,0])
```

T values:

```
[0.  0.2  0.4  0.6  0.8  1.  1.2  1.4  1.6  1.8  2. ]
```

Approximate Y values:

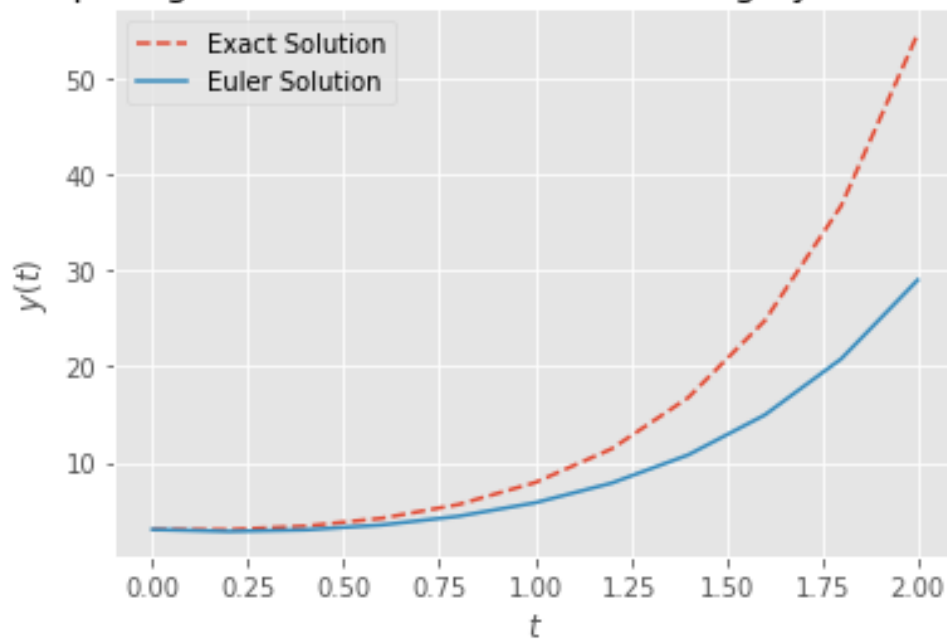
```
[ 3.          2.8          2.96          3.472          4.3808          5.78368
 7.838336    10.7790592    14.94245888    20.80534221    29.0388863 ]
```

```
[226]: plt.plot(T,y_exact(T),label="Exact Solution",linestyle="--")
plt.plot(T,Y[:,0],label="Euler Solution")

plt.title("Comparing Numerical Methods for Solving Systems of ODEs")
plt.ylabel("$y(t)$")
plt.xlabel("$t$")

plt.legend()
plt.show()
```

Comparing Numerical Methods for Solving Systems of ODEs



0.2 4.)

(a.)

```
[53]: A = np.array([[4,1,-1,0],[1,3,-1,0],[-1,-1,5,2],[0,0,2,4]])
      #print(A)

      evals = np.linalg.eigvals(A)
      domEval = np.max(evals)

      print("The dominant eigenvalue is ", domEval)
```

The dominant eigenvalue is 7.086130197651494

(b.)

```
[47]: def PowerMethod(A,x,n,tol=10e-4, N=25):
      """
      Implements the Power Method as described by the algorithm in the textbook.
      """
      k = 1

      xp = np.max(abs(x))
      x = x/xp

      eval_list = np.array([])

      while(k <= N):
          #print(k)
          y = A.dot(x)

          yp = np.max(np.abs(y))
          u = yp

          eval_list = np.append(eval_list,u)
          #print(eval_list)

          #print(u)

          if(yp == 0):
              print("A has eigenvalue 0, select a new vector x and restart.")
              return x,eval_list

          err = np.max(np.abs(x-(y/yp)))

          x = y/yp
          #print(x)

          if(err < tol):
              print("The procedure was successful!")
              return u,x,eval_list
```

```

        k = k + 1

    print("The maximum number of iterations exceeded! The procedure was_
↪unsuccessful.")
    return u,x,eval_list

```

```

[83]: n = 4
      N = 25
      tol = 10e-4
      x0 = np.array([0,1,0,0])

      u,v,evals_P = PowerMethod(A,x0,n,tol,N)

      N1 = evals_P.size
      N1_vals = np.arange(N1)

      print("The dominant eigenvalue is ", u)

```

The procedure was successful!
The dominant eigenvalue is 7.087013746136077

(d.)

