Graphics Pipeline

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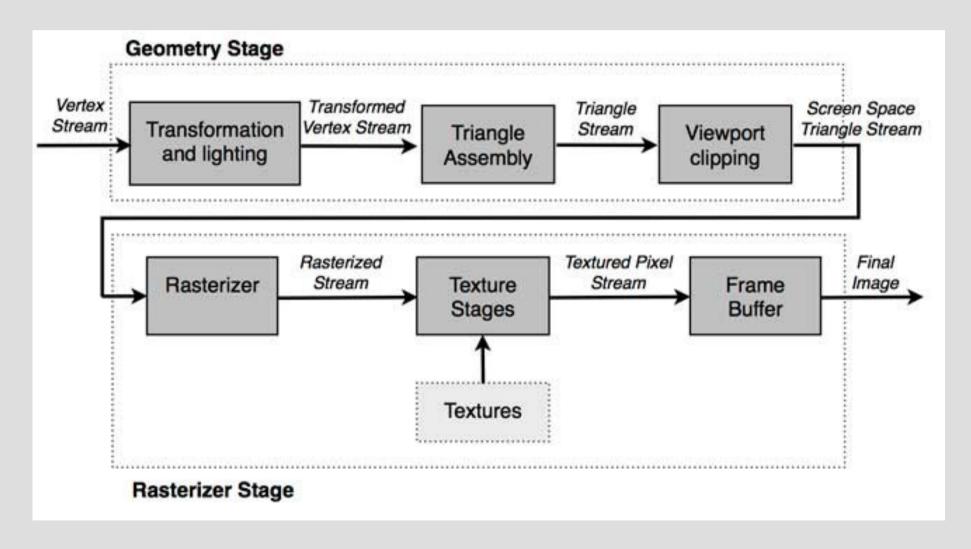
Course www: https://www.scss.tcd.ie/Rachel.McDonnell/

Credits: Real-time Rendering, 3rd Edition, Akenine-Moller

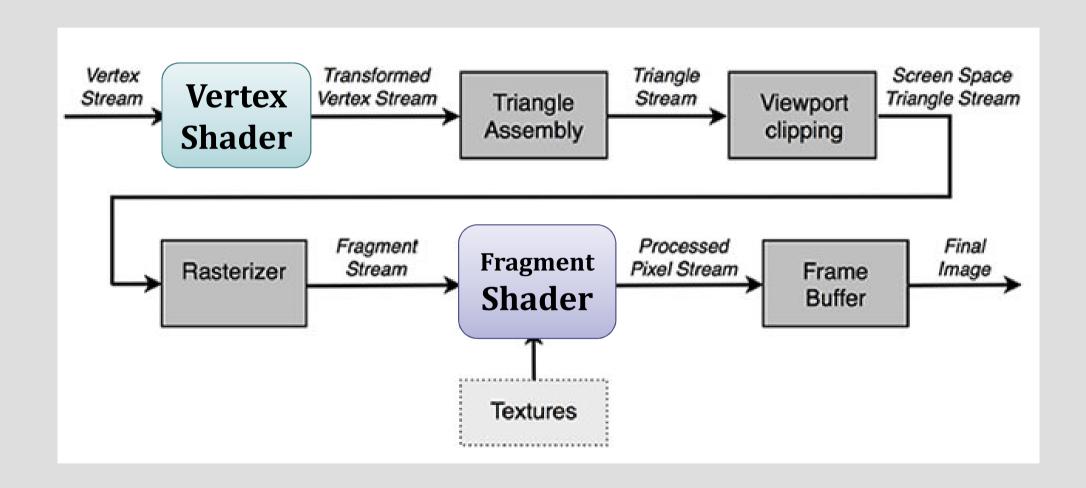
Overview

- Graphics Pipeline
- Graphics Programming
 - OpenGL background
 - OpenGL conventions,
 - GLUT Event loop, callback registration
 - OpenGL primitives, OpenGL objects
 - Shaders
 - Vertex Buffer Objects
 - Books, resources, recommended reading

Fixed Function Pipeline

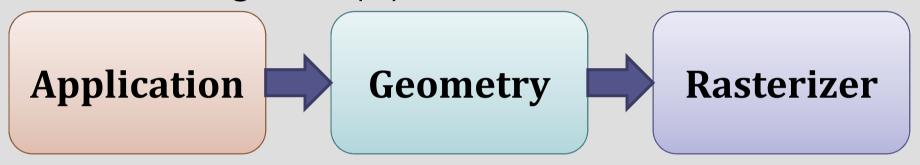


Graphics Programmable Pipeline



Graphics Pipeline Overview

- Coarse Division
- Each stage is a pipeline in itself



 The slowest pipeline stage determines the rendering speed (fps)