```

[84]: def SymmetricPowerMethod(A,x,n,tol=10e-4, N=25):
      """
      Implements the Symmetric Power Method as described by the algorithm in the_
↪textbook.
      """
      k = 1

      x = x/np.linalg.norm(x)

      eval_list = np.array([])

      while(k <= N):
          #print(k)
          y = A.dot(x)

          u = x.dot(y)

          eval_list = np.append(eval_list,u)
          #print(eval_list)

          #print(u)

          y_norm = np.linalg.norm(y)

          if(y_norm == 0):

```

```

        print("A has eigenvalue 0, select a new vector x and restart.")
        return x,eval_list

    err = np.linalg.norm(x - (y/y_norm))

    x = y/y_norm
    #print(x)

    if(err < tol):
        print("The procedure was successful!")
        return u,x,eval_list

    k = k + 1

    print("The maximum number of iterations exceeded! The procedure was_
→unsuccessful.")
    return u,x,eval_list

```

```

[82]: u,v,evals_S = SymmetricPowerMethod(A,x0,n,tol,N)

N2 = evals_S.size
N2_vals = np.arange(N2)

print("The dominant eigenvalue is ", u)

```

The procedure was successful!
The dominant eigenvalue is 7.086117416340071
(e.)

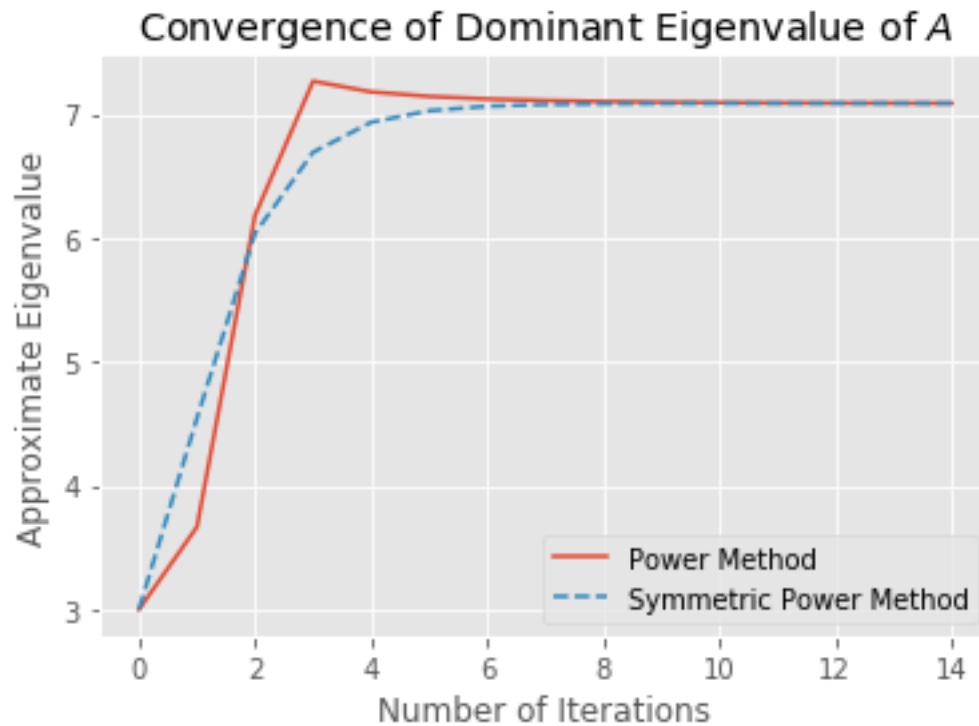
```

[85]: plt.plot(N1_vals,evals_P,label="Power Method")
plt.plot(N2_vals,evals_S,linestyle="--",label="Symmetric Power Method")

plt.title("Convergence of Dominant Eigenvalue of $A$")
plt.xlabel("Number of Iterations")
plt.ylabel("Approximate Eigenvalue")

plt.legend()
plt.show()

```



We can see from the plot that the Symmetric Power Method converges to the value of the dominant eigenvalue faster than the Power Method. Thus, the Symmetric Power Method performs better.

0.3 5.)

```
[86]: def F(f,x,n):
    """
    Evaluates an n dimensional array of functions f at a point x.
    """
    fx = np.zeros([n,1])

    for i in range(n):
        fx[i] = f[i](x)

    return fx

def J(j,x,n):
    """
    Evaluates an n x n matrix of functions j at a point x.
    """
    jx = np.zeros([n,n])
```

```

for i in range(n):
    for k in range(n):
        jx[i,k] = j[i,k](x)

return jx

```

(a.)

```

[87]: def G(f):
        """
        Computes the function  $g(x)$  as defined in the book.
        """
        return np.sum(f**2)

def Grad(J,F):
    """
    Computes the gradient of  $g(x)$  using the Jacobian and  $F$ .
    """
    n = F.shape[0]
    g = 2*np.matmul(np.transpose(J),F)
    return np.reshape(g,n)

```

```

[102]: def SteepestDescent(n,x0,tol,N):
        """
        Implements the Gradient Descent Algorithm according to the algorithm in the
        ↪book.
        """
        k = 1
        x = x0

        x_list = np.array([x])

        while(k <= N):
            #print(k)

            g1 = G(F(f,x,n))
            #print("g1 = ", g1)

            z = Grad(J(j,x,n),F(f,x,n))

            z0 = np.linalg.norm(z)

            if(z0 == 0):
                print("Zero gradient!")
                return x,x_list

            z = z/z0

```

```

#print("z = ", z)

a1 = 0
a3 = 1

g3 = G(F(f,x-a3*z,n))
#print("g3 = ", g3)

while(g3 >= g1):
    a3 = 0.5*a3
    g3 = G(F(f,x-a3*z,n))

    if(a3 < tol/2):
        print("No likely improvement...")
        return x,x_list

a2 = 0.5*a3

g2 = G(F(f,x-a2*z,n))
#print("g2 = ", g2)

h1 = (g2-g1)/a2
h2 = (g3-g2)/(a3-a2)
h3 = (h2-h1)/a3

#print("h1 = ", h1)
#print("h2 = ", h2)
#print("h3 = ", h3)

a0 = 0.5*(a2-h1/h3)
g0 = G(F(f,x-a0*z,n))

#print("a0 = ", a0)
#print("g0 = ", g0)

if(g0 <= g3):
    a = a0
    g = g0
else:
    a = a3
    g = g3

x = x -a*z
x_list = np.append(x_list,[x],axis=0)

```



```

        if(np.abs(g-g1) < tol):
            print("The procedure was successful!")
            return x,x_list

        k = k+1

    print("Maximum number of iterations exceeded!")
    return x,x_list

```

```

[158]: def f1(x):
        return x[0]**3 + (x[0]**2)*x[1] - x[0]*x[2] + 6
    def f2(x):
        return np.exp(x[0]) + np.exp(x[1]) - x[2]
    def f3(x):
        return x[1]**2 - 2*x[0]*x[2] - 4

    def j11(x):
        return 3*(x[0]**2) + 2*x[0]*x[1] - x[2]
    def j12(x):
        return x[0]**2
    def j13(x):
        return -1*x[0]
    def j21(x):
        return np.exp(x[0])
    def j22(x):
        return np.exp(x[1])
    def j23(x):
        return -1
    def j31(x):
        return -2*x[2]
    def j32(x):
        return 2*x[1]
    def j33(x):
        return -2*x[0]