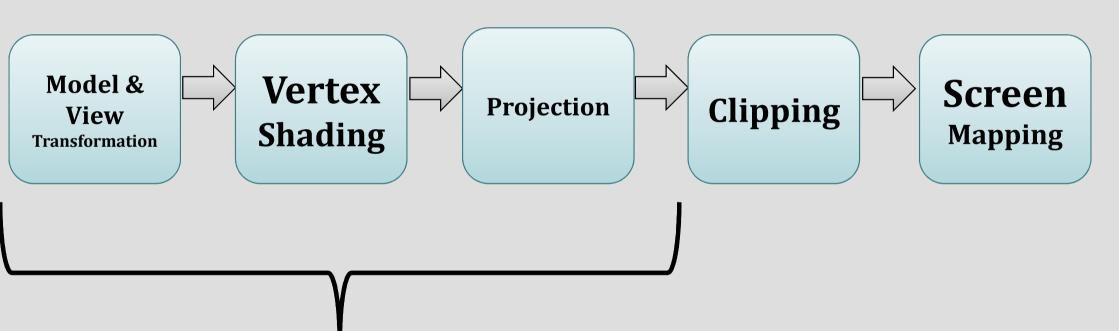
The Application Stage

Application

- Developer has full control
- Executes on the CPU
- At the end of the application stage, the rendering primitives are fed to the geometry stage

The Geometry Stage

Responsible for the per-polygon and per-vertex operations



Implemented in the vertex shader

OpenGL Vertices

- OpenGL uses a 4
 component vector to
 represent a vertex.
- Known as a homogenous coordinate system
- z = 0 in 2D space
- w = 1 usually

$$v = \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}$$

Model & View Transformation

Model & View Transform

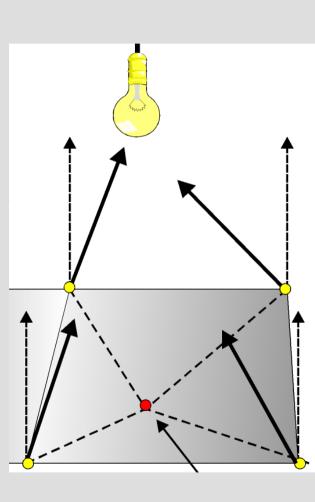
- Models are transformed into several spaces or coordinate systems
- Models initially reside in model space
 - i.e. no transformation
- "Model transform"
 positions the object in
 world coordinates or world
 space
- The view transform



Vertex Shading

Vertex Shading

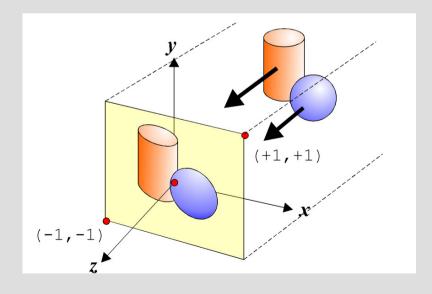
- Shading means determining the effect of a light on a material
- A variety of material data can be stored at each vertex
 - Points location
 - Normal
 - Color
- Vertex shading results (colors, vectors, texture coordinates, or any other kind of shading data) are then send to the rasterization stage to be interpolated



Projection

Projection

- After shading, rendering systems perform projection
- Models are projected from three to two dimensions
- Perspective or orthographic viewing



Clipping

Clipping

- The computer may have model, texture, and shader data for all objects in the scene in memory
- The virtual camera viewing the scene only "sees" the objects within the field of view
- The computer does not need to transform, texture, and shade the objects that are behind or on the sides of the camera

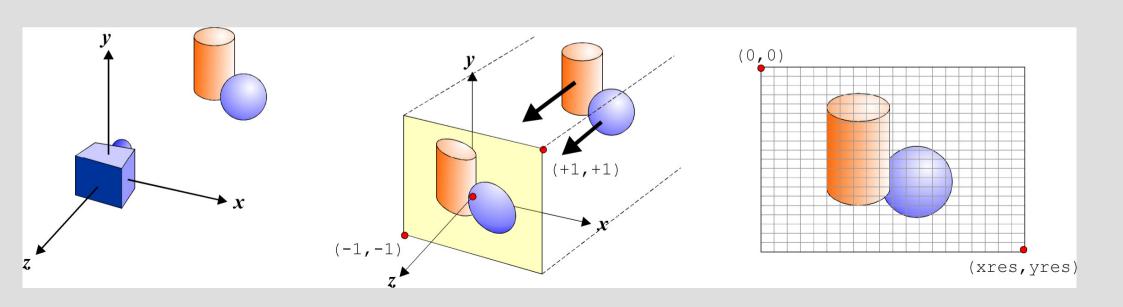
 A clipping algorithm skips these objects making rendering more efficient

Outside view so must be clipped

Screen Mapping

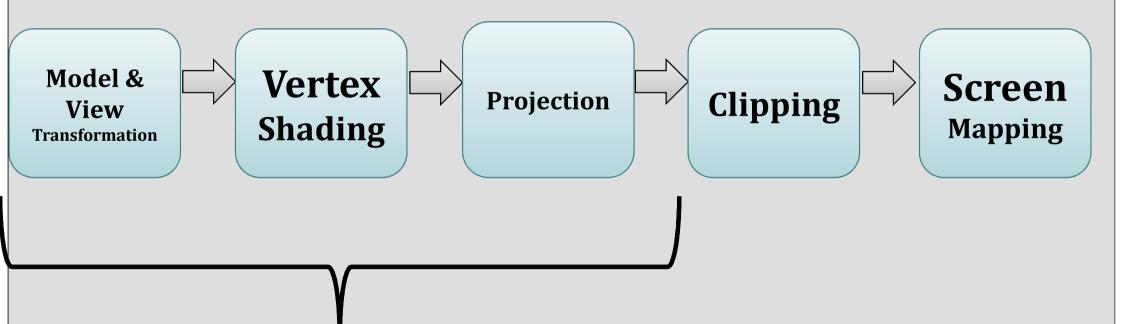
Screen Mapping

- Only the clipped primitives inside the view volume are passed to this stage
- Coordinates are in 3D
- The x- and y-coordinates of each primitive are transformed to for screen coordinates



The Geometry Stage

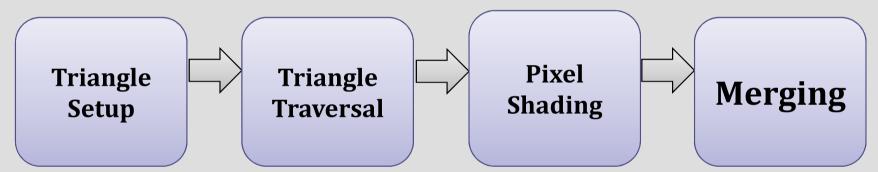
Responsible for the per-polygon and per-vertex operations



Implemented in the vertex shader

The Rasterizer Stage

 Given the transformed and projected vertices with their associated shading data (from geometry stage)



- The goal of the rasterizer stage is to compute and set colors for the pixels covered by the object
- Rasterization: conversion from 3D vertices in screen-space to pixels on the screen

Triangle Setup

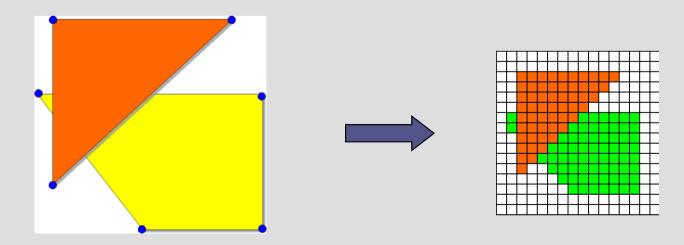
Triangle Setup

- Vertices are collected and converted into triangles.
- Information is generated that will allow later stages to accurately generate the attributes of every pixel associated with the triangle.

Triangle Traversal

Triangle Traversal

- Which pixels are inside a triangle?
- Each pixel that has its centre covered by the triangle is checked
- A fragment is generated for the part of the pixel that overlaps the triangle
- Triangle vertices interpolation



Pixel Shading

Pixel Shading

- Per-pixel shading computations are performed here
- End result is one or more colours to be passed to the next stage
- Executed by programmable
 GPU cores
- NB: Texturing is employed here



Merging

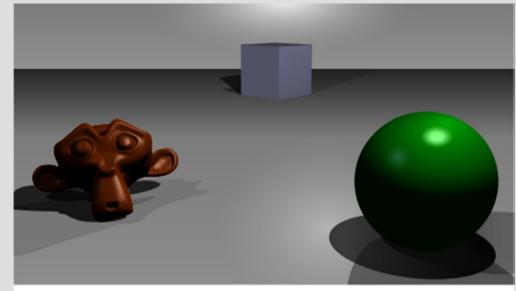
Merging

- Information for each pixel is stored in the colour buffer (a rectangular array of colours)
- Combine the fragment colour produced by the shading stage with the colour currently stored in the buffer

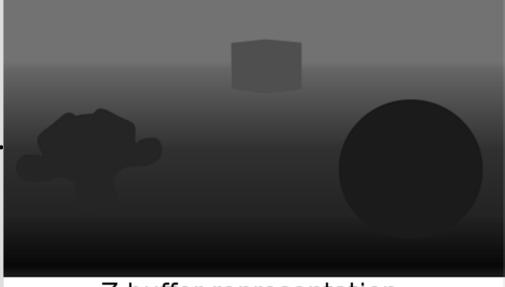
- This stage is also responsible for resolving visibility
 - Using the z-buffer

Z-Buffer

- Arranged as a 2D array with one element for each screen pixel.
- Stores the z-value from the camera to the currently closest primitive
- If another object of the scene must be rendered in the same pixel, the method compares the two depths and chooses the one closer to the observer.
- The chosen depth is then saved to the z-buffer, replacing the old one.



A simple three-dimensional scene



Z-buffer representation

Double Buffering

- Passed the rasterizer stage, those primitives that are visible from the point of view of the camera are displayed on screen
- The screen displays the contents of the color buffer
- To avoid perception of primitives being rasterized, double buffering is used
- Rendering takes place off screen in a back buffer
- Once complete, contents are swapped with the front buffer