    f = np.array([f1,f2,f3])
    j = np.array([[j11,j12,j13],[j21,j22,j23],[j13,j23,j33]])
    x0 = np.array([1,1,1])

    n = 3
    tol = 10e-5
    N = 100

```

```

[163]: x, xvals_SD = SteepestDescent(n,x0,tol,N)
    print("The approximate solution to the system of equations is: \n","x = ", x)

```

No likely improvement...

The approximate solution to the system of equations is:

```
x = [0.11822276 0.52917242 1.02811216]
```

(b.)

```
[160]: def Newton_Method_Systems(n,x0,tol,N):
    k = 1
    x = x0

    x_list = np.array([x])

    while(k <= N):
        #print("iteration ", k)

        fx = F(f,x,n)
        jx = J(j,x,n)

        #print("J(x) = \n", jx)
        #print("F(x) = \n", fx)

        #jx_inv = np.linalg.inv(jx)

        #print("F(x) = \n", fx)
        #print("J(x) = \n", jx)
        #print("J(x) Inverse = \n", jx_inv)

        y = -1*np.linalg.solve(jx,fx)
        y = y.reshape(n)

        x = x + y

        x_list = np.append(x_list,[x],axis=0)

        #print("y = ", y)
        #print("x = ", x)

        if(np.linalg.norm(y) < tol):
            print("The procedure was successful!")
            return x,x_list

        k = k + 1

    print("Max number of iterations surpassed. The procedure was unsuccessful!")
    return x,x_list
```

```
[162]: x,xvals_NM = Newton_Method_Systems(n,x0,tol,N)
print("The approximate solution to the system of equations is: \n","x = ", x)
```

Max number of iterations surpassed. The procedure was unsuccessful!

The approximate solution to the system of equations is:

```
x = [-2.80897387  1.74159019  2.3547992 ]
```

(c.)

```
[170]: def BroydenMethod(n, x0, tol = 10e-6, N = 100):
        """
        Implements Broyden's Method according to the algorithm in the book.
        """
        x = x0.reshape((n,1))
        x_list = np.array([x.flatten()])

        A0 = J(j,x,n)
        v = F(f,x,n)

        A = np.linalg.inv(A0)

        s = -1*np.matmul(A,v)
        x = x + s
        k = 2

        while(k <= N):
            w = v
            v = F(f,x,n)
            y = v - w

            z = -1*np.matmul(A,y)

            p = -1*np.matmul(np.transpose(s),z)

            ut = np.matmul(np.transpose(s),A)

            A = A + (1/p)*np.matmul((s+z),ut)

            s = -1*np.matmul(A,v)
            x = x + s

            x_list = np.append(x_list,[x.flatten()],axis=0)

            if(np.linalg.norm(s) < tol):
                print("The procedure was successful!")
                return x.flatten(),x_list

            k = k + 1
```

```
print("Maximum number of iterations exceeded!")
return x.flatten(),x_list
```

```
[172]: x,xvals_BM = BroydenMethod(n,x0,tol,N)
print("The approximate solution to the system of equations is: \n","x = ", x)
```

The procedure was successful!

The approximate solution to the system of equations is:

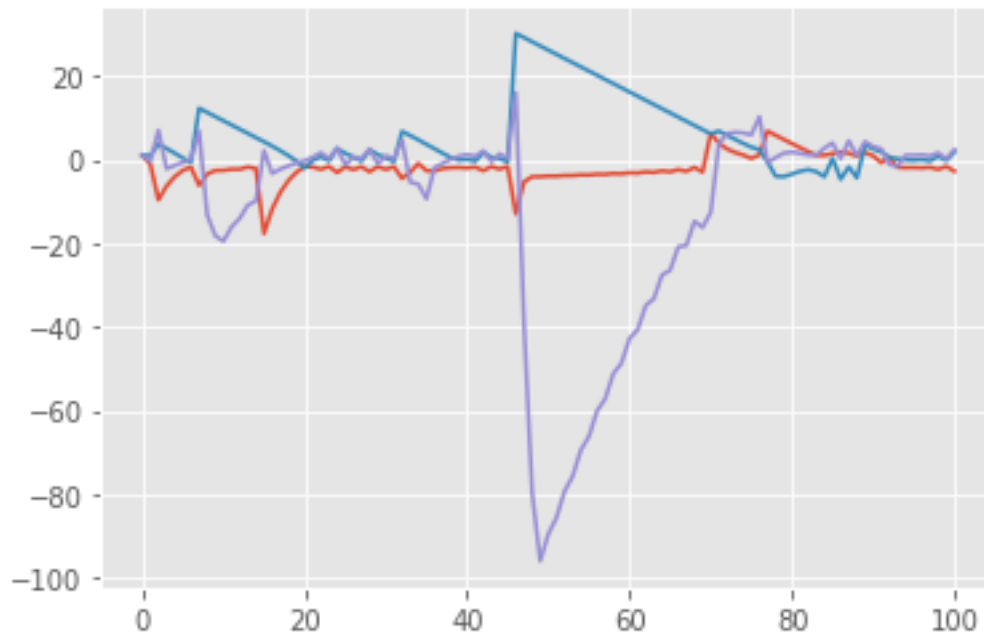
```
x = [-1.4560397 -1.66423221 0.42249382]
```

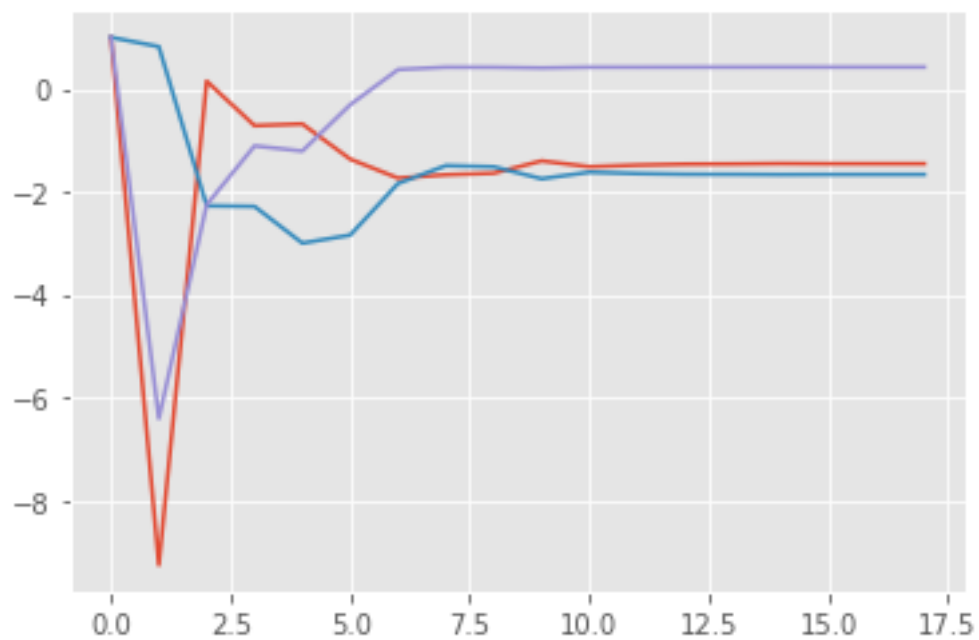
(d.)

```
[188]: N_NM = np.shape(xvals_NM)[0]
N_BM = np.shape(xvals_BM)[0]

NM_vals = np.arange(N_NM)
BM_vals = np.arange(N_BM)

plt.plot(NM_vals,xvals_NM)
plt.show()
plt.plot(BM_vals,xvals_BM)
plt.show()
```





[]: